Solutions to Chapter 10 and 11 Exercises

Problem 10.8

Let

$$s(t) = \sum_{k=-\infty}^{\infty} s_k \exp(j2\pi f_o t).$$

Then

$$\begin{split} s(t-T) &= \sum_{k=-\infty}^{\infty} s_k \exp(j2\pi f_o(t-T)) \\ R_{X,X}(\tau) &= E\left[\sum_k \sum_m s_k s_m^* \exp(j2\pi k f_o(t-T) \exp(-j2\pi m f_o(t+\tau-T))\right] \\ &= \sum_k \sum_m s_k s_m^* \exp(j2\pi (k-m) f_o t) \exp(-j2\pi m f_o \tau) \\ E[\exp(j2\pi (k-m) f_o T)] &= \frac{1}{t_o} \int_0^{t_o} \exp(j2\pi (k-m) f_o u) du \\ &= \begin{cases} 0 & k \neq m \\ 1 & k = m \end{cases} \\ R_{X,X}(\tau) &= \sum_{k=-\infty}^{\infty} |s_k|^2 \exp(-j2\pi k f_o \tau) \\ S_{X,X}(f) &= \sum_{k=-\infty}^{\infty} |s_k|^2 \delta(f-k f_o) \end{split}$$

Hence the process X(t)=s(t-T) has a line spectrum and height of each line is given by the magnitude squared of the Fourier series coefficients.

Problem 10.12

$$R_{X,X}(t_1, t_2) = E[\cos(\omega_c t_1 + B[n_1]\pi/2)\cos(\omega_c t_2 + B[n_2]\pi/2)],$$

where n_1 and n_2 are integers such that $n_1T \leq t_1 < (n_1+1)T$ and $n_2T \leq t_2 < (n_2+1)T/$. For t_1, t_2 such that $n_1 \neq n_2$,

$$R_{X,X}(t_1, t_2) = E[\cos(\omega_c t_1 + B[n_1]\pi/2)]E[\cos(\omega_c t_2 + B[n_2]\pi/2)] = 0,$$

while for t_1, t_2 such that $n_1 = n_2$,

$$R_{X,X}(t_1, t_2) = \frac{1}{2} \cos(\omega_c(t_2 - t_1)) + \frac{1}{2} E[\cos(\omega_c(t_2 + t_1) + \pi B[n_1])]$$

= $\frac{1}{2} \cos(\omega_c(t_2 - t_1)) - \frac{1}{2} \cos(\omega_c(t_2 + t_1))$

Since this autocorrelation depends on more than just $t_1 - t_2$, the process is not WSS.

(b) From part (a),

$$R_{X,X}(t,t+\tau) = \begin{cases} 0 & \text{if } t,t+\tau \text{ are in different intervals,} \\ \frac{1}{2}\cos(\omega_c\tau) - \frac{1}{2}\cos(\omega_c(2t+\tau)) & \text{if } t,t+\tau \text{ are in in the same intervals.} \end{cases}$$

Since the process is not WSS we must take time averages.

$$R_{X,X}(\tau) = \langle R_{X,X}(t,t+\tau) \rangle = (1-p(\tau))\langle 0 \rangle + p(\tau) \langle \frac{1}{2}\cos(\omega_c\tau) - \frac{1}{2}\cos(\omega_c(2t+\tau)) \rangle,$$

where $p(\tau)$ is the fraction of the values of t that lead to t and $t + \tau$ being in the same interval. This function is given by

$$p(\tau) = \begin{cases} 0 & |\tau| > T, \\ 1 - \frac{|\tau|}{T} & |\tau| < T. \end{cases}$$

Therefore,

$$p(\tau) = \operatorname{tri}(t/T)$$

$$R_{X,X}(\tau) = \frac{1}{2}\operatorname{tri}(\tau/T)\cos(\omega_c \tau)$$

$$S_{X,X}(f) = \frac{1}{2}FT[\operatorname{tri}(\tau/T)] * FT[\cos(\omega_c \tau)]$$

using Table E.1 in Appendix E in the text,

$$S_{X,X}(f) = \frac{1}{4}T\operatorname{sinc}^{2}(fT) * (\delta(f - f_{c}) + \delta(f + f_{c}))$$

= $\frac{T}{4}(\operatorname{sinc}^{2}((f - f_{c})T)) + \operatorname{sinc}^{2}((f + f_{c})T))$

Problem 10.14

- (a) The absolute BW is ∞ since S(f) > 0 for all $|f| < \infty$. (b) The 3dB BW, f_3 satisfies

$$\frac{1}{(1+(f_3/B)^2)^3} = \frac{1}{2}$$

$$\Rightarrow f_3 = B\sqrt{2^{1/3}-1} = 0.5098B.$$

(c)

$$\int_{-\infty}^{\infty} f^2 S(f) df = \int_{-\infty}^{\infty} \frac{f^2}{(1 + (f/B)^2)^3} df = B^3 \int_{-\infty}^{\infty} \frac{z^2}{(1 + z^2)^3} dz = \frac{\pi}{8} B^3$$
$$\int_{-\infty}^{\infty} S(f) df = \int_{-\infty}^{\infty} \frac{1}{(1 + (f/B)^2)^3} df = B \int_{-\infty}^{\infty} \frac{1}{(1 + z^2)^3} dz = \frac{3\pi}{8} B$$
$$B_{rms}^2 = \frac{\frac{\pi}{8} B^3}{\frac{3\pi}{8} B} = \frac{B^2}{3}$$
$$B_{rms} = \frac{B}{\sqrt{3}}.$$

Problem 10.19

(a)

$$E[\epsilon^{2}] = E[(Y[n+1] - a_{1}Y[n] - a_{2}Y[n-1])^{2}]$$

= $R_{Y,Y}[0](1 + a_{1}^{2} + a_{2}^{2}) - 2a_{1}(1 - a_{2})R_{Y,Y}[1] - 2a_{2}R_{Y,Y}[2]$

(b)

$$\begin{aligned} \frac{\partial E[\epsilon^2]}{\partial a_1} &= 2a_1 R_{Y,Y}[0] - 2(1 - a_2) R_{Y,Y}[1] = 0 \\ \Rightarrow & R_{Y,Y}[0]a_1 + R_{Y,Y}[1]a_2 = R_{Y,Y}[1] \\ \frac{\partial E[\epsilon^2]}{\partial a_2} &= 2a_2 R_{Y,Y}[0] - 2R_{Y,Y}[2] + 2a_1 R_{Y,Y}[1] = 0 \\ \Rightarrow & R_{Y,Y}[1]a_1 + R_{Y,Y}[0]a_2 = R_{Y,Y}[2] \\ \Rightarrow & \begin{bmatrix} R_{Y,Y}[0]R_{Y,Y}[1] \\ R_{Y,Y}[1] \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} R_{Y,Y}[1] \\ R_{Y,Y}[2] \end{bmatrix} \\ \Rightarrow \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} &= \frac{1}{R_{Y,Y}^2[0] - R_{Y,Y}^2[1]} \begin{bmatrix} R_{Y,Y}[0]R_{Y,Y}[1] - R_{Y,Y}[1]R_{Y,Y}[2] \\ R_{Y,Y}[0]R_{Y,Y}[1] \end{bmatrix} \end{aligned}$$

Problem 11.10

$$\begin{split} Y(t) &= a(S^2(t) + N^2(t) + 2S(t)N(t)) \\ E[Y(t)] &= aE[S^2(t)] + aE[N^2(t)] + 2aE[S(t)N(t)] \\ &= a(\sigma_S^2 + \sigma_N^2). \\ R_{Y,Y}(\tau) &= a^2E[(S^2(t) + N^2(t) + 2S(t)N(t)) \\ &\quad (S^2(t + \tau) + N^2(t + \tau) + 2S(t + \tau)N(t + \tau))] \\ &= a^2E[S^2(t)S^2(t + \tau)] + a^2E[N^2(t)N^2(t + \tau)] \\ &+ 4a^2E[S(t)S(t + \tau)N(t)N(t + \tau)] + a^2E[S^2(t)N^2(t + \tau)] \\ &+ 2a^2E[S^2(t)S(t + \tau)N(t + \tau)] + a^2E[N^2(t)S^2(t + \tau)N(t)] \\ &+ 2a^2E[S(t)N(t)N^2(t + \tau)] \\ &+ 2a^2E[S(t)N(t)N^2(t + \tau)] \\ &= a^2[R_{S,S}^2(0) + 2R_{S,S}^2(\tau) + R_{N,N}^2(0) + 2R_{N,N}^2(\tau) \\ &+ 4R_{S,S}(\tau)R_{N,N}(\tau) + R_{S,S}(0)R_{N,N}(0) + R_{N,N}(0)R_{S,S}(0)] \\ &= a^2[(R_{S,S}^2(0) + R_{N,N}(0))^2 + 2(R_{S,S}(\tau) + R_{N,N}(\tau))^2] \\ &= a^2[(\sigma_S^2 + \sigma_N^2)^2 + 2(R_{S,S}(\tau) + R_{N,N}(\tau))^2]. \end{split}$$

In above Calculation we used the following information:

For two Gaussian random process X(t) and Y(t):

$$E\left[X^{2}(t)Y^{2}(t+\tau)\right] = R_{XX}\left[0\right]R_{YY}\left[0\right] + 2R_{XY}^{2}\left[\tau\right]$$
 If X and Y are correlated
$$E\left[X(t)Y(t)Y(t+\tau)\right] = E\left[X(t)\right]E\left[Y(t)Y(t+\tau)\right]$$
 If X and Y are not correlated

Problem 11.11

For the given PSD's,

$$\begin{aligned} R_{S,S}(\tau) &= F^{-1}[S_{S,S}(f)] = \frac{A^2}{4} (e^{-j2\pi f_c \tau} + e^{j2\pi f_c \tau}) = \frac{A^2}{2} \cos(2\pi f_c \tau) \\ R_{N,N}(\tau) &= F^{-1}[S_{N,N}(f)] = \frac{N_o B}{2} \operatorname{sinc}(B\tau) (e^{-j2\pi f_c \tau} + e^{j2\pi f_c \tau}) \\ &= N_o B \operatorname{sinc}(B\tau) \cos(2\pi f_c \tau) \end{aligned}$$

From these we determine that

$$\sigma_S^2 = R_{S,S}(0) = \frac{A^2}{2},$$

 $\sigma_N^2 = R_{N,N}(0) = N_o B.$

The autocorrelation of $\boldsymbol{Y}(t)$ is then

$$\begin{aligned} R_{Y,Y}(\tau) &= a^2 [(\sigma_s^2 + \sigma_N^2)^2 + 2(R_{s,s}(\tau) + R_{N,N}(\tau))^2] \\ &= a^2 \left[\left(\frac{A^2}{2} + N_o B \right)^2 + 2 \left(\frac{A^2}{2} + N_o B \operatorname{sinc}(B\tau) \right)^2 \cos^2(2\pi f_c \tau) \right] \\ &= a^2 \left[\left(\frac{A^2}{2} + N_o B \right)^2 \\ &+ 2 \left(\frac{A^2}{4} + A^2 N_o B \operatorname{sinc}(B\tau) + (N_o B)^2 \operatorname{sinc}^2(B\tau) \right) (1 + \cos(4\pi f_c \tau)) \right] \end{aligned}$$

Taking FT's, the PSD of $\boldsymbol{Y}(t)$ is then

$$\begin{split} S_{Y,Y}(f) &= a^2 \bigg[\left(\frac{A^2}{2} + N_o B \right)^2 \delta(f) + 2 \left(\frac{A^2}{4} \delta(f) + A^2 N_o \text{rect}(f/B) + N_o^2 B \text{tri}(f/B) \right) \\ &\quad * \left(\delta(f) + \frac{1}{2} \delta(f - 2f_c) + \frac{1}{2} \delta(f + 2f_c) \right) \bigg] \\ &= a^2 \left(\frac{A^2}{2} + A^2 N_o B + (N_o B)^2 \right) \delta(f) + A^2 N_o \text{rect}(f/B) + N_o^2 B \text{tri}(f/B) \\ &\quad + \frac{A^2}{4} \left(\delta(f - 2f_c) + \delta(f + 2f_c) \right) + A^2 N_o \left(\text{rect} \left(\frac{f - 2f_c}{B} \right) + \text{rect} \left(\frac{f + 2f_c}{B} \right) \right) \\ &\quad + N_o^2 B \left(\text{tri} \left(\frac{f - 2f_c}{B} \right) + \text{tri} \left(\frac{f + 2f_c}{B} \right) \right). \end{split}$$

Problem 11.14

$$S_{Y,Y}(f) = S_{X,X}(f)|H(f)|^2 = \frac{a}{1 + (f/f_o)^2} \cdot b^2 \left[\operatorname{rect}\left(\frac{f - f_c}{f_2 - f_1}\right) + \operatorname{rect}\left(\frac{f + f_c}{f_2 - f_1}\right) \right],$$

where $f_c = (f_1 + f_2)/2$. Assuming $f_2 - f_1 \ll f_o$, the input PSD will be approximately constant over the passband of the filter. In that case, the output PSD will be well approximated by

$$S_{Y,Y}(f) \approx S_{X,X}(f_c)|H(f)|^2 = \frac{ab^2}{1 + (f_c/f_o)^2} \cdot \left[\operatorname{rect}\left(\frac{f - f_c}{f_2 - f_1}\right) + \operatorname{rect}\left(\frac{f + f_c}{f_2 - f_1}\right) \right]$$

$$\Rightarrow = \frac{2ab^2(f_2 - f_1)}{1 + (f_c/f_o)^2} \operatorname{sinc}((f_2 - f_1)\tau) \cos(\omega_c \tau).$$

Problem 11.26

 $h(t)=s(t_0-t)$. In this case, $s(t_0-t)=s(t)$ so the impulse response of the matched filter is the same as the signal itself.