## TMS165/MSA350 Stochastic Calculus

## Written Exam Tuesday 27 October 2015 8.30–12.30 am

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AIDS: Two sheets (=four pages) of hand-written notes (computer print-outs and/or xerox-copies are not allowed).

GRADES: 12 points (40%) for grades 3 and G, 18 points (60%) for grade 4, 21 points (70%) for grade VG and 24 points (80%) for grade 5, respectively.

MOTIVATIONS: All answers/solutions must be motivated.

Througout this exam  $B = \{B(t)\}_{t \ge 0}$  denotes a Brownian motion. AND GOOD LUCK!

**Task 1.** Explain how one can actually construct a unit mean exponentially distributed random variable  $X : \Omega \to \mathbb{R}$  on a sample space  $\Omega$  with a probability measure **P** (such that  $\mathbf{P}\{X \le x\} = 1 - e^{-x}$  for  $x \ge 0$ ). (5 points)

**Task 2.** Show that  $\int_0^t B(u) du - \frac{1}{3}B(t)^3$  is a martingale. (5 points)

Task 3. State and prove the isometry property of the Itô integral of simple adapted processes. (5 points)

**Task 4.** Find 
$$X(t)$$
 if  $d(e^{B(t)}) = e^{B(t)} dX(t)$  and  $X(0) = 0$ . (5 points)

**Task 5.** Given real numbers  $\sigma$ ,  $\mu$  and r, find the solution f(x,t) to the PDE  $\frac{\partial f(x,t)}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 f(x,t)}{\partial x^2} + \mu \frac{\partial f(x,t)}{\partial x} = rf(x,t) \text{ for } t \in [0,T], \quad f(x,T) = x^2.$ (5 points)

**Task 6.** The explicit Euler method for finding a numerical solution  $\hat{X}(t)$  to the SDE

$$dX(t) = \mu(X(t), t) dt + \sigma(X(t), t) dB(t) \text{ for } t \in (0, T], \quad X(0) = x_0,$$

based on iteration over the grid  $0 = t_0 < t_1 < \ldots < t_n = T$  goes like  $\hat{X}(t_0) = x_0$  and

$$\hat{X}(t_i) - \hat{X}(t_{i-1}) = \mu(\hat{X}(t_{i-1}), t_{i-1}) \left( t_i - t_{i-1} \right) + \sigma(\hat{X}(t_{i-1}), t_{i-1}) \left( B(t_i) - B(t_{i-1}) \right)$$

for i = 1, ..., n. The fully implicit Euler method for the same task uses  $\mu(\hat{X}(t_i), t_i)$ and  $\sigma(\hat{X}(t_i), t_i)$  instead of  $\mu(\hat{X}(t_{i-1}), t_{i-1})$  and  $\sigma(\hat{X}(t_{i-1}), t_{i-1})$  above (and is typically much more "stable"): Explain why the implicit method is not just as simple as

$$\hat{X}(t_{i}) - \hat{X}(t_{i-1}) = \mu(\hat{X}(t_{i}), t_{i}) (t_{i} - t_{i-1}) + \sigma(\hat{X}(t_{i}), t_{i}) (B(t_{i}) - B(t_{i-1})) \quad \text{for } i = 1, \dots, n,$$
  
but requires more modifications then just replacing  $(\hat{X}(t_{i-1}), t_{i-1})$  with  $(\hat{X}(t_{i-1}), t_{i-1})$ 

but requires more modifications than just replacing  $(X(t_{i-1}), t_{i-1})$  with  $(X(t_i), t_i)$  at two locations. (5 points)

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## Solutions to Written Exam 27 October 2015

**Task 1.** Take  $\Omega = [0, \infty)$ ,  $X(\omega) = \omega$  for  $\omega \in \Omega$  and  $\mathbf{P}\{[a, b]\} = \int_a^b e^{-y} dy$  for  $[a, b] \subseteq \Omega$  to obtain  $\mathbf{P}\{X \le x\} = \mathbf{P}\{\omega \in \Omega : X(\omega) \le x\} = \mathbf{P}\{\omega \le x\} = \mathbf{P}\{[0, x]\} = 1 - e^{-x}$ .

**Task 2.** By Itô's formula we have  $d\left(\int_0^t B(u) \, du - \frac{1}{3}B(t)^3\right) = B(t) \, dt - B(t)^2 \, dB(t) - B(t) \, dt = -B(t)^2 \, dB(t)$ , so that  $\int_0^t B(u) \, du - \frac{1}{3}B(t)^3 = -\int_0^t B(u)^2 \, dB(u)$  which is a martingale since  $-B^2 \in E_T$  for any  $T \ge 0$ .

**Task 3.** This is Property 4 of the properties of the Itô integral of simple adapted processes listed on pages 93-94 in Klebaner's book: See the proof of that property on pages 94-95 in Klebaner's book.

**Task 4.** As X(t) is the stochastic logarithm of  $e^{B(t)}$ , we have  $X(t) = \ln \left( e^{B(t)} / e^{B(0)} \right) + \int_0^t d(e^{B(s)})^2 / (2 (e^{B(s)})^2) = B(t) + \int_0^t ds / 2 = B(t) + t/2.$ 

**Task 5.** Feynman-Kac formula gives  $f(x,t) = \mathbf{E} \{ e^{-r(T-t)} X(T)^2 | X(t) = x \}$ , where X(t) solves the SDE  $dX(t) = \mu dt + \sigma dB(t)$ , so that  $X(t) = X(0) + \mu t + \sigma B(t)$  and  $X(T) = X(t) + \mu (T-t) + \sigma (B(T) - B(t))$ , giving  $f(x,t) = e^{-r(T-t)} (\sigma^2 (T-t) + (\mu (T-t) + x)^2)$ .

**Task 6.** The reason is that  $\sum_{i=1}^{n} \left( \sigma(X(t_i), t_i) - \sigma(X(t_{i-1}), t_{i-1}) \right) \left( B(t_i) - B(t_{i-1}) \right) \rightarrow [\sigma(X(t), t), B(t)] = \int_{0}^{t} d[\sigma(X(s), s), B(s)] = \int_{0}^{t} d\sigma(X(s), s) \, dB(s) = \int_{0}^{t} \left( \sigma'_{x}(X(s), s) \, dX(s) + \frac{1}{2} \sigma''_{xx}(X(s), s) \, d[X, X](s) + \sigma'_{t}(X(s), s) \, ds \right) \, dB(s) = \int_{0}^{t} \sigma'_{x}(X(s), s) \sigma(X(s), s) \, dB(s)^{2} = \int_{0}^{t} \sigma'_{x}(X(s), s) \sigma(X(s), s) \, ds$  is not zero (in general).