# The Laplace driven moving average – a non-Gaussian stationary process

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# Objectives

Background:

- Gaussian process very convenient in environmental sciences since they allow for covariance/spectral modelling.
- Sometimes not sufficient, does not allow for skewed marginal distributions and has often too light tails.

Goals:

- Construct non-Gaussian stationary process...
- ... possessing a spectrum,
- a skewed marginal distribution,
- ▶ and heavier tails than the Gaussian distribution.

Starting point:

the Laplace distributions

## The Laplace distribution – from a historical point of view

First and second Laplace law of error.

- I. The Laplace distribution. (Laplace, 1774).
- II. The normal (Gauss) distribution. (Laplace, 1778).



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## Generalized Laplace distributions



$$\phi(t)=\left(rac{1}{1+rac{\sigma^2t^2}{2}}
ight)$$

Generalization:

$$\phi(t) = \left(\frac{1}{1 - i\mu t + \frac{\sigma^2 t^2}{2}}\right)^{\tau}$$



## Laplace motion - a counterpart to Brownian motion

- A stochastic process  $\Lambda(t)$  is called asymmetric LM if
  - 1. it starts at the origin
  - 2. it has independent and stationary increments
  - 3. the increments have a generalized asymmetric Laplace distribution



Using the Laplace motion  $\Lambda(x)$  one can define a Laplace driven moving average by

$$X(t) = \int_{-\infty}^{\infty} f(t-x) d\Lambda(x).$$

The function f is called a kernel and should satisfy  $\int f^2(x) dx < \infty$ . A similar definition is possible in higher dimensions.

## Spectral properties of Laplace moving averages

 The spectrum of X(t) is given by

$$S(\omega) = rac{ au(\sigma^2 + \mu^2)}{2\pi} |\mathcal{F}f(\omega)|^2$$

- By requiring that f is a symmetric function one can estimate the kernel from the spectral density.
- By "minimum phase" assumptions one can get causal kernels.



# Marginal distribution

- The marginal distribution is given in terms of its characteristic function.
- Moments of the distribution can be computed.
- The method of moments (with first four moments) can be used in fitting the marginal distribution to data.



## Simulation

The LMA can be seen as a convolution of Laplace noise with a kernel f. Discrete version:

$$\int f(t-x)d\Lambda(x)\approx \sum f(t-x_i)\Delta\Lambda(x_i)$$

#### Time domain simulation:

- simulate iid Laplace noise
- convolve the noise with the kernel

#### Frequency domain simulation:

- simulate iid Laplace noise
- ▶ Fourier transform the noise and the kernel *f* using FFT
- ▶ Take product of the Fourier transforms
- ► Take inverse Fourier transform of the product

The Matérn family of covariances is commonly used to describe spatial dependence in geostatistics. It has covariance

$$r(x) = rac{\phi}{2^{eta - 1} \Gamma(eta)} (lpha | x|)^{eta} \mathcal{K}_{eta}(lpha | x|),$$

and spectrum

$$S(\omega) = \frac{\Gamma(\beta + \frac{d}{2})\alpha^{2\beta}}{\Gamma(\beta)\pi^{d/2}} \frac{\phi}{(\alpha^2 + |\omega|^2)^{\beta + \frac{d}{2}}}.$$

d is the dimension  $\phi$  is variance,  $\alpha$  a range parameter,  $\beta$  a smoothness parameter and K is a modified Bessel function.

# Matérn correlations



# ... and kernels



# Symmetric fields

Laplace parameters:  $[\tau, \sigma, \mu, c] = [1, 1, 0, 0].$ 









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## Asymmetric fields

Laplace parameters:  $[ au, \sigma, \mu, c] = [1, 1/\sqrt{2}, 1/\sqrt{2}, -1/\sqrt{2}].$ 



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# Marginal densities



All distributions have mean zero and variance one

A generalized Laplace distributed random variable  $\Lambda$  can be represented using a  $\Gamma(\tau, 1)$ -distributed random variable  $\Gamma$  and standard Gaussian variable B:

$$\Lambda \stackrel{\mathsf{D}}{=} \boldsymbol{c} + \boldsymbol{\mu} \boldsymbol{\Gamma} + \sigma \sqrt{\boldsymbol{\Gamma}} \boldsymbol{B}.$$

Similarly, the Laplace motion can be represented as

$$\Lambda(t) \stackrel{\text{\tiny D}}{=} c \cdot t + \mu \Gamma(t) + \sigma B(\Gamma(t)),$$

where  $\Gamma(t)$  is a Gamma-process with parameter  $\tau$  and B(t) is standard Brownian motion.

Conditional on a specific realisation  $\gamma$  of the gamma-process the Laplace moving average becomes a non-stationary Gaussian process! It will have mean

$$m_1(t) = E[X(t) \mid \Gamma(x) = \gamma(x)] = c \int f(t-x) dx + \mu \int f(t-x) d\gamma(x)$$

and variance

$$\sigma_{11}^2(t) = Var[X(t) \mid \Gamma(x) = \gamma(x)] = \sigma^2 \int f^2(t-x) \, d\gamma(x)$$

both depending on time *t*.

## Example: Rice's formula

- Formula for computing the expected number of level crossings
- Very important in reliability applications
- For Gaussian stationary processes there is a closed form solution



For a non-stationary process

$$E[N_T^+(u)] = \int_0^T \int_0^\infty z f_{Y(t),Y'(t)}(u,z) \, dz \, dt$$

- ▶  $N_T^+(u)$  number of upcrossings of level *u* during [0, T].
- For a Gaussian process the innermost integral can be evaluated.
- ► The outer integral can be computed numerically

## Monte-Carlo approach to Rice's formula

- ►  $N_T^+(u)$  number of upcrossings of level u in time interval [0, T]
- Condition on  $\Gamma(x) = \gamma(x)$ :

$$\mu^{+}(u) = E[N_{1}^{+}(u)] = E[E[N_{1}^{+}(u) \mid \Gamma(x) = \gamma(x)]]$$

Approximate by forming a Monte-Carlo average:

$$\mu^{+}(u) \approx \frac{1}{n} \sum_{k=1}^{n} E[N_{1}^{+}(u) \mid \Gamma(x) = \gamma_{k}(x)]$$

 The terms in the sum are level-crossing intensities for non-stationary Gaussian processes.

# Upcrossing intensity



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- The Laplace driven moving average can be used to model second order stationary loads with skewed marginal distribution.
- The model can be fitted to data using a moment matching approach.
- Simulation can either be done in time or in frequency domain.
- Conditional on a realisation of a gamma-process the LMA becomes a non-stationary Gaussian process.
- ▶ Rice's formula can be evaluated by a Monte-Carlo method.