## TMS 165/MSA350 Stochastic Calculus Part I Fall 2011

## Exercise session 6

**Exercise 1.** Exercise 1 in Stig Larsson's lecture notes "Numerical Methods for Stochastic ODEs".

**Solution.** The task is to prove the estimate (8) given the conditions (1)-(5) and with Grönwall's lemma and Doob's inequality at our disposal. To land the proof we will assume that  $X \in E_T$ , so that the Itô integral involved is a square-integrable martingale: Without this additional assumption (which can be waived at the cost of involving the much deeper Burkholder-Davis-Gundy inequality on page 201 in Klebaner's book for local martingales) we neither know that the Itô integral involved is a martingale or that the isometry formula can be used, which is not what is really meant:) Now the proof is just a version of that of Theorem 3, as we have

$$\begin{split} &\frac{1}{3} \operatorname{\mathbf{E}} \Big\{ \sup_{s \in [0,t]} X(s)^2 \Big\} \\ &= \frac{1}{3} \operatorname{\mathbf{E}} \Big\{ \sup_{s \in [0,t]} \Big( X_0 + \int_0^s \mu(X(r),r) \, dr + \int_0^s \sigma(X(r),r) \, dB(r) \Big)^2 \Big\} \\ &\leq \operatorname{\mathbf{E}} \{ X_0^2 \} + \operatorname{\mathbf{E}} \Big\{ \sup_{s \in [0,t]} \Big( \int_0^s L \left( 1 + |X(r)| \right) dr \Big)^2 \Big\} + \operatorname{\mathbf{E}} \Big\{ \sup_{s \in [0,t]} \Big( \int_0^s \sigma(X(r),r) \, dB(r) \Big)^2 \Big\} \\ &\leq \operatorname{\mathbf{E}} \{ X_0^2 \} + \operatorname{\mathbf{E}} \Big\{ \int_0^t L^2 \left( 1 + |X(r)| \right)^2 dr \int_0^t 1^2 \, dr \Big\} + \Big( \frac{2}{2-1} \Big)^2 \operatorname{\mathbf{E}} \Big\{ \Big( \int_0^t \sigma(X(r),r) \, dB(r) \Big)^2 \Big\} \\ &\leq \operatorname{\mathbf{E}} \{ X_0^2 \} + 2 \, L^2 \, T^2 + 2 \, L^2 \, T \int_0^t \operatorname{\mathbf{E}} \{ X(r)^2 \} \, dr + 4 \int_0^t \operatorname{\mathbf{E}} \{ \sigma(X(r),r)^2 \} \, dr \\ &\leq \operatorname{\mathbf{E}} \{ X_0^2 \} + 2 \, L^2 \, T^2 + 2 \, L^2 \, T \int_0^t \operatorname{\mathbf{E}} \{ X(r)^2 \} \, dr + 8 \, L^2 \, T + 8 \, L^2 \int_0^t \operatorname{\mathbf{E}} \{ X(r)^2 \} \, dr \\ &\leq \operatorname{\mathbf{E}} \{ X_0^2 \} + 2 \, L^2 \, T^2 + 8 \, L^2 \, T + (2 \, L^2 \, T + 8 \, L^2) \int_0^t \sup_{r \in [0,s]} \operatorname{\mathbf{E}} \{ X(r)^2 \} \, dr \\ &\leq \Big( \operatorname{\mathbf{E}} \{ X_0^2 \} + 2 \, L^2 \, T^2 + 8 \, L^2 \, T \Big) \exp \Big\{ \Big( 2 \, L^2 \, T + 8 \, L^2 \Big) \, T \Big\} \quad \text{for } t \in [0,T]. \end{split}$$

Exercise 2 in Larsson's lecture notes.

**Solution.** Consider the operator  $E_T \ni Y \to G(Y) \in E_T$  given by

$$G(Y)(t) = X_0 + \int_0^t \mu(Y(r), r) \, dr + \int_0^t \sigma(Y(r), r) \, dB(r) \quad \text{for } t \in [0, T].$$

Note that Exercise 1 ensures that G maps  $E_T$  on  $E_T$ . Further, note that  $E_T$  is a Banach

space when equipped with the norm  $||X|| = \sup_{t \in [0,T]} \sqrt{E\{X(t)^2\}}$ . By a version of the argument employed in the solution of Exercise 1 we have

$$\begin{split} &\frac{1}{2} \left\| G(Y) - G(Z) \right\|^2 \\ &\leq \frac{1}{2} \operatorname{\mathbf{E}} \Big\{ \sup_{t \in [0,T]} \left( G(Y)(t) - G(Z)(t) \right)^2 \Big\} \\ &= \frac{1}{2} \operatorname{\mathbf{E}} \Big\{ \sup_{t \in [0,T]} \left( \int_0^t (\mu(Y(s),s) - \mu(Z(s),s)) \, ds + \int_0^t (\sigma(Y(s),s) - \sigma(Z(s),s)) \, dB(s) \right)^2 \Big\} \\ &\leq \operatorname{\mathbf{E}} \Big\{ \sup_{t \in [0,T]} \left( \int_0^t L \left| Y(s) - Z(s) \right| \, ds \right)^2 \Big\} + \operatorname{\mathbf{E}} \Big\{ \sup_{t \in [0,T]} \left( \int_0^t (\sigma(Y(s),s) - \sigma(Z(s),s)) \, dB(s) \right)^2 \Big\} \\ &\leq \operatorname{\mathbf{E}} \Big\{ \int_0^T L^2 \left| Y(s) - Z(s) \right|^2 \, ds \int_0^T 1^2 \, ds \Big\} + 4 \operatorname{\mathbf{E}} \Big\{ \left( \int_0^T (\sigma(Y(s),s) - \sigma(Z(s),s)) \, dB(s) \right)^2 \Big\} \\ &\leq L^2 T \int_0^T \operatorname{\mathbf{E}} \big\{ |Y(s) - Z(s)|^2 \big\} \, ds + 4 \int_0^T \operatorname{\mathbf{E}} \big\{ (\sigma(Y(s),s) - \sigma(Z(s),s))^2 \big\} \, ds \\ &\leq (L^2 T + 4 L^2) \int_0^T \operatorname{\mathbf{E}} \big\{ |Y(s) - Z(s)|^2 \big\} \, ds \\ &\leq (L^2 T^2 + 4 L^2 T) \, \|Y - Z\|^2. \end{split}$$

Hence G is a contraction so that the fixed point theorem for contarctions on Banach spaces ensures that there exists a unique  $X \in E_T$  such that G(X) = X. This in turn is of course a unique strong solution to the SDE (1).

Exercise 3. Exercise 3 in Larsson's lecture notes.

**Solution.** By a version of the argument employed in the solution of Exercise 1 we have

$$\begin{split} &\frac{1}{3} \mathbf{E} \big\{ (\hat{X}(t) - X(t))^2 \big\} \\ &= \frac{1}{3} \mathbf{E} \Big\{ \Big( \hat{X}_0 - X_0 + \int_0^t (\mu(\hat{X}(s), s) - \mu(X(s), s)) \, ds + \int_0^t (\sigma(\hat{X}(s), s) - \sigma(X(s), s)) \, dB(s) \Big)^2 \Big\} \\ &\leq \mathbf{E} \big\{ (\hat{X}_0 - X_0)^2 \big\} + \mathbf{E} \Big\{ \Big( \int_0^t L \, |\hat{X}(s) - X(s)| \, ds \Big)^2 \Big\} + \mathbf{E} \Big\{ \Big( \int_0^t (\sigma(\hat{X}(s), s) - \sigma(X(s), s)) \, dB(s) \Big)^2 \Big\} \\ &\leq \mathbf{E} \big\{ (\hat{X}_0 - X_0)^2 \big\} + L^2 T \int_0^t \mathbf{E} \big\{ (\hat{X}(s) - X(s))^2 \big\} \, ds + L^2 \int_0^t \mathbf{E} \big\{ (\hat{X}(s) - X(s))^2 \big\} \, ds \\ &\leq \mathbf{E} \big\{ (\hat{X}_0 - X_0)^2 \big\} \, \exp \big\{ L^2 (1 + T) \, t \big\} \\ &\leq \mathbf{E} \big\{ (\hat{X}_0 - X_0)^2 \big\} \, \exp \big\{ L^2 (1 + T) \, T \big\} \quad \text{for } t \in [0, T]. \end{split}$$

**Exercise 4.** Given some constants  $\mu, \sigma \in \mathbb{R}$ , consider the SDE

$$dX(t) = \mu dt + \sigma X(t) dB(t) \quad \text{for } t \in (0, T], \qquad X(0) = X_0.$$

(a) Show that the unique strong solution to this SDE is given by

$$X(t) = e^{\sigma B(t) - \sigma^2 t/2} \left( X_0 + \mu \int_0^t e^{-\sigma B(s) + \sigma^2 s/2} \, ds \right) \quad \text{for } t \in [0, T].$$

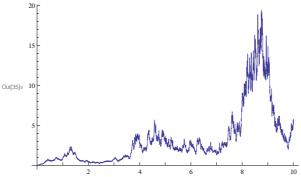
(b) Solve the SDE numerically for  $\mu = \sigma = 1$ , T = 10 and  $X_0 = 0$  by the Euler method. Plot a sample path of the numerical solution and compare with the analytic solution.

**Solution.** (a) According to Theorem 5.4 in Klebaner's book the SDE has a unique strong solution. By application of Itô's formula Theorem 4.17 in Klebaner's book with

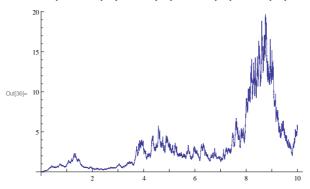
$$f(y,z) = yz$$
,  $Y(t) = e^{\sigma B(t) - \sigma^2 t/2}$  and  $Z(t) = X_0 + \mu \int_0^t e^{-\sigma B(t) + \sigma^2 s/2} ds$ 

(cf. Example 4.25 in Klebaner's book) we further see that Y(t)Z(t) is the solution as

$$\begin{split} d(Y(t)Z(t)) &= Y(t) \, dZ(t) + Z(t) \, dY(t) + dY(t) dZ(t) \\ &= \mu \, dt + Y(t)Z(t) \, \sigma \, dB(t) + (\mu \, dt) \, (\sigma \, dB(t)) \\ &= \mu \, dt + Y(t)Z(t) \, \sigma \, dB(t). \end{split}$$



In[38]= For[i = 1; Xanalytic = {X0}; B = {0}; IntB = {0}, i < steps, i++, AppendTo[B, B[[i]] + dB[[i]]];
AppendTo[IntB, IntB[[i]] + Exp[-sigma\*B[[i]] + sigma^2\*i\*(T/steps)/2]\*T/steps];
AppendTo[Xanalytic, Exp[sigma\*B[[i+1]] - sigma^2\*(i+1)\*(T/steps)/2]\*(X0 + IntB[[i+1]])]];
ListPlot[Xanalytic, PlotJoined+True, PlotRange+ {-0.51, 20.1},
Ticks + {{1000, ""}, {2000, "2"}, {3000, ""}, {4000, "4"}, {5000, ""},
{6000, "6"}, {7000, ""}, {8000, "8"}, {9000, ""}, {10000, "10"}, Automatic}]</pre>



Exercise 5. Exercise 4 in Stig Larsson's lecture notes.

**Solution.** In order to prove (37) we note that the first equation in the proof of Theorem 6 holds with T replaced by any  $s \in [t,T]$ . As the expectation of the martingale on the right-hand side of that equation is zero it follows that  $\mathbf{E}\{u(Z(s;x,t),s)\} = \mathbf{E}\{u(Z(t;x,t),t)\}$  for  $s \in [t,T]$ . Recalling that u(Z(t;x,t),t) = u(x,t) since Z(t;x,t) = x is the initial value of the SDE that is posted just before the proof, we arrive at  $\mathbf{E}\{u(Z(s;x,t),s)\} = u(x,t)$  for  $s \in [t,T]$  [which is the version of (37) we prove].

Exercise 6. Exercise 5 in Larsson's lecture notes.

**Solution.** This follows in the following elementary fashion from integration by parts together with the fact that the functions  $\phi$  and  $\psi$  involved have compact support in  $\mathbb{R} \times (0,T)$  [that is, they are zero outside a closed and bounded set in  $\mathbb{R} \times (0,T)$ ]:

$$\begin{split} &\int_0^T \int_{-\infty}^\infty (L\phi(x,t)) \, \psi(x,t) \, dxdt \\ &= \int_0^T \int_{-\infty}^\infty \left( \frac{\partial \phi(x,t)}{\partial t} + \frac{\partial}{\partial x} \left( \mu(x,t) \phi(x,t) \right) - \frac{\partial^2}{\partial x^2} \frac{\sigma(x,t)^2 \phi(x,t)}{2} \right) \psi(x,t) \, dxdt \\ &= \int_{-\infty}^\infty \left[ \phi(x,t) \psi(x,t) \right]_{t=0}^{t=T} dx - \int_{-\infty}^\infty \int_0^T \phi(x,t) \, \frac{\partial \psi(x,t)}{\partial t} \, dtdx \\ &+ \int_0^T \left[ \mu(x,t) \phi(x,t) \psi(x,t) \right]_{x=-\infty}^{x=\infty} dt - \int_0^T \int_{-\infty}^\infty \mu(x,t) \phi(x,t) \, \frac{\partial \psi(x,t)}{\partial x} \, dxdt \\ &- \int_0^T \left[ \left( \frac{\partial}{\partial x} \frac{\sigma(x,t)^2 \phi(x,t)}{2} \right) \psi(x,t) \right]_{x=-\infty}^{x=\infty} dt + \int_0^T \int_{-\infty}^\infty \left( \frac{\partial}{\partial x} \frac{\sigma(x,t)^2 \phi(x,t)}{2} \right) \frac{\partial \psi(x,t)}{\partial x} \, dxdt \\ &= 0 - \int_{-\infty}^\infty \int_0^T \phi(x,t) \, \frac{\partial \psi(x,t)}{\partial t} \, dtdx \\ &+ 0 - \int_0^T \int_{-\infty}^\infty \phi(x,t) \, \mu(x,t) \frac{\partial \psi(x,t)}{\partial x} \, dxdt \\ &- 0 + \int_0^T \left[ \frac{\sigma(x,t)^2 \phi(x,t)}{2} \, \frac{\partial \psi(x,t)}{\partial x} \right]_{x=-\infty}^{x=\infty} dt - \int_0^T \int_{-\infty}^\infty \frac{\sigma(x,t)^2 \phi(x,t)}{2} \, \frac{\partial^2 \psi(x,t)}{\partial x^2} \, dxdt \\ &= \int_0^T \int_{-\infty}^\infty \phi(x,t) \left( -\frac{\partial \phi(x,t)}{\partial t} - \mu(x,t) \frac{\partial \psi(x,t)}{\partial x} - \frac{\sigma(x,t)^2}{2} \, \frac{\partial^2 \psi(x,t)}{\partial x^2} \right) dxdt \\ &= \int_0^T \int_{-\infty}^\infty \phi(x,t) \left( L^* \psi(x,t) \right) dxdt. \end{split}$$

Note that it is enough to require that one of the functions  $\phi$  and  $\psi$  have compact support for the proof above to work: This will be important in the next exercise.

Exercise 7. Exercise 6 in Larsson's lecture notes.

**Solution.** Using (39) and (40) we shall prove that u(x,t) given by (38) solves (34). [Note that Theorem 6 ensures that solutions to (34) are unique when they exist.] First note that (40) ensures that the terminal value u(x,T) is g(x) as required. In the language of Exercise 5 in Larsson's lecture notes we shall prove that  $L^*u(x,t) = 0$  for u(x,t) given by (38). To that end we note that Exercise 5 in Larsson's lecture notes shows that for any function  $\phi(x,t)$  that has compact support and satisfies  $L\phi(x,t) = 0$  we have

$$\begin{split} \int_0^T & \int_{-\infty}^\infty \phi(x,t) \left( L^\star u(x,t) \right) dx dt = \int_{-\infty}^\infty \int_0^T \int_{-\infty}^\infty \phi(x,t) \left( L^\star p(y,T,x,t) g(y) \right) dx dt dy \\ & = \int_{-\infty}^\infty \int_0^T \int_{-\infty}^\infty \left( L \phi(x,t) \right) p(y,T,x,t) g(y) \, dx dt dy \\ & = 0. \end{split}$$

Assuming that the space of functions  $\phi(x,t)$  with compact support that satisfy  $L\phi(x,t)$  = 0 is rich enough, this proves that  $L^*u(x,t) = 0$ .