

Minsta kvadratproblem:

normalekvationer

$$\min_x \|Ax - b\|_2^2$$

Normalekvationerna:

$$\underbrace{A^T A}_n \text{ matris} x = \underbrace{A^T b}_n \text{ vektor}$$

$$\underbrace{\left[\begin{array}{c} \vdots \\ A^T \\ \vdots \end{array} \right]}_n \cdot \underbrace{\left[\begin{array}{c} \vdots \\ A \\ \vdots \end{array} \right]}_m = \underbrace{\left[\begin{array}{c} \vdots \\ A^T A \\ \vdots \end{array} \right]}_n$$

$$A^T b = \underbrace{\left[\begin{array}{c} \vdots \\ A^T \\ \vdots \end{array} \right]}_n \cdot \underbrace{\left[\begin{array}{c} \vdots \\ b \\ \vdots \end{array} \right]}_m = \underbrace{\left[\begin{array}{c} \vdots \\ A^T b \\ \vdots \end{array} \right]}_n$$

$$\underbrace{\left[\begin{array}{c} \vdots \\ A^T A \\ \vdots \end{array} \right]}_n \cdot \underbrace{\left[\begin{array}{c} \vdots \\ x \\ \vdots \end{array} \right]}_n = \underbrace{\left[\begin{array}{c} \vdots \\ A^T b \\ \vdots \end{array} \right]}_n$$

$$x = \underbrace{(A^T A)^{-1} A^T}_A b = A^+ b$$

Konditionstal för minstakvadratproblem

Vi har 2 problem:

1) $\min_x \|Ax - b\|_2^2$ 2) $\min_y \|Ay - (b+f)\|_2^2$

Lösning:

1) $x = \underbrace{(A^T A)^{-1} A^T}_{A^+} b = A^+ b$ 2) $y = \underbrace{(A^T A)^{-1} A^T}_{A^+} (b+f)$

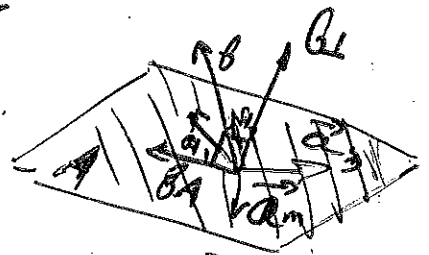
A^+ är pseudoinversen.

$A^+ = \text{pinv}(A)$

$= A^+ (b+f)$

$y - x = A^+ (b+f) - A^+ b = A^+ f$

(*) $\|y - x\|_2 \leq \|A^+\|_2 \cdot \|f\|_2$



Använder: $Ax = b_A$

$\vec{b} = b_A + b_{\perp}$

$e = Ax - b = Ax - (b_A + b_{\perp}) = -b_{\perp}$

(**) $\|b\|_2 \leq \|Ax\|_2 \leq \|A\|_2 \cdot \|x\|_2 \Rightarrow \frac{1}{\|x\|_2} \leq \frac{\|A\|_2}{\|b\|_2}$

Från (*) och (**):

$$\frac{\|y - x\|_2}{\|x\|_2} \leq \underbrace{\|A\|_2 \cdot \|A^+\|_2}_2 \cdot \frac{\|f\|_2}{\|b\|_2}$$

$\nearrow \quad \kappa_2(A) \quad \rightarrow$ konditionstalet för minstakvadratproblem

Kan skrivas som:

$$\frac{\|y - x\|_2}{\|x\|_2} \leq \kappa_2(A) \frac{\|b\|_2}{\|b\|_2} \cdot \frac{\|f\|_2}{\|b\|_2}$$

Practical error bounds

$$\min_x \|Ax - b\|_2^2$$

Lösung: $x = \underbrace{(A^T A)^{-1} A^T}_{A^+} b = A^+ b$

$$A \tilde{x} - b = r \rightarrow \text{residual}$$

$$A \tilde{x} = r + b$$

$$A^T A \tilde{x} = A^T (r + b)$$

$$\tilde{x} = \underbrace{(A^T A)^{-1} A^T}_{A^+} (r + b) = A^+ (r + b)$$

$$x - \tilde{x} = A^+ b - A^+ (r + b) = -A^+ r$$

$$\|x - \tilde{x}\|_2 \leq \|A^+\|_2 \|r\|_2$$

Mult. and divide by $\frac{\|A\|_2}{\|A\|_2}$

$$\frac{\|x - \tilde{x}\|_2}{\|x\|_2} \leq \underbrace{\|A\|_2 \cdot \|A^+\|_2}_{\kappa_2(A)} \cdot \frac{\|r\|_2}{\|b\|_2} = \kappa_2(A) \frac{\|r\|_2}{\|b\|_2}$$

relative error

$$\frac{\|x - \tilde{x}\|_2}{\|x\|_2} \leq \kappa_2(A) \frac{\|b\|_2}{\|b\|_2} \cdot \frac{\|r\|_2}{\|b\|_2}$$

Modellen: $b = e^{A - B/T + C/T^2}$

$\log b = A - \frac{B}{T} + \frac{C}{T^2}$

!!!
känner

Mult. till T^2 :

$T^2 \log b = A \cdot T^2 - B \cdot T + C$
 $= x_1 \cdot 1 - x_2 \cdot T + x_3 \cdot T^2$

els,
kan
räknas

$x_1 := C; x_2 := B; x_3 := A$

$$\begin{matrix} m \\ \left[\begin{array}{ccc} 1 & -T_1 & T_1^2 \\ \vdots & \vdots & \vdots \\ 1 & -T_m & T_m^2 \end{array} \right] \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} T_1^2 \log b \\ \vdots \\ T_m^2 \log b \end{bmatrix}
 \end{matrix}$$

m är antalet punkter var vi kan mäta T.

$\min \|Ax - b\|_2^2$, var $x = (x_1, x_2, x_3)$

$A = \begin{bmatrix} 1 & -T_1 & T_1^2 \\ \vdots & \vdots & \vdots \\ 1 & -T_m & T_m^2 \end{bmatrix}; x = \begin{bmatrix} C \\ B \\ A \end{bmatrix}$

$b = \begin{bmatrix} T_1^2 \log b_1 \\ \vdots \\ T_m^2 \log b_m \end{bmatrix}$

$$\log b = -A + B \log T + \frac{C}{T^2}$$

Mult. T^2 :

$$T^2 \cdot \log b = -A \cdot T^2 + B \cdot T^2 \log T + C$$

$$x_1 = A; \quad x_2 = B; \quad x_3 = C$$

$$T^2 \cdot \log b = -x_1 \cdot T^2 + x_2 \cdot T^2 \log T + x_3 \cdot 1$$

$$\begin{bmatrix} -T_1^2; & T_1^2 \log T_1; & 1 \\ \vdots & \vdots & \vdots \\ -T_m^2; & T_m^2 \log T_m; & 1 \end{bmatrix} \cdot x =$$

$$\begin{bmatrix} T_1^2 \log b_1 \\ \vdots \\ T_m^2 \log b_m \end{bmatrix} \quad \min_x \|Ax - b\|_2^2$$

$$T \log b = \underbrace{x_1}_{T_0} \log b + \underbrace{x_2}_{\log A} T + \underbrace{x_3}_{E}$$

$$\begin{bmatrix} \log b_1; T_1; 1 \\ \vdots \\ \log b_n; T_n; 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} T_1 \log b_1 \\ \vdots \\ T_n \log b_n \end{bmatrix}$$

$E = T \log b$

$\min \|Ax - b\|_2$

Model ekv. är: $A \cdot e^{\frac{E}{T-T_0}} = B$

$$\log A + \frac{E}{T-T_0} = \log B;$$

$$\log A (T-T_0) + E = (T-T_0) \log B = T \log B - T_0 \log B$$

$$\log A T_i - \log A T_0 + E + T_0 \log B = T \log B$$