

Slag:

Variabelbyte 14.4

Trippelintegraler 14.5

Variabelbyte 14.6

Mars centrum 14.7

Variabelbyte

Nya koordinater (u, v) .

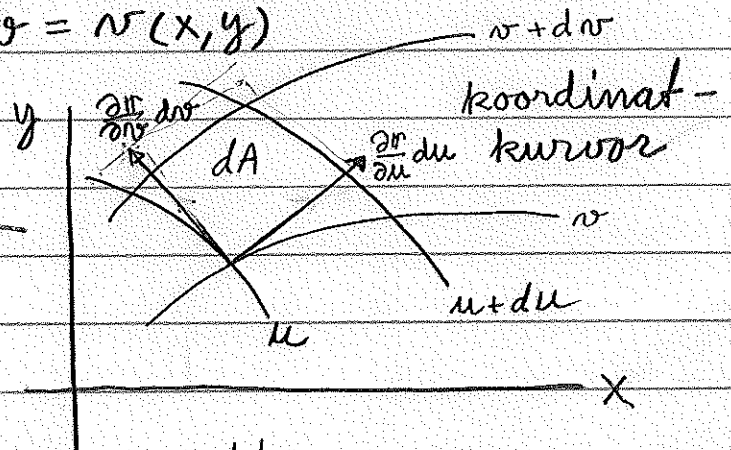
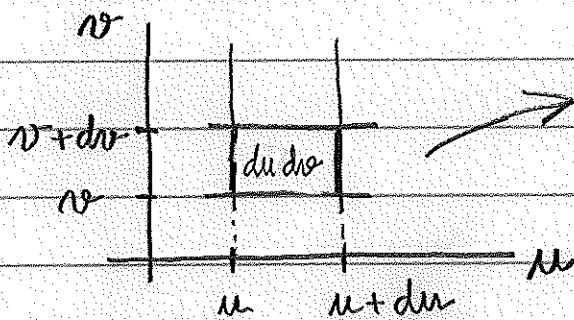
$$\mathbb{R}^2 = \mathbb{R}^2(u, v)$$

Transformation:

$$\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases}$$

Invers transformation:

$$\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$$



$$dA = \left| \frac{\partial \mathbf{r}}{\partial u} du \times \frac{\partial \mathbf{r}}{\partial v} dv \right|$$

spänns upp av tangenterna $\frac{\partial \mathbf{r}}{\partial u} du$ och $\frac{\partial \mathbf{r}}{\partial v} dv$.

$$\frac{\partial \mathbf{r}}{\partial u} du \times \frac{\partial \mathbf{r}}{\partial v} dv = \begin{vmatrix} i & j & k \\ \frac{\partial x}{\partial u} du & \frac{\partial y}{\partial u} du & 0 \\ \frac{\partial x}{\partial v} dv & \frac{\partial y}{\partial v} dv & 0 \end{vmatrix} = \left\{ \begin{array}{l} \text{bryt ut} \\ du \text{ och } dv \end{array} \right\}$$

$$= \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} du dv k = \frac{\partial(x, y)}{\partial(u, v)} du dv k$$

Jacobideterminanten för transformationen:

$$\frac{\partial(x, y)}{\partial(u, v)} = \det \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{pmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \quad \begin{matrix} (\det(A^T) = \det(A)) \\ \downarrow \\ = \end{matrix}$$

$$= \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \det(J'(u, v)) \quad \begin{matrix} = \text{transponerat } J'(u, v)^T \\ \text{av Jacobimatrisen} \end{matrix}$$

determinant-
streck = Jacobimatrisen $J'(u, v)$

Vi får nu

$$dA = \left| \frac{\partial r}{\partial u} du \times \frac{\partial r}{\partial v} dv \right| = \left| \frac{\partial(x, y)}{\partial(u, v)} du dv k \right| =$$

längd
av vektor

$$= \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

abs. belopp

dvs

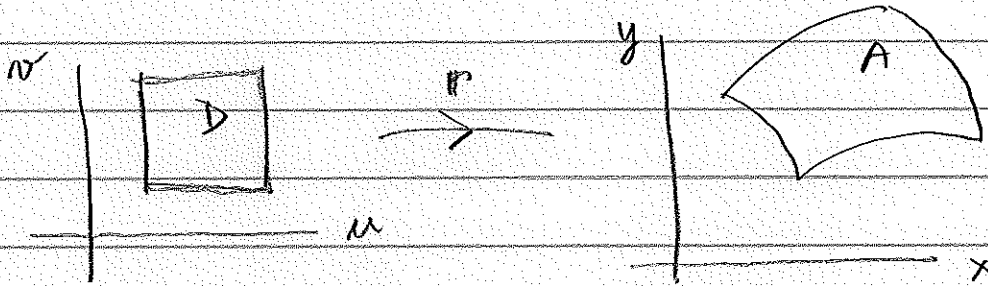
$$\boxed{\begin{aligned} dx dy &= \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv \\ &= | \det(J'(u, v)) | du dv \end{aligned}}$$

Obs: $\left| \frac{\partial(x, y)}{\partial(u, v)} \right|$ är yt-skalan vid

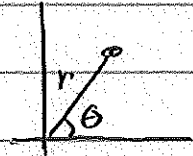
transformationen.

Sats (Variabelbytte i dubbelintegral) ⁽³⁾

$$\iint_A f(x,y) dx dy = \iint_D f(r(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$



Exempel Polära koord (r, θ) .



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \quad \begin{cases} r = \sqrt{x^2 + y^2} \\ \theta = \arctan\left(\frac{y}{x}\right) \end{cases}$$

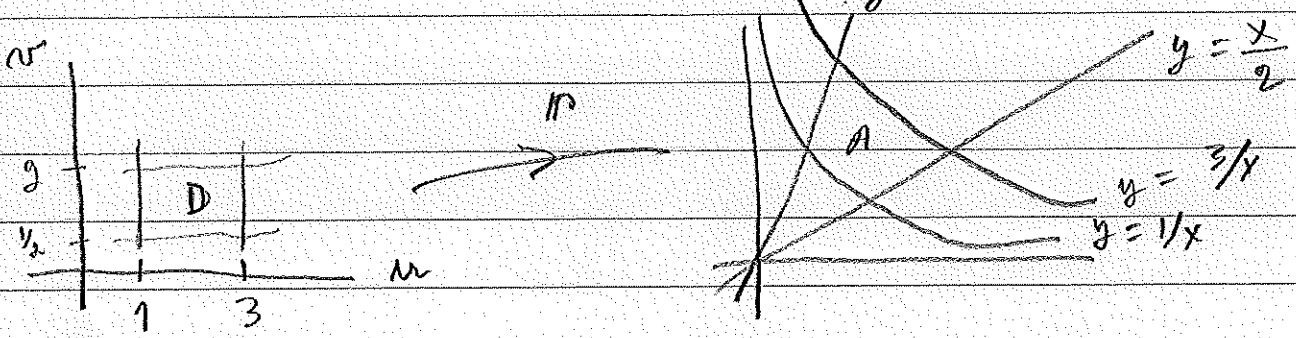
$$\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{vmatrix} = r(\cos^2 \theta + \sin^2 \theta) = r$$

$$dA = \left| \frac{\partial(x,y)}{\partial(r,\theta)} \right| dr d\theta = |r| dr d\theta = r dr d\theta.$$

Exempel

Beräkna $\iint_A \frac{x}{y} dx dy$ där A är området mellan kurvorna

$y = \frac{1}{x}, y = \frac{3}{x}, y = \frac{x}{2}, y = 2x.$



Vi har $1 \leq xy \leq 3, \frac{1}{2} \leq \frac{y}{x} \leq 2$. Detta bestämmer en rektangel D i uv -planet.

Välj därför $u = xy, v = y/x$. Detta är inversa transformationen. Lös ut x, y .

Ekv (2): $y = vx$. I ekv (1): $u = vx^2, x = (\frac{u}{v})^{1/2}$

Sedan $y = v \sqrt{\frac{u}{v}} = \sqrt{uv}$.

Transformationen blir

$$\begin{cases} x = \sqrt{\frac{u}{v}} \\ y = \sqrt{uv} \end{cases}$$

Jacobideterminanten: $\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} =$

$$= \begin{vmatrix} \frac{1}{2\sqrt{uv}} & -\frac{\sqrt{u}}{2\sqrt{v}^3} \\ \frac{\sqrt{v}}{2\sqrt{u}} & \frac{\sqrt{u}}{2\sqrt{v}} \end{vmatrix} = \frac{1}{2v} \quad , \quad dA = \left| \frac{1}{2v} \right| du dv = \frac{1}{2v} du dv$$

Integralen bis

$$\iint_A \frac{x}{y} dx dy = \iint_D \frac{\frac{\sqrt{u}}{v}}{\sqrt{uv}} \frac{1}{2v} du dv =$$

$$= \iint_D \frac{1}{2v^2} du dv = \int_1^3 \left(\int_{\frac{1}{2}}^2 \frac{1}{2v^2} dv \right) du$$

$$= \int_1^3 du \int_{\frac{1}{2}}^2 \frac{1}{2v^2} dv = 2 \cdot \left[\frac{1}{-2v} \right]_{\frac{1}{2}}^2$$

$$= 2 \left(\frac{1}{-4} - \frac{1}{-1} \right) = 2 \cdot \frac{3}{4} = \frac{3}{2}$$

Exempel $\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$

Bewis Låt $I = \int_{-\infty}^{\infty} e^{-x^2} dx$. Då blir

$$I^2 = \int_{-\infty}^{\infty} e^{-x^2} dx \int_{-\infty}^{\infty} e^{-y^2} dy =$$

$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} e^{-x^2} e^{-y^2} dx \right) dy$$

$$= \iint_{\mathbb{R}^2} e^{-x^2-y^2} dx dy$$



polära
↓
=

$$\iint_D e^{-r^2} r dr d\theta = \int_0^{2\pi} \left(\int_0^{\infty} e^{-r^2} r dr \right) d\theta$$

$$= \int_0^{2\pi} d\theta \int_0^{\infty} e^{-r^2} r dr$$

(generaliserad integral,
positiv integrand,
upprepad integration
är tillåten)

$$= 2\pi \left[-\frac{1}{2} e^{-r^2} \right]_0^{\infty} = 2\pi \cdot \frac{1}{2} = \pi$$

Trippelintegralen (14.5)

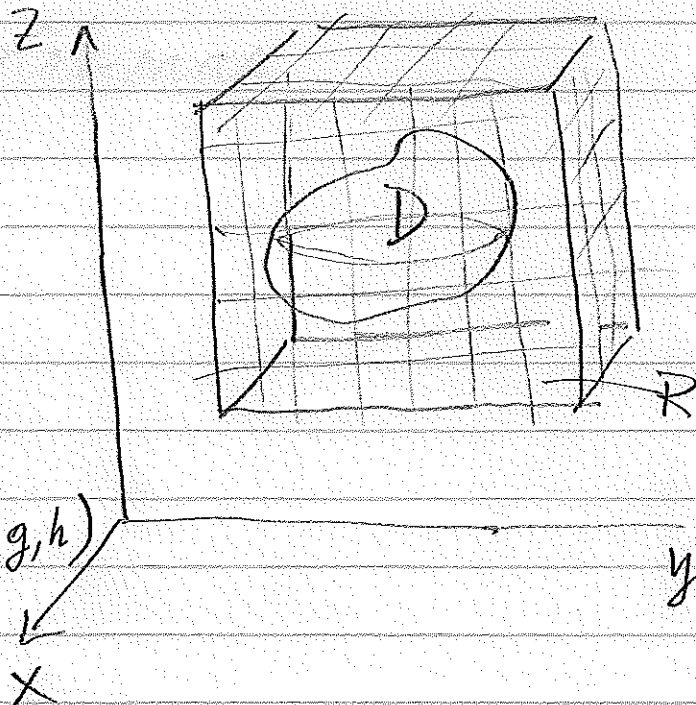
(7)

$$\iiint_D f \, dV = \iiint_D f(x, y, z) \, dx \, dy \, dz$$

definieras med partition av

området D och Riemann-summa.

- Först över rätblock R , sedan allmänt område D



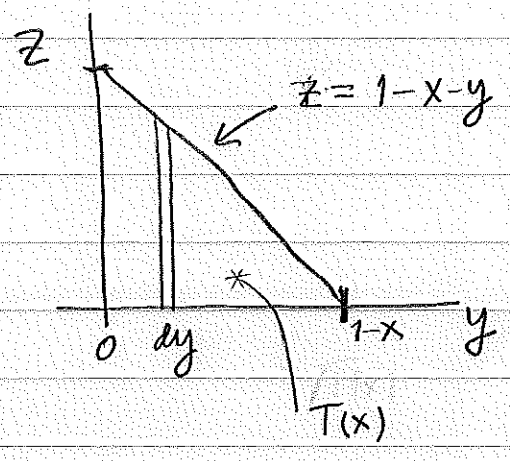
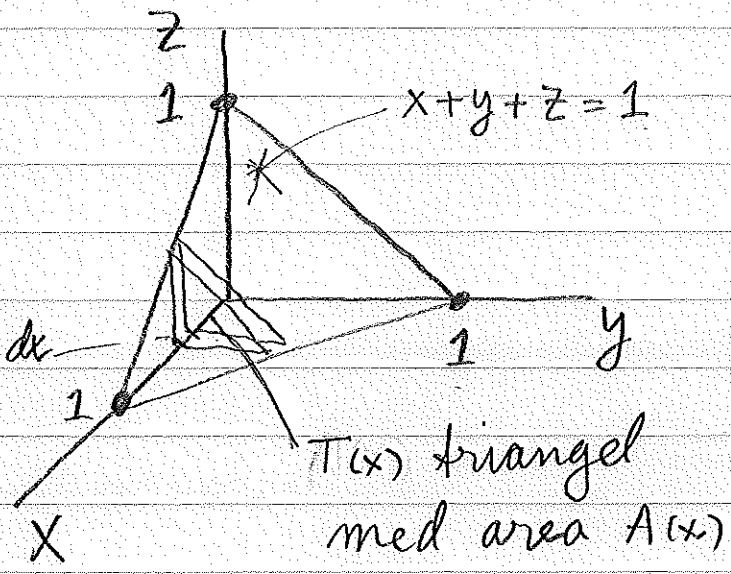
Matlab:

integral3(f, a, b, c, d, g, h)

integrerar över rätblock.

Kan ibland beräknas med upprepad integration.

Exempel Volymen av tetraeder.



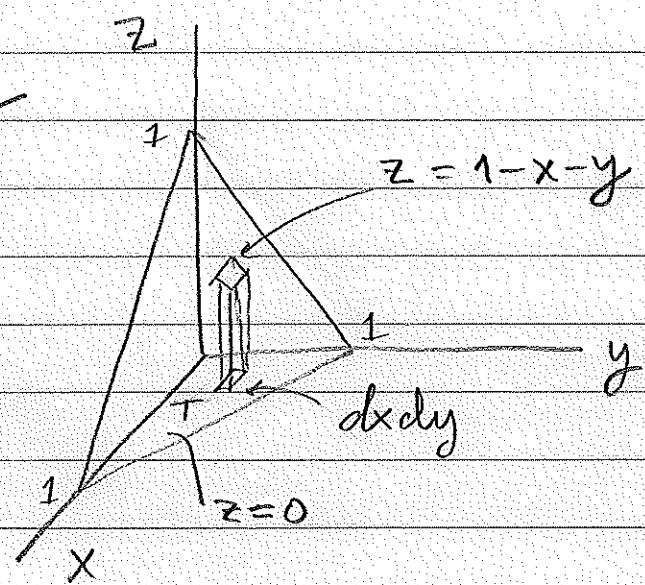
Tetraedern D är enkel i alla riktningar.

1) Skivmetoden:

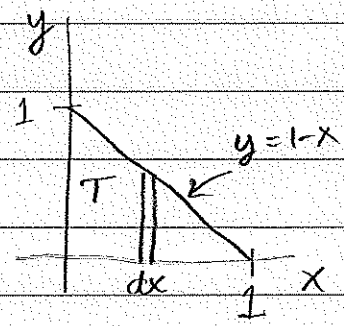
$$\begin{aligned}
 V &= \iiint_D 1 \, dx \, dy \, dz = \int_0^1 A(x) \, dx \\
 &= \int_0^1 \left(\iint_{T(x)} 1 \, dy \, dz \right) dx = \int_0^1 \left(\int_0^{1-x} \left(\int_0^{1-x-y} 1 \, dz \right) dy \right) dx \\
 &= \int_0^1 \left(\int_0^{1-x} [z]_0^{1-x-y} dy \right) dx \\
 &= \int_0^1 \left(\int_0^{1-x} (1-x-y) dy \right) dx = \int_0^1 \left[(1-x)y - \frac{1}{2}y^2 \right]_0^{1-x} dx \\
 &= \frac{1}{2} \int_0^1 (1-x)^2 dx = \frac{1}{2} \left[-\frac{(1-x)^3}{3} \right]_0^1 = \frac{1}{6}.
 \end{aligned}$$

2) Mellan två grafer:

Där är mellan
 $z=0, (x,y) \in T$ och
 $z=1-x-y, (x,y) \in T$



$$V = \iint_T \left(\int_0^{1-x-y} 1 dz \right) dx dy =$$

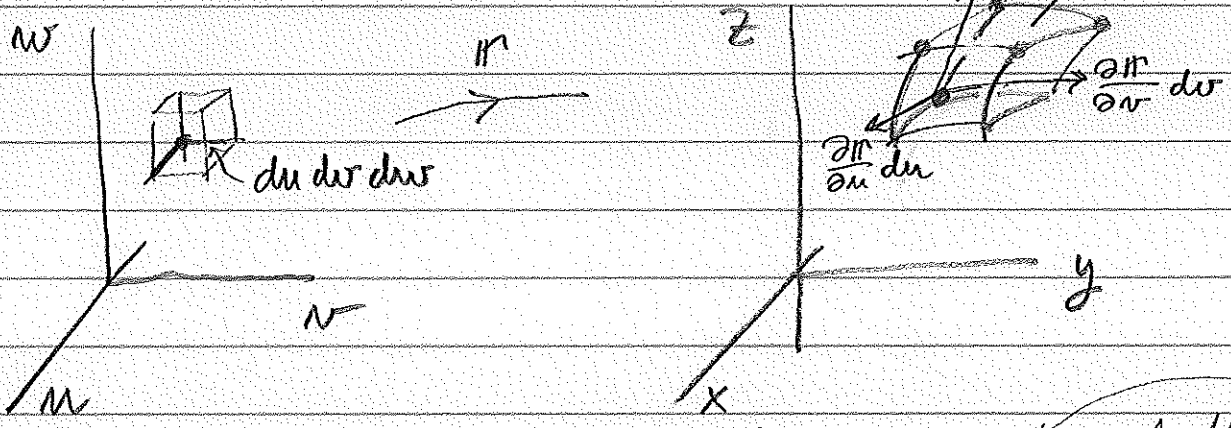


$$= \int_0^1 \left(\int_0^{1-x} \left(\int_0^{1-x-y} 1 dz \right) dy \right) dx = \dots = \frac{1}{6}$$

Variabelbytte. 14.6

Nya koordinater (u, v, w) .

$$\begin{cases} x = x(u, v, w) \\ y = y(u, v, w) \\ z = z(u, v, w) \end{cases} \quad r = r(u, v, w)$$



dV spänns upp av tangenterna:

$$dV = \left| \frac{\partial r}{\partial u} du \cdot \left(\frac{\partial r}{\partial v} dv \times \frac{\partial r}{\partial w} dw \right) \right| = \text{absolutbelopp av trippelprodukten}$$

$$= \left| \frac{\partial (x, y, z)}{\partial (u, v, w)} \right| du dv dw =$$

$$= \left| \det \left(r'(u, v, w) \right) \right| du dv dw$$

absolutbeloppet av Jacobi-determinanten.

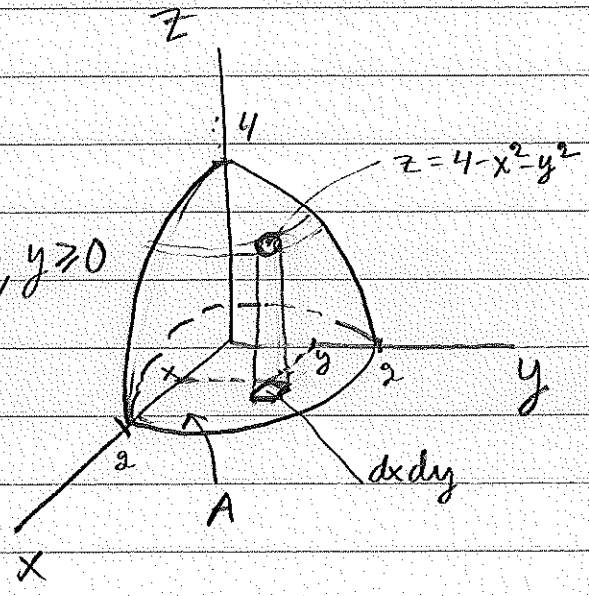
Allmänt område är oftast svårt.

Exempel

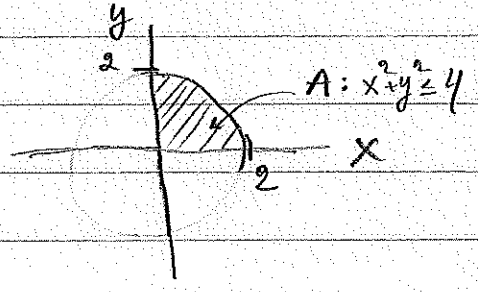
$$I = \iiint_D x \, dx \, dy \, dz$$

$$D: 0 \leq z \leq 4 - x^2 - y^2, \quad x \geq 0, y \geq 0$$

Enkelt i z, dvs
mellan två grafer
z=0 och z=4-x^2-y^2.



Bottenytan A:



$$I = \iint_A \left(\int_0^{4-x^2-y^2} x \, dz \right) dx \, dy$$

$$= \iint_A \left(x \cdot [z]_0^{4-x^2-y^2} \right) dx \, dy$$

$$= \iint_A x(4-x^2-y^2) \, dx \, dy = \{ \text{polära} \} =$$

$$= \int_0^{\pi/2} \int_0^2 r \cos \theta (4-r^2) r \, dr \, d\theta$$

$$= \int_0^{\pi/2} \cos \theta \, d\theta \int_0^2 r^2(4-r^2) \, dr = \underbrace{[\sin \theta]_0^{\pi/2}}_{=1} \int_0^2 (4r^2 - r^4) \, dr = \frac{64}{15}$$

J Matlab :

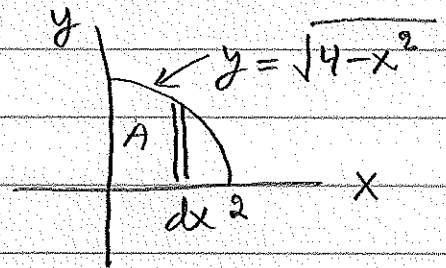
$$\Rightarrow f = @ (x, y, z) (x * (z \leq 4 - x.^2 - y.^2))$$

$$\Rightarrow I = \text{integral3} (f, 0, 2, 0, 2, 0, 4)$$

$$[0, 2] \times [0, 2] \times [0, 4]$$

Se mer detaljer på sista sidan.

Alternativt :



$$I = \iint_A \left(\int_0^{4-x^2-y^2} x \, dz \right) dx dy =$$

$$= \int_0^2 \left(\int_0^{\sqrt{4-x^2}} \left(\int_0^{4-x^2-y^2} x \, dz \right) dy \right) dx =$$

$$= \int_0^2 \int_0^{\sqrt{4-x^2}} x(4-x^2-y^2) \, dy \, dx =$$

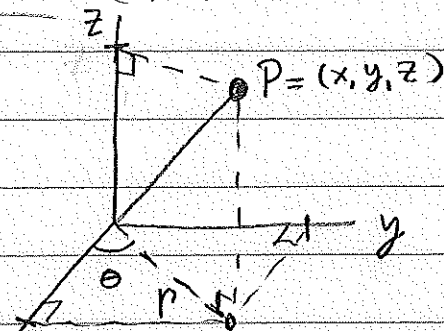
$$= \int_0^2 \left[x(4-x^2)y - x \frac{y^3}{3} \right]_0^{\sqrt{4-x^2}} dx =$$

$$= \int_0^2 \left(x(4-x^2)^{3/2} - \frac{1}{3} x(4-x^2)^{3/2} \right) dx =$$

$$= \frac{1}{3} \int_0^2 2x(4-x^2)^{3/2} dx = \frac{1}{3} \left[\frac{(4-x^2)^{5/2}}{-5/2} \right]_0^2 = \frac{2}{15} 4^{5/2} = \frac{64}{15}$$

Cylindriska koordinater (r, θ, z) .

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$



Jacobi determinanter:

$$\frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

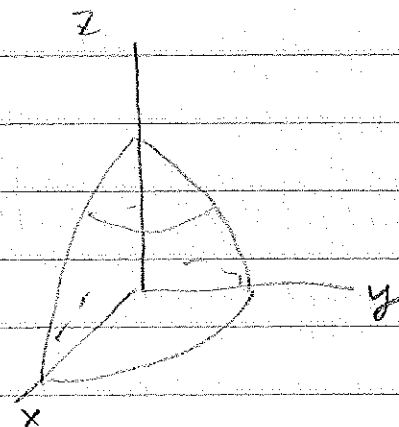
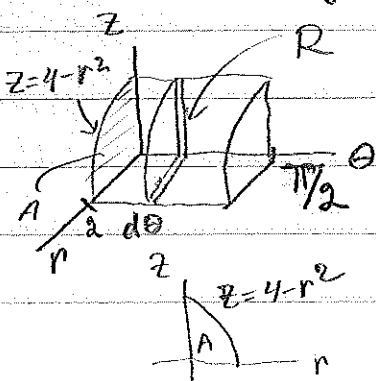
$$= r(\cos^2 \theta + \sin^2 \theta) = r$$

$$dV = r \, dr \, d\theta \, dz$$

Första exemplet

$$0 \leq z \leq 4 - x^2 - y^2 = 4 - r^2$$

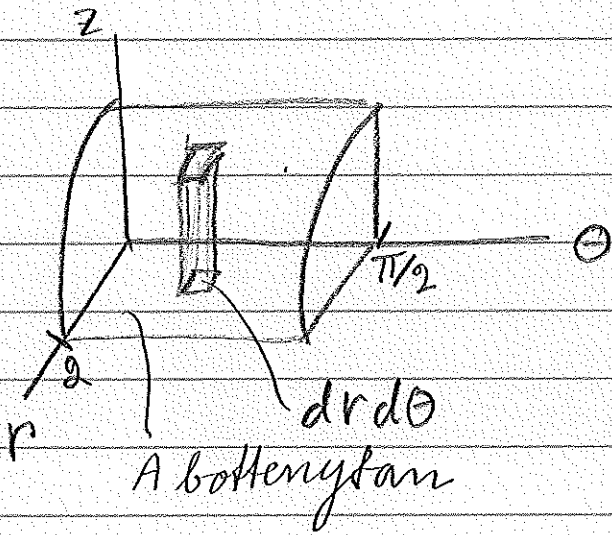
Vi får i cyl. koord: $\begin{cases} 0 \leq r \leq 2 \\ 0 \leq z \leq 4 - r^2 \\ 0 \leq \theta \leq \pi/2 \end{cases}$



$$\begin{aligned} I &= \iiint_D x \, dx \, dy \, dz = \iiint_R r \cos \theta \, r \, dr \, d\theta \, dz \\ &= \int_0^{\pi/2} \left(\int_0^2 r \cos \theta \, r \, dr \, dz \right) d\theta \\ &= \int_0^{\pi/2} \cos \theta \, d\theta \int_0^2 \left(\int_0^{4-r^2} r^2 \, dz \right) dr = 1 \cdot \int_0^2 r^2(4-r^2) \, dr = 64/15 \end{aligned}$$

Detta var "skivmetoden".

Alternativ: R är enkelt i z



$$0 \leq z \leq 4 - r^2, (r, \theta) \in A$$

$$I = \iiint_R r \cos \theta \, r \, dr \, d\theta \, dz = \iint_A \left(\int_0^{4-r^2} r^2 \cos \theta \, dz \right) dr \, d\theta$$

$$= \iint_A r^2 \cos \theta \left[z \right]_0^{4-r^2} dr \, d\theta$$

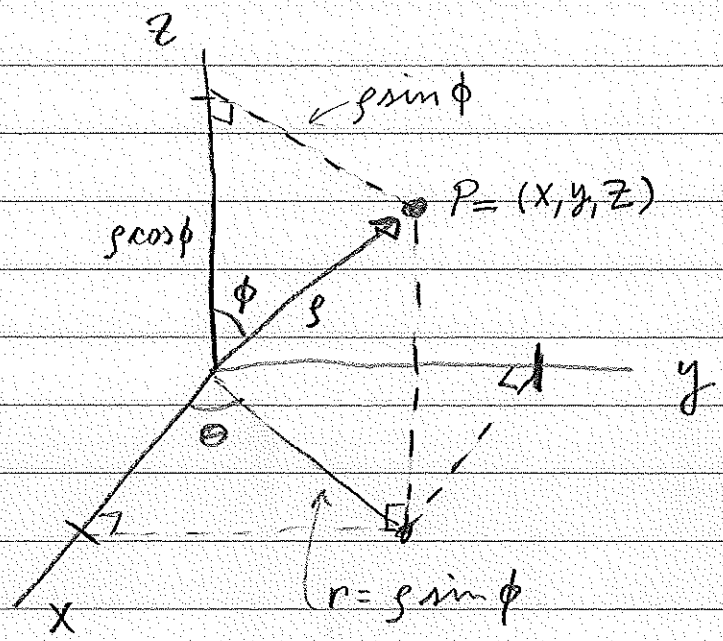
$$= \iint_A (4-r^2) r^2 \cos \theta \, dr \, d\theta = \left\{ A \text{ är rektangel} \right\}$$

$$= \int_0^{\pi/2} \left(\int_0^2 (4-r^2) r^2 \cos \theta \, dr \right) d\theta$$

$$= \int_0^{\pi/2} \cos \theta \, d\theta \int_0^2 (4r^2 - r^4) \, dr = 1 \cdot \frac{64}{15} = \frac{64}{15}$$

Sfäriska koordinater (ρ, φ, θ).

$$\begin{cases} x = \rho \sin \phi \cos \theta \\ y = \rho \sin \phi \sin \theta \\ z = \rho \cos \phi \end{cases}$$



$$\frac{\partial(x, y, z)}{\partial(\rho, \phi, \theta)} = \begin{vmatrix} \sin \phi \cos \theta & \rho \cos \phi \cos \theta & -\rho \sin \phi \sin \theta \\ \sin \phi \sin \theta & \rho \cos \phi \sin \theta & \rho \sin \phi \cos \theta \\ \cos \phi & -\rho \sin \phi & 0 \end{vmatrix} =$$

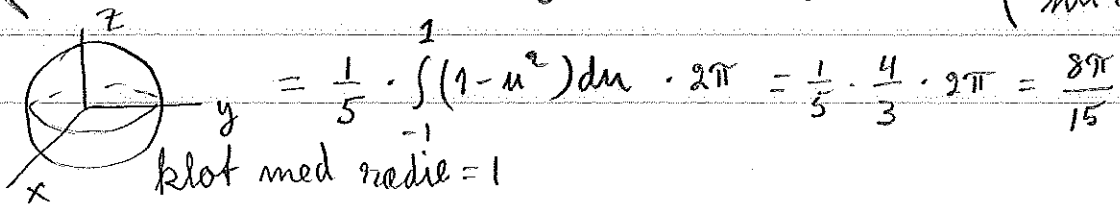
$$= \dots = \rho^2 \sin \phi$$

obs: $\sin \phi \geq 0$ för $\phi \in [0, \pi]$

$$dV = |\rho^2 \sin \phi| d\rho d\phi d\theta = \rho^2 \sin \phi d\rho d\phi d\theta$$

Exempel $\iiint_{B(0,1)} (x^2 + y^2) dx dy dz = \iiint_{\mathcal{R}} (\rho \sin \phi)^2 \rho^2 \sin \phi d\rho d\phi d\theta$

$$\left(\begin{array}{l} 0 \leq \rho \leq 1 \\ 0 \leq \phi \leq \pi \\ 0 \leq \theta \leq 2\pi \end{array} \right) = \int_0^1 \rho^4 d\rho \int_0^\pi \sin^3 \phi d\phi \int_0^{2\pi} d\theta = \left\{ \begin{array}{l} u = -\cos \phi \\ du = \sin \phi d\phi \\ \sin^2 \phi = 1 - u^2 \end{array} \right|_{\phi=0, u=-1}^{\phi=\pi, u=1}$$



14.7 Endast "Moments and Centres of Mass" sid 850-854

Masscentrum: $(\bar{x}, \bar{y}, \bar{z})$ där

$$\bar{x} = \frac{\iiint_R x \delta(x,y,z) dV}{\iiint_R \delta(x,y,z) dV}$$

δ = massföretät = densitet
[kg/m³]

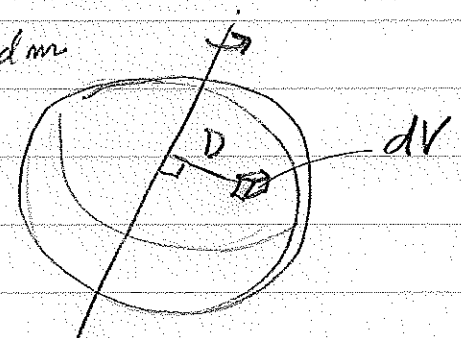
OSN.

På vektorform: $\bar{r} = \frac{\iiint_R r \delta dV}{\iiint_R \delta dV} = \frac{\iiint_R r dm}{\iiint_R dm}$

Tröghetsmoment m.a.p. axel:

$$I = \iiint_R D^2 \delta(x,y,z) dV = \iiint_R D^2 dm$$

D = avståndet till axeln



I har enheten [kg m²].

$$dV = r^2 \sin \phi \, dr \, d\phi \, d\theta \quad (\text{obs: } \sin \phi \geq 0)$$

Exempel. Tröghetsmomentet för klot med radie R m. o. p. z-axeln: $\left(\begin{array}{l} \delta = \text{massfätthet} \\ \left[\frac{\text{kg}}{\text{m}^3} \right] \end{array} \right)$

$$I = \iiint_{\mathcal{B}} (x^2 + y^2) \delta \, dV = \delta \iiint_{0 \ 0 \ 0}^{2\pi \ \pi \ R} (r \sin \phi)^2 r^2 \sin \phi \, dr \, d\phi \, d\theta$$

$$= \delta \int_0^R r^4 \, dr \int_0^\pi \sin^3 \phi \, d\phi \int_0^{2\pi} d\theta = \left\{ \begin{array}{l} u = -\cos \phi \\ du = +\sin \phi \, d\phi \\ \sin^2 \phi = 1 - u^2 \\ \phi = 0 \Rightarrow u = -1, \phi = \pi \Rightarrow u = 1 \end{array} \right.$$

$$= \delta \frac{R^5}{5} \cdot \int_{-1}^1 (1 - u^2) \, du \cdot 2\pi = \delta \frac{R^5}{5} \cdot \frac{4}{3} \cdot 2\pi = \frac{8\pi}{15} \delta R^5$$

$\delta = \text{massfätthet} = \text{konstant} \left[\frac{\text{kg}}{\text{m}^3} \right]$

$$\delta R^5 \left[\frac{\text{kg}}{\text{m}^3} \text{m}^5 \right] = \left[\text{kg} \text{m}^2 \right]$$

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- [Simpler alternative with triplequad \(much less accurate\)](#)
- [Integral3 cannot handle this for some reason.](#)

Example lecture 5.2. Repeated integration with integral3.

```
format long
xmin = 0;
xmax = 2;
ymin = 0;
ymax = @(x) sqrt(4 - x.^2);
zmin = 0;
zmax = @(x,y) 4 - x.^2 - y.^2;

f=@(x,y,z) x;
I=integral3(f,xmin,xmax,ymin,ymax,zmin,zmax)
Iexact=64/15
```

I =

4.2666666666666317

Iexact =

4.266666666666667

Simpler alternative with triplequad (much less accurate)

```
ff=@(x,y,z) (x.*( z<= 4-x.^2-y.^2) );
II=triplequad(ff,0,2,0,2,0,4)
```

II =

4.266558675930201

Integral3 cannot handle this for some reason.

```
ff=@(x,y,z) (x.*( z<= 4-x.^2-y.^2) );
III=integral3(ff,0,2,0,2,0,4)
```

Warning: Reached the maximum number of function evaluations (10000). The result fails the global error test.

Warning: The integration was unsuccessful.

III =

NaN

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