# Anisotropy analysis of 3d point processes

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## **Motivation**



Polar ice is compacted (sintered) snow. During the compression air pores are isolated in the ice.

Image: Freitag 1), Kipfstuhl 1), Stauffer 2) 1) Alfred-Wegener-Institute for polar and marine research, Bremerhaven 2) University Bern



#### Question

Does the location of the pores tell anything about the movements of the ice?

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#### Data



tomographic images of ice samples cylinder 15 mm height, 15 mm diameter imaged inside a cold room at  $-15^{\circ}C$ 

images from three depths: 153 m, 353 m, 505 m

14 samples per depth





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#### Model for pressing

shape of the pores not significant -> concentrate on pore centres

Transformation

volume preserving compression

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} \frac{x}{\sqrt{c}} \\ \frac{y}{\sqrt{c}} \\ cz \end{pmatrix}, 0 < c < 1$$

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Aim

- detection of the distortion
- estimation of the parameter c



#### Methods in 2d

- point-pair rose density (Stoyan, Beneš, 1991)
- directional pair correlation function (Stoyan, Stoyan, 1992)
- Fry-method (Fry, 1979)
- directional K-function, 0-contour of the density  $\frac{d}{d\varphi}K(r,\varphi)$ (Stoyan, Kendall, Mecke, 1995)

Idea

partition of circle compare estimates of summary statistics for different directions

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## Problems and ideas in 3d

measurement of characteristics easy and robust

methods for visualisation of results

#### **Problems**

**Requirements** 

- more parameters than in 2d
- partition of the ball into suitable equal volume parts?

- -> choose cumulative instead of density functions
- -> adapt directions of investigation to the problem



#### Idea



Advantage of cone

- investigate point pattern in double cones aligned along coordinate axes
- compare observations
- large differences -> anisotropy

here:  $\theta = \frac{\pi}{4}$ 

- + easy parametrisation w.r.t. spherical coordinates
- + can be rotated to arbitrary directions -> adaptable to data



## **Directional summary statistics: directional** K

Directional version of the K-function

Second reduced moment measure of the cone C expected number of points within the double cone  $x_0 + C$ 

#### **Estimator**

 $K_{\mathsf{dir}}$ 

$$\lambda^{2} \widehat{K}_{\mathrm{dir},u,\theta}(r) = \sum_{x \in \psi} \sum_{y \in \psi, y \neq x} \frac{\mathbb{1}_{C_{u}(r,\theta)}(x-y)}{|W_{x} \cap W_{y}|}, \ r \ge 0,$$

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 $W_x$  translation of the window W by the vector x |B| volume of a set  $B \subset \mathbb{R}^3$ 



## **Directional summary statistics: local** G

Directional version of the nearest neighbour distance distribution function *G* 

Distribution function of the distance from the typical point of the process to the closest point in the cone  $x_0 + C$ .

#### **Estimator**

 $G_{\mathsf{loc}}$ 

$$\widehat{G}_{\mathsf{loc},u,\theta}(r) = \frac{\sum\limits_{(x,d)\in\psi} \mathbb{1}_{[0,r]}(d) \, \mathbb{1}\{x + C_u(d,\theta) \subset W\}}{\sum\limits_{(x,d)\in\psi} \mathbb{1}\{x + C_u(d,\theta) \subset W\}}, \, r \ge 0.$$

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## Directional summary statistics: global G

Directional version of the nearest neighbour distance distribution function G

Distribution function of the distance between  $x_0$  and its nearest neighbour y conditioned on  $y \in x_0 + C$ .

#### **Estimator**

 $G_{\mathsf{glob}}$ 

$$\widehat{G}_{ ext{glob},u, heta}(r) = rac{\sum\limits_{(x,y)\in\Psi} 1\!\!\!\mathrm{I}_{C_u(r, heta)}(x-y) \ 1\!\!\mathrm{I}_{W\ominus b(0,||x-y||)}(x)}{\sum\limits_{(x,y)\in\Psi} 1\!\!\!\mathrm{I}_{C_u(\infty, heta)}(x-y) \ 1\!\!\mathrm{I}_{W\ominus b(0,||x-y||)}(x)}, \ r \ge 0.$$

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less points investigated, stronger for higher intensities?



#### **Isotropy tests**

#### Given

 $\widehat{S}_x$ ,  $\widehat{S}_y$ ,  $\widehat{S}_z$ 

**Test statistics** 

*n* point patterns  $\psi_1, \ldots, \psi_n$ .

Estimators of one of the summary statistics with respect to the x-, y-, and z-direction.

$$T_{xy} = \int_{r_1}^{r_2} |\hat{S}_x(r) - \hat{S}_y(r)| \, dr, \text{ and}$$
$$T_z = \min\left(\int_{r_1}^{r_2} |\hat{S}_x(r) - \hat{S}_z(r)| \, dr, \int_{r_1}^{r_2} |\hat{S}_y(r) - \hat{S}_z(r)| \, dr\right),$$

where  $[r_1, r_2]$  is a given interval.



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#### **Isotropy tests**

**Test statistics** 

$$T_{xy} = \int_{r_1}^{r_2} |\hat{S}_x(r) - \hat{S}_y(r)| \, dr, \text{ and}$$
$$T_z = \min\left(\int_{r_1}^{r_2} |\hat{S}_x(r) - \hat{S}_z(r)| \, dr, \int_{r_1}^{r_2} |\hat{S}_y(r) - \hat{S}_z(r)| \, dr\right),$$

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Test

Alternative

reject isotropy hypothesis at level  $\alpha$  if  $T_{z,i}$  is larger than 100(1 -  $\alpha$ )% of the estimated  $T_{xy}$  values

Monte Carlo test, if few replications available requires model for the data



#### Simulation study

Investigate different

Compress with pressing factor c.

- degrees of regularity: Matérn hard core point process and packing of balls (force biased algorithm)
- intensities:  $\lambda = 500$  and  $\lambda = 1000$
- hard core radii: R = 0.025, 0.05, and 0.075

Simulate regular point patterns in the unit cube.

- pressing factors: c = 0.7, 0.8, and 0.9



#### Simulation results: Matérn hard core

**Parameters** 

 $\lambda = 500, R = 0.05, and c = 0.8$ 





#### **Simulation results: Force biased**

**Parameters** 

 $\lambda = 500, R = 0.05, and c = 0.8$ 





#### Anisotropy analysis of 3d point processes

#### **Powers of tests** Investigate influence of degree of regularity, intensity, hard core radius, pressing factor interval of observation [0, 1.1R], [0, 4/3R], [0, 0.1] ([0, 0.2], resp.)test intervals 0.05 0.05 0.05 0.075 0.075 R0.075 0.0825 $0^{1}$ 0.067 0.055 0.2 0.1 $r_2$ 99.8 73.8 97.2 91.7 100 $G_{\mathsf{loc}}$ 172

21.3

19.9

 $G_{\mathsf{glob}}$ 

 $K_{dir}$ 

68.2

79.7

powers of the tests on a 5% significance level, based on 1000 realisations

96.6

98.8

93.9

36.9

98.6

100

100

100



## **Existence of outliers**

In real data the existence of outliers, i.e. points which violate the hard core condition, is likely. How does this influence the results?

Therefore:	<ul> <li>use point patterns from previous simulation</li> </ul>
	- choose 5 random points $x_1, \ldots, x_5$ from each pattern
	- include a further point $y_i$ in balls of radius R centred in $x_i$
Result	<ul> <li>decreasing powers of the tests</li> </ul>
	- better results for $K_{dir}$ and $G_{loc}$ than for $G_{glob}$ .

– larger integration intervals should be chosen.



## Alternative: Investigate direction to nearest neighbour

Given	set of unit vectors $v_i = (x_i, y_i, z_i), i = 1, \dots, n$
Orientation matrix	$A = \begin{pmatrix} \sum x_i^2 & \sum x_i y_i & \sum x_i z_i \\ \sum x_i y_i & \sum y_i^2 & \sum y_i z_i \\ \sum x_i z_i & \sum y_i z_i & \sum z_i^2 \end{pmatrix}$
$\lambda_1 \ge \lambda_2 \ge \lambda_3$	eigenvalues of A
Test statistic	largest eigenvalue $\lambda_1$
Significance points	at 5% level: $\frac{1}{3} + \frac{0.873}{\sqrt{n}}$ for $n > 100$ , Anderson, Stephens (1972)
Results	weaker performance than tests based on summary statistics
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#### **Summary of results**

- tests using summary statistics better than analysis of direction to nearest neighbour
- higher regularity, larger intensities, stronger pressing
- integration interval should be chosen suitably
- in most cases:  $K_{dir}$  yields best results
- test with G functions more stable when changing interval
- tests also work for compressed clustered patterns



Higher power for

## **Estimation of the pressing factor**

- rescale by  $(\sqrt{d}, \sqrt{d}, \frac{1}{d})$  with  $d \in [0.6, 1.1]$
- compute statistics

$$T_{\sum,d} = \int_{r_1}^{r_2} \left( |\hat{S}_{x,d}(r) - \hat{S}_{y,d}(r)| + |\hat{S}_{y,d}(r) - \hat{S}_{z,d}(r)| + |\hat{S}_{z,d}(r) - \hat{S}_{x,d}(r)| \right) dr,$$

**Estimator for c** 

$$\hat{c} = \operatorname{argmin}_{d} T_{\sum, d}$$

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#### **Results for simulated data**

#### **Parameters:**

 $\lambda = 500, R = 0.05$ 

$r_2$	С	$\overline{\widehat{c}}_{loc}$	MSE	$\overline{\widehat{c}}_{glob}$	MSE	$ar{\widehat{c}}_K$	MSE
0.055	1.0	0.9828	3.944e-3	0.9795	6.763e-3	0.9875	4.850e-3
0.055	0.9	0.8810	5.813e-3	0.8855	5.138e-3	0.8933	3.631e-3
0.055	0.8	0.7780	5.363e-3	0.7818	4.544e-3	0.7923	2.844e-3
0.055	0.7	0.6880	1.850e-3	0.6913	1.981e-3	0.6860	1.988e-3
0.15	1.0	1.0005	2.625e-3	0.9385	2.081e-2	0.9955	1.813e-3
0.15	0.9	0.8953	2.806e-3	0.9060	1.819e-2	0.8993	1.669e-3
0.15	0.8	0.7968	2.306e-3	0.8655	2.511e-2	0.8030	1.013e-3
0.15	0.7	0.6958	1.631e-3	0.8128	3.222e-2	0.7015	7.125e-4



#### **Ice: Choice of parameters**



- between 329 and 733 pores per sample
- study degree of regularity using isotropic pair-correlation function
- investigation of distances to nearest neighbours shows existence of outliers
- -> choose larger interval of observation

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#### Ice: Isotropy test

Means and confidence bands of directional summary statistics



#### **Ice: Estimation of pressing factors**

sample	153 m	353 m	505 m
$N_V$	380.29	454.79	516.71
$\lambda$	0.2528	0.3403	0.3241
$\widehat{c}_G$	0.807	0.630	0.534
$\widehat{c}_K$	0.821	0.641	0.545





Summary	
We have –	detected the anisotropy within the ice
_	estimated the pressing factor
Nye formula –	simplified ice flow model
->	same trend but absolute values higher in our estimates (approx. 0.1)
However	bedrock conditions not taken into account unknown so far due to incomplete drilling could shift expected pressing factors to higher values

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#### **Further example: Foam**

aluminium foam: pressed before foaming process degree of isotropy grows during foaming



grey: aluminium white: foaming agent black: pore



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