MVE165/MMG630, Applied Optimization Lecture 3

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2009-03-20



Lecture 3

Alternative optimal solutions

DRAW GRAPH!!

Example:

maximize
$$z = 2x_1 + 4x_2$$

subject to $x_1 + 2x_2 \le 5$
 $x_1 + x_2 \le 4$
 $x_1, x_2 > 0$

- ▶ The extreme points $(0, \frac{5}{2})$ and (3, 1) have the same optimal value z = 10
- ▶ All solutions that are positive linear (convex) combinations of these are optimal:

$$(x_1, x_2) = \alpha \cdot (0, \frac{5}{2}) + (1 - \alpha) \cdot (3, 1), \quad 0 \le \alpha \le 1$$

▶ Reduced cost of a non-basic variable is 0 in an optimal basis

A general linear program in standard form

 \triangleright A linear program with n non-negative variables, m equality constraints (m < n), and non-negative right hand sides:

maximize
$$z=\sum_{j=1}^n c_j x_j$$
 subject to $\sum_{j=1}^n a_{ij} x_j = b_i, \quad i=1,\ldots,m,$ $x_j \geq 0, \quad j=1,\ldots,n.$

On matrix form it is written as:

maximize
$$z = \mathbf{c}^{\mathrm{T}}\mathbf{x}$$
, subject to $\mathbf{A}\mathbf{x} = \mathbf{b}$, $\mathbf{x} \ge \mathbf{0}^n$,

where $\mathbf{x} \in \mathbb{R}^n$, $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{b} \in \mathbb{R}^m_+$ $(\mathbf{b} \ge \mathbf{0}^m)$, and $\mathbf{c} \in \mathbb{R}^n$.

General derivation of the simplex method

- \triangleright B = set of basic variables, N = set of non-basic variables
- $\Rightarrow |B| = m \text{ and } |N| = n m$
- ▶ Partition matrix/vectors: $\mathbf{A} = (\mathbf{B}, \mathbf{N}), \mathbf{x} = (\mathbf{x}_B, \mathbf{x}_N), \mathbf{c} = (\mathbf{c}_B, \mathbf{c}_N)$
- ▶ The matrix **B** (**N**) contains the columns of **A** corresponding to the index set B(N) — Analogously for \mathbf{x} and \mathbf{c}
- Rewrite the linear program:

$$\begin{bmatrix} \text{maximize } z = \mathbf{c}^{\mathrm{T}} \mathbf{x} \\ \text{subject to } \mathbf{A} \mathbf{x} = \mathbf{b}, \\ \mathbf{x} \geq \mathbf{0}^{n} \end{bmatrix} = \begin{bmatrix} \text{maximize } z = \mathbf{c}_{B}^{\mathrm{T}} \mathbf{x}_{B} + \mathbf{c}_{N}^{\mathrm{T}} \mathbf{x}_{N} \\ \text{subject to } \mathbf{B} \mathbf{x}_{B} + \mathbf{N} \mathbf{x}_{N} = \mathbf{b}, \\ \mathbf{x}_{B} \geq \mathbf{0}^{m}, \ \mathbf{x}_{N} \geq \mathbf{0}^{n-m} \end{bmatrix}$$

► Substitute:
$$\mathbf{x}_B = \mathbf{B}^{-1}\mathbf{b} - \mathbf{B}^{-1}\mathbf{N}\mathbf{x}_N \Longrightarrow$$

maximize
$$z = \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{b} + [\mathbf{c}_N^{\mathrm{T}} - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N}] \mathbf{x}_N$$

subject to $\mathbf{B}^{-1} \mathbf{b} - \mathbf{B}^{-1} \mathbf{N} \mathbf{x}_N \ge \mathbf{0}^m$, $\mathbf{x}_N \ge \mathbf{0}^{n-m}$

Optimality and feasibility

Optimality condition (for maximization)

The basis B is optimal if $\mathbf{c}_N^{\mathrm{T}} - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N} \leq \mathbf{0}^{n-m}$ (marginal values = reduced costs < 0)

If not, choose as entering variable $j \in N$ the one with the largest value of the reduced cost $c_i - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{A}_i$

Feasibility condition

For all $i \in B$ it holds that $x_i = (\mathbf{B}^{-1}\mathbf{b})_i - (\mathbf{B}^{-1}\mathbf{A}_i)_i x_i$

Choose the leaving variable $i^* \in B$ according to

$$i^* = \arg\min_{i \in B} \left\{ \frac{(\mathbf{B}^{-1}\mathbf{b})_i}{(\mathbf{B}^{-1}\mathbf{A}_j)_i} \middle| (\mathbf{B}^{-1}\mathbf{A}_j)_i > 0 \right\}$$

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In the simplex tableau we have

basis	-z	\mathbf{x}_B	×N	S	RHS
-z	1	0	$\mathbf{c}_{N}^{\mathrm{T}} - \mathbf{c}_{B}^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N}$	$-\mathbf{c}_{B}^{\mathrm{T}}\mathbf{B}^{-1}$	$-\mathbf{c}_{B}^{\mathrm{T}}\mathbf{B}^{-1}\mathbf{b}$
x _B	0	I	$B^{-1}N$	\mathbf{B}^{-1}	$B^{-1}b$

- **s** denotes possible slack variables (columns for **s** are copies of certain columns for $(\mathbf{x}_B, \mathbf{x}_N)$
- ▶ The computations performed by the simplex algorithm involve matrix inversions and updates of these
- ► A non-basic (basic) variable enters (leaves) the basis ⇒ one column, \mathbf{A}_i , of \mathbf{B} is replaced by another, \mathbf{A}_k
- ▶ Row operations \Leftrightarrow Updates of \mathbf{B}^{-1} (and $\mathbf{B}^{-1}\mathbf{N}$, $\mathbf{B}^{-1}\mathbf{b}$, and $\mathbf{c}_{\mathbf{R}}^{\mathrm{T}}\mathbf{B}^{-1}$
- ⇒ Efficient numerical computations are crucial for the performance of the simplex algorithm

Derivation of duality

 \triangleright A linear program with optimal value z^*

maximize
$$z:= 20x_1 + 18x_2$$
 weights subject to $7x_1 + 10x_2 \le 3600$ (1) v_1 $16x_1 + 12x_2 \le 5400$ (2) v_2 $x_1, x_2 \ge 0$

- ► How large can z* be?
- \triangleright Compute upper estimates of z^* , e.g.
 - Multiply (1) by $3 \Rightarrow 21x_1 + 30x_2 < 10800 \Rightarrow z^* < 10800$
 - ► Multiply (2) by $1.5 \Rightarrow 24x_1 + 18x_2 < 8100 \Rightarrow z^* < 8100$
 - ► Combine: $0.6 \times (1) + 1 \times (2) \Rightarrow 20.2x_1 + 18x_2 < 7560 \Rightarrow z^* < 7560$
- ▶ Do better than guess—compute optimal weights!
- ▶ Value of estimate: $w = 3600v_1 + 5400v_2 \rightarrow min$
- $7v_1 + 16v_2 > 20$ ► Constraints on weights: $10v_1 + 12v_2 > 18$

The best (lowest) possible upper estimate of z^*

minimize
$$w := 3600v_1 + 5400v_2$$
 subject to $7v_1 + 16v_2 \ge 20$ $10v_1 + 12v_2 \ge 18$ $v_1, v_2 \ge 0$

- A linear program!
- ▶ It is called the **dual** of the original linear program

The lego model—the market problem

► Consider the lego problem

- ▶ Option: Sell blocks instead of making furniture
- $\triangleright v_1(v_2)$ = price of a large (small) block
- Market wish to minimize payment: minimize $6v_1 + 8v_2$
- ▶ I sell if prices are high enough:
 - $\triangleright 2v_1 + 2v_2 > 1600$
- otherwise better to make tables
- $v_1 + 2v_2 > 1000$
- otherwise better to make chairs

 $v_1, v_2 > 0$

- prices are naturally non-negative

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Linear programming duality

▶ To each primal linear program corresponds a dual linear program

[Primal] minimize
$$z = \mathbf{c}^{\mathrm{T}}\mathbf{x}$$
, subject to $\mathbf{A}\mathbf{x} = \mathbf{b}$, $\mathbf{x} \geq \mathbf{0}^n$, [Dual] maximize $w = \mathbf{b}^{\mathrm{T}}\mathbf{y}$, subject to $\mathbf{A}^{\mathrm{T}}\mathbf{y} \leq \mathbf{c}$.

► On component form:

In practice ...

► A primal linear program

minimize
$$z = 2x_1 + 3x_2$$

subject to $3x_1 + 2x_2 = 14$
 $2x_1 - 4x_2 \ge 2$
 $4x_1 + 3x_2 \le 19$
 $x_1, x_2 \ge 0$

▶ The corresponding dual linear program

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Rules for constructing the dual program (p. 327)

${\sf maximization}$	\Leftrightarrow	minimization
dual program	\Leftrightarrow	primal program
primal program	\Leftrightarrow	dual program
constraints		variables
\geq	\Leftrightarrow	≤ 0
\leq	\Leftrightarrow	≥ 0
=	\Leftrightarrow	free
variables		constraints
≥ 0	\Leftrightarrow	\geq
≤ 0	\Leftrightarrow	<u> </u>
free	\Leftrightarrow	=

The dual of the dual of any linear program equals the primal

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Duality properties (Ch. 7.5)

▶ Weak duality: Let x be a feasible point in the primal (minimization) and \mathbf{v} be a feasible point in the dual (maximization). Then,

$$z = \mathbf{c}^{\mathrm{T}} \mathbf{x} > \mathbf{b}^{\mathrm{T}} \mathbf{y} = \mathbf{w}$$

- **Strong duality**: In a pair of primal and dual linear programs, if one of them has an optimal solution, so does the other, and their optimal values are equal.
- ▶ Complementary slackness: If x is optimal in the primal and \mathbf{y} is optimal in the dual, then $\mathbf{x}^{\mathrm{T}}(\mathbf{c} - \mathbf{A}^{\mathrm{T}}\mathbf{y}) = \mathbf{y}^{\mathrm{T}}(\mathbf{b} - \mathbf{A}\mathbf{x}) = 0$.

If x is feasible in the primal, y is feasible in the dual, and $\mathbf{x}^{\mathrm{T}}(\mathbf{c} - \mathbf{A}^{\mathrm{T}}\mathbf{y}) = \mathbf{y}^{\mathrm{T}}(\mathbf{b} - \mathbf{A}\mathbf{x}) = 0$, then \mathbf{x} and \mathbf{y} are optimal for their respective problems.

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Relations between primal and dual optimal solutions

primal (dual) problem	\iff	dual (primal) problem
unique and non-degenerate solution	\iff	unique and non-degenerate solution
unbounded solution	\Longrightarrow	no feasible solutions
no feasible solutions	\Longrightarrow	unbounded solution or no feasible solutions
degenerate solution	\iff	alternative solutions

Exercises on duality

▶ Formulate and solve graphically the dual of:

minimize
$$z = 6x_1 + 3x_2 + x_3$$

subject to $6x_1 - 3x_2 + x_3 \ge 2$
 $3x_1 + 4x_2 + x_3 \ge 5$
 $x_1, x_2, x_3 > 0$

- ▶ Then find the optimal primal solution
- ▶ Verify that the dual of the dual equals the primal

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Sensitivity analysis

- ▶ How does the optimum change when the right hand sides (resources, e.g.) change?
- ▶ When the objective coefficients (prices, e.g.) change?
- ▶ Assume that the basis *B* is optimal:

maximize
$$z = \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{b} + [\mathbf{c}_N^{\mathrm{T}} - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N}] \mathbf{x}_N$$

subject to $\mathbf{B}^{-1} \mathbf{b} - \mathbf{B}^{-1} \mathbf{N} \mathbf{x}_N \ge \mathbf{0}^m$, $\mathbf{x}_N \ge \mathbf{0}^{n-m}$

$$\mathbf{x}_B = \mathbf{B}^{-1}\mathbf{b} - \mathbf{B}^{-1}\mathbf{N}\mathbf{x}_N$$

Changes in the right hand side coefficients

- ▶ Suppose **b** changes to $\mathbf{b} + \Delta \mathbf{b}$
- ⇒ New optimal value:

$$z^{\text{new}} = \mathbf{c}_B^{\text{T}} \mathbf{B}^{-1} (\mathbf{b} + \Delta \mathbf{b}) = z + \mathbf{c}_B^{\text{T}} \mathbf{B}^{-1} \Delta \mathbf{b}$$

- ▶ The current basis is feasible if $\mathbf{B}^{-1}(\mathbf{b} + \Delta \mathbf{b}) \geq 0$
- ▶ If not: negative values will occur in the right hand side
- ► The reduced costs are unchanged (negative, at optimum) ⇒ this can be resolved using the *dual simplex method*



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Changes in the right hand side coefficients

► Consider the linear program

minimize
$$z = -x_1 - 2x_2$$
 subject to $-2x_1 + x_2 \le 2$ $-x_1 + 2x_2 \le 7$ Draw graph!! $x_1 \le 3$ $x_1, x_2 \ge 0$

▶ The optimal solution is given by

basis	-z	x_1	<i>x</i> ₂	s_1	s ₂	<i>S</i> 3	RHS
<u></u>	1	0	0	0	1	2	13
<i>x</i> ₂	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	5
x_1	0	1	0	0	Ō	$\bar{1}$	3
s_1	0	0	0	1	$-\frac{1}{2}$	<u>3</u>	3

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Changes in the right hand side coefficients

▶ Change the right hand side according to

$$\begin{array}{lll} \text{minimize} & z = & -x_1 & -2x_2 \\ \text{subject to} & & -2x_1 & +x_2 & \leq 2 \\ & & -x_1 & +2x_2 & \leq 7+\delta \\ & & x_1 & & \leq 3 \\ & & x_1, x_2 & \geq 0 \end{array}$$

► The change in the right hand side is given by $\mathbf{B}^{-1}(0, \delta, 0)^{\mathrm{T}} = (\frac{1}{2}\delta, 0, -\frac{1}{2}\delta)^{\mathrm{T}} \Rightarrow \text{new optimal tableau:}$

basis	-z	x_1	<i>x</i> ₂	s_1	<i>s</i> ₂	<i>5</i> 3	RHS
-z	1	0	0	0	1	2	$13 + \delta$
<i>x</i> ₂	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	$5 + \frac{1}{2}\delta$
x_1	0	1	0	0	Ō	1	3
s_1	0	0	0	1	$-\frac{1}{2}$. <u>3</u>	$3-\frac{1}{2}\delta$

▶ The current basis is feasible if $-10 \le \delta \le 6$

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Changes in the right hand side coefficients

▶ Suppose $\delta = 8$:

basis	-z	<i>x</i> ₁	<i>x</i> ₂	s_1	<i>s</i> ₂	<i>5</i> ₃	RHS
-z	1	0	0	0	1	2	21
<i>x</i> ₂	0	0	1	0	$\frac{1}{2}$	1/2	9
x_1	0	1	0	0	ō	$\overline{1}$	3
s_1	0	0	0	1	$-\frac{1}{2}$	<u>3</u>	-1

- ► Dual simplex iteration:
- $lacktriangleright s_1 = -1$ has to leave the basis
- ► Find the smallest ratio between reduced costs (for non-basic columns) and (negative) elements in the "s₁-row" (to stay optimal)
- ▶ s₂ will enter the basis **New optimal** tableau:

basis	-z	<i>x</i> ₁	<i>x</i> ₂	s_1	<i>s</i> ₂	<i>s</i> ₃	RHS
-z	1	0	0	2	0	5	19
<i>x</i> ₂	0	0	1	1	0	2	8
x_1	0	1	0	0	0	1	3
<i>s</i> ₂	0	0	0	-2	1	-3	2

Changes in the objective coefficients

- ▶ Suppose **c** changes to $\mathbf{c} + \Delta \mathbf{c}$
- ▶ The new optimal value:

$$z^{\text{new}} = (\mathbf{c}_B + \Delta \mathbf{c}_B)^{\text{T}} \mathbf{B}^{-1} \mathbf{b} = z + \Delta \mathbf{c}_B^{\text{T}} \mathbf{B}^{-1} \mathbf{b}$$

- ▶ The current basis is optimal if $(\mathbf{c}_N + \Delta \mathbf{c}_N)^{\mathrm{T}} - (\mathbf{c}_B + \Delta \mathbf{c}_B)^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N} \leq \mathbf{0}$
- ▶ If not: more simplex iterations to find the optimal solution



Changes in the objective coefficients

▶ Change the objective according to

$$\begin{array}{llll} \text{minimize} & z = & -x_1 & +(-2+\delta)x_2 \\ \text{subject to} & & -2x_1 & +x_2 & \leq 2 \\ & & -x_1 & +2x_2 & \leq 7 \\ & & x_1 & & \leq 3 \\ & & x_1, x_2 & \geq 0 \end{array}$$

▶ The changes in the reduced costs are given by $-(\delta,0,0)\mathbf{B}^{-1}\mathbf{N}=(-\frac{1}{2}\delta,-\frac{1}{2}\delta)\Rightarrow$ new optimal tableau:

basis	-z	<i>x</i> ₁	<i>x</i> ₂	s ₁	<i>s</i> ₂	<i>s</i> ₃	RHS
-z	1	0	0	0	$1-\frac{1}{2}\delta$	$2-\frac{1}{2}\delta$	$13-5\delta$
	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	5
x_1	0	1	0	0	Ō	$\bar{1}$	3
s_1	0	0	0	1	$-\frac{1}{2}$	<u>3</u>	3

▶ The current basis is optimal if $\delta \leq 2$

Changes in the objective coefficients

▶ Suppose $\delta = 4$: new tableau:

basis	-z	<i>x</i> ₁	<i>x</i> ₂	<i>s</i> ₁	s ₂	<i>s</i> ₃	RHS
-z	1	0	0	0	-1	0	-7
	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	5
x_1	0	1	0	0	Ō	$\bar{1}$	3
s ₁	0	0	0	1	$-\frac{1}{2}$	<u>3</u> 2	3

▶ Let s_2 enter and x_2 leave the basis. New optimal tableau:

basis	-z	x_1	x_2	s_1	<i>s</i> ₂	<i>s</i> ₃	RHS
z	1	0	2	0	0	1	3
<i>s</i> ₂	0	0	2	0	1	1	10
x_1	0	1	0	0	0	1	3
<i>s</i> ₁	0	0	1	1	0	2	8