

Fö 6.2

Ytintegral och flödesintegral

$$\mathcal{S}: \vec{r} = \vec{r}(u, v), \quad (u, v) \in D$$

• tangenter: $\frac{\partial \vec{r}}{\partial u}, \frac{\partial \vec{r}}{\partial v}$

• normalvektor: $\vec{N} = \pm \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v}$ (in/ut, upp/ner)

• enhetsnormal: $\hat{N} = \frac{\vec{N}}{|\vec{N}|}$

• ytelement: $dS = \left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| du dv = |\vec{N}| du dv$

• normalytelement:

$$d\vec{S} = \pm \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} du dv = \vec{N} du dv = \hat{N} dS$$

Exempel Sphär: $x^2 + y^2 + z^2 = R^2$

Sfäriska koordinater: $\rho = R$

$$\begin{cases} x = R \sin \phi \cos \theta & \theta \in [0, 2\pi] \\ y = R \sin \phi \sin \theta & \phi \in [0, \pi] \\ z = R \cos \phi \end{cases}$$

$$\frac{\partial \vec{r}}{\partial \phi} = R \cos \phi \cos \theta \vec{i} + R \cos \phi \sin \theta \vec{j} - R \sin \phi \vec{k}$$

$$\frac{\partial \vec{r}}{\partial \theta} = -R \sin \phi \sin \theta \vec{i} + R \sin \phi \cos \theta \vec{j}$$

$$\frac{\partial \vec{r}}{\partial \phi} \times \frac{\partial \vec{r}}{\partial \theta} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ R \cos \phi \cos \theta & R \cos \phi \sin \theta & -R \sin \phi \\ -R \sin \phi \sin \theta & R \sin \phi \cos \theta & 0 \end{vmatrix}$$

$$= R^2 \sin \phi \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos \phi \cos \theta & \cos \phi \sin \theta & -\sin \phi \\ -\sin \theta & \cos \theta & 0 \end{vmatrix}$$

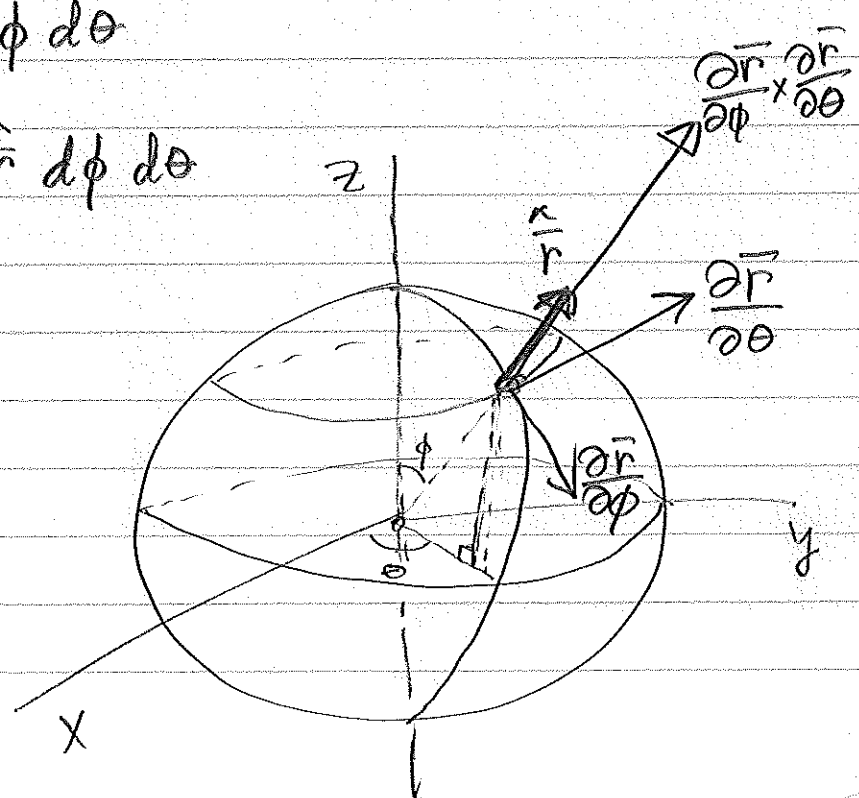
$$= R^2 \sin \phi \left(\sin \phi \cos \theta \vec{i} + \sin \phi \sin \theta \vec{j} + \cos \phi \vec{k} \right) = \frac{R}{R} \frac{R}{|\vec{r}|} = \hat{r}$$

$$= R^2 \sin \phi \hat{r}$$

$$\left| \frac{\partial \vec{r}}{\partial \phi} \times \frac{\partial \vec{r}}{\partial \theta} \right| = R^2 \sin \phi \quad (\text{abs: } \sin \phi \geq 0)$$

$$dS = R^2 \sin \phi d\phi d\theta$$

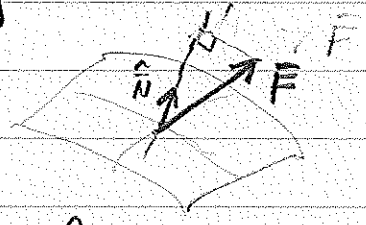
$$d\vec{S} = \pm R^2 \sin \phi \hat{r} d\phi d\theta$$



Ytintegral: $\iint_{\mathcal{P}} f \, dS = \iint_D f(\vec{r}(u,v)) \left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| \, du \, dv$

Flödesintegral: $\iint_{\mathcal{P}} \vec{F} \cdot d\vec{S} = \iint_{\mathcal{P}} \vec{F} \cdot \hat{N} \, dS$

Normalkomponent: $\vec{F} \cdot \hat{N}$



Exempel Massflöde genom \mathcal{P} .

\vec{v} hastighetsfält $\left[\frac{m}{s} \right]$

δ densitet $\left[\frac{kg}{m^3} \right]$

$\vec{F} = \delta \vec{v}$ massflödesstäthet $\left[\frac{kg}{m^2 s} \right]$

Flödet: $\iint_{\mathcal{P}} \vec{F} \cdot d\vec{S} = \iint_{\mathcal{P}} \vec{F} \cdot \hat{N} \, dS$

$= \iint_{\mathcal{P}} \underbrace{\delta \vec{v}}_{\left[\frac{kg}{m^2 s} \right]} \cdot \underbrace{\hat{N}}_{[m^2]} \, dS \quad \left[\frac{kg}{s} \right]$

Flödesintegralen kräver att det finns ett entydigt normalvektorfält \vec{N} på \mathcal{P} , dvs en orienterbar yta. Möbius band går inte!

F08.1

Grad, div, rot.

11

16.1 Grad, div, rot.

endast sid 888 - 892 + exempel 3, 5

Med nabla-operatoren

$$\vec{\nabla} = \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k}$$

kan vi bilda

gradienten av skalärt fält:

$$\vec{\nabla} \phi = \text{grad } \phi = \frac{\partial \phi}{\partial x} \vec{i} + \frac{\partial \phi}{\partial y} \vec{j} + \frac{\partial \phi}{\partial z} \vec{k}$$

och divergensen och rotationen
("curl") av vektorfält:

$$\vec{\nabla} \cdot \vec{F} = \operatorname{div} \vec{F} =$$

$$= \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) \cdot (F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k})$$

$$= \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

$$\vec{\nabla} \times \vec{F} = \operatorname{rot} \vec{F} = \operatorname{curl} \vec{F}$$

$$= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

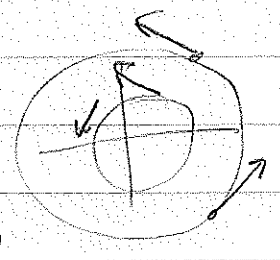
$$= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \vec{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \vec{j}$$

$$+ \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \vec{k}$$

Jag skriver $\vec{\nabla} \phi$, $\vec{\nabla} \cdot \vec{F}$, $\vec{\nabla} \times \vec{F}$, aldrig grad
div och rot.

exempel 5 Helkroppsvrotation

$$\vec{v} = \Omega (-y \vec{i} + x \vec{j})$$

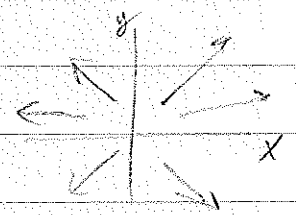


$$\vec{\nabla} \cdot \vec{v} = \Omega \left(\frac{\partial}{\partial x} (-y) + \frac{\partial}{\partial y} x \right) = 0$$

$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -\Omega y & \Omega x & 0 \end{vmatrix} = 0\vec{i} + 0\vec{j} + 2\Omega \vec{k} = 2\Omega \vec{k}$$

Divergerar inte, men roterar.

exempel $\vec{F} = x \vec{i} + y \vec{j} + z \vec{k}$



$$\vec{\nabla} \cdot \vec{F} = 1 + 1 + 1 = 3$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = 0\vec{i} + 0\vec{j} + 0\vec{k}$$

Divergerar, Roterar ej.

exempel 3

(4)

$$\vec{F} = m \frac{\vec{r}}{\rho^3} = \frac{m}{\rho^3} (x \vec{i} + y \vec{j} + z \vec{k})$$

$$\frac{\partial F_1}{\partial x} = \frac{\frac{\partial x}{\partial x} \rho^3 - x \frac{\partial \rho^3}{\partial x}}{\rho^6} = m \frac{\rho^3 - x \cdot 3 \rho^2 \frac{\partial \rho}{\partial x}}{\rho^6}$$

$$= m \frac{\rho^3 - x \cdot 3 \rho^2 \cdot \frac{x}{\rho}}{\rho^6}$$

$$= m \frac{\rho^2 - 3x^2}{\rho^5}$$

$$\begin{aligned} \rho &= \sqrt{x^2 + y^2 + z^2} \\ \frac{\partial \rho}{\partial x} &= \frac{2x}{2\sqrt{x^2 + y^2 + z^2}} \\ &= \frac{x}{\rho} \end{aligned}$$

På samma vis

$$\frac{\partial F_2}{\partial y} = m \frac{\rho^2 - 3y^2}{\rho^5}$$

$$\frac{\partial F_3}{\partial z} = m \frac{\rho^2 - 3z^2}{\rho^5}$$

så att (för $\rho \neq 0$)

$$\vec{\nabla} \cdot \vec{F} = m \frac{3\rho^2 - 3(x^2 + y^2 + z^2)}{\rho^5} = 0$$

Utflödet genom sfär med radie R , $\mathcal{V} = \{(x, y, z) : \rho = R\}$

$$\iint_{\mathcal{V}} \vec{F} \cdot \hat{N} dS = \int_{\phi=0}^{\pi} \int_{\theta=0}^{2\pi} m \frac{\vec{r}}{\rho^3} \cdot \frac{\vec{r}}{\rho} R^2 \sin \phi d\phi d\theta = m \int_0^{\pi} \int_0^{2\pi} \sin \phi d\phi d\theta$$

$$\begin{cases} dS = R^2 \sin \phi d\phi d\theta \\ \hat{N} = \frac{\vec{r}}{|\vec{r}|} = \hat{r} \end{cases}$$

$$= \frac{\rho^2}{\rho^4} = \frac{1}{\rho^2} = \frac{1}{R^2}$$

$$= 4\pi m$$

16.2 Ratneregler

Satz 3

a) $\nabla(\phi\psi) = \psi \nabla\phi + \phi \nabla\psi$

b) $\nabla \cdot (\phi \vec{F}) = \nabla\phi \cdot \vec{F} + \phi \nabla \cdot \vec{F}$

c) $\nabla \times (\phi \vec{F}) = \nabla\phi \times \vec{F} + \phi \nabla \times \vec{F}$

d) $\nabla \cdot (\vec{F} \times \vec{G}) = (\nabla \times \vec{F}) \cdot \vec{G} - \vec{F} \cdot (\nabla \times \vec{G})$

e) $\nabla \times (\vec{F} \times \vec{G}) =$ se boken

f) $\nabla \cdot (\vec{F} \cdot \vec{G}) =$ se boken

g) $\nabla \cdot (\nabla \times \vec{F}) = 0$

h) $\nabla \times (\nabla\phi) = \vec{0}$

i) $\nabla \times (\nabla \times \vec{F}) = \nabla(\nabla \cdot \vec{F}) - \Delta \vec{F}$

Beweis av a, b, c, d, g, h.
Resten utan bevis.

$$\begin{aligned}
(b) \quad \nabla \cdot (\phi F_1 \vec{i} + \phi F_2 \vec{j} + \phi F_3 \vec{k}) &= \frac{\partial}{\partial x}(\phi F_1) + \frac{\partial}{\partial y}(\phi F_2) + \frac{\partial}{\partial z}(\phi F_3) \\
&= \frac{\partial \phi}{\partial x} F_1 + \phi \frac{\partial F_1}{\partial x} + \frac{\partial \phi}{\partial y} F_2 + \phi \frac{\partial F_2}{\partial y} + \frac{\partial \phi}{\partial z} F_3 + \phi \frac{\partial F_3}{\partial z} \\
&= \nabla\phi \cdot \vec{F} + \phi \nabla \cdot \vec{F}
\end{aligned}$$

Obs: $\vec{F} = \nabla\phi \stackrel{(h)}{\Rightarrow} \nabla \times \vec{F} = \nabla \times \nabla\phi = \vec{0}$.

Alltså: ett konservativt fält är rotationsfritt. Detta är det nödvändiga villkoret från 15.2.

Villkoret $\nabla \times \vec{F} = \vec{0}$ är tillräckligt villkor enligt Sats 4.

Sats 4 Antag 1) $\nabla \times \vec{F} = \vec{0}$ i D

2) D enhelt sammankhängande
 Då är \vec{F} konservativt i D, dvs det finns en potential ϕ så att $\nabla\phi = \vec{F}$ i D.

Detta betyder att om $\nabla \times \vec{F} = \vec{0}$ så är följande system av PDE lösbart:

$$\begin{cases} \frac{\partial \phi}{\partial x} = F_1 \\ \frac{\partial \phi}{\partial y} = F_2 \\ \frac{\partial \phi}{\partial z} = F_3 \end{cases}$$

Exempel. $\vec{F} = \vec{r}$. Då är $\nabla \times \vec{F} = \nabla \times \vec{r} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = \vec{0}$.

Vi löser $\begin{cases} \frac{\partial \phi}{\partial x} = x \\ \frac{\partial \phi}{\partial y} = y \\ \frac{\partial \phi}{\partial z} = z \end{cases} \Rightarrow \begin{cases} \phi = \frac{1}{2}x^2 + f(y, z) \\ \phi = \frac{1}{2}y^2 + g(x, z) \\ \phi = \frac{1}{2}z^2 + h(x, y) \end{cases} \begin{cases} \text{Tag } f(y, z) = \frac{1}{2}(y^2 + z^2) + C \\ g(x, z) = \frac{1}{2}(x^2 + z^2) + C \\ h(x, y) = \frac{1}{2}(x^2 + y^2) + C \end{cases}$

$\phi(x, y, z) = \frac{1}{2}(x^2 + y^2 + z^2) + C = \frac{1}{2}|\vec{r}|^2 + C = \frac{1}{2}r^2 + C$