

Numerical Lecture Notes

Thm

Let \bar{X} and \hat{X} be solutions to SDE with initial values X_0 and \hat{X}_0 . Then for $C = C(L, T)$

$$E \left(\max_{0 \leq t \leq T} |\hat{X}(t) - X(t)|^2 \right) \leq C E(|\hat{X}_0 - X_0|^2).$$

Proof

$$\phi(t) = E \left(\max_{0 \leq s \leq t} |\hat{X}(s) - X(s)|^2 \right)$$

$$= E \left(\max_{0 \leq s \leq t} \left| \hat{X}_0 - X_0 + \int_0^s [u(\hat{X}(r), r) - u(X(r), r)] dr + \int_0^s [\sigma(\hat{X}(r), r) - \sigma(X(r), r)] dB(r) \right|^2 \right)$$

$$\leq 3E(|\hat{X}_0 - X_0|^2) + 3E \left(\max_{0 \leq s \leq t} \left| \int_0^s (\hat{u} - u) dr \right|^2 \right) + 3E \left(\max_{0 \leq s \leq t} \left| \int_0^s (\hat{\sigma} - \sigma) dB \right|^2 \right)$$

$$\stackrel{\text{Cauchy-Schwarz}}{\leq} 3E(|\hat{X}_0 - X_0|^2) + 3E \left(\max_{0 \leq s \leq t} \int_0^s |\hat{u}'|^2 dr \int_0^s (\hat{u} - u)^2 dr \right) + 12E \left(\int_0^t (\hat{\sigma}' - \sigma') dB dr \right)^2$$

$$\stackrel{\text{Isometry}}{\leq} 3E(|\hat{X}_0 - X_0|^2) + 3E \left(\int_0^t (\hat{u}' - u')^2 dr \right) + 12E \left(\int_0^t (\hat{\sigma}' - \sigma')^2 dr \right)$$

$$\stackrel{\text{Lipschitz}}{\leq} 3E(|\hat{X}_0 - X_0|^2) + 3TL^2 \int_0^t E((\hat{X}(r) - X(r))^2) dr + 12L^2 \int_0^t E((\hat{\sigma}(r) - \sigma(r))^2) dr$$

$$\leq 3E(|\hat{X}_0 - X_0|^2) + (3TL^2 + 12L^2) \int_0^t \phi(r) dr \stackrel{\text{Grönwall}}{\Rightarrow}$$

$$\phi(t) \leq 3E(|\hat{X}_0 - X_0|^2) e^{(3TL^2 + 12L^2)t} \quad \begin{aligned} & \text{for } t \in [0, T] \\ & \text{finish by taking } t = T. \end{aligned}$$

Thm

For $C = C(L, T)$ we have

$$E(|X(t) - X(s)|^2) \leq C (1 + E(X_0^2)) |t-s| \quad \text{for } s, t \in [0, T].$$

N.2

[Proof]

$$E(|X(t) - X(s)|^2) = E\left(\left|\int_s^t \mu(X(r), r) dr + \int_s^t \sigma(X(r), r) dB(r)\right|^2\right)$$

$$\left[\leq \frac{(x+y)^2}{2x^2+2y^2}\right] \leq 2E\left(\left(\int_s^t \mu dr\right)^2\right) + 2E\left(\left(\int_s^t \sigma dB\right)^2\right)$$

$$\left[\text{Cauchy-Schwarz}^2 \text{ isometry}\right] \leq 2 \int_s^t 1^2 dr \int_s^t E(\mu^2) dr + 2E\left(\int_s^t \sigma^2 dr\right)$$

$$\left[\text{linear growth}\right] \leq 4(t-s) \int_s^t L^2 E(1^2 + |X(r)|^2) dr + 4 \int_s^t L^2 E(1^2 + |X(r)|^2) dr$$

$$\left[\text{Theorem 1} \atop \text{Stig's notes}\right] \leq 4(T-s) L^2 (1 + C(1 + E(X_0^2))(T-s))$$

[Notation]

$$0 = t_0 < t_1 < \dots < t_N = T, h_n = t_{n+1} - t_n, \Delta B_n = B(t_{n+1}) - B(t_n)$$

$$X(t_{n+1}) = X(t_n) + \int_{t_n}^{t_{n+1}} \mu(X(s), s) ds + \int_{t_n}^{t_{n+1}} \sigma(X(s), s) dB(s), X(0) = X_0$$

$$\begin{aligned} Y_{n+1} &= Y_n + \mu(Y_n, t_n) \int_{t_n}^{t_{n+1}} ds + \sigma(Y_n, t_n) \int_{t_n}^{t_{n+1}} dB(s) \\ &= Y_n + \mu(Y_n, t_n) h_n + \sigma(Y_n, t_n) \Delta B_n, Y_0 \approx X_0 \end{aligned}$$

$$Y(t) = Y_0 + \int_0^t \bar{\mu}(s) ds + \int_0^t \bar{\sigma}(s) dB(s) \text{ satisfies } Y(t_n) = Y_n \text{ for}$$

$$\bar{\mu}(s) = \mu(Y_n, t_n) \text{ and } \bar{\sigma}(s) = \sigma(Y_n, t_n) \text{ for } s \in [t_n, t_{n+1}],$$

[Thm]

IF $E(|Y_0 - X_0|^2) \leq kh$ and $E(X_0^2) \leq M$ then

$$E\left(\max_{0 \leq t \leq T} |Y(t) - X(t)|^2\right) \leq Ch$$

Proof

$$\phi(t) = E \left(\max_{0 \leq s \leq t} |Y(s) - X(s)|^2 \right)$$

$$\left[\frac{(x+y+z)^2}{\leq 3(x+y+z)^2} \right] \leq 3E((Y_0 - X_0)^2) + 3E \left(\max_{0 \leq s \leq t} \left(\int_0^s (\bar{u}(r) - u(r)) dr \right)^2 \right) + 3E \left(\max_{0 \leq s \leq t} \left(\int_0^s (\bar{\sigma}(r) - \sigma(r)) dB(r) \right)^2 \right)$$

$$\left[\begin{array}{l} \text{Cauchy-Schwarz} \\ \text{Doob} \end{array} \right] \leq 3Kh + 3 \int_0^t \int_0^s |u(r) - u(H)|^2 dr ds + 12E \left(\int_0^t (\bar{\sigma}(r) - \sigma(r)) dB(r) \right)^2$$

$$\left[\text{Isometry} \right] \leq 3Kh + 3T \int_0^t E((\bar{u}(r) - u(r))^2) dr + 12 \int_0^t E((\bar{\sigma}(r) - \sigma(r))^2) dr = (*)$$

$$E(\bar{u}(s) - u(s))^2 \leq 2E(|u(s) - u(X(s), t_n)|^2) + 2E(|u(X(s), t_n) - u(X(s), s)|^2)$$

$$\leq 2L^2 E(|Y(t_n) - X(s)|^2) + 2L^2 |t_n - s|^2$$

$$\leq 4L^2 E(|Y(t_n) - X(t_n)|^2) + 4L^2 E(|X(t_n) - X(s)|^2) + 2L^2 h_n^2$$

$$\leq 4L^2 E \left(\max_{0 \leq s \leq s} |Y(s) - X(s)|^2 \right) + \underbrace{4L^2 C h_n}_{} + 2L^2 h_n^2 \quad \text{for } s \in [t_n, t_{n+1}]$$

$$\leq \epsilon h_n \leq Ch$$

We get same with other constants for $E((\bar{\sigma}(s) - \sigma(s))^2)$
and so we have

$$\phi(t) = Ch + \int_0^t \phi(s) ds \quad \text{for } t \in [0, T] \text{ so that}$$

$$\phi(t) = Ch e^{Bt} \quad \text{for } t \in [0, T].$$

Ito-Taylor expansion

N.4

$$dX(t) = u(X(t), t) dt + \sigma(X(t), t) dB(t)$$

$$X(t) = X(t_0) + \int_{t_0}^t u(X(s), s) ds + \int_{t_0}^t \sigma(X(s), s) dB(s) \quad (*)$$

$$f(X, s) = f(X(t_0), t_0) + \int_{t_0}^s f'_x(X(r), r) [u(X(r), r) dr + \sigma(X(r), r) dB(r)]$$

$$+ \int_{t_0}^s \frac{1}{2} f''_{xx}(X(r), r) \sigma(X(r), r)^2 dr + \int_{t_0}^s F'_x(X(r), r) dr \quad (**)$$

Using $(**)$ with $f(x, t) = u(x, t)$ and $f'(x, t) = \sigma(x, t)$ in $(*)$ gives

$$\begin{aligned} \underline{\underline{X(t)}} &= \underline{\underline{X(t_0)}} + \underline{(t - t_0)} \underline{u(X(t_0), t_0)} + \int_{t_0}^t \int_{t_0}^s u'_x(X(r), r) u(X(r), r) dr ds \\ &\quad + \int_{t_0}^t \int_{t_0}^s u'_x(X(r), r) \sigma(X(r), r) dr ds + \int_{t_0}^t \int_{t_0}^s \frac{1}{2} u''_{xx}(X(r), r) \sigma(X(r), r)^2 dr ds \\ &\quad + \int_{t_0}^t \int_{t_0}^s u'_x(X(r), r) dr ds + \underline{(B(t) - B(t_0)) \sigma(X(t_0), t_0)} \\ &\quad + \int_{t_0}^t \int_{t_0}^s \sigma'_x(X(r), r) u(X(r), r) dr dB(s) + \int_{t_0}^t \int_{t_0}^s \sigma'_x(X(r), r) \sigma(X(r), r) dB(r) dB(s) \\ &\quad + \int_{t_0}^t \int_{t_0}^s \frac{1}{2} \sigma''_{xx}(X(r), r) \sigma(X(r), r)^2 dr dB(s) + \int_{t_0}^t \int_{t_0}^s \sigma'^0_x(X(r), r) dr dB(s) \end{aligned}$$

The underlined — parts of above make up the motivation for the Euler (Maruyama) method for numerical approximative solution of the SDE. By adding the ~~numerical~~ part similarly approximated by

$$(\sigma'_x \sigma)(X(t_0), t_0) \int_{t_0}^t \int_{t_0}^s dB(r) dB(s) = (\sigma'_x \sigma)(X(t_0), t_0) \int_{t_0}^t (B(s) - B(t_0)) dB(s)$$

$$= (\sigma'_x \sigma)(X(t_0), t_0) \left(\frac{1}{2} (B(t)^2 - B(t_0)^2 - (t - t_0) - B(t_0)(B(t) - B(t_0))) \right) = (\sigma'_x \sigma)(X(t_0), t_0) \left(\frac{1}{2} (B(t) - B(t_0))^2 - \frac{1}{2} (t - t_0) \right)$$

we get the most used higher-order Milstein method.

Weak numerical solutions

N.5

In a strong solution one is given $u(x,t)$, $\sigma(x,t)$ and $B(t)$ and should use them to manufacture $X(t)$.

In a weak solution one is given $u(x,t)$, $\sigma(x,t)$ and should use them to manufacture $B(t)$ and $X(t)$.

In theory the difference is bigger than it may seem in practice. There exist SDE which has unique weak solution but no strong solution, e.g., Tanaka SDE
 $dX(t) = \text{sign}(X(t)) dB(t)$.

Uniqueness of strong solution means

$$P(X_1(t) = X_2(t)) = 1 \text{ for all solutions } X_1(t) \text{ and } X_2(t)$$

Uniqueness of weak solution means

$$F_{X_1(t_1), \dots, X_n(t_n)}(x_1, \dots, x_n) = F_{X_2(t_1), \dots, X_n(t_n)}(x_1, \dots, x_n).$$

The numerical methods we have seen so far are strong numerical methods in the sense that if we are given $u(x,t)$, $\sigma(x,t)$ and $B(t)$ we can plug in them in method and get $X(t)$ - example Euler, implicit Euler, Milstein.

When we use this methods in computer no one gives us $B(t)$ so we still create $B(t)$ ourselves to get going.

Example (Langevin equation) $dX(t) = -\alpha X(t) dt + \sigma dB(t)$

$$\text{Euler method } Y_{n+1} = Y_n - \alpha Y_n (t_{n+1} - t_n) + \sigma (B(t_{n+1}) - B(t_n))$$

is used in applied lecture. Exact solution is

$$X(t) = e^{-\alpha t} \left(X_0 + \int_0^t \sigma e^{\alpha r} dB(r) \right)$$

which gives

$$X(t) = e^{-\alpha(t-s)} X(s) + \underbrace{e^{-\alpha t} \int_s^t \sigma e^{\alpha r} dB(r)}_{N(0, \frac{\sigma^2}{2\alpha} (1 - e^{-2\alpha(t-s)}))}$$

$$f_{X(t)|X(s)}(y|x) = \frac{1}{\sqrt{2\pi} \frac{\sigma^2}{2\alpha} (1 - e^{-2\alpha(t-s)})} e^{-\frac{(y - e^{-\alpha(t-s)} X(s))^2}{\frac{\sigma^2}{2\alpha} (1 - e^{-2\alpha(t-s)})}}$$

so we can create an exact weak solution at times $0 = t_0 < t_1 < \dots < t_N = T$ by doing

$$X(t_{n+1}) = e^{-\alpha(t_{n+1}-t_n)} X(t_n) + NID(0, \frac{\sigma^2}{2\alpha} (1 - e^{-2\alpha(t_{n+1}-t_n)}))$$

$$n = 0, \dots, N-1, \quad X(0) = x_0$$

We cannot do an exact theoretical solution in

N.7

reality because we cannot calculate

$$\int_0^t e^{\int_s^t dB(u)} \text{ exactly!}$$

Remember that solution to SDE are Markov processes. Their transition probability densities

$$p(y, t, x, s) = f_{X(t) | X(s)}(y | x)$$

satisfy the Kolmogorov backward PDE

$$u(x, s) \frac{\partial p}{\partial x} + \frac{\sigma(x, s)^2}{2} \frac{\partial^2 p}{\partial x^2} + \frac{\partial p}{\partial s} = 0$$

and by solving that PDE for a $p(y, t, x, s)$ that satisfies

$$\lim_{s \rightarrow -\infty} \int_{-\infty}^{+\infty} g(y) p(y, t, x, s) dy = g(x)$$

for smooth $g(x)$ one can find $p(y, t, x, s)$.

But given an OK family of transition PDF there exists a Markov process that uses these transition PDF's and that Markov process is weak solution to SDE.

One can create an exact weak solution by the recursive scheme

Simulate $\underline{X}(t_{n+1})$ with PDF $p(\cdot, t_{n+1}, \underline{X}(t_n), t_n)$
for $n=0, \dots, N-1$,

$$\underline{X}(0) = \underline{x}_0$$

To create a exact weak solution
is in principle same as finding the
Markov transition density.

And a numerical weak scheme
same as approximating the
Markov transition density.

The Euler method

$$\underline{Y}_{n+1} = \underline{Y}_n + u(\underline{Y}_n, t_n)(t_{n+1} - t_n) + \sigma(\underline{Y}_n, t_n)(B(t_{n+1}) - B(t_n))$$

we have seen has strong convergence

$$\sqrt{E(\max_{0 \leq n \leq N} |\underline{Y}_n - \underline{X}(t_n)|^2)} \leq Ch^{1/2} \text{ for } h = \max_{0 \leq n \leq N-1} t_{n+1} - t_n$$

so

$$E(\max_{0 \leq n \leq N} |\underline{Y}_n - \underline{X}(t_n)|) \leq \sqrt{E(\max_{0 \leq n \leq N} |\underline{Y}_n - \underline{X}(t_n)|^2)} \leq Ch^{1/2}$$

But if we use same Euler method
to just approximate $g(\underline{X}(t))$ with $g(\underline{Y}_N)$

$$\text{we have } |E(g(\underline{Y}_N)) - E(g(\underline{X}(t)))| \leq ch$$

N.9

The proof of this uses some quite difficult PDE techniques.

If we want to find $E(g(\underline{x}(t)))$ in reality we have to generate many independent observations $\{g(\underline{y}_N^{(i)})\}_{i=1}^n$ of $g(\underline{y}_N)$ and then use Monte Carlo

$$E(g(\underline{x}(t))) \approx E(g(\underline{y}_N)) \approx \frac{1}{n} \sum_{i=1}^n g(\underline{y}_N^{(i)}).$$