

Lecture 1. Probabilities - Definitions, Examples and Basic Tools

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Risk is a quantity derived both from the probability that a particular hazard will occur and the magnitude of the consequence of the undesirable effects of that hazard. The term risk is often used informally to mean the probability of a hazard occurring.

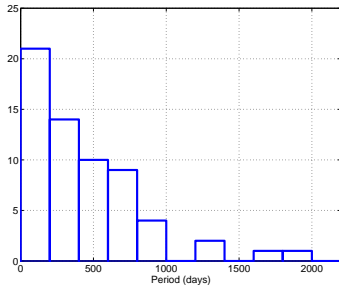
Probabilities are numbers, assigned to (events) statements about outcome of an experiment, that express the chances that the statement is true.

Statistics is the scientific application of mathematical principles to the collection, analysis, and presentation of numerical data.

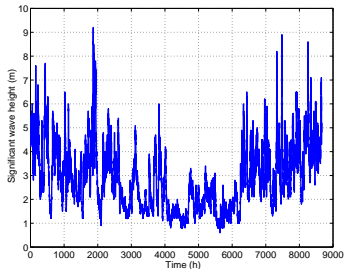
Common usages of the concept of probability:

- ▶ To describe variability of outcomes of repeatable experiments, e.g. chances of getting “Heads” in a flip of a coin, chances of failure of a component (mass production) or of occurrence of a large earthquake worldwide during one year.
- ▶ To quantify the uncertainty of an outcome of a non-repeatable event. Here the probability will depend on the available information.
Example. (Modeling, estimation of model parameters, evaluations of probabilities, uncertainties of risks estimates.)
- ▶ To measure the present state of knowledge, e.g. the probability that the detected tumor is malignant.

Examples of data



Histogram: Periods in days between serious earthquakes 1902–1977.



Measurements of Significant wave height,

Jan 1995 – Dec 1995.

How high is 100-years significant wave?

Probabilities

Term *experiment* is used to refer to any process whose outcome is not known in advance. Consider an experiment.

- ▶ Sample space \mathcal{S} : A collection of all possible outcomes.
- ▶ Sample point $s \in \mathcal{S}$: An element in \mathcal{S} .
- ▶ Event A : A subset of sample points, $A \subset \mathcal{S}$ for which a statement about an outcome is true.

Rules for probabilities:

$$P(A \cup B) = P(A) + P(B), \quad \text{if } A \cap B = \emptyset.$$

For any event A ,

$$0 \leq P(A) \leq 1.$$

Statements which are always false have **probability zero**, similarly,

always-true statements have **probability one**

Example 1

Independence

For a sample space \mathcal{S} and a probability measure P , the events $A, B \subset \mathcal{S}$ are called **independent** if

$$P(A \cap B) = P(A) \cdot P(B).$$

Two events A and B are **dependent** if they are not independent, i.e.

$$P(A \cap B) \neq P(A) \cdot P(B).$$

Example 2

How to find "useful" probabilities:

- ▶ Classically for finite sample spaces \mathcal{S} , if all outcomes are equally probable then

$$P(A) = \text{number of outcomes for which } A \text{ is true} / \text{number of outcomes}$$

- ▶ Employ a concept of independence. *Example 3*
- ▶ Employ a concept of conditional probabilities.

If everybody agrees with the choice of P , it is called an **objective probability**. (If a coin is "fair" the probability of getting tails is 0.5.)

For many problems the probability will depend on the information a person has when estimating the chances that a statement A is true. One then speaks of **subjective probability**.

Conditional probability

Conditional probability:

$$P(B | A) = \frac{P(A \cap B)}{P(A)}$$

The chances that some statement B is true when we *know* that some statement A is true.

Example 4

Law of total probability

Let A_1, \dots, A_n be a partition of the sample space.

Then for any event B

$$P(B) = P(B|A_1)P(A_1) + P(B|A_2)P(A_2) + \dots + P(B|A_n)P(A_n)$$

Example 5

Bayes' formula

Again let A_1, \dots, A_n be a partition of the sample space, i.e. we have n excluding hypothesis and only one of them is true. The evidence is that B is true. Which of alternatives is most likely to be true?

Bayes' formula:

$$P(A_i|B) = \frac{P(A_i \cap B)}{P(B)} = \frac{P(B|A_i)P(A_i)}{P(B)} = \frac{P(A_i)}{P(B)}P(B|A_i)$$

Name due to *Thomas Bayes* (1702-1761)

Likelihood: $L(A_i) = P(B|A_i)$ (How likely is the observed event B under alternative A_i ?)

Example 6

Odds¹ (fractional odds)² for events A_1 and A_2 : Any positive numbers q_1 and q_2 such that

$$\frac{q_1}{q_2} = \frac{P(A_1)}{P(A_2)}$$

Let A_1, A_2, \dots, A_n be a partition of the sample space having odds q_i , i.e. $P(A_j)/P(A_i) = q_j/q_i$. Then

$$P(A_i) = \frac{q_i}{q_1 + \dots + q_n}$$

¹ The language of odds such as "ten to one" for intuitively estimated risks is found in the sixteenth century, well before the invention of mathematical probability.[1] Shakespeare writes in Henry IV:

Knew that we ventured on such dangerous seas that if we wrought out life 'twas ten to one.

²European odds: $q_i = 1/P(A_i)$ - if you bet 1 SEK on A_i then you get q_i SEK if A_i is true (occurs) or lose your bet if A_i is false. Odds 1:4 corresponds to European odds 5.

Bayes' formula formulated using odds

Bayes' formula can be conveniently written by means of *odds*:

$$q_i^{\text{post}} = P(B | A_i) q_i^{\text{prior}}$$

Prior odds: q_i^{prior} for A_i **before** B is known.

Posterior odds: q_i^{post} for A_i **after** it is known that B is true.

Example 7

Conditional independence

Events B_1, B_2 are **conditionally independent** given a partition A_1, A_2, \dots, A_k of the sample space if

$$P(B_1 \cap B_2 | A_i) = P(B_1 | A_i)P(B_2 | A_i).$$

Events B_1, \dots, B_n are conditionally independent if all pairs B_i, B_j are conditionally independent.

Odds: Recursive updating

Let A_1, A_2, \dots, A_k be a partition of the sample space, and B_1, \dots, B_n, \dots a sequence of true statements (evidences).

If the evidences B are conditionally independent of A_i then the **posterior odds** can be computed recursively using the induction

$$q_i^0 = q_i^{\text{prior}}$$

$$q_i^n = P(B_n | A_i) q_i^{n-1}, \quad n = 1, 2, \dots$$

Example 8: Waste-water treatment:

Solve problem 2.6. **Examples in this lecture "click"**