Department of Mathematics Göteborg

Numerical Linear Algebra, TMA265/MMA600

Solutions to the examination 23 October 2009

 $\begin{array}{l} \mathbf{1} & A^{T}A(x+\delta x) = A^{T}(b+\delta b) \\ & A^{T}Ax = A^{T}b \end{array} \right\} \Rightarrow A^{T}A\delta x = A^{T}\delta b \Rightarrow \delta x = (A^{T}A)^{-1}A^{T}\delta b = A^{+}\delta b \\ \Rightarrow & \|\delta x\|_{2} \leq \|A^{+}\|_{2}\|\delta b\|_{2} \Rightarrow \frac{\|\delta x\|_{2}}{\|x\|_{2}} \leq \|A^{+}\|_{2}\frac{\|\delta b\|_{2}}{\|x\|_{2}} = \|A^{+}\|_{2}\|A\|_{2}\frac{\|b\|_{2}\|\delta b\|_{2}}{\|A\|_{2}\|b\|_{2}\|x\|_{2}} = \kappa(A)\frac{\|b\|_{2}\|\delta b\|_{2}}{\|A\|_{2}\|b\|_{2}\|x\|_{2}} \\ \text{By the inequality } & \|Ax\|_{2} \leq \|A\|_{2}\|x\|_{2} \text{ and the fact that } \cos\theta = \frac{\|Ax\|_{2}}{\|b\|_{2}} \text{ we now get} \\ \frac{\|\delta x\|_{2}}{\|x\|_{2}} \leq \kappa(A)\frac{\|b\|_{2}\|\delta b\|_{2}}{\|Ax\|_{2}\|b\|_{2}} = \kappa(A)\frac{1}{\cos\theta}\frac{\|\delta b\|_{2}}{\|b\|_{2}}. \end{array}$

2) See text book or lecture notes.

3a) If x_0 is a solution to Ax = b, then all $x = x_0 + x_h$, where $x_h \in N(A)$, are solutions, since $Ax = Ax_0 + Ax_h = Ax_0 = b$. $||x||_2$ is minimized if $x \in N(A)^{\perp} = R(A^T)$ i.e. for $x = A^T y$ for some $y \in R^m$ and then $b = Ax = AA^T y$ i.e. the problem is solved by 1) $AA^T y = b, 2$ $x = A^T y$. **3b)** $(AA^T)^T = (A^T)^T A^T = AA^T$ so AA^T is symmetric. $x^T AA^T x = (A^T x)^T (A^T x) \ge 0$ and $(A^T x)^T (A^T x) = 0 \Leftrightarrow A^T x = 0 \Leftrightarrow x = 0$, since A^T has full rank, so AA^T is positive definite.

4) Use a Givens rotation
$$R(2,3,\theta) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{bmatrix}$$
 to zero-out the (3,1) element:
 $R(2,3,\theta)A = \begin{bmatrix} 0 & -1 & 1 \\ 4c - 3s & 2c - 4s & 0 \\ 4s + 3c & 2s + 4c & 0 \end{bmatrix}$. By $s = -3/5$, $c = 4/5$ we get the desired
 $R(2,3,\theta)A = \begin{bmatrix} 0 & -1 & 1 \\ 5 & 4 & 0 \\ 0 & 2 & 0 \end{bmatrix}$ and then
 $R(2,3,\theta)AR(2,3,\theta)^{T} = \begin{bmatrix} 0 & -1 & 1 \\ 5 & 4 & 0 \\ 0 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4/5 & -3/5 \\ 0 & 3/5 & 4/5 \end{bmatrix} = \begin{bmatrix} 0 & -1/5 & -7/5 \\ 5 & 16/5 & -12/5 \\ 0 & 8/5 & -6/5 \end{bmatrix}$.

5a) $G = U\Sigma V^T$ where $U \in \mathbb{R}^{m \times m}$ and $V \in \mathbb{R}^{n \times n}$ are orthogonal and $\Sigma \in \mathbb{R}^{m \times n}$ is quasidiagonal with the singular values of G in decreasing order $\sigma_1 \ge \sigma_2 \ge ... \ge \sigma_r > 0$, $\sigma_{r+1} = \sigma_{r+2} = \sigma_n = 0$. **5b)** $G = U\Sigma V^T \Rightarrow H = \begin{bmatrix} O & V\Sigma U^T \\ U\Sigma V^T & O \end{bmatrix}$. Now, $W = \frac{1}{\sqrt{2}} \begin{bmatrix} V & V \\ U & -U \end{bmatrix}$ is orthogonal since $W^T W = \frac{1}{2} \begin{bmatrix} VV^T + VV^T & O \\ O & UU^T + UU^T \end{bmatrix} = \begin{bmatrix} I & O \\ O & I \end{bmatrix} = I$. Further $W \begin{bmatrix} \Sigma & O \\ O & \Sigma \end{bmatrix} W^T = \begin{bmatrix} O & V\Sigma U^T \\ U\Sigma V^T & O \end{bmatrix} = H$, so $D = \begin{bmatrix} \Sigma & O \\ O & \Sigma \end{bmatrix}$ contains the eigenvalues and W contains the eigenvectors as columns, by the spectral theorem.

$$\begin{aligned} \mathbf{6a} \text{ For } H \text{ first calculate } \hat{u} &= \begin{bmatrix} 2\\0\\0\\0 \end{bmatrix} - \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} = \begin{bmatrix} 1\\-1\\-1\\-1 \\-1 \end{bmatrix} \text{ and normalize to } u = \frac{1}{2} \begin{bmatrix} 1\\-1\\-1\\-1\\-1 \end{bmatrix}. \end{aligned}$$

$$\text{The Householder reflection becomes } H = I - 2uu^T \text{ and } HA = \begin{bmatrix} 2 & 0 & 0 & 1\\0 & -1 & 1 & 0\\0 & 0 & -1 & 1\\0 & 1 & 0 & 0 \end{bmatrix}.$$

$$\text{For } Z \text{ we calculate } \hat{u} &= \begin{bmatrix} 1\\0\\0 \end{bmatrix} - \begin{bmatrix} 0\\0\\1 \end{bmatrix} = \begin{bmatrix} 1\\0\\-1 \end{bmatrix} \text{ and normalize to } u = \frac{1}{\sqrt{2}} \begin{bmatrix} 0\\1\\0\\-1 \end{bmatrix}.$$

$$\text{The Householder reflection becomes } Z = I - 2uu^T \text{ and } HAZ = \begin{bmatrix} 2 & 1 & 0 & 0\\0 & 0 & 1 & -1\\0 & 1 & -1 & 0\\0 & 0 & 0 & 1 \end{bmatrix}.$$

7) See text book or lecture notes.

8a) Congruent transformation: $A \to X^T A X$ with X nonsingular. The inertia is preserved, *inertia*(A) = (ν, ζ, π) where ν, ζ and π is the number of negative, zero and positive eigenvalues, respectively.

8b) The eigenvalues of $A - \sigma I$ are $\lambda_i - \sigma$ for eigenvalues λ_i of A and λ_i , i = 1, 2, 3, 4 are integers (by the hint). By a) $A - \sigma I$ and D have the same inertia in particular the same π . From the table we see that A has 4 eigenvalues larger than 0, 3 eigenvalues larger than 1, 2 eigenvalues larger that 2 etc. We conclude that the eigenvalues are 1, 2, 4 and 5.

8c) By Gerschgorin: $\lambda \in \{|z-2| \leq 2\} \cup \{|z-3| \leq 2\} \cup \{|z-4| \leq 2\} \cup \{|z-3| \leq 2\} \Rightarrow \lambda \in [0, 6]$. The eigenvalues are real since A is symmetric.