

MVE136 Random Signals Analysis

Written exam Friday 1 November 8.30–12.30

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AIDS: Beta or 2 sheets (=4 pages) of hand-written notes (computer print-outs and/or xerox-copies are not allowed), but not both these aids.

GRADES: 12 (40%), 18 (60%) and 24 (80%) points for grade 3, 4 and 5, respectively.

MOTIVATIONS: All answers/solutions must be motivated. GOOD LUCK!

Task 1. Two jointly WSS jointly Gaussian continuous time random processes $X(t)$ and $Y(t)$, $t \in \mathbb{R}$, have common mean $\mu_X = \mu_Y = 0$, common autocorrelation function $R_{XX}(\tau) = R_{YY}(\tau) = e^{-|\tau|}$ and crosscorrelation function $R_{XY}(\tau) = \frac{1}{2} e^{-|\tau|}$ for $\tau \in \mathbb{R}$. Calculate $P(X(1)+Y(2) > 3)$. [HINT: For $X(t)$ and $Y(t)$ jointly Gaussian each linear combination $\sum_{i=1}^m a_i X(s_i) + \sum_{j=1}^n b_j Y(t_j)$ is normal distributed.] **(5 points)**

Task 2. Let $X(t)$, $t \geq 0$, be a Poisson process with arrival rate (intensity) 1. Calculate $P(X(1) \geq 1, X(2) \leq 2, X(3) \geq 1)$. **(5 points)**

Task 3. A Markov chain $X(n)$, $n = 0, 1, 2, \dots$, has states (possible values) 0 and 1 with starting distribution $\pi(0) = (1 \ 0)$ and transition matrix $P = \begin{pmatrix} 1/3 & 2/3 \\ 2/3 & 1/3 \end{pmatrix}$. Calculate $R_{XX}(2, 4) = E(X(2)X(4))$. **(5 points)**

Task 4. Find a WSS continuous time random process $X(t)$, $t \in \mathbb{R}$, that has autocorrelation function $R_{XX}(\tau) = 1$ for $\tau \in \mathbb{R}$. Also calculate the PSD $S_{XX}(f)$. **(5 points)**

Task 5. In a digital communication system 1 is represented by sending an analogue continuous time deterministic signal $s(t)$, $t \in \mathbb{R}$, while 0 is represented by sending 0. The signal is sent on a noisy channel with a zero-mean Gaussian WSS continuous time white noise process $N(t)$, $t \in \mathbb{R}$, having $R_{NN}(\tau) = (N_0/2) \delta(\tau)$ and $S_{NN}(f) = N_0/2$. Hence the received signal is $X(t) = s(t) + N(t)$ if 1 is sent and $X(t) = N(t)$ if 0 is sent.

To obtain best signal detection at detection time t_0 the received signal $X(t)$ is processed through a matched filter LTI system with impulse response $h(u) = s(t_0 - u)$ for $u \in \mathbb{R}$ designed to maximize the signal to noise ratio

$$\begin{aligned} \text{SNR} &= \frac{(h \star s)(t_0)^2}{\text{Var}((h \star N)(t_0))} = \frac{(h \star s)(t_0)^2}{E((h \star N)(t_0)^2)} = \frac{(\int_{-\infty}^{\infty} s(t_0 - u)^2 du)^2}{\int_{-\infty}^{\infty} |H(f)|^2 S_{NN}(f) df} \\ &= \frac{2}{N_0} \frac{(\int_{-\infty}^{\infty} s(u)^2 du)^2}{\int_{-\infty}^{\infty} |H(f)|^2 df} = \frac{2}{N_0} \frac{(\int_{-\infty}^{\infty} s(u)^2 du)^2}{\int_{-\infty}^{\infty} h(u)^2 du} = \frac{2}{N_0} \int_{-\infty}^{\infty} s(u)^2 du \end{aligned}$$

At detection it is decided that 1 was sent if $(h \star X)(t_0) > \frac{1}{2}(h \star s)(t_0)$ while it is decided that 0 was sent if $(h \star X)(t_0) \leq \frac{1}{2}(h \star s)(t_0)$. Find the probabilities for erroneous detection $P(\text{decision 1 when 0 was sent})$ and $P(\text{decision 0 when 1 was sent})$. [HINT: As $(h \star N)(t_0)$ is normal distributed so is $(h \star X)(t_0)$.] **(5 points)**

Task 6. Shortly describe Blackman-Tukey's method to improve on PSD estimation. What improvement does it bring and what is a possible drawback? **(5 points)**

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Solutions to written exam 1 November 2019

Task 1. As $X(1)+Y(2)$ is $N(\mu, \sigma^2)$ with $\mu = \mu_X + \mu_Y = 0$ and $\sigma^2 = \text{Var}\{X(1)+Y(2)\} = E((X(1)+Y(2))^2) = R_{XX}(0) + 2R_{XY}(1) + R_{YY}(0) = 2 + e^{-1}$ we have $P(X(1)+Y(2) > 3) = 1 - \Phi\left(\frac{3-\mu}{\sigma}\right) = 1 - \Phi\left(\frac{3}{\sqrt{2+e^{-1}}}\right)$.

Task 2. The possible values of $(X(1), X(2) - X(1))$ are $(1, 0)$, $(1, 1)$ and $(2, 0)$ with probabilities $P(\text{Po}(1)=1) \cdot P(\text{Po}(1)=0) = e^{-2}$, $P(\text{Po}(1)=1) \cdot P(\text{Po}(1)=1) = e^{-2}$ and $P(\text{Po}(1)=2) \cdot P(\text{Po}(1)=0) = \frac{1}{2}e^{-2}$, respectively, so that $P(X(1) \geq 1, X(2) \leq 2, X(3) \geq 1) = P(X(1) \geq 1, X(2) \leq 2) = \frac{5}{2}e^{-2}$.

Task 3. As $P^{(2)} = P^2 = \begin{pmatrix} 5/9 & 4/9 \\ 4/9 & 5/9 \end{pmatrix}$ we have $E(X(2)X(4)) = 1 \cdot 1 \cdot P(X(2)=1, X(4)=1) = (\pi(2))_1 (P^{(2)})_{11} = (\pi(0) P^2)_1 (P^2)_{11} = \frac{4}{9} \cdot \frac{5}{9} = \frac{20}{81} \approx \frac{1}{4}$.

Task 4. Let Y be an $N(0, 1)$ -distributed random variable and set $X(t) = Y$ for $t \in \mathbb{R}$. Further, $S_{XX}(f) = \delta(f)$ since $(\mathcal{F}^{-1}\delta)(\tau) = (\mathcal{F}\delta)(\tau) = 1$.

Task 5. Symmetry gives $P(\text{decision 0 when 1 sent}) = P(\text{decision 1 when 0 sent}) = P((h \star N)(t_0) > \frac{1}{2}(h \star s)(t_0)) = P(N(0, \text{Var}((h \star N)(t_0))) > \frac{1}{2}(h \star s)(t_0)) = 1 - \Phi\left(\frac{1}{2}\sqrt{\text{SNR}}\right)$.

Task 6. See Tomas McKelvey's lecture slides.