MVE165/MMG630, Applied Optimization Lecture 1

Introduction; course map; operations research; modelling optimization applications; graphic solution

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Course homepage & PingPong

- www.math.chalmers.se/Math/Grundutb/CTH/mve165/1112
- https://pingpong.gate.chalmers.se
- Details, information on assignments and computer exercises, deadlines, lecture notes, exercises etc
- Will be updated with new information every course week

Course contents and organization

Contents

- Applications of optimization
- Mathematical modelling
- Theory properties of models
- Solution techniques algorithms
- Software solvers

Organization

- Lectures mathematical optimization theory
- Computer exercises get used to software solvers
- Guest lectures applications of optimization
- Assignments modelling, use solvers, written reports, opposition & oral presentation
- Assignment work should be done in groups of < two persons
- Define your project groups on the PingPong page for MVE165
- GU students not having PingPong-entries: sign a list

Literature

- Main course book.
 - English version: Optimization (2010)
 - Swedish version: Optimeringslära (2008)

by J. Lundgren, M. Rönnqvist, and P. Värbrand. Studentlitteratur.

- Exercise book:
 - English version: Optimization Exercises (2010)
 - Swedish version: Optimeringslära Övningsbok (2008)

by M. Henningsson, J. Lundgren, M. Rönngvist, and P. Värbrand. Studentlitteratur.

- Cremona/Studentlitteratur/Adlibris/...
- Hand-outs

Examination requirements

- Perform three project assignments in groups of two students
 - For Assignment 3 there will be three alternatives
- Written reports of three assignments
- A written opposition to another group's report of Assignment 2
- An oral presentation of Assignment 3
- Presence at one full oral presentation session
- To be able to receive a grade higher than 3 or G, the written reports and opposition as well as the oral presentation must be of high quality. Students aiming at grade 4, 5, or VG must also pass an oral exam

- Linear optimization, modelling, theory, solution methods, sensitivity analysis
- Discrete optimization models, properties, and solution methods
- Optimization models that can be described as flows in networks, theory, and solution methods
- Multi-objective optimization
- Overview of non-linear optimization models, properties, and solution methods
- Mixes of the above

Optimization: "Do something as good as possible"

- Something: Which are the decision alternatives?
 - $x_{ij} = \begin{cases} 1 & \text{if customer } j \text{ is visited } directly \text{ after customer } i \\ 0 & \text{else} \end{cases}$
 - $y_{ik} = \begin{cases} 1 & \text{if customer } i \text{ is visited by vehicle } k \\ 0 & \text{else} \end{cases}$
- Possible: What restrictions are there?
 - Each customer should be visited exactly once
 - Time windows, transport needs and capacity, pick up at one customer – deliver at another, different types of vehicles, ...
- Good: What is a relevant optimization criterion?
 - Minimize the total distance / travel time / emissions / waiting time / ...

The classical travelling salesperson problem

 Variants of routing problems: e.g., refrigerated goods, transportation service for the disabled, school buses, ...

Examples of application areas

Logistics: production and transport

- Optimize routes for transports, snow removal, school buses, ...
- Location of stores
- Planning of wood cut and transports
- Packing of containers
- Production planning and scheduling

Energy

- Energy production planning
- Investmen in techniques for energy production
- Location of power plants and infrastructure

Finance

- Financial risk management
- Portfolio optimization
- Investment planning

Medicine

- Compute radiation directions/intensities at cancer treatment
- Reconstruct images from x-ray measurements
- Optimal timing for organ transplants

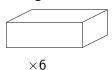
A manufacturing example:

Produce tables and chairs from two types of blocks

Small block



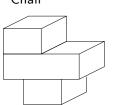
Large block

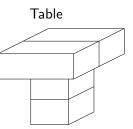




Chair







A manufacturing example, continued

- A chair is assembled from one large and two small blocks
- A table is assembled from two blocks of each size
- Only 6 large and 8 small blocks are avaliable
- A table is sold at a revenue of 1600:-
- A chair is sold at a revenue of 1000:-
- Assume that all items produced can be sold and determine an optimal production plan

- Something What decision alternatives? ⇒ Variables
 - x_1 = number of tables produced and sold
 - x_2 = number of chairs produced and sold
- Possible What restrictions? ⇒ Constraints
 - Maximum supply of large blocks: 6

$$2x_1+x_2\leq 6$$

Maximum supply of small blocks: 8

$$2x_1+2x_2\leq 8$$

• Physical restrictions (also: x_1, x_2 integral)

$$x_1, x_2 \geq 0$$

- **Good** Relevant optimization criterion? ⇒ Objective function
 - Maximize the total revenue

$$1600x_1 + 1000x_2 \rightarrow \mathsf{max}$$

Solve the model using LEGO!

- Start at no production: $x_1 = x_2 = 0$ Use the "best marginal profit" to choose the item to produce
 - x_1 has the highest marginal profit (1600:-/table) ⇒ produce as many tables as possible
 - At $x_1 = 3$: no more large blocks left
- The marginal value of x_2 is now 200:- since taking apart one table (-1600:-) yields two chairs (+2000:-) \Rightarrow 400:-/2 chairs
 - Increase x_2 maximally \Rightarrow decrease x_1
 - At $x_1 = x_2 = 2$: no more small blocks
- The marginal value of x_1 is negative (to build one more table one has to take apart two chairs \Rightarrow -400:-)
 - The marginal value of x_2 is -600:- (to build one more chair one table must be taken apart)
 - \implies Optimal solution: $x_1 = x_2 = 2$

(0)

Geometric solution of the model

maximize
$$z = 1600x_1 + 1000x_2$$
 subject to $2x_1 + x_2 \le 6$ $2x_1 + 2x_2 \le 8$ $x_2 + x_1, x_2 \ge 0$ $x^* = (2,2)$

(1)

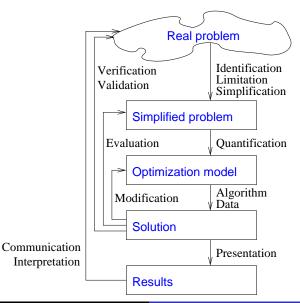
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Operations Research (OR) (Swedish: Operationsanalys)

- Scientific view on problem solving regarding complex systems
- "OR means to prepare a foundation for rational decisions by utilizing systematic scientific methods and — where possible and meaningful — by utilizing quantitative models"
- The problem is considered as a system of components which cooperate and influence each other
- The activities studied are described by models, used to
 - better understand the depicted system,
 - understand the consequences of different decisions, and
 - choose the "best" alternative due to some criterion.

Introduction Optimization & OR Modelling Models Definition Example OR & optimization

The process of optimization



History of Operations Research

- During world war II decision problems became systematically treated: Operations Research
- After the war: use of operations research for civil operations
- The ideas spread to many countries
- Early operations research include inventory planning

- Euler (1735): Seven bridges of Köningsberg (graph theory)
- Gauss (1777–1855): 1st optimization technique, steepest descent
- W.R. Hamilton (1857): "icosian game" ⇒ the travelling salesperson problem (Hamilton cycle)



- L.V. Kantorovich (1939): A linear model for optimization of plywood manufactoring and an algorithm for its solution
- George B. Dantzig (1947): Linear programming the simplex algorithm (exponential time)
 - Program
 ⇔ military training and logistics schedules
- Kantorovich and Koopmans (1975): Nobel Memorial Prize in Economic Sciences
- N. Karmarkar (1984) algorithm for linear programming (polynomial time)

- Commission: Deliver windows over a six-month period
- Demand during the respective months: 100, 250, 190, 140, 220 & 110 units
- Production cost per unit (window): 50 €,45 €, 55 €, 48 €, 52€ & 50€
- Store a manufactured window from one month to the next at 8€
- Requirement: Meet the demand and minimize the costs
- Find an optimal production schedule

Define the decision variables

 x_i = number of units produced in month i = 1, ..., 6 y_i = units left in the inventory at the end of month $i=1,\ldots,6$

• The "flow" of windows can be illustrated as:

production (x_i) : inventory (y_i) : demand: 100 250 190 140 220

Define the limitations/constraints

Each month:

initial inventory + production - ending inventory = demand

$$0 + x_1 - y_1 = 100
y_1 + x_2 - y_2 = 250
y_2 + x_3 - y_3 = 190
y_3 + x_4 - y_4 = 140
y_4 + x_5 - y_5 = 220
y_5 + x_6 - y_6 = 110
x_i , y_i > 0, i = 1,..., 6$$

Objective function: minimize the costs for production and storage

Production cost (€):

$$50 x_1 + 45 x_2 + 55 x_3 + 48 x_4 + 52 x_5 + 50 x_6$$

Inventory cost (€):

$$8(y_1 + y_2 + y_3 + y_4 + y_5 + y_6)$$

Objective:

minimize
$$50x_1 + 45x_2 + 55x_3 + 48x_4 + 52x_5 + 50x_6 + 8(y_1 + y_2 + y_3 + y_4 + y_5 + y_6)$$

A complete (general) optimization model

minimize
$$\sum_{i=1}^{6} c_i x_i + 8 \sum_{i=1}^{6} y_i,$$

subject to $y_{i-1} + x_i - y_i = d_i, \quad i = 1, \dots, 6,$
 $y_0 = 0,$
 $x_i, y_i \geq 0, \quad i = 1, \dots, 6,$

The vector of demand:

$$d = (d_i)_{i=1}^6 = (100, 250, 190, 140, 220, 110)$$

The vector of production costs:

$$c = (c_i)_{i=1}^6 = (50, 45, 55, 48, 52, 50)$$

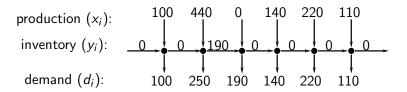
An optimal solution—optimal production schedule

Optimal production each month:

$$x = (x_i)_{i=1}^6 = (100, 440, 0, 140, 220, 110)$$

Optimal inventory each month:

$$y = (y_i)_{i=0}^6 = (0, 0, 190, 0, 0, 0, 0)$$



The minimal total cost is 49980 €

Mathematical optimization models

$$\left[\begin{array}{ll} \text{minimize or maximize} & f(x_1,\ldots,x_n) \\ \text{subject to} & g_i(x_1,\ldots,x_n) & \left\{\begin{array}{l} \leq \\ = \\ \geq \end{array}\right\} & b_i, \quad i=1,\ldots,m \end{array}\right]$$

- x_1, \ldots, x_n are the decision variables
- f and g_1, \ldots, g_m are given functions of the decision variables
- b_1, \ldots, b_m are specified constant parameters
- The functions can be nonlinear, e.g. quadratic, exponential, logarithmic, non-analytic, ...
- In general, linear forms are more tractable than non-linear

Linear optimization models (programs)

- The production inventory model is a linear program (LP), i.e., all relations are described by linear forms
- A general linear program:

• A general linear program:
$$\begin{bmatrix} & \text{min or max} & c_1x_1+\ldots+c_nx_n \\ & \text{subject to} & a_{i1}x_1+\ldots+a_{in}x_n & \left\{\begin{array}{c} \leq \\ = \\ \geq \end{array}\right\} & b_i, \quad i=1,\ldots,m \\ & x_j & \geq & 0, \quad j=1,\ldots,n \end{array} \end{bmatrix}$$

• The non-negativity constraints on x_i , j = 1, ..., n are not necessary, but usually assumed (reformulation always possible)

Discrete/integer/binary modelling

- A variable is called discrete if it can take only a countable set of values, e.g.,
 - Continuous variable: $x \in [0, 8] \iff 0 < x < 8$
 - Discrete variable: $x \in \{0, 4.4, 5.2, 8.0\}$
 - *Integer* variable: $x \in \{0, 1, 4, 5, 8\}$
- A binary variable can only take the values 0 or 1, i.e., all or nothing

E.g., a wind-mill can produce electricity only if it is built

- Let y = 1 if the mill is built, otherwise y = 0
- Capacity of a mill: C
- Production $x \le Cy$ (also limited by wind force etc.)
- In general, models with only continuous variables are more tractable than models with integrality/discrete requirements on the variables, but exceptions exist! More about this later.

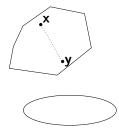
Convex sets

• A set S is convex if, for any elements $\mathbf{x}, \mathbf{y} \in S$ it holds that

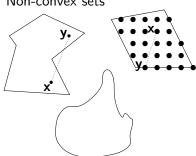
$$\alpha \mathbf{x} + (1 - \alpha)\mathbf{y} \in S$$
 for all $0 \le \alpha \le 1$

Examples:

Convex sets



Non-convex sets



⇒ Intersections of linear (in)equalities ⇒ convex sets

Convex and concave functions

• A function f is convex on the set S if, for any elements $x, y \in S$ it holds that

$$f(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \le \alpha f(\mathbf{x}) + (1 - \alpha)f(\mathbf{y})$$
 for all $0 \le \alpha \le 1$

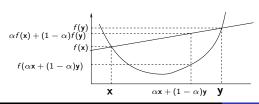
• A function f is concave on the set S if, for any elements $x, y \in S$ it holds that

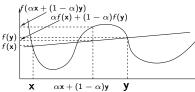
$$f(\alpha \mathbf{x} + (1 - \alpha)\mathbf{y}) \ge \alpha f(\mathbf{x}) + (1 - \alpha)f(\mathbf{y})$$
 for all $0 \le \alpha \le 1$

⇒ Linear functions are convex (and concave)

Convex function

Non-convex function





Global solutions of convex and linear optimization problem

- [Theorem 11.3] Let x* be a local minimizer of a convex function over a convex set. Then x* is also a global minimizer.
- ⇒ Every *local optimum* of a linear optimization problem is a global optimum
 - If a linear optimization problem has any optimal solutions, at least one optimal solution is at an extreme point of the feasible set
- ⇒ Search for optimal extreme point(s)
 - Next lecture: Linear optimization problems and the simplex method