# Lecture 3

#### Last updated by Serik Sagitov: December 2, 2012

#### Abstract

A course based on the book Probability and Random Processes by Geoffrey Grimmett and David Stirzaker. Chapter 5. Generating functions and their applications (5.6-5.10). Chapter 6. Markov chains (6.1-6.3).

## **1** Characteristic functions

If X takes values k = 0, 1, 2, ... with probabilities  $p_k$  and  $\sum_{k=0}^{\infty} p_k = 1$ , then the distribution of X is fully described by its probability generating function

$$G(s) = \mathbb{E}(s^X) = \sum_{k=0}^{\infty} p_k s^k.$$

Key property: if X and Y are independent, then  $G_{X+Y}(s) = G_X(s)G_Y(s)$ . Examples

- Bernoulli distribution G(s) = q + ps,
- binomial distribution  $G(s) = (q + ps)^n$ ,
- Poisson distribution  $G(s) = e^{\lambda(s-1)}$ .

Moment generating function of X is  $M(t) = \mathbb{E}(e^{tX})$ . In the continuous case  $M(t) = \int e^{tx} f(x) dx$ . Computing moments

$$\begin{split} \mathbb{E}(X) &= G'(1), \quad \mathbb{E}(X(X-1)) = G''(1), \\ \mathbb{E}(X) &= M'(0), \quad \mathbb{E}(X^k) = M^{(k)}(0). \end{split}$$

Examples of moment generating functions

- Normal distribution  $M(t) = e^{t\mu + \frac{1}{2}t^2\sigma^2}$ ,
- exponential distribution  $M(t) = \frac{\lambda}{\lambda t}$  for  $t < \lambda$ ,
- Gamma $(\alpha, \lambda)$  distribution  $M(t) = \left(\frac{\lambda}{\lambda t}\right)^{\alpha}$  for  $t < \lambda$ ,
- Cauchy distribution M(0) = 1,  $M(t) = \infty$  for  $t \neq 0$ .

The characteristic function of X is complex valued  $\phi(t) = \mathbb{E}(e^{itX})$ . The joint characteristic function for  $\mathbf{X} = (X_1, \dots, X_n)$  is  $\phi(\mathbf{t}) = \mathbb{E}(e^{i\mathbf{t}\mathbf{X}^t})$ . Examples of characteristic functions

- normal distribution  $\phi(t) = e^{it\mu \frac{1}{2}t^2\sigma^2}$ ,
- gamma distribution  $\phi(t) = \left(\frac{\lambda}{\lambda it}\right)^{\alpha}$ ,
- Cauchy distribution  $\phi(t) = e^{-|t|}$ ,
- multivariate normal distribution  $\phi(\mathbf{t}) = e^{i\mathbf{t}\boldsymbol{\mu}^{\mathrm{t}} \frac{1}{2}\mathbf{t}\mathbf{V}\mathbf{t}^{\mathrm{t}}}$ .

From the last example it follows that given a vector  $\mathbf{X} = (X_1, \ldots, X_n)$  with a multivariate normal distribution any linear combination  $\mathbf{aX}^t = a_1 X_1 + \ldots + a_n X_n$  is normally distributed since

$$\mathbb{E}(e^{t\mathbf{a}\mathbf{X}^{t}}) = \phi(t\mathbf{a}) = e^{it\mu - \frac{1}{2}t^{2}\sigma^{2}}, \quad \mu = \mathbf{a}\boldsymbol{\mu}^{t}, \quad \sigma^{2} = \mathbf{a}\mathbf{V}\mathbf{a}^{t}.$$

# 2 Weak law of large numbers

**Definition 1** Convergence in distribution  $X_n \xrightarrow{d} X$  means

 $\mathbb{P}(X_n \leq x) \to \mathbb{P}(X \leq x)$  for all x such that  $\mathbb{P}(X = x) = 0$ .

This is equivalent to the weak convergence  $F_n \xrightarrow{d} F$  of distribution functions when  $F_n(x) \to F(x)$  at each point x where F is continuous.

Properties of characteristic functions

- two r.v. have the same characteristic function iff they have the same distribution function,
- if  $X_n \xrightarrow{d} X$ , then  $\phi_n(t) \to \phi(t)$  for all t,
- conversely, if  $\phi(t) = \lim_{n \to \infty} \phi_n(t)$  exists and continuous at t = 0, then  $\phi$  is cf of some F, and  $F_n \stackrel{d}{\to} F$ .

**Theorem 2** If  $X_1, X_2, \ldots$  are iid with finite mean  $\mu$  and  $S_n = X_1 + \ldots + X_n$ , then

$$S_n/n \xrightarrow{d} \mu, \quad n \to \infty$$

Proof. Let  $F_n$  and  $\phi_n$  be the df and cf of  $n^{-1}S_n$ . To prove  $F_n(x) \xrightarrow{d} 1_{\{x \ge \mu\}}$  we have to see that  $\phi_n(t) \to e^{it\mu}$  which is obtained using a Taylor expansion

$$\phi_n(t) = \left(\phi_1(tn^{-1})\right)^n = \left(1 + i\mu tn^{-1} + o(n^{-1})\right)^n \to e^{it\mu}$$

**Remarks**. Statistical application: the sample mean is a consistent estimate of the population mean. Counterexample: if  $X_i$  has the Cauchy distribution, then  $S_n/n \stackrel{d}{=} X_1$  since  $\phi_n(t) = \phi_1(t)$ .

### 3 Central limit theorem

According the LLN  $|S_n - n\mu|$  is much smaller than n. This difference is of order  $\sqrt{n}$ .

**Theorem 3** If  $X_1, X_2, \ldots$  are iid with finite mean  $\mu$  and positive finite variance  $\sigma^2$ , then for any x

$$\mathbb{P}\Big(\frac{S_n - n\mu}{\sigma\sqrt{n}} \le x\Big) \to \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-y^2/2} dy, \quad n \to \infty.$$

Proof. Let  $\psi_n$  be the cf of  $\frac{S_n - n\mu}{\sigma \sqrt{n}}$ . Using a Taylor expansion we obtain

$$\psi_n(t) = \left(1 - \frac{t^2}{2n} + o(n^{-1})\right)^n \to e^{-t^2/2}.$$

**Remarks**. Important example: simple random walks. 280 years ago de Moivre (1733) obtained the first CLT in the symmetric case with p = 1/2.

Statistical application: the standardized sample mean has the sampling distribution which is approximately N(0, 1). Approximate 95% confidence interval formula for the mean  $\bar{X} \pm 1.96 \frac{s}{\sqrt{n}}$ .

#### 4 Markov chains

Conditional on the present value, the future of the system is independent of the past. A Markov chain  $\{X_n\}_{n=0}^{\infty}$  with countably many states and transition matrix **P** with elements  $p_{ij}$ 

$$\mathbb{P}(X_n = j | X_{n-1} = i, X_{n-2} = i_{n-2}, \dots, X_0 = i_0) = p_{ij}.$$

The *n*-step transition matrix with elements  $p_{ij}^{(n)} = \mathbb{P}(X_{n+m} = j | X_m = i)$  equals  $\mathbf{P}^n$ . Given the initial distribution **a** as the vector with components  $a_i = \mathbb{P}(X_0 = i)$ , the distribution of  $X_n$  is given by the vector  $\mathbf{aP}^n$  since

$$\mathbb{P}(X_n = j) = \sum_{i = -\infty}^{\infty} \mathbb{P}(X_n = j | X_0 = i) \mathbb{P}(X_0 = i) = \sum_{i = -\infty}^{\infty} a_i p_{ij}^{(n)}.$$

Examples:

- IID chain has transition probabilities  $p_{ij} = p_i$ ,
- simple random walk has transition probabilities  $p_{ij} = p1_{\{j=i+1\}} + q1_{\{j=i-1\}}$ ,
- Bernoulli process has transition probabilities  $p_{ij} = p \mathbf{1}_{\{j=i+1\}} + q \mathbf{1}_{\{j=i\}}$  and state space  $S = \{0, 1, 2, \ldots\}$ .

Let  $T_i = \min\{n \ge 1 : X_n = i\}$  and put  $f_{ij}^{(n)} = \mathbb{P}(T_j = n | X_0 = i)$ . Define the generating functions

$$P_{ij}(s) = \sum_{n=0}^{\infty} s^n p_{ij}^{(n)}, \qquad F_{ij}(s) = \sum_{n=1}^{\infty} s^n f_{ij}^{(n)}.$$

It is not difficult to see that

$$\begin{split} P_{ij}(s) &= \mathbf{1}_{\{j=i\}} + F_{ij}(s) P_{jj}(s) \\ P_{ii}(s) &= \frac{1}{1 - F_{ii}(s)}. \end{split}$$

Classification of states

- state *i* is called recurrent (persistent), if  $\mathbb{P}(T_i < \infty | X_0 = i) = 1$ , otherwise *i* is called a transient state,
- a recurrent state *i* is called null-recurrent, if  $\mathbb{E}(T_i|X_0=i)=\infty$ ,
- state *i* is called positive-recurrent, if  $\mathbb{E}(T_i|X_0=i) < \infty$ .

Since  $F_{ii}(1) = \mathbb{P}(T_i < \infty | X_0 = i)$ , we conclude that state *i* is recurrent iff  $P_{ii}(1) = \infty$ .

Theorem 4 State i is recurrent iff

$$\sum_{n=1}^{\infty} p_{ii}^{(n)} = \infty.$$
<sup>(1)</sup>

A recurrent state *i* is null-recurrent iff  $p_{ii}^{(n)} \to 0$ .

**Example**. For a simple random walk

$$\mathbb{P}(S_{2n} = i | S_0 = i) = \binom{2n}{n} (pq)^n.$$

Using the Stirling formula  $n! \sim n^n e^{-n} \sqrt{2\pi n}$  we get

$$p_{ii}^{(2n)} \sim \frac{(4pq)^n}{\sqrt{\pi n}}, \quad n \to \infty$$

Criterium of recurrence (1) holds only if p = 0.5 when  $p_{ii}^{(2n)} \sim \frac{1}{\sqrt{\pi n}}$ . The one and two-dimensional symmetric simple random walks are null-recurrent but the three-dimensional walk is transient!

**Definition 5** The period d(i) of state *i* is the greatest common divisor of *n* such that  $p_{ii}^{(n)} > 0$ . We call *i* periodic if  $d(i) \ge 2$  and aperiodic if d(i) = 1.

If two states i and j communicate with each other, then

- i and j have the same period,
- i is transient iff j is transient,
- i is null-recurrent iff j is null-recurrent.

**Definition 6** A chain is called irreducible if all states communicate with each other.

All states in an irreducible chain have the same period d. It is called the period of the chain. Example: a simple random walk is periodic with period 2. Irreducible chains are classified as transient, recurrent, positively recurrent, or null-recurrent.

**Definition 7** State *i* is absorbing if  $p_{ii} = 1$ . More generally, *C* is called a closed set of states, if  $p_{ij} = 0$  for all  $i \in C$  and  $j \notin C$ .

The state space S can be partitioned uniquely as

$$S = T \cup C_1 \cup C_2 \cup \dots,$$

where T is the set of transient states, and the  $C_i$  are irreducible closed sets of recurrent states. If S is finite, then at least one state is recurrent and all recurrent states are positively recurrent.