Assignment 3b: The Traveling Salesman Problem MVE165/MMG631: Linear and integer optimisation with applications

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2 Mathematical formulation



- Heuristics
- Relaxation algorithms

Assignment

Traveling Salesman Problem (TSP)

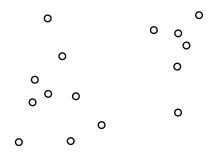
- One of the most studied problems in the area of optimization.
- The name is a mystery, but gives a clear connection to the applications of the problem.
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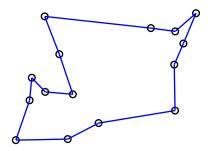
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Definition: Traveling Salesman Problem.

Given a list of cities and their pairwise distances, find the shortest possible tour that visits each city exactly once.



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The TSP has many applications.

- Logistics.
- Production (microchips).
- DNA-sequencing.
- Agriculture.
- Internet planning.

The TSP is a *NP-complete* problem (the decision version of it).

- No polynomial algorithm for solving it to optimality.
- Exponential in the number of cities.
- (N-1)! different tours.

Large problems solved to optimality

- VLSI problem (85,900 nodes). Solved 2004, first studied 1991.
- Shortest tour between all the cities in Sweden (24,978 cities) found in 2001. Length \approx 72,500 km

Let c_{ij} be the distance from city *i* to city *j*.

Symmetric TSP (undirected graph)

 $c_{ij} = c_{ji}, \quad \forall \text{ cities } i, j$

Special cases

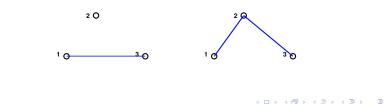
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Symmetric TSP (undirected graph)

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Metric TSP (triangle inequality satisfied)

$$c_{ik} + c_{kj} \geq c_{ij}, \quad \forall ext{ cities } i, j, k$$



- Consider a set $\mathcal{N} = \{1, \dots, N\}$ of cities.
- Let c_{ij} be the distance from city *i* to city *j*.
- Let $\mathcal{L} \subseteq \mathcal{N} \times \mathcal{N}$ denote the undirected links in the graph. We use $\mathcal{L} = \{(i,j) : i, j \in \mathcal{N}, i < j\}$
- Introduce binary variables x_{ij} where

 $x_{ij} = \begin{cases} 1 & \text{if there is a connection between city } i \text{ and city } j \\ 0 & \text{otherwise} \end{cases}$

$$\begin{array}{ll} \text{minimize} & \sum_{(i,j)\in\mathcal{L}} c_{ij}x_{ij}, \\ \text{subject to} & \sum_{j\in\mathcal{N}:(i,j)\in\mathcal{L}} x_{ij} + \sum_{j\in\mathcal{N}:(j,i)\in\mathcal{L}} x_{ji} = 2 \quad , \qquad i\in\mathcal{N} \\ & \sum_{(i,j)\in\mathcal{L}:\{i,j\}\in\mathcal{S}} x_{ij} \leq |\mathcal{S}| - 1, \; \forall \mathcal{S}\subset\mathcal{N}: 2 \leq |\mathcal{S}| \leq N-2 \\ & x_{ij}\in\{0,1\} \quad , \qquad i,j\in\mathcal{N}. \end{array}$$

- Objective is to minimize the total length of the tour.
- First constraints makes sure that we visit each city once.
- Second constraint makes sure that no subtours are allowed.

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• From each subset of cities, we must travel at least once to another city not included in the subset.

$$\sum_{(i,j)\in\mathcal{L}:i\in\mathcal{S},j\in\mathcal{N}\setminus\mathcal{S}} x_{ij} + \sum_{(j,i)\in\mathcal{L}:i\in\mathcal{S},j\in\mathcal{N}\setminus\mathcal{S}} x_{ji} \geq 2, \quad \forall \mathcal{S}\subset\mathcal{N}: 2\leq |\mathcal{S}|\leq N-2.$$

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One problem with the model is that the number of subtour constraints in both formulations are $\approx 2^N$.

Exact algorithms.

- Brute force technique. Enumerate all possible tours, choose the shortest one. $\sim O(N!)$
- Held-Karp algorithm. Use dynamic programming. $\sim \mathcal{O}(N^2 2^N)$

Prize for finding an algorithm $\sim \mathcal{O}(1.9999^N)$

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Have to use

- Heuristics: Find feasible and acceptable solutions.
- *Relaxation algorithms*: Produce lower bounds on optimal objective value.

Together these algorithms can provide us with an optimality interval

Strategies, rules for obtaining feasible solutions.

Deterministic

- Based on simple rules for choosing tours: *Nearest neighbour, Insertion heuristics*
- Based on solving easier subproblems. *MST-heuristic, Christophides heuristic*

Probabilistic

- Based on stochastic rules for choosing tours.
- Genetic algorithms, simulated annealing, ant colony optimization.

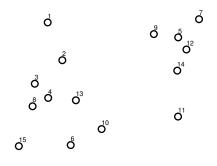


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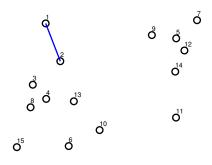
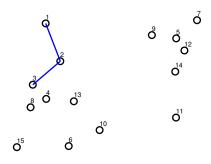
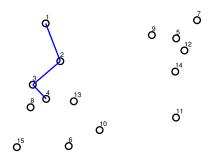
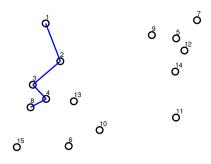
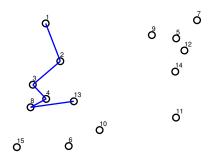


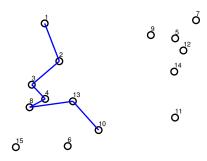
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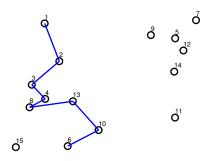


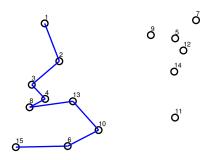


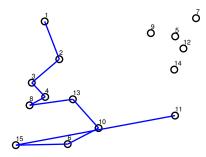


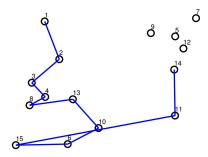


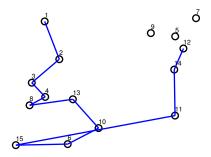


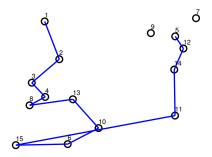


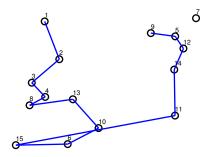




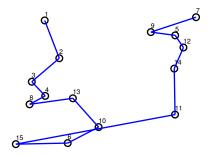






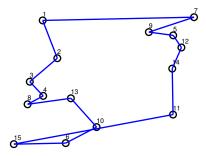


Nearest neighbour heuristic



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Algorithms for improving a feasible solution. Local search heuristics. Utilize the fact that we are considering *metric* TSP problems.



Examples: k-opt heuristics, crossing elimination

Gives lower bounds on objective value. Trick is to relax the problem such that

- the reduced problem is easy to solve, and
- the lower bound given by the relaxation is good.

Tradeoff between the two objectives.

Examples: Branch and bound, Cutting plane methods, 1-tree Lagrangian relaxation.

Idea:

• Lagrangian relax the assignment constraints

$$\sum_{j \in \mathcal{N}: (i,j) \in \mathcal{L}} x_{ij} + \sum_{j \in \mathcal{N}: (j,i) \in \mathcal{L}} x_{ji} = 2$$
 $i \in \mathcal{N}$

for all nodes except one, say node s. This means assigning a Lagrangian multiplier to each node (node price).

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Resulting problem is a 1-MST problem, which is the problem of finding a minimum spanning tree on the nodes N \ {s}, and then connecting node s to the tree by two links.

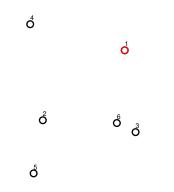
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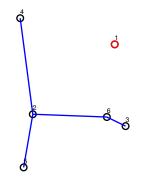
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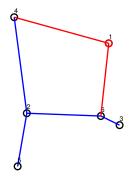
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- Iteratively updating the node prices such that we increase our lower bound in each iteration.

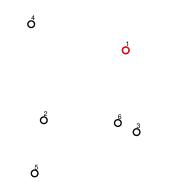


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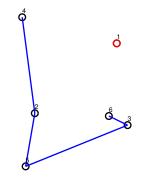


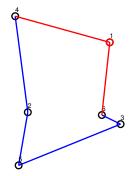




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What do you do in the assignment?

- You get familiar with one of the most studied problems in optimization.
- You will use CPLEX to solve some small problems.
- You develop and implement different algorithms, both heuristics and relaxation algorithms.
- You get more familiar with *either* the theory of relaxation algorithms *or* probabilistic heuristics.

Optimal tour of Sweden

