

Representations of $\mathfrak{sl}(2, \mathbb{C})$

Let us consider the standard generators X, Y, H of $\mathfrak{sl}(2, \mathbb{C})$ satisfying the commutator relationships

$$[H, X] = 2X, \quad [H, Y] = -2Y, \quad [X, Y] = H$$

Now let V be a finite-dimensional irreducible representation. Under the action of H we can split up V into eigenspaces $V = \bigoplus_{\alpha} V_{\alpha}$ with a finite number of eigenvalues α .

The first basic fact we want to establish is that X and Y permute these eigenspaces, which follows from two simple calculations.

So let $v \in V_{\alpha}$

$$\begin{aligned} HXv &= XHv + [H, X]v = \alpha Xv + 2Xv = (\alpha + 2)Xv \\ HYv &= YHv + [H, Y]v = \alpha Yv - 2Yv = (\alpha - 2)Yv \end{aligned}$$

Thus X shifts "two steps" to the "right" $XV_{\alpha} \subset V_{\alpha+2}$ while Y shifts to the left $YV_{\alpha} \subset V_{\alpha-2}$

In particular XY and YX (none of which actually belong to $\mathfrak{sl}(2)$) operate on each of the eigenspaces V_{α} . The underlying idea is now to look at eigenvectors of these actions.

More specifically, consider $V_{\alpha} \neq 0$ such that $XV_{\alpha} = 0$. This is always possible for any non-trivial finite-dimensional V .

Pick a non-trivial element $v \in V_{\alpha}$. The contention is that it is automatically an eigenvector for XY (and trivially YX). In fact

$$XYv = YXv + [X, Y]v = HV = \alpha v$$

Hence its eigenvalue is α .

We would now like to look at the iterates v, Yv, Y^2v, \dots . They are all linearly independent as they belong to distinct eigenvalues. But they are also all eigenvectors for XY . In fact by induction we can assume that $XY(Y^k v) = \lambda(k)Y^k v$ with $\lambda(0) = \alpha$. Thus

$$\begin{aligned} XY(Y^{k+1}v) &= YX(Y^{k+1}v) + HY^{k+1}v = YXY(Y^k v) + (\alpha - 2(k+1))v = \\ &= (\lambda(k) + \alpha - 2(k+1))Y^{k+1} \end{aligned}$$

showing incidentally that $\lambda(k+1) = \lambda(k) + \alpha - 2(k+1)$. By induction we prove that $\lambda(k) = (k+1)\alpha - k(k+1)$. But the fact that $Y^k v$ are eigenvectors for XY means that X permutes, in fact shifts, the iterates $Y^k v$.

$$XY^{k+1}v = \lambda(k)Y^k v$$

. Thus the linear space spanned by those iterates is not only invariant under Y (by construction) and H (each iterate an eigenvector of H) but also under X . By irreducibility we conclude that they span the entire space V .

Finally the iterates can only be finite in number, there is an $N > 0$ such that $Y^{N+1}v = 0$ but $Y^N v \neq 0$. This means

$$0 = XY^{N+1}v = \lambda(N+1)Y^N v$$

thus $\lambda(N+1) = 0$ which translates into $\alpha = N$.

We have now elucidated the structure of the finite-dimensional irreducible representations of $\mathfrak{sl}(2)$. The pertinent facts are

- i) The only eigenvalues are integers, and they all differ by multiples of two.
- ii) All eigenvalues belong to 1-dimensional eigenspaces.

The top eigenvalue is N and $Y^k v$ correspond to $N - 2k$. In particular the lowest eigenvalue will be $-N$. Thus in particular we see that the eigenvalues are symmetrical with respect to the origin.

All irreducible representations corresponding to a given N are isomorphic, and by using the basis $e_i = Y^k v$ with $i = (N - 2k)$ we can describe the representation as follows

$$\begin{aligned} He_i &= ie_i \\ Ye_i &= e_{i-2} \\ Xe_i &= \frac{(N+1)^2 - (i+1)^2}{4} e_{i+2} \end{aligned}$$

for a set of vectors $e_{-N}, e_{-N+2}, \dots, e_{N-2}, e_N$ with an obvious convention for indices going out of bound. Note that such a representation is $N+1$ dimensional

It is also straightforward to check that this does indeed give a representation of $\mathfrak{sl}(2)$ by checking the commutator relations.

So let us look at the cases for small N .

$N = 0$ This is the trivial one dimensional representation

$N = 1$ This is the canonical, or standard, representation of $\mathfrak{sl}(2)$ on \mathbb{C}^2 as a Lie subalgebra of $\mathfrak{gl}(2, \mathbb{C})$. The matrix representation for H, X and Y becomes the standard.

$N = 2$ This is the adjoint representation of $\mathfrak{sl}(2)$ on itself. The irreducibility of it shows that $\mathfrak{sl}(2)$ is simple. The eigenspaces of H corresponding to $-2, 0, 2$ are of course spanned by Y, H and X .

Now any (finite-dimensional) representation of $\mathfrak{sl}(2)$ is a sum of irreducible. From this we can conclude some general facts.

So let V be a representation and let $w(\alpha) = \dim V_\alpha$. Then the weight function w takes non-zero values only on the integers, and is zero for almost all.

Furthermore

A) $w(\alpha) = w(-\alpha)$

B) V has a unique decomposition $V = V_+ \oplus V_-$ such that the corresponding weight functions w_- and w_+ vanish on even and odd integers respectively. For those weight functions we have uni-modularity i.e $w(\alpha) \geq w(\beta)$ if $|\alpha| \leq |\beta|$.

We also note that we can recover the representation from the weight function, thus it determines the representation uniquely. Furthermore any function satisfying A) and B) can occur as a weight-function.

The symmetry condition A) shows that the dual V^* of a $\mathfrak{sl}(2)$ representation is isomorphic to V . Another way of putting this is to say that there is a $\mathfrak{sl}(2)$ invariant linear map $q : V \rightarrow V^*$ which gives rise to a $\mathfrak{sl}(2)$ invariant non-degenerate bilinear form Q via $Q(x, y) := q(x)(y)$. Conversely given such a bilinear form, we can get an invariant map $q : V \rightarrow V^*$ by reversing the equality $q(x)(y) := Q(x, y)$. We have hence showed that the space $V \times V$ contains trivial summands (intersecting the open subset non-degenerate forms).

In general we would like to compute the weight function for representations. So let us consider some standard examples.

$V \otimes W$. Writing $V = \oplus V_\alpha$ and $W = \oplus W_\beta$ we get a decomposition $V \otimes W = \oplus V_\alpha \otimes W_\beta$. If $v \otimes w \in V_\alpha \otimes W_\beta$ then $H(v \otimes w) = Hv \otimes w + v \otimes Hw = (\alpha + \beta)v \otimes w$. Hence $V_\alpha \otimes W_\beta$ corresponds to eigenvectors with eigenvalue $\alpha + \beta$.

As we have $\dim V = \sum_\alpha \dim V_\alpha$ and $\dim W = \sum_\beta \dim W_\beta$ we get

$$\dim V \otimes W = \sum_{\alpha, \beta} \dim V_\alpha \dim W_\beta = \sum_{\alpha, \beta} \dim V_\alpha \otimes W_\beta$$

exhausting the tensor product.

Hence we can write down the weightfunction $w_{V \otimes W}$ in terms of the weightfunctions w_V and w_W . In fact we get

$$w_{V \otimes W}(\gamma) = \sum_{\alpha + \beta} w_V(\alpha) w_W(\beta)$$

thus in fact it is given by the convolution of w_V and w_W .

In particular this applies to $\text{Hom}(V, W) = V^* \otimes W = V \otimes W$. We can also look at $V = W$ and the symmetric and alternating part.

Clearly

$$w_{S^2(V)}(\gamma) = \sum_{\alpha \leq \beta} w_V(\alpha) w_V(\beta)$$

$$w_{\bigwedge^2(V)}(\gamma) = \sum_{\alpha < \beta} w_V(\alpha) w_V(\beta)$$

More generally we can write down the corresponding formulas for $S^n(V)$ and $\bigwedge^n(V)$.

If V is the standard 2-dimensional representation of $\mathfrak{sl}(2)$ given by $x \in V_1$ and $y \in V_{-1}$ we can consider $S^n(V)$ the vectorspace of all binary forms of degree n .

By the product rule we easily see that $Hx^n = nx^n$ and $Hy^n = -ny^n$ and more generally $Hx^k y^{n-k} = (n - 2k)x^k y^{n-k}$. Thus we recognise this as the unique irreducible module of dimension $n + 1$. Thus from now on we will have a standard notation for them.

Thus a general problem (an equivalent reformulation of the weightfunction) is to decompose any representation into sums of the $S^n(V)$. So let us do this for a few examples.

So let V be the standard representation with $w(1) = w(-1) = 1$. Then the weight function of $V \times V$ will satisfy $w(-2) = w(2) = 1, w(0) = 2$ hence we have the decomposition

$$\text{Hom}(V, V) = V \times V = S^2(V) \oplus \mathbb{C}$$

Where the last summand is the trivial representation, which is actually isomorphic with $\bigwedge^2(V)$.

Now we have in general a map $\text{Hom}(V, V) \rightarrow \mathbb{C}$ given by the Trace. This is actually not only linear but \mathfrak{g} linear for any liealgebra \mathfrak{g} operating on V provided \mathbb{C} is given the trivial structure. To see this in general we make use of the identity $V^* \times V = \text{Hom}(V, V)$ for which each decomposable element $v^* \otimes v$ is mapped onto the map $x \mapsto v^*(x)v$. The trace of this map is easily computed to be equal to $v^*(v)$.

We have by definition

$$g(v^* \otimes v) = (gv^* \otimes v + v^* \otimes gv)$$

Thus evaluating trace gives

$$\text{Tr}(g(v^* \otimes v)) = (gv^*(v) + v^*(gv) = v^*(-gv) + v^*(gv) = 0$$

The kernel of the trace map is hence a submodule which hence should be identified with $S^2(V)$ the traceless matrices.

We also see that $\bigwedge^2(V)$ is trivial, thus the alternating bilinear forms (unique up to a scalar) on V are $\mathfrak{sl}(2)$ invariant, and it must be those that effect the isomorphism between V and V^* as we see that $S^2(V)$ is irreducible and hence do not contain any invariant elements.

We can now in general decompose

$$S^n(V) \otimes S^m(V) = \bigoplus_{\alpha=0}^m S^{n+m-2\alpha}(V)$$

One of the projections $S^n(V) \otimes S^m(V) \rightarrow S^{n+m}(V)$ can be given a natural interpretation as the multiplication of binary forms. The other projections are a little bit more subtle.

Let V be the standard 2-dimensional representation of $\mathfrak{sl}(2, \mathbb{C})$. To this there will be a corresponding representation of the Lie-group $SL(2, \mathbb{C})$ in the obvious way. Both representations induce actions on $P(V) = \mathbb{C}P^1$ which in the latter case coincides with the standard representation of the group of Moebius transformations $PSL(2, \mathbb{C})$ on the Riemannsphere $\mathbb{C}P^1$.

To each Moebius transformation A is associated two fixed points, those are given by the eigenvectors to the corresponding action on V . In the same way to each element $a \in \mathfrak{sl}(2)$ there are two corresponding eigenvectors, which corresponds to the fixed points on the Riemann sphere.

Conversely given any two fixed points, there is a 1- parameter subgroups fixing them. It is given by the exponentiation of the line of elements $ta \in \mathfrak{sl}(2)$ with the given eigenspaces.

There are two types of elements. Either the fixedpoints are distinct, or they coincide. The first type corresponds to semi- simple elements the second to nilpotent elements.

In the action of $\mathfrak{sl}(2)$ on V all elements v are equivalent. Each v determines either a 2-dimensional subgroup of $PSL(2, \mathbb{C})$ or a 2-dimensional subalgebra of $\mathfrak{sl}(2)$ given by the projective stabilisator $Sv = \{a : av = \lambda v\}$. (The stabilisator of the action on $P(V)$) It contains a distinguished element (up to a multiplicative scalar) - the uni-(nil)potent element (corresponding to $\lambda = 1, (0)$). Any two Sv_1 and Sv_2 have

a non-empty intersection, the 1-parameter subgroup generated by the fixed points v_1, v_2 .

The un-ordered pairs of points on $\mathbb{C}P^1 = P(V)$ are parametrised by a $\mathbb{C}P^2$, more precisely by $P(S^2(V))$, the linear system of binary quadrics, via its zeroes. This $\mathbb{C}P^2$ comes equipped with a canonically given conic, corresponding to the nilpotent elements.

This projective plane can also be thought of as parametrising all 1-parameter subgroups of $PSL(2, \mathbb{C})$ or equivalently, all vector fields, up to multiplication with a scalar. Thus the lifting to $\mathfrak{sl}(2)$ gives a parametrisation of all complex vector fields on the Riemann-sphere.

Clearly the lie-algebra structure on $S^2(V)$ is the one given by the identification of this space with $\mathfrak{sl}(2)$. It can be useful to explain this in detail.

Recall that we have a map $\pi : V \otimes V \rightarrow \bigwedge^2(V) \equiv \mathbb{C}$ given by $x \otimes y \mapsto x \wedge y$. The kernel of this map is obviously given by $S^2(V)$. Now recall that the wedge product on V determines a $\mathfrak{sl}(2)$ invariant bilinear form on V which effects the isomorphism with V with its dual V^* . Hence we can write down an identification of $V \otimes V$ with $\text{Hom}(V, V)$ via $v \otimes w \mapsto (x \mapsto (v \wedge x)w)$. The trace of this mapping is clearly $v \wedge w$ which actually identifies π with the Trace.

A basis for $S^2(V)$ is given by $x^2 = x \otimes x, xy = \frac{1}{2}(x \otimes y + y \otimes x), y^2 = y \otimes y$ given a basis x, y for V . It is natural to chose the latter basis as self-dual (i.e. letting $x \wedge y = 1$). Via the identification of $V \times V$ with $\text{Hom}(V, V)$ we will get matrix representations for the elements x^2, xy, y^2 as follows

$$\begin{aligned} x \otimes x &\mapsto \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \\ x \otimes y &\mapsto \begin{pmatrix} -\frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix} \\ y \otimes y &\mapsto \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix} \end{aligned}$$

Thus to each binary form $ax^2 + bxy + cy^2$ we associate the element $\begin{pmatrix} -\frac{b}{2} & a \\ -c & \frac{b}{2} \end{pmatrix}$.

Notice that the discriminant $4ac - b^2$ corresponds to the determinant (up to a trivial factor 4) of the matrix.

By this transportation of structure we get the liealgebra structure on $S^2(V)$. Set $X = x^2, Y = y^2$ and $Z = xy$ and we get $[Z, X] = -X, [Z, Y] = Y, [X, Y] = 2Z$.

The adjoint action of $\mathfrak{sl}(2)$ on $S^2(V)$ has more structure. As we noted there is a distinguished conic D (the discriminant conic of nilpotent elements). Given any semi-simple element H its polar with respect to D will intersect the conic in two points X, Y corresponding to the eigenvectors of the adjoint map $ad(H)$. Conversely given any line L in $P(S^2(V))$ it is in general not a subalgebra, in fact $[L, L]$ will correspond to the polar of the line. Thus the subalgebras will correspond exactly to the lines tangent to the distinguished conic D . We hence get a geometric picture of all the subalgebras of $\mathfrak{sl}(2)$. The 1-dimensional ones will correspond to the points, and the 2-dimensional to the tangents to D .

As a vectorspace $S^2(V)$ is clearly not homogenous with respect to the action. Given an element $v \in \mathfrak{sl}(2)$ its stabiliser Sv will depend on what type of element v is. If v is semi-simple (i.e $v \notin D$) then S_v is simply the subalgebra spanned by

v (i.e. the point v itself considered projectively). But if $v \in D$ then Sv coincides with the tangent line.

As the reader already must have suspected the conic D is \mathfrak{sl} invariant. (In fact it is given by the Killing form on $\mathfrak{sl}(2)$) $S^2(V)$ is irreducible, but the space $S^2(S^2(V))$ is not. In fact given

$$S^2V \otimes S^2(V) = S^4(V) \oplus S^2(V) \oplus S^0(V)$$

we can identify

$$\begin{aligned} S^2(S^2(V) \otimes S^2(V)) &= S^4(V) \oplus S^0(V) \\ \bigwedge^2(S^2(V)) &= S^2(V) \end{aligned}$$

Clearly $S^0(V) = \mathbb{C}$ is identified with the space spanned by the invariant conic D . Note that the isomorphism between $S^2(V)$ and its dual $S^2(V^*)$ is now effected by D which is symmetric.

Thus the projection $S^2(V) \otimes S^2(V) \rightarrow \mathbb{C}$ is given by evaluation of the quadratic form D . Conversely given any other quadratic form Q complementary to D we can evaluate Q by plugging in x^2, y^2 and xy appropriately and get a binary quartic, an element of $S^4(V)$. Finally the projection map $S^2(V) \otimes S^2(V) \rightarrow \bigwedge^2(S^2(V)) \equiv S^2(V)$ recaptures the adjoint representation.

Exercises

1 Given a $\mathfrak{sl}(2)$ representation W with weightfunction w . Show that the dimension of the trivial subrepresentation is given by

$$w(0)^2 - w(1)^2 + 2 \sum_{\alpha > 0} w(\alpha)^2 - w(1 + \alpha)w(1 - \alpha)$$

and check that this expression is always non-negative. Give conditions when it is zero.

2 Let V be the standard representation of $\mathfrak{sl}(2)$. Decompose the following modules into irreducible components

- i) $S^2(V) \otimes S^2(V) \otimes S^2(V)$
- ii) $S^3(S^2(V))$
- iii) $S^2(S^3(V))$
- iv) $S^3(S^3(V))$

3 With V as in the previous exercise. Given the decomposition

$$S^2(V) \otimes V = S^3(V) \oplus V$$

Show that the projection $S^2(V) \otimes V \rightarrow V$ gives the standard representation of $\mathfrak{sl}(2)$ on V .

In the same vein given

$$S^2(V) \otimes S^2(V) = S^4(V) \oplus S^2(V) \oplus \mathbb{C}$$

Interpret the projections

$$S^2(V) \otimes S^2(V) \rightarrow S^2(V) \text{ and } S^2(V) \otimes S^2(V) \rightarrow \mathbb{C}$$