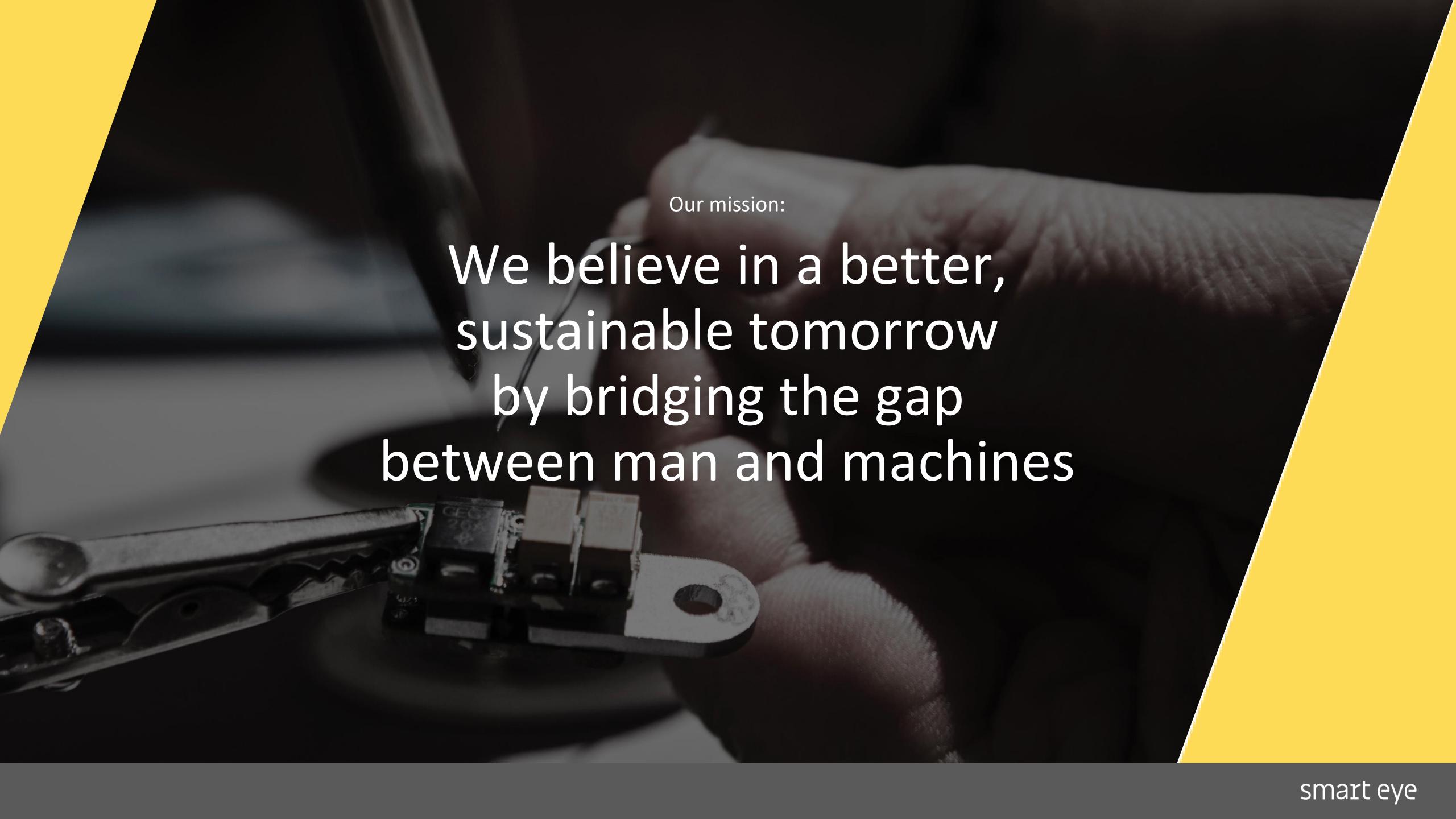


#### Real Time Eye Tracking

My Dagen 2017

Erik Svensson

# It began with a dream that made us see further



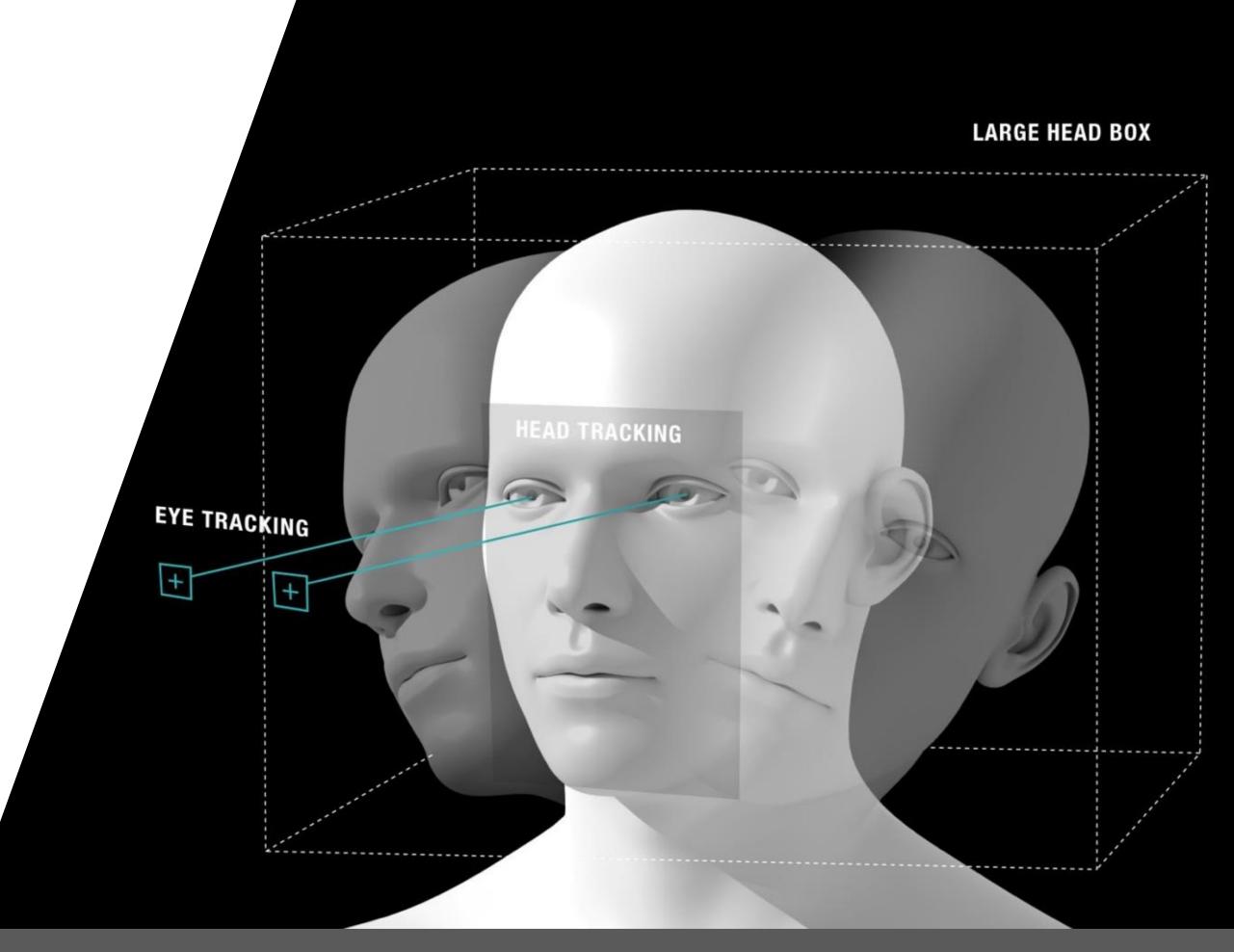


# Smart Eye AB - The Company -

- Founded in 1999
  - -Focus originally to replace mouse, soon abandoned
  - -PC performance good enough for real time tracking
- ~70 employees
- Most are MSc / PhD
- Office in Göteborg
- Market leader
- Non-intrusive Head- and Gaze Tracking
  - -Vehicles
  - -Real-life situations

#### Eye Tracking - What is it?

- Gaze Direction
- Head Pose, 3+3 DOE
- Eyelid Opening
- Pupil Diameter
- Extras
- Identity
  - -Feelings (Happy/Angry/Surprised/Sad/...)
  - -Agitation/stress level
  - -Mouth movements (Talking/Yawning/...)



## Eye Tracking - Why?

- Driver/Pilot Behavior
- Usability Studies / HMI Evaluation
- Marketing
- Web pages, Magazines, Ads, Packages
- Cognition Research
- Training
- Active Safety in Vehicles
- Drowsiness, an early warning
- Inattention



#### Products

- Smart Eye Pro
  - -2-8 cameras, research grade, semi automatic
- DR120
  - -2 cameras integrated into a computer monitor
- AntiSleep
  - -Mono-camera, fully automatic
- Embedded
  - -Embedded version, HW cost << USD100
- Add-ons & integration
  - -Scene Camera, Time Synchronization, Remote Logging, Remote Control, EEG Integration, Interfaces to simulator engines & analysis software

## Philosophy

- No strings attached
- Must work in real situations
- All kinds of light
- Large head movements
- Glasses, sunglasses and contact lenses
- Flexible installation
- Small cameras
- Free placement





Market

Worldwide

Industry

-Volvo, Nissan, Ford, Daimler Chrysler, GM, Toyota, Audi, Saab, Mercedes, Subaru, VW, Airbus, SNCF, KEPRI

Universities and research institutes

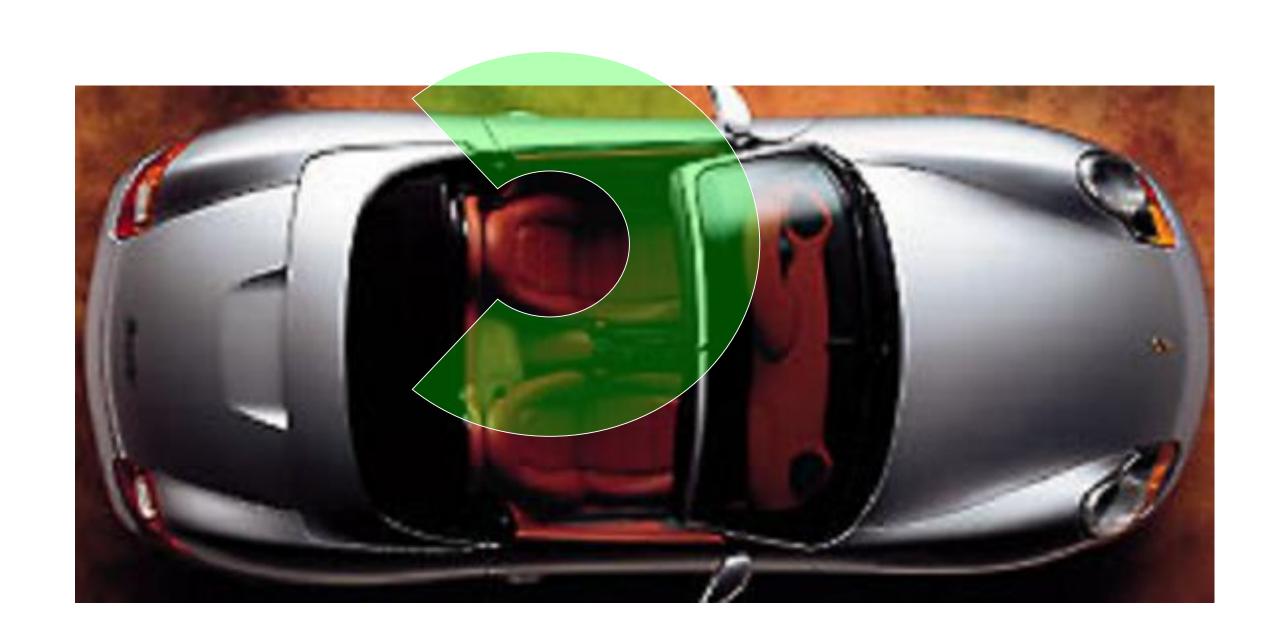
-NASA, US Army, Deutsche Luft und Raumfahrt,
Operator Performance Laboratories, Beckman Institute,
Flygsimulatorcentrum, VTI, Skogforsk,
Sahlgrenska University Hospital



#### Movie Time...

- •Web Page Layout
- Scene Camera Drive

# Sample installations



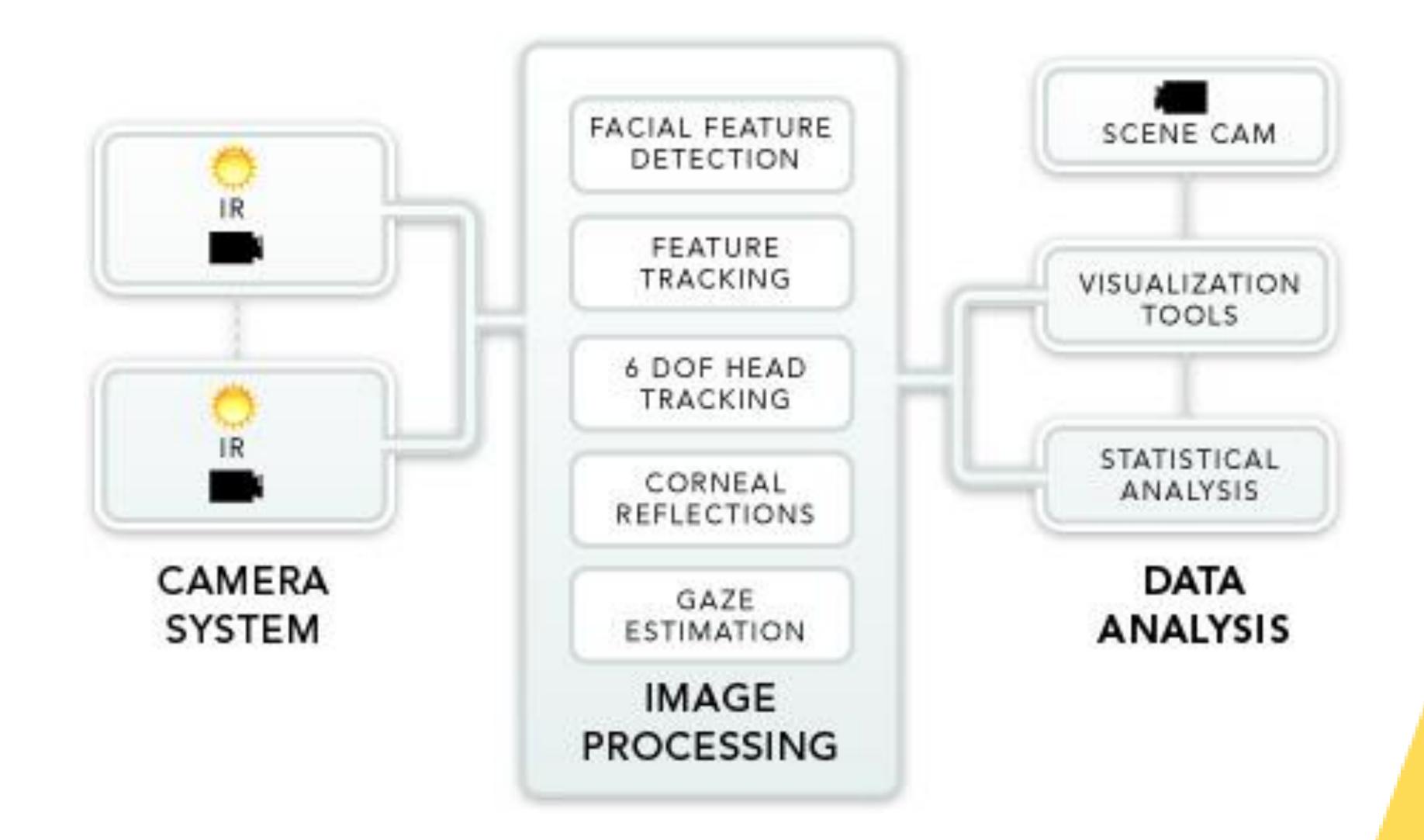








#### How does it work?



#### Challenges

- Environment
  - -No light, Direct sun, Quickly varying light, Vibration
- Facial Appearance
  - -Age, Gender, Beard, Hairstyle, Glasses, Make-up, Sunglasses, Wrinkles, Moles, Piercings/tattoos..
- Human Behavior
  - -Head rotations, Talking, Cellphone, Eating, Grooming, Gestures, Occlusions..
- Technical
   xGB/min, (soft) real time

#### Imaging Subsystem

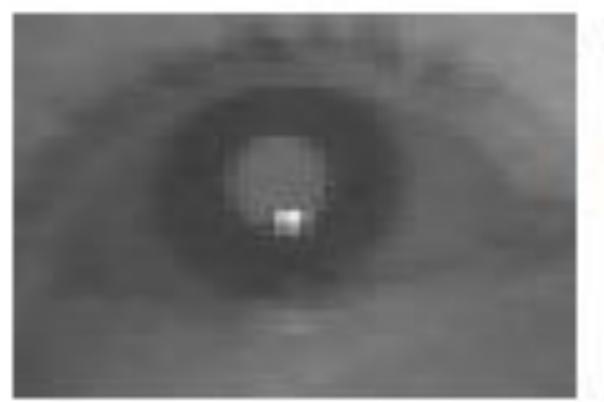
- Active lighting
- Near Infrared
- Suppress external light (especially sunlight)
- Reflex reduction mode
- Calibrated geometry
- Intrinsic (lens and image sensor)
- Extrinsic (camera placement)
- Synchronized cameras

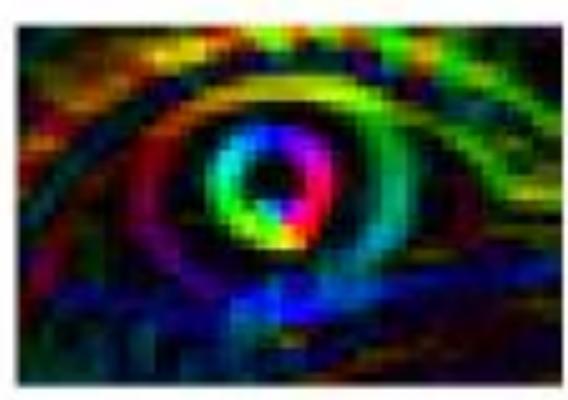
#### Head Tracking

- Tracking templates
- Corner-like features, Multiple views
- Predict search region using dynamics
- Contrast normalization, 2D sub-pixel correlation
- New features/views added while tracking
- Pose estimation
- Semi-rigid 3D head model
- Nonlinear optimization, Outlier removal
- Redundancy handles occlusions

#### Eye Tracking

- Find eyeball and eyelid state
- Locate
  - -Eye corners & eye center (geometry)
  - -Iris, pupil and eyelid edges (gradients; strength, direction)
  - -Specular reflections from illuminators (blobs; center, size)

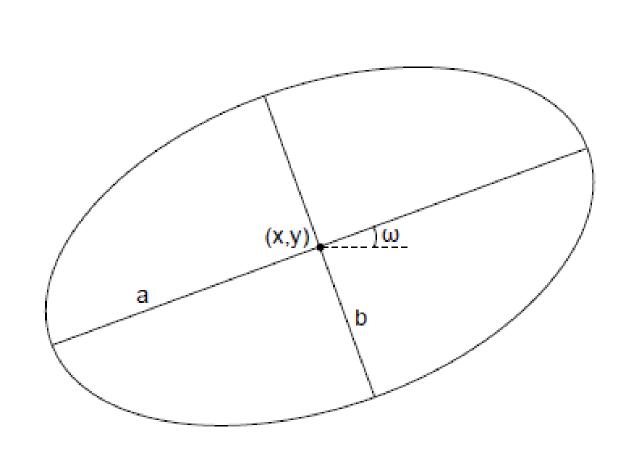


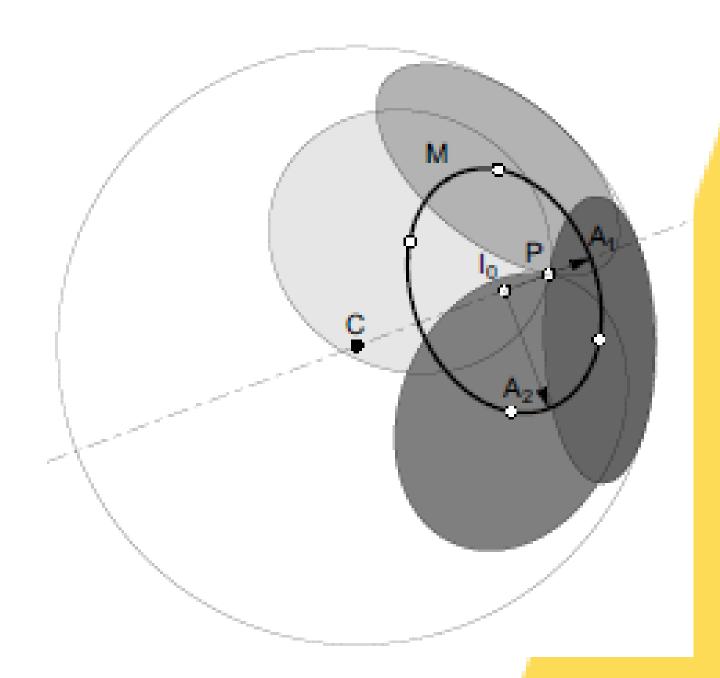


#### Iris/Pupil Tracking

a special Hough transform using geometrical constraints

- Ellipse search
- 5DOF in the general case, numerically expensive...
- We know all dimensions and where the eye center is located (3DOF), so there are only 2DOF left!







14 november 2016