

TMA521/MMA510
Optimization, project course
Lecture 1
Introduction: simple/difficult problems,
matroid problems

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TMA521/MMA510 Optimization, project course

▶ Teachers/Examiners

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▶ Guest lecturers Karin Thörnblad & Adam Wojciechowski

▶ Schedule on the course homepage

www.math.chalmers.se/Math/Grundutb/CTH/tma521/1011/

≈ 3 meetings/lectures per week during four weeks

▶ Two projects:

- ▶ Lagrangian relaxation for a VLSI design problem (Matlab)
- ▶ (Different) decomposition methods applied to a real production scheduling problem (AMPL/Cplex, Matlab)

▶ Literature: *Optimization theory for large systems* (Lasdon, 2002, Cremona), *An introduction to continuous optimization* (Andréasson et al., Cremona), hand-outs from books and articles, lecture notes

▶ Examination: Written reports on the two projects Oral presentations and opposition!

▶ For higher grades than pass (4, 5, VG): oral exam

Topics: Turn difficult problems into sequences of simpler ones using decomposition and coordination

Prerequisites

- ▶ Linear Programming (LP), (Mixed) Integer Linear programming ((M)ILP), NonLinear Programming (NLP),

Decomposition methods covered

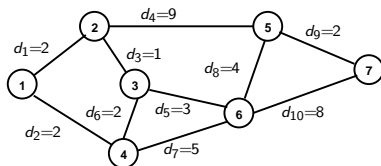
- ▶ Lagrangian relaxation (for MILP, NLP)
- ▶ Dantzig–Wolfe decomposition (for LP)
- ▶ Benders decomposition (for MILP, NLP)
- ▶ Column generation (for LP, MILP, NLP)
- ▶ Heuristics (for ILP)
- ▶ Branch & Bound (for MILP, non-convex NLP)
- ▶ Greedy algorithms (for ILP, NLP)
- ▶ Subgradient optimization (for convex NLP, Lagrangian duals)

Examples of simple problems

- ▶ For *simple problems*, there exist *polynomial algorithms* preferably with a small largest exponent
- ▶ Simple problems belong to the complexity class \mathcal{P}
- ▶ Network flow problems (see Wolsey):
 - ▶ Shortest paths
 - ▶ Maximum flows
 - ▶ Minimum cost (single-commodity) network flows
 - ▶ The transportation problem
 - ▶ The assignment problem
 - ▶ Maximum cardinality matching
- ▶ Linear programming (see Andréasson et al.)
- ▶ Problems over simple matroids — next!

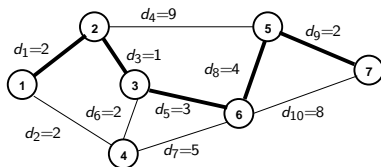
Example: Shortest path

Find the shortest path from node 1 to node 7



d_i = length of edge i

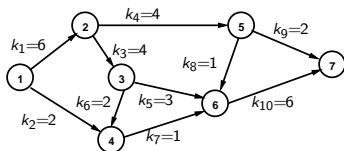
Shortest path from node 1 to node 7



Total length: 12

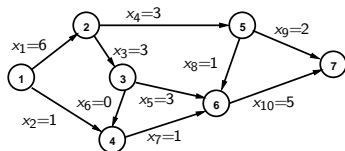
Example: Maximum flow

Find the maximum flow from node 1 to node 7



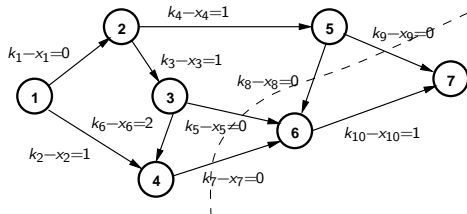
k_i = flow capacity of arc i

Maximum flow from node 1 to node 7



x_i = optimal flow through arc i

Minimum cut separating nodes 1 and 7



$k_i - x_i$ = residual flow capacity on arc i

Matroids and the greedy algorithm (Lawler)

- ▶ Greedy algorithm
 - ▶ Create a “complete solution” by iteratively choosing the best alternative
 - ▶ Never regret a previous choice

- ▶ Which problems can be solved using such a simple method?

- ▶ Problems whose feasible sets can be described by [matroids](#)

Matroids and independent sets

- ▶ Given a finite set \mathcal{E} and a family \mathcal{F} of subsets of \mathcal{E} :
If $\mathcal{I} \in \mathcal{F}$ and $\mathcal{I}' \subseteq \mathcal{I}$ imply $\mathcal{I}' \in \mathcal{F}$, then the elements of \mathcal{F} are called **independent**
- ▶ A **matroid** $M = (\mathcal{E}, \mathcal{F})$ is a structure in which \mathcal{E} is a finite set of **elements** and \mathcal{F} is a **family of subsets** of \mathcal{E} , such that
 1. $\emptyset \in \mathcal{F}$ and all proper subsets of a set \mathcal{I} in \mathcal{F} are in \mathcal{F}
 2. If \mathcal{I}_p and \mathcal{I}_{p+1} are sets in \mathcal{F} with $|\mathcal{I}_p| = p$ and $|\mathcal{I}_{p+1}| = p + 1$, then \exists an element $e \in \mathcal{I}_{p+1} \setminus \mathcal{I}_p$ such that $\mathcal{I}_p \cup \{e\} \in \mathcal{F}$
- ▶ Let $M = (\mathcal{E}, \mathcal{F})$ be a matroid and $\mathcal{A} \subseteq \mathcal{E}$.
If \mathcal{I} and \mathcal{I}' are **maximal independent subsets** of \mathcal{A} , then $|\mathcal{I}| = |\mathcal{I}'|$

Example I: Matric matroids

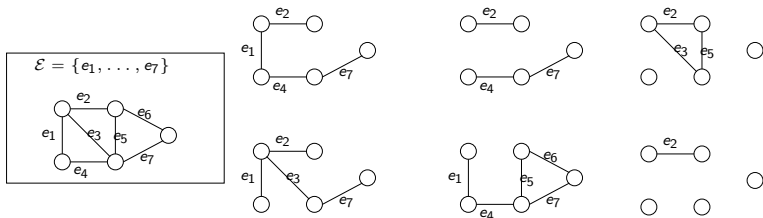
- ▶ \mathcal{E} = a set of column vectors in \mathbb{R}^n
- ▶ \mathcal{F} = the set of linearly independent subsets of vectors in \mathcal{E} .

- ▶ Let $n = 3$ and $\mathcal{E} = [e_1, \dots, e_5] = \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 3 & 2 & 0 & 0 & 1 \end{bmatrix}$

- ▶ We have:
 - ▶ $\{e_1, e_2, e_3\} \in \mathcal{F}$ and $\{e_2, e_3\} \in \mathcal{F}$ but
 - ▶ $\{e_1, e_2, e_3, e_5\} \notin \mathcal{F}$ and $\{e_1, e_4, e_5\} \notin \mathcal{F}$

Example II: Graphic matroids

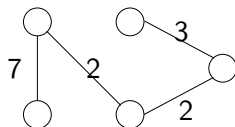
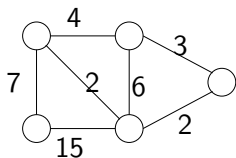
- ▶ $\mathcal{E} = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7\}$ = the set of links (edges) in an undirected graph
- ▶ \mathcal{F} = the set of all cycle-free subsets of edges in \mathcal{E}



- ▶ $\{e_1, e_2, e_4, e_7\} \in \mathcal{F}$, $\{e_2, e_4, e_7\} \in \mathcal{F}$, $\{e_2, e_3, e_5\} \notin \mathcal{F}$,
 $\{e_1, e_2, e_3, e_7\} \in \mathcal{F}$, $\{e_1, e_4, e_5, e_6, e_7\} \notin \mathcal{F}$, $\{e_2\} \in \mathcal{F}$.

Matroids and the greedy algorithm applied to Example II

- ▶ Let $w(e)$ be the cost of element $e \in \mathcal{E}$.
Problem: Find the element $\mathcal{I} \in \mathcal{F}$ of **maximal cardinality** such that **the total cost is at minimum/maximum**
- ▶ Example II, continued: $w(\mathcal{E}) = (7, 4, 2, 15, 6, 3, 2)$



An element $\mathcal{I} \in \mathcal{F}$ of maximal cardinality with minimum total cost

The Greedy algorithm for minimization problems

1. $\mathcal{A} = \emptyset$.
2. Sort the elements of \mathcal{E} in increasing order with respect to $w(e)$.
3. Take the first element $e \in \mathcal{E}$ in the list. If $\mathcal{A} \cup \{e\}$ is still independent \implies let $\mathcal{A} := \mathcal{A} \cup \{e\}$.
4. Repeat from step 3. with the next element—until either the list is empty, or \mathcal{A} possesses the maximal cardinality.

What are the special versions of this algorithm for Examples I and II?

Example I: Linearly independent vectors—matric matroids

- ▶ Let

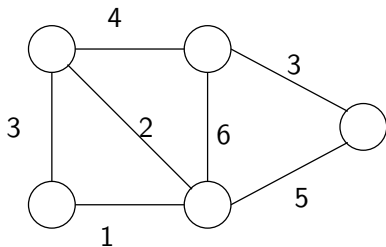
$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 2 & 0 & 1 \\ 0 & -1 & -1 & 1 & 1 \\ 3 & 2 & 8 & 1 & 4 \\ 2 & 1 & 5 & 0 & 2 \end{pmatrix},$$
$$\mathbf{w}^T = (10 \quad 9 \quad 8 \quad 4 \quad 1).$$

- ▶ Choose the maximal independent set with the maximum weight
- ▶ Can this technique solve linear programming problems?

Example II: minimum spanning trees (MST)

—graphic matroids

- ▶ The maximal cycle-free set of links in an undirected graph is a **spanning tree**
- ▶ In a graph $\mathcal{G} = (\mathcal{N}, \mathcal{E})$, it has $|\mathcal{N}| - 1$ links
- ▶ Classic greedy algorithm—**Kruskal's algorithm** has complexity $O(|\mathcal{E}| \cdot \log(|\mathcal{E}|))$. The main cost is in the sorting itself
- ▶ **Prim's algorithm** builds the spanning tree through graph search techniques, from node to node; complexity $O(|\mathcal{N}|^2)$.



Example III: continuous knapsack problem (in fact not a matroid problem)

- ▶ Continuous relaxation of the 0/1-knapsack problem (BKP):

$$\begin{aligned} & \text{maximize } f(\mathbf{x}) := \sum_{j=1}^n c_j x_j, \\ & \text{subject to } \sum_{j=1}^n a_j x_j \leq b, \quad (a_j, b \in \mathcal{Z}_+) \\ & \quad \quad \quad 0 \leq x_j \leq 1, \quad j = 1, \dots, n. \end{aligned}$$

- ▶ Greedy algorithm:
 1. Sort c_j/a_j in descending order
 2. Set the variables to 1 until the knapsack is full
 3. One variable may become fractional and the rest zero
- ▶ Linear programming duality shows that the greedy algorithm solves the problem correctly

Example III, continued

Linear programming dual:

$$\begin{array}{ll} \text{minimize} & bu + \sum_{j=1}^n w_j, \\ \text{subject to} & a_j u + w_j \geq c_j, \quad j = 1, \dots, n, \\ & u \geq 0, \\ & w_j \geq 0, \quad j = 1, \dots, n \end{array}$$

Hint: Complementarity slackness.

Example III, continued: Binary knapsack problem

- ▶ Rounding down the fractional variable value yields a feasible solution to (BKP)
- ▶ Is it also optimal in (BKP)?

$$\begin{aligned} & \text{maximize } f(\mathbf{x}) := 2x_1 + c x_2, \\ & \text{subject to } x_1 + c x_2 \leq c, \quad (c \in \mathcal{Z}_+) \\ & \quad \quad \quad x_1, x_2 \in \{0, 1\}, \end{aligned}$$

- ▶ If $c \geq 2$ then $\mathbf{x}^* = (0, 1)^T$ and $f^* = c$.
- ▶ The greedy algorithm, plus rounding, always yields $\bar{\mathbf{x}} = (1, 0)^T$, with $f(\bar{\mathbf{x}}) = 2$
- ▶ This solution is arbitrarily bad (when c is large)

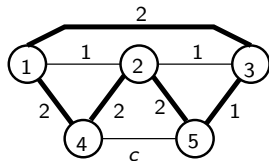
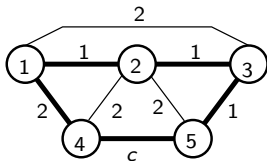
Example IV: The traveling salesperson problem (TSP)

The greedy algorithm for the TSP:

1. Start in node 1
2. Go to the nearest node which is not yet visited
3. Repeat step 2 until no nodes are left
4. Return to node 1; the tour is closed

► Greedy solution

Not optimal whenever $c > 4$.

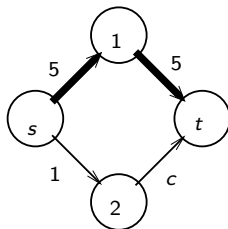
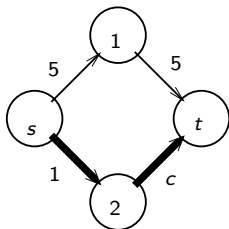


Optimal solution for $c \geq 4$

Example V: the shortest path problem (SPP)

- ▶ The greedy algorithm constructs a path that uses – locally – the cheapest link to reach a new node. Optimal?
- ▶ Greedy solution

Not optimal whenever $c > 9$



Optimal solution for $c \geq 9$

Example VI: Semi-matching

$$\text{maximize } f(\mathbf{x}) := \sum_{i=1}^m \sum_{j=1}^n w_{ij} x_{ij},$$

$$\text{subject to } \sum_{j=1}^n x_{ij} \leq 1, \quad i = 1, \dots, m,$$

$$x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, j = 1, \dots, n.$$

► Semi-assignment

Replace maximum \implies minimum; " \leq " \implies "="; let $m = n$

► Algorithm

For each i :

1. choose the best (lowest) w_{ij}
2. Set $x_{ij} = 1$ for that j , and $x_{ij} = 0$ for every other j

Matroid types

- ▶ **Graph matroid:** \mathcal{F} = the set of forests in a graph $\mathcal{G} = (\mathcal{N}, \mathcal{E})$.
Example problem: MST
- ▶ **Partition matroid:** Consider a partition of \mathcal{E} into m sets $\mathcal{B}_1, \dots, \mathcal{B}_m$ and let d_i ($i = 1, \dots, m$) be non-negative integers. Let

$$\mathcal{F} = \{ \mathcal{I} \mid \mathcal{I} \subseteq \mathcal{E}; \quad |\mathcal{I} \cap \mathcal{B}_i| \leq d_i, \quad i = 1, \dots, m \}.$$

Example problem: semi-matching in bipartite graphs.

- ▶ **Matrix matroid:** $S = (\mathcal{E}, \mathcal{F})$, where \mathcal{E} is a set of column vectors and \mathcal{F} is the set of subsets of \mathcal{E} with linearly independent vectors.
- ▶ **Observe:** The above matroids can be expressed as matrix matroids!

Problems over matroid intersections

- ▶ Given two matroids $M = (\mathcal{E}, \mathcal{P})$ and $N = (\mathcal{E}, \mathcal{R})$, find the maximum cardinality set in $\mathcal{P} \cap \mathcal{R}$
- ▶ **Example 1:** maximum-cardinality matching in a bipartite graph is the intersection of two partition matroids (with $d_i = 1$).
DRAW ILLUSTRATION!
- ▶ The intersection of two matroids can *not* be solved by using the *greedy algorithm*
- ▶ There exist *polynomial algorithms* for them, though
- ▶ *Examples:* bipartite matching and assignment problems can be solved as maximum flow problems, which are polynomially solvable

Problems over matroid intersections, cont.

- ▶ **Example 2:** The traveling salesperson problem (TSP) is the intersection of three matroids:
 - ▶ one graph matroid
 - ▶ two partition matroids(formulation on next page: assignment + tree constraints)
- ▶ TSP is *not* solvable in polynomial time.
- ▶ **Conclusion** (not proven here):
 - ▶ Matroid problems are extremely easy to solve (greedy works)
 - ▶ Two-matroid problems are polynomially solvable
 - ▶ Three-matroid problems are very difficult (exponential solution time)
- ▶ The TSP—different mathematical formulations give rise to different algorithms when Lagrangean relaxed or otherwise decomposed

Tree formulation

$$\text{minimize } \sum_{i=1}^n \sum_{j=1}^n c_{ij} x_{ij}$$

$$\text{subject to } \sum_{j=1}^n x_{ij} = 1, \quad i \in \mathcal{N}, \quad (1)$$

$$\sum_{i=1}^n x_{ij} = 1, \quad j \in \mathcal{N}, \quad (2)$$

$$\sum_{i \in \mathcal{S}} \sum_{j \in \mathcal{S}} x_{ij} \leq |\mathcal{S}| - 1, \quad \mathcal{S} \subset \mathcal{N}, \quad (3)$$

$$x_{ij} \in \{0, 1\}, \quad i, j \in \mathcal{N}.$$

- ▶ (1)–(2): assignment; (3): cycle-free
- ▶ Relax (3) \Rightarrow Assignment
- ▶ Relax (1)–(2) & add the sum of (1) \Rightarrow 1-MST

Node valence based formulation

$$\text{minimize} \quad \sum_{i=1}^n \sum_{j=1}^n c_{ij} x_{ij}$$

$$\text{subject to} \quad \sum_{j=1}^n x_{ij} = 2, \quad i \in \mathcal{N}, \quad (1)$$

$$\sum_{i=1}^n \sum_{j=1}^n x_{ij} = n, \quad (2)$$

$$\sum_{(i,j) \in (\mathcal{S}, \mathcal{N} \setminus \mathcal{S})} x_{ij} \geq 1, \quad \mathcal{S} \subset \mathcal{N}, \quad (3)$$

$$x_{ij} \in \{0, 1\}, \quad i, j \in \mathcal{N}.$$

- ▶ (1): valence = 2; (2): sum of (1); (3): cycle-free (alt. version)
- ▶ Hamiltonian cycle = spanning tree + one link \Rightarrow every node receives valence = 2
- ▶ Relax (1), except for node $s \Rightarrow$ 1-tree relaxation.
- ▶ Relax (3) \Rightarrow 2-matching.

Tree-based formulation for directed graphs

$$\begin{aligned} & \text{minimize} && \sum_{(i,j) \in \mathcal{E}} c_{ij} x_{ij} \\ & \text{subject to} && \sum_{j:(i,j) \in \mathcal{E}} x_{ij} = 1, && i \in \mathcal{N}, && (1) \\ & && \sum_{i:(i,j) \in \mathcal{E}} x_{ij} = 1, && j \in \mathcal{N}, && (2) \\ & && \sum_{(i,j) \in \mathcal{E}} x_{ij} = |\mathcal{N}|, && && (3) \\ & && \sum_{(i,j) \in (\mathcal{S}, \mathcal{N} \setminus \mathcal{S})^+} x_{ij} + \sum_{(j,i) \in (\mathcal{S}, \mathcal{N} \setminus \mathcal{S})^-} x_{ij} \geq 1, && \mathcal{S} \subset \mathcal{N}, && (4) \\ & && x_{ij} \in \{0, 1\}, && (i, j) \in \mathcal{E}. \end{aligned}$$

- ▶ (1)–(2): assignment; (3): redundant; (4) cycle-free
- ▶ Relax (1) or (2), plus (4) \Rightarrow semi-assignment
- ▶ Relax (3) plus (4) \Rightarrow assignment
- ▶ Relax (1), and (2) except for node $s \Rightarrow$ directed 1-tree