

## MVE136 Random Signals Analysis

Written exam Friday 27 October 2017 8.30–12.30

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AIDS: Beta or 2 sheets (=4 pages) of hand-written notes (computer print-outs and/or xerox-copies are not allowed), but not both these aids.

GRADES: 12 (40%), 18 (60%) and 24 (80%) points for grade 3, 4 and 5, respectively.

MOTIVATIONS: All answers/solutions must be motivated. GOOD LUCK!

**Task 1.** Calculate the mean function  $\mu_X(t)$  and the autocorrelation function  $R_{XX}(s, t)$  for the continuous time random process  $X(t)$ ,  $t \geq 0$ , given by  $X(t) = e^{-Ut}$ , where  $U$  is a random variable that is uniformly distributed over the interval  $[0, 1]$ . **(5 points)**

**Task 2.** Is it possible for a two state Markov chain not to have a stationary distribution? **(5 points)**

**Task 3.** Let  $W(t)$ ,  $t \geq 0$ , be a zero-mean continuous time Gaussian process with autocorrelation function  $R_{WW}(s, t) = \min(s, t)$ . Find the probability  $\Pr(\int_0^1 W(t) dt > 1)$ . **(5 points)**

**Task 4.** For a continuous time LTI system with WSS input and output  $X(t)$  and  $Y(t)$ , respectively, with PSD's  $S_{XX}(f)$  and  $S_{YY}(f)$ , respectively, and with transfer function  $H(f)$  it holds that  $S_{YY}(f) = |H(f)|^2 S_{XX}(f)$ . Prove this fact. **(5 points)**

**Task 5.** A continuous time communication system transmits a square pulse  $s(t) = 1$  for  $t \in [0, 1]$  and  $s(t) = 0$  for  $t \notin [0, 1]$  on a noisy channel so that the received signal is  $R(t) = s(t) + N(t)$  where  $N(t)$  is white noise. The received signal  $R(t)$  is processed through a matched filter with output  $Y(t)$  that produces the optimum SNR at time  $t = t_0$ . Find the impulse response  $h(t)$  of the matched filter as well as the value of  $Y(t_0)$ . **(5 points)**

**Task 6.** We have collected four measurements

$$x[0] = 0.3, \quad x[1] = -0.2, \quad x[2] = 0.1 \quad \text{and} \quad x[3] = -0.3,$$

of a discrete time WSS random process  $\{x[n]\}_{n=-\infty}^{\infty}$  and we wish to find a mathematical model for the measured process. We select to use a simple AR(1)-model  $x[n] + a_1 x[n-1] = e[n]$  for  $n \in \mathbb{Z}$ , where  $\{e[n]\}_{n=-\infty}^{\infty}$  is discrete time white noise: Your task is to estimate the parameter  $a_1$  and the white noise variance  $\sigma_e^2 = \mathbf{E}\{e[n]^2\}$ . **(5 points)**

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### Solutions to written exam 27 October 2017

**Task 1.**  $\mu_X(t) = E[X(t)] = E[e^{-Ut}] = \int_0^1 e^{-ut} du = \dots = (1 - e^{-t})/t$  for  $t > 0$  while (by inspection)  $\mu_X(0) = 1$  and similarly  $R_{XX}(s, t) = E[X(s)X(t)] = E[e^{-Us}e^{-Ut}] = \dots = (1 - e^{-(s+t)})/(s+t)$  for  $s+t > 0$  with  $R_{XX}(0, 0) = 1$ .

**Task 2.** A stationary distribution  $\pi$  exists if and only if we can solve

$$\begin{cases} [\pi_1 \ \pi_2] = [\pi_1 \ \pi_2] \begin{bmatrix} 1-p & p \\ q & 1-q \end{bmatrix} \\ \pi_1 + \pi_2 = 1 \end{cases} \Leftrightarrow \begin{cases} p\pi_1 = q\pi_2 \\ \pi_1 + \pi_2 = 1 \end{cases} \Leftrightarrow \begin{cases} \begin{cases} \pi_1 = q/(p+q) \\ \pi_2 = p/(p+q) \end{cases} & \text{if } p+q > 0 \\ \pi_1 + \pi_2 = 1 & \text{if } p+q = 0 \end{cases} .$$

As this always have at least one solution a stationary distribution always exists.

**Task 3.** As the random variable  $\int_0^1 W(t) dt$  is Gaussian (being a linear combination of Gaussian process values) with mean  $E[\int_0^1 W(t) dt] = \int_0^1 E[W(t)] dt = 0$  and variance  $\text{Var}(\int_0^1 W(t) dt) = \text{Cov}(\int_0^1 W(s) ds, \int_0^1 W(t) dt) = \int_0^1 \int_0^1 \text{Cov}(W(s), W(t)) ds dt = \int_0^1 \int_0^1 \min(s, t) ds dt = \dots = 1/3$  we have  $\Pr(\int_0^1 W(t) dt > 1) = \Pr(N(0, 1/3) > 1) = 1 - \Phi(\sqrt{3})$ .

**Task 4.** This is done in Section 11.1 of the book by Miller and Childers.

**Task 5.** According to Example 11.6 in the book by Miller and Childers we have  $h(t) = s(t_0 - t)$  and  $Y(t_0) = (h \star R)(t_0) = 1 + \int_0^1 N(u) du$ .

**Task 6.** As the autocorrelation function  $r_x[k]$  of the AR(1)-process satisfies the Yule-Walker equations

$$a_1 r_x[0] + r_x[1] = 0 \quad \text{and} \quad r_x[0] + a_1 r_x[1] = \sigma_e^2,$$

we obtain estimates  $\hat{a}_1$  and  $\hat{\sigma}_e^2$  of the parameters  $a_1$  and  $\sigma_e^2$  by solving the equations

$$\hat{a}_1 \hat{r}_x[0] + \hat{r}_x[1] = 0 \quad \text{and} \quad \hat{r}_x[0] + \hat{a}_1 \hat{r}_x[1] = \hat{\sigma}_e^2$$

giving

$$\hat{a}_1 = -\hat{r}_x[1]/\hat{r}_x[0] \quad \text{and} \quad \hat{\sigma}_e^2 = \hat{r}_x[0] - \hat{r}_x[1]^2/\hat{r}_x[0],$$

where

$$\hat{r}_x[0] = \frac{1}{4} \sum_{n=0}^3 x[n]^2 = \dots = 0.0575 \quad \text{and} \quad \hat{r}_x[1] = \frac{1}{4} \sum_{n=0}^2 x[n]x[n+1] = \dots = -0.0275.$$