

**Questions for the course**  
**Numerical Linear Algebra**  
**TMA265/MMA600**

**Date: 2014 January 16, Time: 8.30 - 12.30, Place: at CTH,  
Maskinhuset**

**Question 1**

- 1. Find eigenvalues for a matrix  $A$  which is defined as

$$\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 5 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

**(1p)**

- 3. Find inverse matrix  $A^{-1}$  to the matrix  $A$  defined as

$$\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 3 & 5 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

via the matrix of cofactors. **(2p)**

- 2. Compute  $\|A\|_\infty, \|A\|_1$  for matrix  $A$  defined as

$$\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 3 & 5 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

Find conjugate transpose matrix  $A^*$  to this matrix  $A$ . **(1p)**

**Question 2**

- 1. Describe the main idea of Cholesky factorization of the matrix  $A$  for solution of a system of linear equation  $Ax = b$ . **(2p)**
- 2. Prove that if there exists a unique lower triangular nonsingular matrix  $L$  with positive diagonal entries such that  $A = LL^T$  then  $A$  is symmetric positive definite matrix.

**(2p)**

**Question 3**

- 1. Derive the relative condition number  $k_{CR}(A)$  of the matrix  $A$  (called also as Bauer condition number or Skeel condition number). **(2p)**
- 2. Let the matrix  $A$  is defined as

$$\mathbf{A} = \begin{bmatrix} a_{11} & 0 \\ 0 & 1 \end{bmatrix}$$

and the vector  $b = [a_{11}, 1]^T$  is such that  $x = A^{-1}b$ . Determine  $k_{CR}(A)$ .

**(2p)**

**Question 4**

- 1. Give definitions for three main methods (normal equations, QR decomposition and SVD) which solve the linear least squares problem.

**(2p)**

- 2. Let  $A = U\Sigma V^T$  be the SVD decomposition of the  $m$ -by- $n$  matrix  $A$ , where  $m \geq n$ . Prove that the eigenvalues of the symmetric matrix  $AA^T$  are  $\sigma_i^2$  and  $m - n$  zeros.

**(2p)**

- 3. Let  $A = U\Sigma V^T$  be the SVD decomposition of the  $m$ -by- $n$  matrix  $A$ , where  $m \geq n$ . Let  $m$ -by- $n$  pixel image corresponds to the matrix  $A$ . Write formula for compressed image  $A_k$  which will be the best rank- $k$  approximation of the matrix  $A$ .

**(2p)****Question 5**

- Compute  $QR$  decomposition of the matrix  $A$  using Householder reflections:

$$\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 4 & 0 \\ 0 & 3 & 3 \end{bmatrix}$$

**(2p)**

- Compute  $QR$  decomposition of the matrix  $A$  using Given's rotations

$$\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 4 & 0 \\ 0 & 3 & 3 \end{bmatrix}$$

**(1p)****Question 6**

- 1. Give the definition for a matrix pencil, regular and singular pencils.

**(1p)**

- 2. Let  $A - \lambda B$  is

$$\mathbf{A} - \lambda \mathbf{B} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Determine eigenvalues of  $A - \lambda B$ .**(2p)****Question 7**

- 1. Write algorithm for the Power method to find largest eigenvalue of the matrix  $A$  and the corresponding eigenvector. **(1p)**

- 2. Write Inverse iteration algorithm. Describe difference between this algorithm and the Power method.

**(2p)**

## Numerical Linear Algebra

### TMA265/MMA600

### Solutions to the examination at 16 January 2014

#### Question 1

1. We should solve characteristic equation  $\det(A - \lambda I) = 0$  :

$$\det \begin{bmatrix} 2 - \lambda & 0 & 1 \\ 0 & 5 - \lambda & 0 \\ 0 & 1 & -\lambda \end{bmatrix} = 0.$$

Solving above equation for  $\lambda$  we get three eigenvalues  $\lambda_1 = 2, \lambda_2 = 0, \lambda_3 = 5$  which are solutions to the equation  $(2 - \lambda)(-5\lambda + \lambda^2) = 0$ .

2. By definition of an inverse matrix we have:

$$A^{-1} = \frac{1}{\det A} (C^T)_{ij}$$

Thus,

$$C = \begin{bmatrix} 0 & 0 & 3 \\ 1 & 0 & -2 \\ -5 & 3 & 10 \end{bmatrix},$$

$$C^T = \begin{bmatrix} 0 & 1 & -5 \\ 0 & 0 & 3 \\ 3 & -2 & 10 \end{bmatrix},$$

and thus  $A^{-1} = \frac{1}{3} \cdot \begin{bmatrix} 0 & 1 & -5 \\ 0 & 0 & 3 \\ 3 & -2 & 10 \end{bmatrix}.$

3. We use definition of  $A^*$ :

$$A^* = \overline{A^T}.$$

$$A^T = \begin{bmatrix} 2 & 3 & 0 \\ 0 & 5 & 1 \\ 1 & 0 & 0 \end{bmatrix}.$$

$$\|A\|_1 = \max(5, 6, 1) = 6, \|A\|_\infty = \max(3, 8, 1) = 8.$$

#### Question 2

1. See Lecture 5 and the course book.
2. Since  $A = LL^T$  then  $x^T Ax = (x^T L)(Lx) = \|L^T x\|_2^2 > 0$  for all  $x \neq 0$  and thus  $A$  is s.p.d.

#### Question 3

1. See Lectures 4 and the course book:  $k_{CR}(A) = \max_i |A^{-1}| \cdot |A|$  is the componentwise relative condition number of  $A$ .
2. Since  $|A^{-1}| \cdot |A| = I$  then  $k_{CR}(A) = 1$ .

#### Question 4

1. See Lecture 7 and the course book.
2. See Lecture 7 and Theorem 3.3 of the course book.
3. Since  $A = U\Sigma V^T$  then by Theorem 3.3 of the course book  $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$  will be the best rank-k approximation of the matrix  $A$ .  $A_k$  will represent the compressed image of  $A$ .

### Question 5

- 1. We only need to zero the (3, 2) entry.  
Take the (1, 1) minor

$$A' = M_{11} = \begin{pmatrix} 4 & 0 \\ 3 & 3 \end{pmatrix}.$$

and apply Householder transformation to get:

$$\mathbf{u} = \mathbf{x} + \alpha \mathbf{e}_1,$$

where  $\mathbf{x} = (4, 3)^T$ ,  $\alpha = -\text{sign}(4) \cdot \|\mathbf{x}\|$

$$\mathbf{v} = \frac{\mathbf{u}}{\|\mathbf{u}\|}.$$

Here,

$$\alpha = -5.$$

Therefore

$$\mathbf{u} = (-1, 3)^T, \quad \|\mathbf{u}\| = \sqrt{10}.$$

and  $\mathbf{v} = \frac{1}{\sqrt{10}}(-1, 3)^T$ , and then

$$P_2' = I - \frac{2}{\sqrt{10}^2} \begin{pmatrix} -1 \\ 3 \end{pmatrix} \begin{pmatrix} -1 & 3 \end{pmatrix} \\ \begin{pmatrix} 0.8 & 0.6 \\ 0.6 & -0.8 \end{pmatrix}.$$

Then the matrix of the Householder transformation is

$$P_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0.8 & 0.6 \\ 0 & 0.6 & -0.8 \end{pmatrix}$$

Now, we find

$$R = P_2 A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 5 & 1.8 \\ 0 & 0 & -2.4 \end{pmatrix}.$$

The matrix  $P$  is orthogonal and  $R$  is upper triangular, so  $A = QR$  is the required QR-decomposition with  $P = P_2^T$ .

- 2. To obtain QR decomposition of the matrix  $A$

$$\mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 4 & 0 \\ 0 & 3 & 3 \end{bmatrix}$$

using Given's rotation we have to zero out (3, 2) element of the matrix  $A$ .

We construct Given's matrix  $G_2$  in order to zero out (3, 2) element of the matrix  $A$ .

To do that we compute  $c, s$  from the known  $a = 4$  and  $b = 3$  as

$$\begin{bmatrix} c & -s \\ s & c \end{bmatrix} \cdot \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} r \\ 0 \end{bmatrix}$$

to get formulas:

$$r = \sqrt{a^2 + b^2} = \sqrt{4^2 + 3^2} = 5,$$

$$c = \frac{a}{r} = 0.8,$$

$$s = \frac{-b}{r} = -0.6.$$

The second Given's matrix will be

$$\mathbf{G}_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & c & -s \\ 0 & s & c \end{bmatrix}$$

or

$$\mathbf{G}_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.8 & 0.6 \\ 0 & -0.6 & 0.8 \end{bmatrix}$$

Then upper triangular matrix  $R$  in the QR decomposition will be

$$\mathbf{R} = \mathbf{G}_2 \cdot \mathbf{A} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 5 & 1.8 \\ 0 & 0 & 2.4 \end{bmatrix}$$

Then  $A = G_2^T \cdot R = QR$  will be QR decomposition of the matrix  $A$  with  $Q = G_2^T$ .

### Question 6

- 1. See Lecture 11 and the course book.
- 2. Since

$$A - \lambda B = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 0 \end{bmatrix} - \lambda \begin{bmatrix} 2 & & \\ & 0 & \\ & & 1 \end{bmatrix}.$$

Then  $p(\lambda) = \det(A - \lambda B) = (1 - 2\lambda) \cdot (1 - 0\lambda) \cdot (0 - \lambda) = (2\lambda - 1)\lambda$ , so the eigenvalues are  $\lambda = \frac{1}{2}, 0$  and  $\infty$ .  $\diamond$

### Question 7

- 1. See Lecture 11 and the course book:  
Alg. Power method: Given  $x_0$ , we iterate

$$i = 0$$

repeat

$$y_{i+1} = Ax_i$$

$$x_{i+1} = y_{i+1} / \|y_{i+1}\|_2 \quad (\text{approximate eigenvector})$$

$$\tilde{\lambda}_{i+1} = x_{i+1}^T A x_{i+1} \quad (\text{approximate eigenvalue})$$

$$i = i + 1$$

until convergence

- 2. . See Lecture 11 and the course book:

We apply the power method to  $(A - \sigma I)^{-1}$  instead of  $A$ , where  $\sigma$  is called a *shift*. This will let us converge to the eigenvalue closest to  $\sigma$ , rather than just  $\lambda_1$ . This method is called *inverse iteration* or the *inverse power method*.

Alg. Inverse iteration: Given  $x_0$ , we iterate

$$i = 0$$

*repeat*

$$y_{i+1} = (A - \sigma I)^{-1}x_i$$

$$x_{i+1} = y_{i+1}/\|y_{i+1}\|_2 \quad (\text{approximate eigenvector})$$

$$\tilde{\lambda}_{i+1} = x_{i+1}^T A x_{i+1} \quad (\text{approximate eigenvalue})$$

$$i = i + 1$$

*until convergence*

$A = S\Lambda S^{-1}$  implies  $A - \sigma I = S(\Lambda - \sigma I)S^{-1}$  and so  $(A - \sigma I)^{-1} = S(\Lambda - \sigma I)^{-1}S^{-1}$ . Thus  $(A - \sigma I)^{-1}$  has the same eigenvectors  $s_i$  as  $A$  with corresponding eigenvalues  $((\Lambda - \sigma I)^{-1})_{jj} = (\lambda_j - \sigma)^{-1}$ . We expect that  $x_i$  to converge to the eigenvector corresponding to the largest eigenvalue in absolute value.