

TMA690 Partial Differential Equations - Exam

Date: Thursday, 11 January

Time: 8.30-12.30

- Please write your answers to SECTION A on the actual exam paper and hand it in together with your solution to problems in SECTION B.
- Telephone contact during the exam: Anders Hildeman, ext. 5325.
- The final exam is worth 50 points. 20 points are required for a pass grade 3, 30 points for grade 4, and 40 points for grade 5. The bonus points gathered during the course are added to your exam total.
- Solutions will be announced after the end of the exam on the course homepage.
- You may view the exams on Friday, January 19, 10.30-11.30 in MV:L15.

SECTION A

Indicate whether the following statements are True or False by putting T or F in the box. You will get 1 point for each right answer.

1. The linear space V of continuous functions $f : [0, 1] \rightarrow \mathbb{R}$ equipped with the norm $\|f\| = \left(\int_0^1 |f(s)|^2 ds \right)^{1/2}$ is a Banach space. F

2. The space $H_0^1(0, 1)$ is a closed subspace of $H^1(0, 1)$. T

3. The weak derivative $\frac{\partial v}{\partial x_2}$ of a function $v = v(x_1, x_2) \in L^2((0, 1) \times (0, 1))$ is a function that belongs to $L^2((0, 1) \times (0, 1))$. F

4. The bilinear form $a : H^1(0, 1) \times H^1(0, 1) \rightarrow \mathbb{R}$ defined by

$$a(u, v) = \int_0^1 u'v' dx,$$

where u' and v' are the generalized derivatives of u and v is coercive. F

5. Functions that belong to $H^1((0, 1) \times (0, 1))$ are continuous. F

6. Let $\Omega = (0, 1) \times (0, 1)$ and let Γ denote its boundary. Let $a(x, y) = 1 + x^2 + y^2$. The equation

$$\begin{aligned} -\nabla \cdot (a \nabla u) &= 0, \text{ in } \Omega, \\ u|_{\Gamma} &= 1 \end{aligned}$$

has a unique weak solution. T

7. If u is twice continuously differentiable and $-u'' + u \leq 0$ on $(0, 1)$, then

$$\max_{x \in [0, 1]} u(x) \leq u(1).$$

F

8. If u_1 and u_2 are classical solutions of the initial value problems

$$\begin{aligned}\frac{\partial u_i}{\partial t} - \Delta u_i &= 0 \text{ in } \mathbb{R}^3 \times \mathbb{R}_+, \quad i = 1, 2, \\ u_i(x, y, z, 0) &= i e^{-x^2 - y^2 - z^2} \quad i = 1, 2,\end{aligned}$$

then $|u_1(x, y, z, t) - u_2(x, y, z, t)| \leq 1$ in $\mathbb{R}^3 \times \mathbb{R}_+$.

T

9. If u is a sufficiently smooth solution of

$$\begin{aligned}u_{tt} - u_{xx} &= 0 \text{ in } (0, 1) \times (0, \infty) \\ u(0, t) = u(1, t) &= 0, \quad t > 0, \\ u(x, 0) &= x - x^2, \quad x \in (0, 1), \\ u_t(x, 0) &= x, \quad x \in (0, 1),\end{aligned}$$

then $\int_0^1 (u_t(x, t))^2 + (u_x(x, t))^2 dx = \frac{2}{3}$ for all $t \geq 0$.

T

10. The only solution of the initial value problem

$$\begin{aligned}u_t - \Delta u &= 0 \text{ in } \mathbb{R}^3 \times (0, \infty) \\ u(x, y, z, 0) &= 0,\end{aligned}$$

is the function $u(x, y, z, t) = 0$.

F

SECTION B

Solve the following problems and hand in your detailed answers.

11. (a) State the Riesz Representation Theorem. (2)
 (b) State the Lax-Milgram Lemma. (2)
12. (a) Let $\Omega \subset \mathbb{R}^d$ is a bounded domain with appropriately smooth boundary. Define the weak derivative $\frac{\partial v}{\partial x_i}$ ($i = 1, 2, \dots, d$) of a function $v \in L^2(\Omega)$ and explain when does $\frac{\partial v}{\partial x_i}$ belong to $L^2(\Omega)$. (3)
 (b) Define the Sobolev space $H^1(\Omega)$. (2)
13. State and prove Friedrich's inequality. (8)
14. Let $\Omega \subset \mathbb{R}^2$ be a bounded domain with smooth boundary Γ . Give a weak (variational) formulation of the problem

$$\begin{aligned} -\Delta u &= 1 \text{ in } \Omega \\ \frac{\partial u}{\partial n} + u &= 0 \text{ on } \Gamma. \end{aligned}$$

Prove existence and uniqueness of a weak solution. (8)

15. (a) Define the space of test functions on \mathbb{R} and the convergence of test functions. (1)
 (b) Define distribution (generalized function) on \mathbb{R} . (1)
 (c) Define the derivative of a distribution on \mathbb{R} . (1)
 (d) Define the weak convergence of distributions on \mathbb{R} . (1)
 (e) Let $g(x) = \frac{3}{4}(1 - x^2)$ for $|x| \leq 1$ and $g(x) = 0$ for $|x| > 1$. Show that if $g_\varepsilon(x) = \frac{1}{\varepsilon}g(\frac{1}{\varepsilon}x)$ then the regular distribution u_{g_ε} associated with g_ε converges weakly to δ as $\varepsilon \rightarrow 0$, where δ denotes the Dirac delta distribution (concentrated at 0). (4)

16. Solve the partial differential equation

$$x\partial_x u + 3y\partial_y u = 0,$$

subject to the boundary condition $u(1, y) = y^2$. (7)

SECTION B

(11) (a) Let V be a Hilbert space with scalar product (\cdot, \cdot) . For each bounded linear functional L on V there is a unique $u \in V$ such that

$$L(v) = (v, u) \quad \forall v \in V.$$

Furthermore, $\|L\|_{V^*} = \|u\|_V$.

(b) Let V be a Hilbert space. If the bilinear form $a(\cdot, \cdot)$ is bounded and coercive on V and L is a bounded linear functional on V , then there is a unique vector $u \in V$ such that

$$a(u, v) = L(v) \quad \forall v \in V.$$

Furthermore, there is $C > 0$, such that

$$\|u\|_V \leq C \|L\|_{V^*}.$$

(12) (a) Let $v \in C^2$. The weak derivative of v $\left(\frac{\partial v}{\partial x_i}\right)$ is the ^{linear} functional:

$$\frac{\partial v}{\partial x_i}(\varphi) = - \int_{\mathbb{R}^n} v \frac{\partial \varphi}{\partial x_i} dx \quad \forall \varphi \in C_0^1(\mathbb{R}^n).$$

It then is a constant $C > 0$ such that

$$\left| \frac{\partial v}{\partial x_i}(\varphi) \right| \leq C \|\varphi\|_{L^2} \quad \forall \varphi \in C_0^1(\mathbb{R}^n)$$

then, as C_0^1 is dense in $L^2(\mathbb{R}^n)$, the functional $\frac{\partial v}{\partial x_i}$ can be extended to a bounded linear

functional defined on $L^2(\Omega)$, still denoted by $\frac{\partial v}{\partial x_i}$. (2)

In this case, by the Riesz Representation Theorem, there is $w \in L^2(\Omega)$ such that

$$\frac{\partial v}{\partial x_i}(\varphi) = \int_{\Omega} w \varphi \, dx.$$

We then say that the weak derivative $\frac{\partial v}{\partial x_i}$ belongs to $L^2(\Omega)$ and $\frac{\partial v}{\partial x_i} = w$.

(b) The space $H^1(\Omega)$ consists of functions $v \in L^2(\Omega)$ such that $\frac{\partial v}{\partial x_i} \in L^2(\Omega)$ for all $i=1, \dots, d$. It is a Hilbert space with inner product

$$\begin{aligned} (v, w)_{H^1} &= (v, w)_{L^2} + (\nabla v, \nabla w)_{L^2} \\ &= \int_{\Omega} v w \, dx + \sum_{i=1}^d \int_{\Omega} \frac{\partial v}{\partial x_i} \frac{\partial w}{\partial x_i} \, dx. \end{aligned}$$

(13) Friedrich's inequality:

$$\|v\|_{L^2(\Omega)} \leq C \left(\|\nabla v\|_{L^2(\Omega)}^2 + \|v\|_{L^2(\Omega)}^2 \right)^{1/2} \quad \forall v \in C^1$$

where $\Omega \subset \mathbb{R}^d$ is a bounded domain with appropriately smooth boundary.

Proof. Let $\phi = \frac{1}{2d} |x|^2$, then $\Delta \phi = 1$. Therefore,

$$\int_{\Omega} v^2 \, dx = \int_{\Omega} v^2 \Delta \phi \, dx = \int_{\partial \Omega} v^2 \nabla \phi \cdot n \, ds - 2 \int_{\Omega} v \nabla v \cdot \nabla \phi \, dx$$

$$\Rightarrow \|v\|^2 \leq \int_{\partial \Omega} v^2 |\nabla \phi| \, ds + 2 \int_{\Omega} |v| |\nabla v| |\nabla \phi| \, dx$$

Since Ω is bounded, there is $m > 0$ such that

$\max_{\bar{\Omega}} |\nabla \phi| < M.$ Thus

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$$\|v\|^2 \leq M \int_{\Omega} v^2 ds + 2M \int_{\Omega} |\nabla v| dx$$

$$\leq M \|v\|_{L^2(\Omega)}^2 + \int_{\Omega} \frac{|v|^2}{2} + \frac{(2M |\nabla v|)^2}{2} dx$$

$$= M \|v\|_{L^2(\Omega)}^2 + \frac{1}{2} \|v\|^2 + 2M^2 \|v\|_1^2$$

$$\Rightarrow \frac{1}{2} \|v\|^2 \leq M \|v\|_{L^2(\Omega)}^2 + 2M^2 \|v\|_1^2$$

$$\Rightarrow \|v\|_{L^2(\Omega)}^2 \leq C (\|v\|_{L^2(\Omega)} + \|\nabla v\|_{L^2(\Omega)}^2) \quad \square$$

(14) $-\Delta u = 1 \quad \text{in } \Omega$

$$\frac{\partial u}{\partial n} + u = 0 \quad \text{on } \partial \Omega.$$

let $v \in C^1(\Omega)$. then

$$\int_{\Omega} 1 \cdot v dx = \int_{\Omega} -\Delta u v dx = - \int_{\Omega} \frac{\partial u}{\partial n} v ds + \int_{\Omega} \nabla u \cdot \nabla v dx$$

$$= \int_{\Omega} u v ds + \int_{\Omega} \nabla u \cdot \nabla v dx$$

Weierstrass Approximation: Find $u \in H^1(\Omega)$ such that

$$\int_{\Omega} \nabla u \cdot \nabla v dx + \int_{\Omega} u v ds = \int_{\Omega} v dx \quad \forall v \in H^1(\Omega).$$

let $V = H^1(\Omega)$. the bilinear

$$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v dx + \int_{\Omega} u v ds$$

$$L(v) = \int_{\Omega} v dx$$

• a is bilinear, symmetric ✓

• a is bounded:

$$|a(u, v)| \leq \|Du\| \|Dv\| + \|u\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)}$$

↓ Trace inequality.

$$\leq \|u\|_1 \cdot \|v\|_1 + C^2 \|u\|_1 \|v\|_1$$

$$= (1 + C^2) \|u\|_1 \|v\|_1$$

• a is coercive:

$$a(v, v) = \|v\|_1^2 + \|v\|_{L^2(\Omega)}^2 \geq \|v\|_1^2 + \frac{1}{2} \|v\|_{L^2(\Omega)}^2 = \frac{1}{2} \|v\|_1^2 + \frac{1}{2} (\|v\|_1^2 + \|v\|_{L^2(\Omega)}^2)$$

$$\geq \frac{1}{2} \|v\|_1^2 + C \|v\|_{L^2(\Omega)}^2 \geq \min(\frac{1}{2}, C) (\|v\|_1^2 + \|v\|_{L^2(\Omega)}^2) = \alpha \|v\|_1^2$$

↑
Friedrich's inequality.

• L is bounded:

$$|L(v)| = \left| \int_{\Omega} 1 \cdot v \, dx \right| \leq \left(\int_{\Omega} 1^2 \, dx \right)^{1/2} \cdot \left(\int_{\Omega} v^2 \, dx \right)^{1/2} = C \|v\|_1^2$$

$$\leq C \|v\|_1^2$$

therefore, by Riesz (or Lax-Milgram), there is a unique $u \in H^1(\Omega)$ such that

$$a(u, v) = L(v).$$

- 15 (a) The space of test functions C_0^∞ consists of functions $\phi: \mathbb{R} \rightarrow \mathbb{R}$ such that
- (a) $\phi^{(m)}$ exists for all $m=1, 2, \dots$
 - (b) $\phi = 0$ outside of a bounded and closed interval.

convergence of test functions:

(5)

$$\phi_j \rightarrow \phi \quad \forall j$$

(a) ϕ and ϕ_j vanish outside of a common bounded and closed interval

(a) if $\phi_j^{(m)} \rightarrow \phi^{(m)}$ uniformly for all $m=0,1,2,\dots$

(b) A distribution u is a linear functional on C_0^∞ that is continuous with respect to the convergence of test functions:

$$\text{if } \phi_j \rightarrow \phi \quad \text{then } u(\phi_j) \rightarrow u(\phi).$$

(c) Let u be a distribution. Then u' is a distribution defined by $u'(\phi) = -u(\phi')$ $\forall \phi \in C_0^\infty$.

(d) A sequence of distributions (u_j) converges to a distribution u weakly if

$$u_j(\phi) \rightarrow u(\phi) \quad \forall \phi \in C_0^\infty.$$

(e) To show: $u_{g_\varepsilon}(\phi) \rightarrow \phi(0) \quad \forall \phi \in C_0^\infty$.

Note: $g_\varepsilon \geq 0, \int_{\mathbb{R}} g_\varepsilon dx = 1 = \int_{-1}^1 g_\varepsilon(x) dx$

$$|u_{g_\varepsilon}(\phi) - \phi(0)| = \left| \int_{\mathbb{R}} g_\varepsilon(x) \phi(x) dx - \int_{\mathbb{R}} g_\varepsilon(x) \phi(0) dx \right|$$

$$\leq \int_{\mathbb{R}} g_\varepsilon(x) |\phi(x) - \phi(0)| dx = \int_{-1}^1 g_\varepsilon(x) |\phi(x) - \phi(0)| dx$$

$$\leq \sup_{x \in [-\varepsilon, \varepsilon]} |\phi(x) - \phi(0)| = \sup_{z \in [-\varepsilon, \varepsilon]} |\phi(z) - \phi(0)| \rightarrow 0$$

as $\varepsilon \rightarrow 0$ because ϕ is continuous at 0.

96) Ansatz für die Separation:

$$\dot{x} = x \quad \dot{y} = 3y$$

$$\Rightarrow x(t) = ce^t \quad y(t) = De^{3t}$$

$$\Rightarrow \zeta(t) = (ce^t, De^{3t}) \quad \text{or with } s = ce^t,$$

$$\zeta(s) = (s, Ks^3) \quad \text{or with } s = r+1$$

$$\zeta(r) = (r+1, K(r+1)^3). \quad \text{Then } \zeta(0) = (1, K) \in P.$$

$$\text{Let } \text{Nud: } \left. \begin{array}{l} r+1 = \tilde{x}^2 \\ K(r+1)^3 = \tilde{y}^3 \end{array} \right\} K = \frac{\tilde{y}^2}{\tilde{x}^3}$$

$$\Rightarrow \zeta(r) = (r+1, \frac{\tilde{y}^2}{\tilde{x}^3} (r+1))$$

$$u(\tilde{x}, \tilde{y}) = v(\zeta(0)) = \left(\frac{\tilde{y}^2}{\tilde{x}^3} \right)^2$$

The solution is $u(x, y) = y^2 \cdot x^{-6}$

$$\text{Check: } u(1, y) = y^2$$

$$\left. \begin{array}{l} x \partial_x u = -6 y^2 x^{-6} \\ 3y \partial_y u = 6 y^2 x^{-6} \end{array} \right\} x \partial_x u + 3y \partial_y u = 0.$$