

Matematik Chalmers

**Tentamen i TMA026 Partiella differentialekvationer, fk, TM, 2006–08–28 f V**

Telefon: Christoffer Cromvik 0762–721860

Inga hjälpmmedel. Kalkylator ej tillåten.

You may get up to 10 points for each problem plus points for the hand-in problems.

Grades: 3: 20–29p, 4: 30–39p, 5: 40–.

---

**1.** Prove the inequality

$$(1) \quad \|v\|_{L_2(\Omega)}^2 \leq C \left( \|\nabla v\|_{L_2(\Omega)}^2 + \|v\|_{L_2(\Gamma)}^2 \right) \quad \forall v \in H^1(\Omega).$$

Here  $\Omega$  is a bounded domain in  $\mathbf{R}^d$  with smooth boundary  $\Gamma$ . (Do it for a square domain in the plane if you cannot do the general case.)

**2.** Give a weak formulation and prove existence and uniqueness of solutions to the boundary value problem

$$-\nabla \cdot (a \nabla u) = f, \quad \text{in } \Omega,$$

$$a \frac{\partial u}{\partial n} + h(u - g) = 0, \quad \text{on } \Gamma,$$

under suitable assumptions on the coefficients  $a, h$  and the data functions  $f, g$ . Hint: use (1).

**3.** Consider

$$u_t - \Delta u = f, \quad \text{in } \Omega \times \mathbf{R}^+,$$

$$u = 0, \quad \text{on } \Gamma \times \mathbf{R}^+,$$

$$u(\cdot, 0) = v, \quad \text{in } \Omega.$$

(a) Prove that

$$|u(t)|_1^2 + \int_0^t (\|u_t(s)\|^2 + \|\Delta u(s)\|^2) ds \leq C \left( |v|_1^2 + \int_0^t \|f(s)\|^2 ds \right), \quad t \geq 0.$$

(b) Assume  $f = 0$ . Prove that

$$\int_0^t s \|u_t(s)\|^2 ds \leq C \|v\|^2, \quad t \geq 0.$$

**4.** Consider the same equation as in Problem 3. (a) Formulate a semidiscrete finite element method (discretized only in the  $x$ -variables) for this problem.

(b) Prove an error estimate.

**5.** State and prove the maximum principle for the heat equation.

/stig

**1.** Integrate by parts in the identity  $\int_{\Omega} v^2 dx = \int_{\Omega} v^2 \Delta \phi dx$ , where  $\phi(x) = \frac{1}{2d}|x|^2$ .

**2.** Assume

$$a(x) \geq a_0 > 0, \quad h(x) \geq h_0 > 0$$

Assume  $f \in L_2(\Omega)$ ,  $g \in L_2(\Gamma)$ . Weak formulation: Find  $u \in H^1$  such that

$$a(u, v) = L(v) \quad \forall v \in H^1$$

where

$$\begin{aligned} a(v, w) &= \int_{\Omega} a \nabla v \cdot \nabla w dx + \int_{\Gamma} h v w ds \\ L(v) &= \int_{\Omega} f v dx + \int_{\Gamma} g v ds \end{aligned}$$

Coercivity:

$$\begin{aligned} a(v, v) &= \int_{\Omega} a \nabla v \cdot \nabla v dx + \int_{\Gamma} h v^2 ds \\ &\geq a_0 \int_{\Omega} |\nabla v|^2 dx + h_0 \int_{\Gamma} v^2 ds \\ &\geq \frac{1}{2} a_0 \int_{\Omega} |\nabla v|^2 dx + \min(\frac{1}{2} a_0, h_0) \left( \int_{\Omega} |\nabla v|^2 dx + \int_{\Gamma} v^2 ds \right) \\ &\geq \frac{1}{2} a_0 \int_{\Omega} |\nabla v|^2 dx + C \int_{\Omega} |v|^2 dx \\ &\geq C \left( \int_{\Omega} |\nabla v|^2 dx + \int_{\Omega} |v|^2 dx \right) \\ &= C \|v\|_1^2 \quad \forall v \in H^1 \end{aligned}$$

Boundedness:

$$\begin{aligned} |a(v, w)| &\leq \max(\|a\|_{L_\infty}, \|h\|_{L_\infty}) \left( \|v\|_1 \|w\|_1 + \|v\|_{L_2(\Gamma)} \|w\|_{L_2(\Gamma)} \right) \quad (\text{trace inequality}) \\ &\leq C \|v\|_1 \|w\|_1 \end{aligned}$$

Similarly:

$$\begin{aligned} |L(v)| &\leq \|f\| \|v\| + C \|g\|_{L_2(\Gamma)} \|v\|_{L_2(\Gamma)} \\ &\leq C (\|f\| + \|g\|_{L_2(\Gamma)}) \|v\|_1 \end{aligned}$$

Existence and uniqueness now follows from Riesz's representation theorem.

**3.** Weak formulation:

$$\begin{aligned} u(t) &\in H_0^1, \quad u(0) = v, \\ (u_t, \phi) + a(u, \phi) &= (f, \phi), \quad \forall \phi \in H_0^1, \quad t > 0. \end{aligned}$$

(a) Choose  $\phi = u_t(t)$ :

$$\begin{aligned} (u_t, u_t) + a(u, u_t) &= (f, u_t) \\ \|u_t\|^2 + \frac{1}{2}D_t|u|_1^2 &\leq \|f\|\|u_t\| \leq \frac{1}{2}\|f\|^2 + \frac{1}{2}\|u_t\|^2 \\ \int_0^t \|u_t\|^2 ds + |u(t)|_1^2 &\leq |v|_1^2 + \int_0^t \|f\|^2 ds \end{aligned}$$

Then use also

$$\int_0^t \|\Delta u\|^2 ds = \int_0^t \|u_t - f\|^2 ds \leq C \left( \int_0^t \|u_t\|^2 ds + \int_0^t \|f\|^2 ds \right)$$

(b) Choose  $\phi = tu_t(t)$  and also  $\phi = u(t)$ .

**4.** (a)

$$\begin{aligned} u_h(t) &\in S_h, \quad u_h(0) = v_h, \\ (u_{h,t}, \chi) + a(u_h, \chi) &= (f, \chi), \quad \forall \chi \in S_h, \quad t > 0. \end{aligned}$$

where  $S_h$  is the usual family of piecewise linear finite element spaces based on a family of triangulations of  $\Omega$ , and  $v_h \in S_h$  is some approximation of  $v$ .

(b) This is Theorem 10.1.

**5.** See the book.

/stig