

Ergodic, primal convergence in dual subgradient schemes for convex programming, II: the case of inconsistent primal problems

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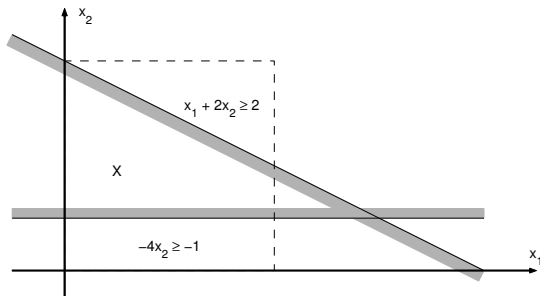
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Large-Scale Optimization

2018–01–29

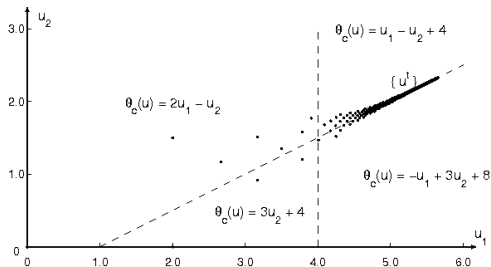
Introduction

- We consider a possibly **infeasible, i.e., inconsistent**, convex optimization problem



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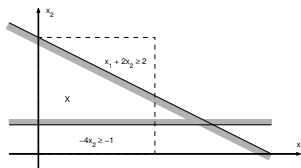
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 - Apply a Lagrangian dual method to this problem
- ⇒ **Divergence** of the dual iterates



(a) The sequence $\{u^k\}$

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- Will the primal sequence of **subproblem solutions** still yield relevant information about the primal solution?



- Subproblem (extreme) solutions $\in \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$

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 - Associate a primal-dual convex-concave program with a **saddle point problem**
 - ... and homogenize the dual problem

- Convergence results for a **subgradient optimization** algorithm applied to the Lagrange dual

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 - Construct an **ergodic, i.e., averaged, sequence** of primal subproblem solutions
- ⇒ Convergence to a saddle point

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⇔ the unique dual solution of the saddle-point problem

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 - For LP: The **original objective function is minimized** over the subset of minimum infeasibility

Introduction

To start, we wish to solve a convex program:

$$\underset{x}{\text{minimize}} \quad f(x), \quad (1a)$$

$$\text{subject to} \quad g(x) \leq 0^m, \quad (1b)$$

$$x \in X \quad (1c)$$

- $\emptyset \neq X \subset \mathbb{R}^n$ – convex and compact set
- $g : \mathbb{R}^n \mapsto \mathbb{R}^m, f : \mathbb{R}^n \mapsto \mathbb{R}$ – convex functions
- **Lagrange function** w.r.t. relaxing the constraints (1b):

$$\mathcal{L}_f(x, u) := f(x) + u^\top g(x), \quad (x, u) \in \mathbb{R}^n \times \mathbb{R}^m \quad (2)$$

- **Lagrangian dual function**:

$$\theta_f(u) := \min_{x \in X} \mathcal{L}_f(x, u), \quad u \in \mathbb{R}^m \quad (3)$$

- **Lagrangian dual problem**:

$$\underset{u \in \mathbb{R}_+^m}{\text{maximize}} \quad \theta_f(u) \quad (4)$$

Results for the case of consistency

- Assume $\{x \in X \mid g(x) \leq 0^m\} \neq \emptyset$
- ⇒ The optimal value of the convex program (1): $\theta_f^* > -\infty$
- Set of **optimal solutions**:
 $X_f^* := \{x \in X \mid g(x) \leq 0^m, f(x) \leq \theta_f^*\}$
- Lagrangean dual problem:

$$\theta_c^* := \max_{u \in \mathbb{R}_+^m} \theta_f(u) \quad (5)$$

- The **dual optimal set is bounded** (provided a Slater condition, i.e., $\{x \in X \mid g(x) < 0^m\} \neq \emptyset$):

$$U_f^* := \{u \in \mathbb{R}_+^m \mid \theta_f(u) \geq \theta_f^*\} \neq \emptyset$$

- Lagrangean **subproblem solution** at $u \in \mathbb{R}^m$:

$$x_f(u) \in X_f(u) := \operatorname{argmin}_{x \in X} \{f(x) + u^\top g(x)\} \quad (6)$$

Dual subgradient algorithm

- **Subdifferential** of θ_f at $u \in \mathbb{R}^m$:

$$\begin{aligned}\partial\theta_f(u) &:= \left\{ \gamma \in \mathbb{R}^m \mid \theta_f(w) \leq \theta_f(u) + \gamma^T (w - u), w \in \mathbb{R}^m \right\} \\ &= \{ g(x) \mid x \in X_f(u) \}\end{aligned}$$

- **Subgradient algorithm** applied to the dual (5):

$$u^0 \geq 0; \quad u^{t+1} := [u^t + \alpha_t g(x_f(u^t))]_+ \quad t = 0, 1, \dots \quad (7)$$

Convergence to a dual optimal set and point

Theorem

Apply the subgradient method (7) to the dual program (5). If the step lengths α_t fulfil the divergent series conditions

$$\alpha_t > 0 \quad \forall t; \quad \{\alpha_t\} \rightarrow 0; \quad \left\{ \sum_{s=0}^{t-1} \alpha_s \right\} \rightarrow \infty. \quad (8a)$$

Then^a $\{\text{dist}(u^t; U_f^*)\} \rightarrow 0$ and $\{\theta_f(u^t)\} \rightarrow \theta_f^*$
If, in addition,

$$\sum_{s=0}^{\infty} \alpha_s^2 < \infty \quad (8b)$$

holds, then^b $\{u^t\} \rightarrow u^\infty \in U_f^*$.

^aErmol'ev, Yu.M. (1966): *Methods for solving nonlinear extremal problems*, Cybernetics 2(4), 1–14

^bShepilov, M.A. (1976): *Method of the generalized gradient for finding the absolute minimum of a convex function*, Cybernetics 12, 547–553

Convergence of an ergodic (averaged) sequence of primal subproblem solutions to the primal optimal set

- Cumulative step lengths:

$$A_t := \sum_{s=0}^{t-1} \alpha_s, \quad t = 1, 2, \dots \quad (9)$$

- Averaged/ergodic primal sequence:

$$\bar{x}_f^t := \frac{1}{A_t} \sum_{s=0}^{t-1} \alpha_s x_f(u^s), \quad t = 1, 2, \dots \quad (10)$$

Theorem

^a Apply the subgradient method (7), (8) to the dual program (5).

Then,

$$\{\text{dist}(\bar{x}_f^t; X_f^*)\} \rightarrow 0 \quad \text{and} \quad \{f(\bar{x}^t)\} \rightarrow \theta_f^*$$

^aLarsson, Patriksson, Strömberg (1999): *Ergodic, primal convergence in dual subgradient schemes for convex programming*, Math. Prog. 86:283–312

The case of inconsistency

- Assume that $\{x \in X \mid g(x) \leq 0^m\} = \emptyset$
- Lagrangean dual problem:

$$\infty = \sup_{u \in \mathbb{R}_+^m} \theta_f(u) \quad (11)$$

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- A cone of feasible and ascent directions for the dual (11)
 $C := \{w \in \mathbb{R}_+^m \mid w^\top g(x) > 0, x \in X\}$

Theorem

A theorem of the alternative:

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- Note: The cone C is independent of the objective function f

Divergence in the case of inconsistency

Theorem

Assume that $\{x \in X \mid g(x) \leq 0^m\} = \emptyset$.

Let the sequence $\{u^t\}$ be generated by

$$u^0 \geq 0; \quad u^{t+1} = [u^t + \alpha_t g(x_f(u^t))]_+$$

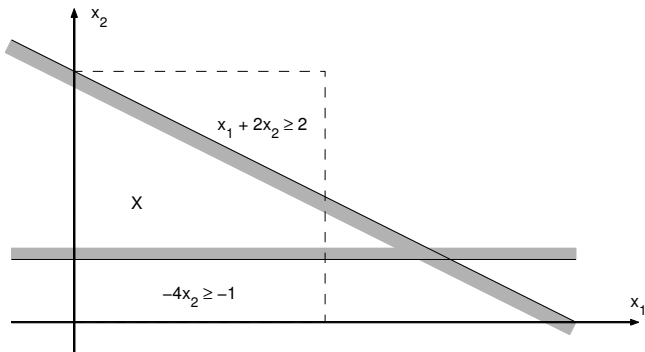
with $\alpha_t > 0$, $\{\alpha_t\} \rightarrow 0$, and $\left\{ \sum_{s=0}^{t-1} \alpha_s \right\} \rightarrow \infty$, applied to the dual program

$$\sup_{u \in \mathbb{R}_+^m} \theta_f(u).$$

Then $\{\|u^t\|\} \rightarrow \infty$ as $t \rightarrow \infty$

A numerical illustration — the primal space

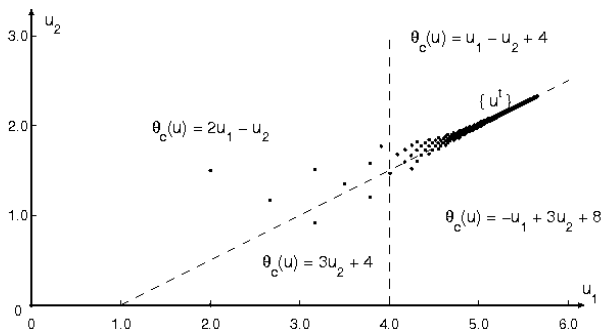
Let $m = n = 2$, $f(x) = 4x_1 + 2x_2$, $g(x) = \begin{pmatrix} 2 & -x_1 & -2x_2 \\ -1 & & +4x_2 \end{pmatrix}$, and $X = [0, 1]^2$.



A numerical illustration — the dual space

$$\theta_f(u) = \begin{cases} 2u_1 - u_2, & u_1 \leq 4, u_1 - 2u_2 \leq 1, \\ 3u_2 + 2, & u_1 \leq 4, u_1 - 2u_2 \geq 1, \\ u_1 - u_2 + 4, & u_1 \geq 4, u_1 - 2u_2 \leq 1, \\ -u_1 + 3u_2 + 6, & u_1 \geq 4, u_1 - 2u_2 \geq 1, \end{cases}$$

A couple of numbers in the figure are incorrect ...



(a) The sequence $\{u^i\}$

The homogeneous dual

- Assume $X \neq \emptyset$ but $\{x \in X \mid g(x) \leq 0^m\} = \emptyset$

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The homogeneous dual

- Assume $X \neq \emptyset$ but $\{x \in X \mid g(x) \leq 0^m\} = \emptyset$
- We will study the case when $f(x) = 0$ and restrict the dual space to the unit ball
- The Lagrange function at (x, u) for $u \neq 0$

$$\mathcal{L}_f(x, u) = \|u\| \left(\frac{f(x)}{\|u\|} + \frac{u^T g(x)}{\|u\|} \right) \quad (12)$$

- As the value of $\|u\|$ increases, the term $f(x)$ in the computation of $x_f(u)$ will **tend to be negligible**
- For $t \gg 1$ the subgradient method (7), (8a) tackles an **approximation** of the **homogeneous dual** – the Lagrange dual of a pure feasibility problem:

$$\underset{u \in \mathbb{R}_+^m}{\text{maximize}} \theta_0(u) \quad (13)$$

The homogeneous dual

$$\theta_0(u) = \min_{x \in X} \{u^\top g(x)\}, \quad u \in \mathbb{R}^m \quad (14)$$

- The function θ_0 is **superlinear** – its hypograph is a nonempty and convex cone in \mathbb{R}^{m+1}
- $\Rightarrow \theta_0(\delta u) = \delta \theta_0(u)$ holds for all $\delta \geq 0$ and all $u \in \mathbb{R}^m$
- Directional derivative $\theta'_0(u; d)$, of θ_0 at u in direction d :

$$\theta'_0(0; d) = \theta_0(d) \quad \text{holds for all } d \in \mathbb{R}^m \quad (15)$$

- The homogeneous dual (13) is interpreted as **searching for a steepest feasible ascent direction of θ_0**
- \Rightarrow Maximize θ_0 over the set $V = \{u \in \mathbb{R}_+^m \mid \|u\| \leq 1\}$

$$\theta_0^{V*} := \max_{u \in V} \theta_0(u) = \max_{d \in V} \theta'_0(0; d) \quad (16)$$

An associated saddle point problem

- By definition of θ_0 and (16):

$$\theta_0^{V^*} = \max_{u \in V} \left\{ \min_{x \in X} \left\{ u^\top g(x) \right\} \right\} = \min_{x \in X} \left\{ \max_{u \in V} \left\{ g(x)^\top u \right\} \right\} \quad (17)$$

since $u^\top g(x)$ is convex in x (for $u \in \mathbb{R}_+^m$) and linear in u , and since the sets X and V are convex and compact

- Define the mappings $X_0(\cdot) : V \mapsto 2^X$ and $V(\cdot) : X \mapsto 2^V$ by

$$X_0(v) := \operatorname{argmin}_{x \in X} \left\{ v^\top g(x) \right\}, \quad v \in V$$

$$V(x) := \operatorname{argmax}_{v \in V} \left\{ g(x)^\top v \right\}, \quad x \in X$$

- Saddle point property:

$$\bar{x} \in X_0(\bar{v}) \text{ and } \bar{v} \in V(\bar{x})$$



(\bar{x}, \bar{v}) is a saddle point for $v^\top g(x)$ on $X \times V$

Characterization of the set of saddle points

- LEMMA

$$x \in X \Rightarrow V(x) = \left\{ \frac{[g(x)]_+}{\|[g(x)]_+\|} \right\}$$

- The set $X_0^* \times V^*$ of saddle points is characterized as:

$$X_0(V^*) = X_0^* := \operatorname{argmin}_{x \in X} \|[g(x)]_+\| \quad \text{“minimum total infeasibility”}$$

$$V(x^*) = V^* := \operatorname{argmax}_{v \in V} \theta_0(v) \quad \text{“steepest ascent direction”}$$

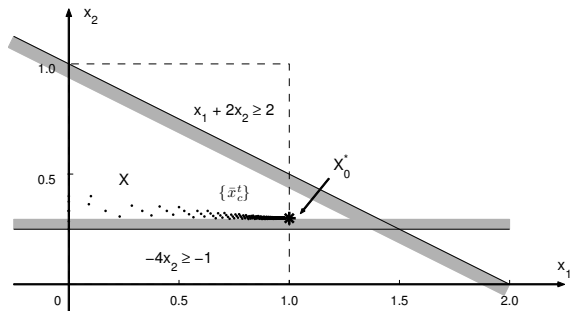
- LEMMA

$X_0^* \neq \emptyset$ is convex and compact

$V^* = V(x^*)$ (a singleton) irrespective of $x^* \in X_0^*$

Note: $V^* \in C$ (the cone of feasible ascent directions for θ_f)

Numerical illustrations — the primal space



Figur: $m = n = 2$, $f(x) = 4x_1 + 2x_2$, $g(x) = \begin{pmatrix} 2 & -x_1 & -2x_2 \\ -1 & & +4x_2 \end{pmatrix} \leq \begin{pmatrix} 0 \\ 0 \end{pmatrix}$,
 $X = [0, 1]^2$, $X_0^* = (1, \frac{3}{10})$

Dual and primal convergence in the inconsistent case — convergence in the homogeneous dual

Theorem

Let the sequence $\{u^t\}$ be generated by the subgradient method

$$u^0 \geq 0; \quad u^{t+1} := [u^t + \alpha_t g(x_f(u^t))]_+$$

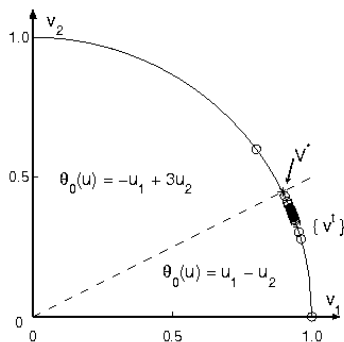
with $\alpha_t > 0$, $\{\alpha_t\} \rightarrow 0$, and $\left\{ \sum_{s=0}^{t-1} \alpha_s \right\} \rightarrow \infty$. Then

$$\{v^t\} := \left\{ \frac{u^t}{\max_{s \leq t} \{1, \|u^s\|\}} \right\} \rightarrow V^* \quad \text{and} \quad \{\theta_0(v^t)\} \rightarrow \theta_0^{V^*}$$

A numerical illustration — the homogeneous dual

$$\theta_0(u) = \begin{cases} u_1 - u_2, & u_1 \leq 2u_2, \\ -u_1 + 3u_2, & u_1 \geq 2u_2, \end{cases} \quad \theta_0^{V^*} = \frac{1}{\sqrt{5}}$$

$$\{v^t\} = \left\{ \frac{u^t}{\max_{s \leq t} \{1, \|u^s\|\}} \right\} \rightarrow V^* = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

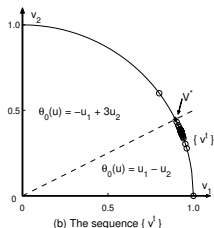
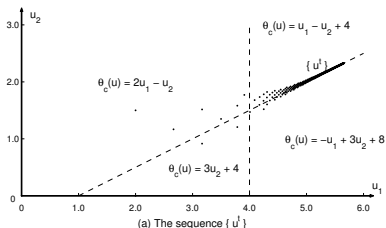


(b) The sequence $\{v^t\}$

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$\{u^t\}$ diverges in the direction V^* of steepest ascent of θ_f over \mathbb{R}_+^m

Convergence to a saddle point

Theorem (Convergence of the primal ergodic sequence)

$\{\text{dist}(\bar{x}_f^t; X_0(V^*))\} \rightarrow 0$ as $t \rightarrow \infty$ where $\bar{x}_f^t = \frac{1}{A_t} \sum_{s=0}^{t-1} \alpha_s x_f(u^s)$

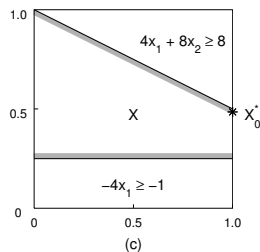
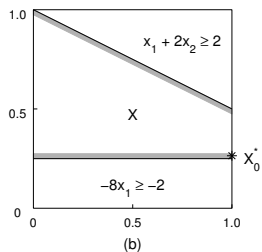
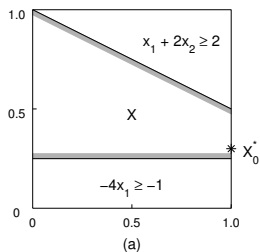
Theorem (Convergence of the homogeneous dual sequence)

$\{\text{dist}(v^t; V(\bar{x}_f^\infty))\} \rightarrow 0$ as $t \rightarrow \infty$ where \bar{x}_f^∞ is an accumulation point of $\{\bar{x}_f^t\}$

Theorem (Convergence to a saddle point)

$\{\text{dist}((\bar{x}_f^t, v^t); X_0(V^*) \times V(\bar{x}_f^\infty))\} \rightarrow 0$ as $t \rightarrow \infty$ where
 $\bar{x}_f^\infty \in X_0(V^*) = X_0^*$ and $V(\bar{x}_f^\infty) = V^* = \frac{[g(\bar{x}_f^\infty)]_+}{\|[g(\bar{x}_f^\infty)]_+\|}$

Further results: The effect of constraint scaling on the solution set X_0^*



Main references and further reading

- Larsson, Patriksson, Strömberg (1996): *Conditional subgradient optimization—theory and applications*, European Journal of Operational Research 88:382–403
- Larsson, Patriksson, Strömberg (1999): *Ergodic, primal convergence in dual subgradient schemes for convex programming*, Mathematical Programming 86:283–312
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- Gustavsson, E., Patriksson, M., Strömberg, A.-B. (2015): *Primal convergence from dual subgradient methods for convex optimization*. Mathematical Programming 150(2), 365–390 (increase convergence speed)