Department of Mathematical Sciences, Chalmers & University of Gothenburg

MMA421, TMA014 Ordinary differential equations and dynamical systems

2012-03-08 kl. 8.30-12.30

You may not bring any notes, books or any other aids, not even a calculator! To pass the exam (*i.e.* to obtain the grade "G" for (MMA421, GU), or grade "3" (TMA014, Chalmers)), you need 15 points. The final grade on the course depends also on the computer assignments. **Telephone:** Dawan Mustafa, tel. 0703-088304

- 1. Let C be a closed subset of a Banach space X, and let $K : C \to C$ be a contraction. Explain what is meant by the word *contraction*, and state and prove the *contraction mapping principle*.
- (5p)

(5p)

- 2. State the definition of a Liapunov function. Let $L = U \to \mathbb{R}$ be a Liapunov function for the fixed point $x_0 \in U$, and let S_{δ} be the connected component of the set $\{x \in U \text{ such that } L(x) \leq \delta\}$. Let $B_{\varepsilon}(x_0) = \{x \text{ such that } |x - x_0| < \varepsilon\}$ be the open ball of radius ε around x_0 . Prove that for every $\varepsilon > 0$, there is $\delta > 0$ such that $S_{\delta} \subset B_{\varepsilon}(x_0)$.
- 3. Use Liapunov's method for proving that the origin is asymptotically stable for the following system of ode's:

$$\dot{x} = (x - y)(x^2 + y^2 - 1) \dot{y} = (x + y)(x^2 + y^2 - 1)$$

Be careful to show that your Liapunov function satisfies all requirements of a Liapunov function. There may be other methods for proving stability, but the one that I ask for is Liapunov's method. (5p)

4. Sketch the phase portrait of the system

$$\begin{aligned} \dot{x} &= x(2-y) \\ \dot{y} &= 2x^2 - y \end{aligned} \tag{5p}$$

- 5. Consider the linear system $\dot{x} = Ax$, where $x(t) \in \mathbb{R}^3$ and A is a real 3×3 -marix. Determine the flow generated by this differential equation, and determine all possible ω_+ limiting sets (depending on the matrix A and initial points x(0)). (5p)
- 6. Find a local change of coordinates that "straightens out" the vector field

$$F = \begin{pmatrix} F_1(x,y) \\ F_2(x,y) \end{pmatrix} = \begin{pmatrix} x+y^2 \\ -y \end{pmatrix}$$

near the point (0, 1), *i.e.* a transformation such that in the new coordinates, the vector field is given by $\tilde{F} = (0, 1)$.

(Hint: begin by computing the flow of the ode for the original vector field; doing this correctly gives 2 points).

Is it possible to find a global change of coordinates with this property?

(5p)

Good luck! Bernt W.