

# MVE136 Random Signals Analysis

Written exam Monday 19 August 2013 2 – 6 pm

TEACHER AND JOUR: Patrik Albin, telephone 070 6945709.

AIDS: Beta or 2 sheets (4 pages) of hand-written notes (computer print-outs and/or xerox-copies are not allowed), but not both these aids.

GRADES: 12 (40%), 18 (60%) and 24 (80%) points for grade 3, 4 and 5, respectively.

GOOD LUCK!

**Task 1.** Let  $X$  and  $Y$  be zero-mean, unit variance Gaussian random variables with correlation coefficient  $\rho$ . Suppose we form two new random variables  $U$  and  $V$  using a linear transformation as

$$U = aX + bY \quad \text{and} \quad V = cX + dY,$$

where  $a, b, c$  and  $d$  are real (non-random) coefficients/constants. Find constraints on  $a, b, c$  and  $d$  such that  $U$  and  $V$  are independent. **(5 points)**

**Task 2.** Find the probability  $Pr(X(1) + X(2) > 3)$  for a Poisson process with rate 1. **(5 points)**

**Task 3.** Consider a discrete time Markov chain  $X(n)$  with state space  $E$  and transition probability matrix  $P$  given by

$$E = \{0, 1\} \quad \text{and} \quad P = \begin{bmatrix} 1/2 & 1/2 \\ 1/4 & 3/4 \end{bmatrix},$$

respectively. What initial distribution  $\pi(0)$  of the chain will give a distribution  $\pi(2)$  of the value of the chain  $X(2)$  at time  $n = 2$  given by  $\pi(2) = [1/3 \ 2/3]$ ? **(5 points)**

**Task 4.** The PSD  $S_{XX}(f)$  of a continuous time WSS process  $X(t)$  has the properties to be real and symmetric (=even). Prove one of these properties. **(5 points)**

**Task 5.** Give an example of a continuous time impulse response function  $h$  that has the property that when a continuous time white noise process  $N(t)$  with PSD  $S_{NN}(f) = N_0/2$  is input to an LTI system with this impulse response, then the output process  $Y(t)$  from the system has PSD  $S_{YY}(f)$  that is decreasing for  $f \geq 0$  and satisfies  $S_{YY}(f_0) = S_{YY}(0)/2 = N_0/4$  for a certain frequency  $f_0 > 0$ . (In other words the LTI system is a lowpass filter with 3dB bandwidth  $f_0$ .) **(5 points)**

**Task 6.** Suppose that we observe

$$x[n] = d[n] + w[n],$$

where both  $d[n]$  and  $w[n]$  are wide sense stationary signals and

$$E\{d[n-k]w[n]\} = 0 \quad \text{for all } k \text{ and } n.$$

Further assume that  $r_d[0] = 1$  and  $r_d[1] = 0.5$  whereas  $r_w[n] = \delta[n]$ .

Your task is to design a causal FIR-Wiener filter of length two:

$$\hat{d}[n] = h[0]x[n] + h[1]x[n-1].$$

Use the Wiener-Hopf equations to compute the optimal filter coefficients  $h[0]$  and  $h[1]$ , i.e., the coefficients that minimize the mean squared error  $E\{(d[n] - \hat{d}[n])^2\}$ . **(5**

**points)**

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### Solutions to written exam Monday 19 August 2013

**Task 1.** This is Exercise 5.29 in the 2004 edition of Miller and Childers's (=Exercise 5.30 in the 2012 edition). The solution is available at the URL

[www.math.chalmers.se/Stat/Grundutb/CTH/mve135/1011/Exercises/HomeExercise4.pdf](http://www.math.chalmers.se/Stat/Grundutb/CTH/mve135/1011/Exercises/HomeExercise4.pdf)

**Task 2.** As  $X(1) + X(2) = (X(2) - X(1)) + 2X(1)$  where  $X(2) - X(1)$  and  $X(1)$  are independent Po(1)-distributed we have  $Pr(X(1) + X(2) > 3) = Pr((X(2) - X(1)) + 2X(1) > 3) = Pr(X(1) \geq 2) + Pr(X(1) = 1, X(2) - X(1) > 1) + Pr(X(1) = 0, X(2) - X(1) > 3) = (1 - e^{-1} - e^{-1}) + e^{-1}(1 - e^{-1} - e^{-1}) + e^{-1}(1 - e^{-1} - e^{-1} - \frac{1}{2}e^{-1} - \frac{1}{6}e^{-1})$ .

**Task 3.** Writing  $\pi(0) = [p \ 1-p]$ , we have

$$[1/3 \ 2/3] = \pi(2) = \pi(0) P^2 = [p \ 1-p] \begin{bmatrix} 3/8 & 5/8 \\ 5/16 & 11/16 \end{bmatrix} = [\frac{5}{16} + \frac{p}{16} \ \frac{11}{16} - \frac{p}{16}] \Leftrightarrow p = \frac{1}{3}.$$

**Task 4.** As the autocorrelation function  $R_{XX}(\tau)$  is symmetric we have  $S_{XX}(-f) = \int_{-\infty}^{\infty} R_{XX}(\tau) e^{-j2\pi(-f)\tau} d\tau = \int_{-\infty}^{\infty} R_{XX}(\tau) e^{-j2\pi f(-\tau)} d\tau = \int_{-\infty}^{\infty} R_{XX}(-\hat{\tau}) e^{-j2\pi f\hat{\tau}} d\hat{\tau} = \int_{-\infty}^{\infty} R_{XX}(\hat{\tau}) e^{-j2\pi f\hat{\tau}} d\hat{\tau} = S_{XX}(f)$  and  $\overline{S_{XX}(f)} = \overline{\int_{-\infty}^{\infty} R_{XX}(\tau) e^{-j2\pi f\tau} d\tau} = \int_{-\infty}^{\infty} R_{XX}(\tau) e^{j2\pi f\tau} d\tau = [see above] = S_{XX}(f)$ .

**Task 5.** If we take  $h(t) = \exp(-t/t_0)u(t)/t_0$  then we have  $H(f) = F[h(t)] = 1/(1 + j2\pi f t_0)$ , so that  $S_{YY}(f) = |H(f)|^2 S_{NN}(f) = (N_0/2)/(1 + 4\pi^2 f^2 t_0^2)$  satisfies the imposed requirements when  $t_0 = 1/(2\pi f_0)$ .

**Task 6.** For completeness, this solution will contain a derivation of the Wiener-Hopf (WH) equations. Let us denote the estimation error as  $e[n] = d[n] - \hat{d}[n]$ . We know that the optimal filter is such that

$$E\{e[n]x[n-k]\} = 0 \quad \text{for } k = 0, 1.$$

We obtain the WH-equations by plugging in the expression for  $e[n]$  in the above equation:

$$E\{(d[n] - h[0]x[n] - h[1]x[n-1])x[n-k]\} = r_{dx}[k] - h[0]r_x[k] - h[1]r_x[k-1] = 0$$

for  $k = 0, 1$ . We can express these equations in matrix form as

$$\begin{bmatrix} r_x[0] & r_x[1] \\ r_x[1] & r_x[0] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} r_{dx}[0] \\ r_{dx}[1] \end{bmatrix}.$$

Here we have

$$r_{dx}[k] = \mathbf{E}\{d[n] x[n-k]\} = \mathbf{E}\{d[n] (d[n-k] + w[n-k])\} = r_d[k]$$

since  $d[n]$  and  $w[n-k]$  are uncorrelated. Similarly,

$$r_x[k] = \mathbf{E}\{(d[n] + w[n]) (d[n-k] + w[n-k])\} = r_d[k] + r_w[k].$$

Inserting this together with the information given in the problem into the matrix form of the WH-equation we arrive at

$$\begin{bmatrix} 2 & 0.5 \\ 0.5 & 2 \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix}$$

with solution

$$h[0] = \frac{1 - \frac{1}{8}}{2 - \frac{1}{8}} \approx 0.47 \quad \text{and} \quad h[1] = \frac{8}{60} \approx 0.13,$$

which is the final answer to the problem.