### Lecture 12. Confidence intervals - - revisited

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# ML estimates for typical models:

Distribution	ML estimates	$(\sigma_{\mathcal{E}}^2)^*$
$X \in Po( heta)$	$\theta^* = \bar{x}$	$\frac{\theta^*}{n}$
$K \in Bin(n,p)$	$\theta^* = \frac{k}{n}$	$\frac{\theta^*(1-\theta^*)}{n}$
$X\in Exp( heta)$	$\theta^* = \bar{x}$	$\frac{(\theta^*)^2}{n}$
$X \in N(m,\sigma^2)$	$\theta^* = (\bar{x}, s_n^2)$	$\big(\frac{s_n^2}{n},\frac{2(s_n^2)^2}{n}\big)$

**Example** - times between earthquakes: Model exponential cdf  $P(T \le t) = 1 - \exp(-t/a)$ ; With  $\theta = a$  table gives  $a^* = 437.2$  days; Variance of estimation error

$$(\sigma_{\mathcal{E}}^2)^* = \frac{(\theta^*)^2}{n} = \frac{437.2^2}{63} = 3034, \quad \mathsf{day}^2.$$

Hence the standard deviation is  $\sqrt{3034}=55.08$  days. "Common sense" uncertainty 437.2  $\pm$  2  $\cdot$  55.08.

## In general

- Choose a cdf  $F(x; \theta)$  for data ( $\theta$  unknown parameter to be selected).
- Compute likelihood function L(θ) (odds for θ). Find θ\* the value of parameter maximizing the likelihood function (having maximal odds).
- $e = \theta \theta^*$  estimation error (unknown) and modeled as rv.  $\mathcal{E}$ .
  - If  $E[\mathcal{E}] = 0$  then estimation is unbiased.
  - ▶ If standard deviation of the error  $\sigma_{\mathcal{E}} \rightarrow 0$  as  $n \rightarrow \infty$  then estimation is consistent.
- For large n (number of observations) *E* is approximately normally distributed N(0, σ<sub>E</sub><sup>2</sup>), σ<sub>E</sub> is an estimated by σ<sub>E</sub><sup>\*</sup>.

Error in expected time between earthquakes  $\mathcal{E}$  is approx. N(0, 3083).

### Quantiles of $\mathcal{E}$ :

The error distribution  $F_{\mathcal{E}}(e)$  describes sizes of errors as well as the frequencies with which those occur. Often one uses quantiles  $e_{\alpha}$  to describe the variability. Obviously we have that

$$\mathsf{P}(\mathbf{e}_{1-\alpha/2} \leq \mathcal{E} \leq \mathbf{e}_{\alpha/2}) = 1 - \alpha, \quad \text{or} \quad \mathsf{P}(\mathcal{E} \leq \mathbf{e}_{\alpha}) = 1 - \alpha.$$

If  $\mathcal{E}$  is approximately  $N\left(0, (\sigma_{\mathcal{E}}^2)^*\right)$  then

$$e_{\alpha/2} \approx \lambda_{\alpha/2} \cdot \sigma_{\mathcal{E}}^*, \qquad e_{1-\alpha/2} \approx -\lambda_{\alpha/2} \cdot \sigma_{\mathcal{E}}^*.$$

Quantiles of the standard normal distribution.

$\alpha$	0.10	0.05	0.025	0.01	0.005	0.001
$\lambda_{lpha}$	1.28	1.64	1.96	2.33	2.58	3.09

### Approximative confidence interval:

**Example - times between earthquakes:** Let choose  $\alpha = 0.05$ , then

 $e_{\alpha/2} \approx 1.96 \cdot \sqrt{3083} = 108.8$ , and  $e_{1-\alpha/2} \approx -1.96 \cdot \sqrt{3083} = -108.8$ .

Consequently P( $-108.8 \le \mathcal{E} \le 108.8$ )  $\approx 0.95$ . Since  $\theta^* = 437.2$  we say that with approximate confidence  $1 - \alpha = 0.95$ 

 $-108.8 \le \theta - \theta^* \le 108.8$ , or  $\theta \in [437.2 - 108.8, 437.2 + 108.8]$ 

Confidence interval can be seen as an **interval estimate** of a parameter, i.e. instead of one value we give a set of possible values.

In general for any ML-estimator, the approximate  $1-\alpha^*$  confidence interval is

$$\theta^* - \lambda_{\alpha/2} \cdot \sigma_{\mathcal{E}}^* \le \theta \le \theta^* + \lambda_{\alpha/2} \cdot \sigma_{\mathcal{E}}^*.$$

Since  $\theta^* \approx E[\Theta^*]$  while  $\sigma_{\mathcal{E}}^* \approx \sqrt{V[\Theta^*]}$  one can also give the following alternative formulation

 $\mathsf{E}[\Theta^*] - \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[\Theta^*]} \le \theta \le \mathsf{E}[\Theta^*] + \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[\Theta^*]},\tag{1}$ 

with approximative confidence  $1 - \alpha$ . Here  $\Theta^*$  is approx.  $N(\theta^*, (\sigma_{\mathcal{E}}^2)^*)$ .

**Example:** Suppose we are interested in probability that distance between earthquakes is longer than 1500 days, viz. p = P(T > 1500). An possible estimate is

$$p^* = \exp(-1500/\theta^*) = \exp(-1500/437.2) = 0.0324.$$

Confidence interval: Let write  $P^* = \exp(-1500/\Theta^*)$  and employ (??):

$$\mathsf{E}[P^*] - \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[P^*]} \le \theta \le \mathsf{E}[P^*] + \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[P^*]},$$

then use **Gauss' formulae** to evaluate  $E[P^*]$ ,  $V[P^*]$ , see blackboard. **This approach is called Delta-method**.

#### More complex example:

Suppose that we are measuring the concentration of radon in buildings. At some location 40 houses were selected at random out of 200. Then average yearly concentration X were measured. The requirement is that the yearly mean concentration should be below 200 Bq/m<sup>3</sup>. By plotting the 40 measurement on normal probability paper we conclude that the measured values are  $N(m, \sigma^2)$ . The  $m^* = \bar{x} = 120$  while  $(\sigma^2)^* = s_n^2 = 400$ . One decided to compute the quantile  $x_{0.001}$ ,

$$x_{0.001}^* = 120 + 3.09 \cdot \sqrt{400} = 181.8 < 200.$$

Hence the number of houses that can have concentration above 181 is  $160 \cdot 0.001 = 0.16$  which is small. Find confidence interval for  $x_{0.001}$  instead of  $x_{0.001}^*$ ! Let  $X_{0.001}^*$  be the estimator then employ (??):

$$\mathsf{E}[X_{0.001}^*] - \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[X_{0.001}^*]} \le \theta \le \mathsf{E}[X_{0.001}^*] + \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[X_{0.001}^*]}.$$

Let  $M^*$  and  $\Sigma^*$  be the estimators of mean m and  $\sigma^2$ , resp., then

$$V[X_{0.001}^*] = V[M^* + 3.09 \cdot \sqrt{\Sigma^*}].$$

Use Gauss formulas and  $\left(\mathsf{V}[M^*],\mathsf{V}[\Sigma^*]\right) \approx \left(\frac{s_n^2}{n},\frac{2(s_n^2)^2}{n}\right)$ ,  $\mathsf{Cov}[M^*,\Sigma^*] = 0$ .

### Gauss' Approximations.

Let X and Y be independent random variables with expectations  $m_X, m_Y, n_Y$ , respectively. For a smooth function h the following approximations

$$\begin{aligned} \mathsf{E}[h(X,Y)] &\approx h(m_X,m_Y), \\ \mathsf{V}[h(X,Y)] &\approx \left[h_1(m_X,m_Y)\right]^2 \mathsf{V}[X] + \left[h_2(m_X,m_Y)\right]^2 \mathsf{V}[Y] \\ &+ 2h_1(m_X,m_Y) h_2(m_X,m_Y) \operatorname{Cov}[X,Y]. \end{aligned}$$

where

$$h_1(x,y) = \frac{\partial}{\partial x}h(x,y), \qquad h_2(x,y) = \frac{\partial}{\partial y}h(x,y).$$

In our case  $X = M^*$ ,  $Y = \Sigma^*$  and  $h(x, y) = x + 3.09\sqrt{y}$  hence

$$h_1(x,y) = 1,$$
  $h_2(x,y) = 3.09 \cdot /(2\sqrt{y}).$ 

#### Even more complex example:

Recall the data of 22 lifetimes (there were (n = 22) units tested). For ball bearings lifetime X the *rating life*,  $L_{10}$  should be estimated.<sup>1</sup> Assume the Weibull model is valid for the distribution of the lifetime:

$$F_X(x) = 1 - e^{-(x/a)^c}, \quad x \ge 0,$$

then  $L_{10} = a \cdot \left(-\ln(1-\frac{1}{10})\right)^{1/c}$ . For our data set  $a^* = 82.08$  and  $c^* = 2.06$  and hence

$$L_{10}^* = a^* \cdot \left(-\ln(1-\frac{1}{10})\right)^{1/c^*} = 27.53 \cdot 10^6$$

What about the confidence interval? Again employ (??):

$$\mathsf{E}[L_{10}^*] - \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[L_{10}^*]} \le \theta \le \mathsf{E}[L_{10}^*] + \lambda_{\alpha/2} \cdot \sqrt{\mathsf{V}[L_{10}^*]},$$

and use **Gauss' formulae** to evaluate  $E[L_{10}^*]$ ,  $V[L_{10}^*]$ .

 $^{1}L_{10}$  satisfies P(X  $\leq L_{10}$ ) = 1/10.

Now we can compute the variance

$$V[L_{10}^*] = V[h(A^*, C^*)] \approx h_1(a^*, c^*)^2 V[A^*] + h_2(a^*, c^*)^2 V[C^*] + 2 h_1(a^*, c^*) \cdot h_2(a^*, c^*) \operatorname{Cov}[A^*, C^*] = 18.5.$$

Since  $\sqrt{V[L_{10}^*]} \approx 4.3$ , then with approximate confidence 95%  $L_{10}$  is in  $[27.53-1.96\cdot4.3, 27.53+1.96\cdot4.3] = [19.1, 36.0]$  millions of revolutions.

### Connection to hypothesis testing:

If one wishes to test whether a parameter  $\theta$  has a specific value

 $H_0: \theta = \theta_0$ 

One chooses size of error  $\alpha$ , i.e. probability of rejecting a true hypothesis is  $\alpha$ . Then the test can be performed by constructing an interval that with confidence  $1 - \alpha$  contains the true value of the parameter.

If  $\theta_0$  is not contained in the interval than one rejects the hypothesis  $H_0$  that  $\theta = \theta_0$ .

Suppose that a dealer claims that  $L_{10} = 40$  millions of resolutions. Since our confidence interval [19.1, 36.0] does not contain value 40 thus, with "about" 5% probability of making error, we reject the hypothesis that the quality of the ball bearings is  $L_{10} = 40$  millions of resolutions.

#### Examples of exact confidence intervals:

Suppose we have *n* observations  $\bar{\mathbf{x}} = \sum x_i/n$  then:

▶  $1 - \alpha$  confidence interval for *m* in N(*m*,  $\sigma^2$ ) ( $\sigma$  unknown)

$$\left[\bar{\bf x} - t_{\alpha/2}(n-1)\frac{s_{n-1}}{\sqrt{n}}, \ \bar{\bf x} + t_{\alpha/2}(n-1)\frac{s_{n-1}}{\sqrt{n}}\right]$$

where  $s_{n-1}^2 = \sum (x_i - \bar{\mathbf{x}})^2 / (n-1)$ .

▶  $1 - \alpha$  confidence interval for *m* in Po(*m*)

$$\theta \in \left[\frac{\chi^2_{1-\alpha/2}(2n\bar{\mathbf{x}})}{2n}, \frac{\chi^2_{\alpha/2}(2n\bar{\mathbf{x}}+2)}{2n}\right]$$

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▶  $1 - \alpha$  confidence interval for *a* in Exp(*a*)

$$heta \in \left[ rac{2nar{\mathbf{x}}}{\chi^2_{lpha/2}(2n)}, \ rac{2nar{\mathbf{x}}}{\chi^2_{1-lpha/2}(2n)} 
ight]$$

## Credibility intervals:

- In the Bayessian approach the lack of knowledge of parameter value θ is described using the probability densities f(θ) (odds). Random variable Θ having the pdf f(θ) models our knowledge about θ.
- The initial knowledge is described using f<sup>prior</sup>(θ) density and as the data are gathered it is updated

$$f^{\mathsf{post}}(\theta) = c L(\theta) f^{\mathsf{prior}}(\theta).$$

The pdf f<sup>post</sup>(θ) summarizes our knowledge about θ. However if one value of for the parameter is needed then

$$\theta^{\text{predictive}} = \mathsf{E}[\Theta] = \int \theta f^{\text{post}}(\theta) \, d\theta.$$

If one wishes to describe the variability of θ by means of an interval then the so called credibility interval can be computed

$$[\theta_{1-\alpha/2}^{\mathsf{post}}, \ \theta_{\alpha/2}^{\mathsf{post}}]$$