

# Matrices, geometry, and mappings

## Vector spaces, linear mappings, independence, and bases

Now we know intuitively what a vector is, and what an  $N$ -dimensional space is. There is a need, however, to know more firmly, i.e. formally.

**Definition:** A vector space is a set of elements (we usually call them vectors) together with rules for addition of elements and multiplication of an element by a scalar. The result of adding two elements or multiplying an element by a scalar must be an element that is a member of the original set.

**Note 1:** The addition and multiplication must obey the commutative and distributive laws, for example

$$\begin{aligned}\mathbf{x}_1 + \mathbf{x}_2 &= \mathbf{x}_2 + \mathbf{x}_1 \\ c(\mathbf{x}_1 + \mathbf{x}_2) &= c \mathbf{x}_1 + c \mathbf{x}_2\end{aligned}$$

**Note 2:** A vector space is also called a linear space.

**Note 3:** Of course,  $\mathbb{R}^N$  is a vector space.

**Note 4:** The concept of a vector space is, however, much wider than that. For instance, the set of all mappings from  $\mathbb{R}^1$  to  $\mathbb{R}^1$  with conventional addition is a vector space.



We need to know what a linear mapping is:

**Definition:** A mapping,  $M$ , is linear iff

$$\begin{aligned}M(a_1 + a_2) &= M(a_1) + M(a_2) \\ M(c a) &= c M(a) \quad c \in \mathbb{R}^1 (\mathbb{C}^1)\end{aligned}$$

**Note 5:** Linear mappings obey the *superposition principle*, which is expressed in this definition.

**Exercise 1:** Given the mapping from  $x \in \mathbb{R}^1$  to  $y \in \mathbb{R}^1$

$$y = kx + \ell,$$

where the 'parameters'  $k, \ell \in \mathbb{R}^1$ , which values of  $k$  and  $\ell$  make the mapping linear?

**Note 6:** An  $M$  by  $N$  matrix  $A$  represents a linear mapping from  $\mathbb{R}^N$  to  $\mathbb{R}^M$ :

$$\mathbf{y} = A \mathbf{x}, \quad \mathbf{x} \in \mathbb{R}^N, \quad \mathbf{y} \in \mathbb{R}^M$$

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We will now define linear independence and the concept of a basis for a vector space.

The vectors  $\mathbf{v}_1, \dots, \mathbf{v}_K$  are linearly independent iff

$$\sum_{k=1}^K c_k \mathbf{v}_k = 0 \implies c_k = 0 \forall k$$

**Note 7:** Manipulate the equation above:

$$0 = \sum_{k=1}^K c_k \mathbf{v}_k = [\mathbf{v}_1 \dots \mathbf{v}_K] \begin{bmatrix} c_1 \\ \vdots \\ c_K \end{bmatrix} = V \mathbf{c}$$

An equivalent statement to make is thus:

The column vectors of the matrix  $V$  are linearly independent iff

$$V \mathbf{c} = 0 \implies \mathbf{c} = 0$$

**Note 8:** In  $\mathbb{R}^N$ , at most  $N$  vectors can be linearly independent. We abstain from proving this.

Now let us study vectors that span a vector space and define the concept of a basis for the space.

The  $N$ -dimensional vectors  $\mathbf{v}_1, \dots, \mathbf{v}_K$  span  $\mathbb{R}^N$  iff for every  $\mathbf{x} \in \mathbb{R}^N$  you can find a set of coefficients  $c_k$  so that

$$\mathbf{x} = \sum_{k=1}^K c_k \mathbf{v}_k$$

**Note 9:** The vectors  $\{\mathbf{v}_k\}$  span the space if you can reach any point in the space by means of some linear combination.

**Note 10:** The above can be written

$$\mathbf{x} = V \mathbf{c}, \quad V = [\mathbf{v}_1, \dots, \mathbf{v}_K], \quad \mathbf{c}^T = [c_1, \dots, c_K]$$

**Note 11:** It is required that  $K \geq N$

Vectors  $\{\mathbf{v}_k\}$  that

- span  $\mathbb{R}^N$
- are linearly independent

are said to form a basis for  $\mathbb{R}^N$ .

**Note 12:** A basis is never unique. Consider, for instance,

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  on one hand, and

$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  on the other. Both sets of vectors are linearly independent and span the plane.

**Note 13:** The concept of dimension of a space originates *not* from the length of the vectors but from the number of vectors in a basis for the space.

**Example:** The vectors

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{and} \quad \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

span a plane in  $\mathbb{R}^3$ . The plane has dimension 2.

An orthogonal basis is a basis where all vectors are mutually orthogonal.

An orthonormal basis is an orthogonal basis where all vectors have unit length.

If  $N$  linearly independent vectors span a space, then any other set of vectors that are linearly independent and span the same space must have  $N$  members. This is the fundamental property embodied in the concept of dimension.

Please run the m-file bases2D in Matlab.

```

% bases2D.m
% run this program several times, random data.
clear

% get two random vectors
v1=3*rand(2,1);
v2=3*rand(2,1);

% Make them orthogonal
v2o=v2-v1'*v2*v1/(v1'*v1);

% Make them orthonormal
v1on=v1/norm(v1);
v2on=v2o/norm(v2o);

% Get suitable scaling for plots
k=max([norm(v1) norm(v2) norm(v2o) 1]);
ax=[-k k -k k];

% Plot the stuff
figure(1), clf, axis(ax), axis equal, hold on
plot([0 v1(1)], [0 v1(2)], 'r', [0 v2(1)], [0 v2(2)], 'g')
plot(v1(1), v1(2), 'rp', v2(1), v2(2), 'gp')
title( 'Two random vectors - a basis for the plane')

figure(2), clf, axis(ax), axis equal, hold on
plot([0 v1(1)], [0 v1(2)], 'r', [0 v2o(1)], [0 v2o(2)], 'g')
plot(v1(1), v1(2), 'rp', v2o(1), v2o(2), 'gp')
title( 'The vectors made orthogonal - an orthogonal basis')

figure(3), clf, axis(ax), axis equal, hold on
plot([0 v1on(1)], [0 v1on(2)], 'r', [0 v2on(1)], [0 v2on(2)], 'g')
plot(v1on(1), v1on(2), 'rp', v2on(1), v2on(2), 'gp')
title(' The vectors made orthonormal - an orthonormal basis')

```