

Lösningar till **tenta i ODE och matematisk modellering, MMG511, MVE162 (MVE161)**

Answer first those questions that look simpler, then take more complicated ones etc.  
 Good luck!

1. Formulate general properties of solutions to linear (non-autonomous) systems of ODE:

$x' = A(t)x$ . Give a proof to the statement about the dimension of the space of all solutions to a linear system of ODE. **(4p)** The set of all solutions to a linear system of ODE with  $n \times n$  matrix  $A(t)$  possibly dependent on time  $t$  is a linear vector space having dimension  $n$ , the same as the size of the matrix  $A(t)$ . **Check the proof in the course book.**

2. Formulate and prove the theorem about instability of equilibrium points to autonomous ODE by Lyapunov's method. **(4p) Check the formulation and the proof in the course book.**

3. Consider the following system of ODE:  $\frac{d\vec{r}(t)}{dt} = A\vec{r}(t)$ , with a constant matrix

4.  $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$ . Give general solution to the system. Find all initial data such that corresponding solutions are bounded. **(4p)**

**Answer.**  $r = C_1 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + C_2 e^t \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} + C_3 e^t \begin{bmatrix} -1 \\ -t-1 \\ t \end{bmatrix}$

**Solution.**  $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$ , characteristic polynomial:  $\lambda^3 - 2\lambda^2 + \lambda = 0$ .

Observe that  $\lambda^3 - 2\lambda^2 + \lambda = \lambda(\lambda - 1)^2 = 0$

Eigenvectors:  $v_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \leftrightarrow \lambda_1 = 0$  with simple eigenvalue  $\lambda_1$ ;  $v_2 = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \leftrightarrow \lambda_2 = 1$ ,

where  $\lambda_2$  is a multiple eigenvalue with algebraic multiplicity  $n_2 = 2$ .

$A - \lambda_2 I = \begin{bmatrix} -1 & 1 & 1 \\ 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}$ . generalized eigenvector  $v_2^{(1)} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$  satisfies the equation

$(A - \lambda_2 I)v_2^{(1)} = v_2$  or in matrix form:  $\begin{bmatrix} -1 & 1 & 1 \\ 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$ .

Corresponding equations are:  $\begin{cases} -x + y + z = 0 \\ x = -1 \\ -x = 1 \end{cases} \implies x = -1; y = -1; z = 0; v_2^{(1)} = \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}$

For arbitrary initial data  $x_0 \in \mathbb{R}^3$ ,  $x_0 = C_1 v_1 + C_2 v_2 + C_3 v_2^{(1)}$  the general solution is expressed as:

$$x(t) = e^{At} x_0 = C_1 e^{\lambda_1 t} v_1 + C_2 e^{\lambda_2 t} v_2 + [I + (A - \lambda_2 I)t] e^{\lambda_2 t} v_2^{(1)}$$

Calculate the last term:

$$\begin{aligned}
[I + (A - \lambda_2 I) t] v_2^{(1)} &= \left( \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} + t \begin{bmatrix} -1 & 1 & 1 \\ 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix} \right) \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix} \\
&= \begin{bmatrix} -t+1 & t & t \\ t & 1 & 0 \\ -t & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ -t-1 \\ t \end{bmatrix}
\end{aligned}$$

Collect all terms and get the answer. Observe that one can multiply any term in the answer with  $-1$  or with any other number, the answer will be still correct. One can get different answers choosing eigenvectors  $v_1$  and  $v_2$  in different ways.

5. Consider the system of ODEs. Find all equilibrium points, investigate their stability and if possible define which type they belong to.

$$\begin{cases} x' = 4 - 4x - 2y \\ y' = xy \end{cases} \quad (4p)$$

Answer:  $(1, 0)$  saddle point, unstable;  $(0, 2)$  degenerate knot

Solution. Equilibrium points are  $(1, 0)$  and  $(0, 2)$ .

$$\text{Jacoby matrix is } \frac{D}{D(x,y)} \begin{bmatrix} 4 - 4x - 2y \\ xy \end{bmatrix} = \begin{bmatrix} -4 & -2 \\ y & x \end{bmatrix}$$

For the point  $(1, 0)$  Jacobi matrix is equal to  $A = \begin{bmatrix} -4 & -2 \\ 0 & 1 \end{bmatrix}$ , with eigenvalues  $\lambda_1 = -4 < 0$ ,  $\lambda_2 = 1 > 0$ .

It implies that the equilibrium point is a saddle point and is unstable.

For the point  $(0, 2)$  the Jacobi matrix is equal to  $B = \begin{bmatrix} -4 & -2 \\ 2 & 0 \end{bmatrix}$ , with multiple eigenvalue  $\lambda_1 = \lambda_2 = -2$ .

It implies that the equilibrium point is asymptotically stable, it is improper stable node.

6. Show that the following system of ODEs has a periodic solution.

$$\begin{cases} x' = x - 2y - x(2x^2 + y^2) \\ y' = 4x + y - y(2x^2 + y^2) \end{cases} \quad (4p)$$

**Solution.** Consider the following test function:  $V(x, y) = 2x^2 + y^2$ . Denoting the right hand side in the equation by vectorfunction  $F(x, y)$  we conclude that

$$\nabla V \cdot F = 4x^2 - 8xy - 4x^2(2x^2 + y^2) + 8xy + 2y^2 - 2y^2(2x^2 + y^2) = 2(1 - (2x^2 + y^2))(2x^2 + y^2).$$

It implies that the elliptic shaped ring:  $R = \{(x, y) : 0.5 \leq (2x^2 + y^2) \leq 2\}$  is a positive invariant compact set for the ODE, because velocity vectors are directed inside of this ring both on its outer and inner boundaries ( $\nabla V \cdot F < 0$  for  $(2x^2 + y^2) = 2$  and  $\nabla V \cdot F > 0$  for  $(2x^2 + y^2) = 0.5$ ). The origin is the only equilibrium point of the system. One can see it by observing that  $V(x, y) = 2x^2 + y^2$  is positive definite and  $\nabla V \cdot F(x, y) = 0$  only if  $(x, y) = (0, 0)$  or if  $(2x^2 + y^2) = 1$ . But it is easy to see from the expression for the right hand side for the ODE that in the last case  $(x, y)$  cannot be equilibrium point because the right hand side becomes linear with nondegenerate matrix and is zero only in the origin  $(x, y) = (0, 0)$ .

By the Poincaré-Bendixson theorem the positively invariant set  $R$  not including any equilibrium point must include at least one orbit of a periodic solution.

7. Formulate Banach's contraction principle. Consider the following operator

$$K(x)(t) = \int_0^1 x^2(s) ds + At^2,$$

for all  $t \in [0, 1]$  acting in the Banach space  $C([0, 1])$  of continuous functions with norm  $\|x\| = \sup_{t \in [0, 1]} |x(t)|$ .

Find using Banach's contraction principle, conditions on the real constant  $A$  such that the operator  $K(x)(t)$  has a fixed point. (4p)

**Solution.**

Consider first the  $C([0, 1])$  norm of the operator  $K(x)$ .

$$\|K(x)\|_{C([0,1])} = \sup_{t \in [0,1]} \left| \int_0^1 x^2(s) ds + At^2 \right| \leq \left( \|x\|_{C([0,1])} \right)^2 + A.$$

The operator  $K$  will have fixed point  $y \in C([0, 1])$  according to the Banach contraction principle if it would be a contraction in a subset  $B \subset C([0, 1])$ . The last means that for any continuous functions  $z(t)$  and  $w(t)$  in  $B$  the estimate  $\|K(z) - K(w)\|_{C([0,1])} < \lambda \|z - w\|_{C([0,1])}$  must be satisfied with a number  $\lambda < 1$ .

$$\text{Consider } \|K(z) - K(w)\|_{C([0,1])} = \left\| \int_0^1 z^2(s) ds - \int_0^1 w^2(s) ds \right\|_{C([0,1])} =$$

$$\left\| \int_0^1 |z(s) - w(s)| \cdot |z(s) + w(s)| ds \right\|_{C([0,1])} \leq$$

$$\left( \sup_{t \in [0,1]} |z(t)| + \sup_{t \in [0,1]} |w(t)| \right) \left( \sup_{t \in [0,1]} |z(t) - w(t)| \right) = \left( \|z\|_{C([0,1])} + \|w\|_{C([0,1])} \right) \|z - w\|_{C([0,1])}$$

It implies that for  $\|z\|_{C([0,1])}$  and  $\|w\|_{C([0,1])}$  strictly smaller than  $1/2$  the norm  $\|K(z) - K(w)\|_{C([0,1])} < 1$ .

To check conditions of the Banach principle we need to find for which conditions

the ball  $B = \left\{ w \in C([0, 1]) : \|w\|_{C([0,1])} < 1/2 \right\}$  in  $C([0, 1])$  is mapped by the operator  $K$  into itself: namely

$\|K(w)\|_{C([0,1])} < 1/2$ . The estimate at the beginning of the consideration shows that it will be valid if  $A < 1/4$ , because

$$\text{for } w \in B \text{ it implies that } \|K(w)\|_{C([0,1])} \leq \left( \|w\|_{C([0,1])} \right)^2 + A \leq 1/4 + A \text{ for } w \in B.$$

Max. 24 points;

Threshold for marks: for GU: **VG**: 19 points; **G**: 12 points. For Chalmers: **5**: 21 points; **4**: 17 points; **3**: 12 points;

One must pass both the home assignments and the exam to pass the course. Total points for the course are calculated as  $Total = 0.32Assignments + 0.68Exam$  - the average of the points for the home assignments (32%) and for this exam (68%). The same threshold is valid for the exam, for the home assignments, and for the total points for the course.