

Lecture 3: Method evaluation and tuning parameter selection

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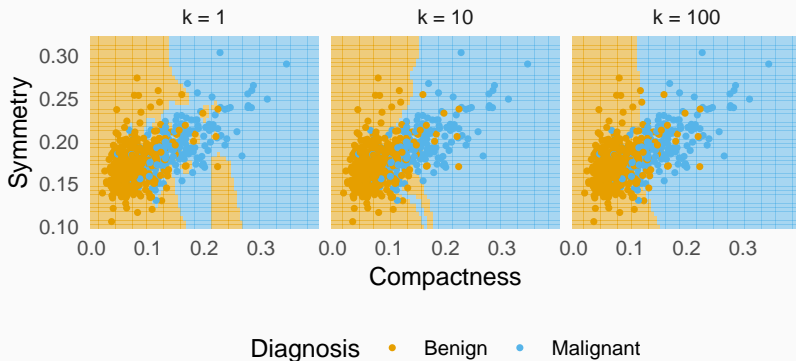
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Evaluating performance of a statistical method

Goals

- ▶ **Model selection:** Choose a hyper-parameter or model structure, e.g. k in kNN regression/classification, or “Choose between logistic regression, LDA and kNN”
- ▶ **Model assessment:** How well did a model do on a data set?

How to choose the best k for kNN?



- ▶ UCI breast cancer wisconsin (diagnostic) data set¹
- ▶ Which k will do **best for class prediction** of new data?

¹[https://archive.ics.uci.edu/ml/datasets/Breast+Cancer+Wisconsin+\(Diagnostic\)](https://archive.ics.uci.edu/ml/datasets/Breast+Cancer+Wisconsin+(Diagnostic))

Error rates (I)

- ▶ **Remember:** To determine the optimal regression function or classifier we looked at expected prediction loss

$$J(f) = \mathbb{E}_{p(\mathbf{x},y)} [L(y, f(\mathbf{x}))]$$

Note that f was thought to be an arbitrary unknown function.

- ▶ **Now:** f is estimated from data under some model assumption
- ▶ The resulting regressor/classifier $\hat{f}(\cdot|\mathcal{T})$ is fixated after estimation but dependent on the training samples \mathcal{T}
- ▶ **Expected prediction error for a fixed training set \mathcal{T}**

$$R(\mathcal{T}) = \mathbb{E}_{p(\mathbf{x},y)} [L(y, \hat{f}(\mathbf{x}|\mathcal{T}))]$$

- ▶ **Conditional expected prediction error** for a fixed training set \mathcal{T}

$$R(\mathcal{T}) = \mathbb{E}_{p(\mathbf{x},y)} [L(y, \hat{f}(\mathbf{x}|\mathcal{T}))]$$

- ▶ Training samples are random too!
- ▶ **Total expected prediction error**

$$R = \mathbb{E}_{p(\mathcal{T})} [R(\mathcal{T})] = \mathbb{E}_{p(\mathcal{T})} [\mathbb{E}_{p(\mathbf{x},y)} [L(y, \hat{f}(\mathbf{x}|\mathcal{T}))]]$$

▶ Training error

$$R^{tr} = \frac{1}{n} \sum_{l=1}^n L(y_l, \hat{f}(\mathbf{x}_l | \mathcal{T}))$$

where

$$\mathcal{T} = \{(y_l, \mathbf{x}_l) : 1 \leq l \leq n\}$$

▶ Test error

$$R^{te} = \frac{1}{m} \sum_{l=1}^m L(\tilde{y}_l, \hat{f}(\tilde{\mathbf{x}}_l | \mathcal{T}))$$

where $(\tilde{y}_l, \tilde{\mathbf{x}}_l)$ for $1 \leq l \leq m$ are new samples from the same distribution as \mathcal{T} , i.e. $p(\mathcal{T})$.

Empirical error rates (II)

Can we directly use these empirical rates and approximate total or conditional expected prediction error?

Observations:

- ▶ \mathcal{T} has already been used to determine $\hat{f}(\cdot|\mathcal{T})$ and usually methods aim to minimize training error
- ▶ Training error is often smaller for more complex models (so-called **optimism of the training error**) since they can adjust better to the available data (**overfitting!**)
- ▶ How do we get new samples from the data distribution $p(\mathcal{T})$? What do we do if all we have is the training sample?

Splitting up the data

- ▶ **Holdout method:** If we have a lot of samples, **randomly split** available data into **training set** and **test set**
- ▶ **c -fold cross-validation:** If we have few samples
 1. **Randomly split** available data into c equally large subsets, so-called **folds**.
 2. By taking turns, use $c - 1$ folds as the **training set** and the last fold as the **test set**

Approximations of expected prediction error

- ▶ Use **test error** for hold-out method, i.e.

$$R^{te} = \frac{1}{m} \sum_{l=1}^m L(\tilde{y}_l, \hat{f}(\tilde{\mathbf{x}}_l | \mathcal{T}))$$

where $(\tilde{y}_l, \tilde{\mathbf{x}}_l)$ for $1 \leq l \leq m$ are the elements in the test set.

- ▶ Use average **test error** for c-fold cross-validation, i.e.

$$R^{cv} = \frac{1}{n} \sum_{j=1}^c \sum_{(y_l, \mathbf{x}_l) \in \mathcal{F}_j} L(y_l, \hat{f}(\mathbf{x}_l | \mathcal{F}_{-j}))$$

where \mathcal{F}_j is the j -th fold and \mathcal{F}_{-j} is all data except fold j .

Careful data splitting

- ▶ **Note:** For the approximations to be justifiable, test and training sets need to be identically distributed
- ▶ **Splitting has to be done randomly**
- ▶ If data is unbalanced, then **stratification** is necessary.
Examples:
 - ▶ Class imbalance
 - ▶ Continuous outcome is observed more often in some intervals than others (e.g. high values more often than low values)

Error estimation and tuning parameters

The holdout method and cross-validation can be used to determine tuning parameters.

1. For a sequence of tuning parameters $\lambda_1, \dots, \lambda_S$ calculate

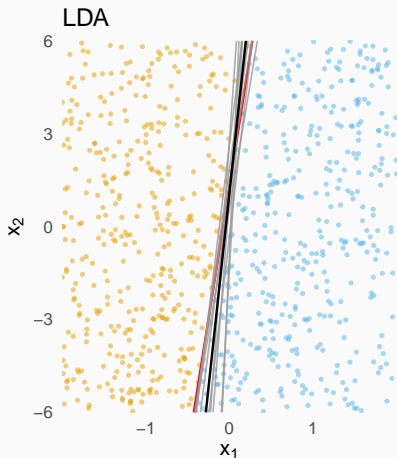
$$R^{cv}(\lambda_s) = \frac{1}{n} \sum_{j=1}^c \sum_{(y_l, \mathbf{x}_l) \in \mathcal{F}_j} L(y_l, \hat{f}(\mathbf{x}_l | \lambda_s, \mathcal{F}_{-j}))$$

2. Choose

$$\hat{\lambda} = \arg \min_{\lambda_s} R^{cv}(\lambda_s)$$

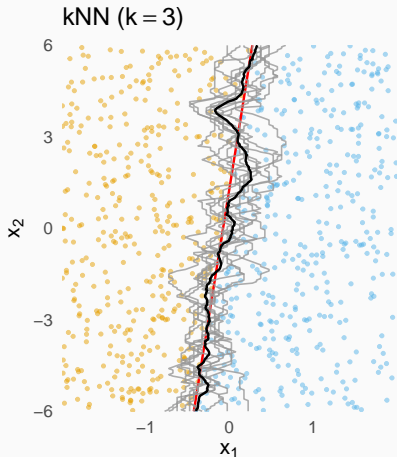
Also works for a sequence of methods M_1, \dots, M_S (e.g. kNN, QDA, Logistic Regression)

Global rule & Simple boundary



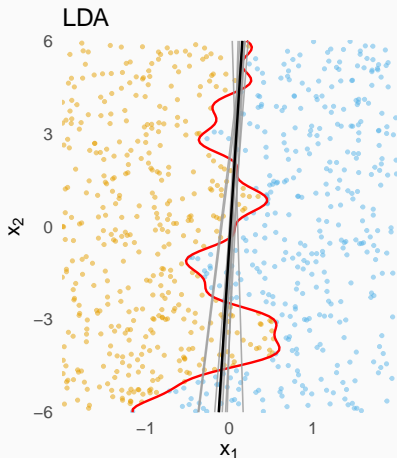
- ▶ The **red** line is the true boundary.
- ▶ Each grey line represents a fit to randomly chosen 20% of all data.
- ▶ The black line is the average of the grey lines.
- ▶ Here: **low variance** and **low bias**

Local rule & Simple boundary



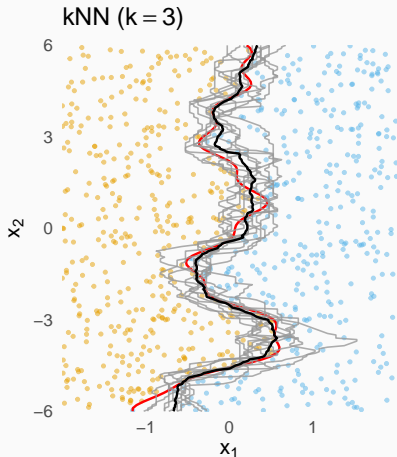
- ▶ Here: **high variance** but on average **low bias**

Global rule & Complex boundary



- ▶ Here: **low variance** but also **large bias**

Local rule & Complex boundary



- ▶ Here: **high variance** but on average **low bias**

Observations

- ▶ **Local rules** are built using data in a local neighbourhood, can capture complex boundaries, but have high variance
- ▶ **Global rules** are built using all data, are usually less flexible, but have low variance
- ▶ **Bias-Variance Trade-off**: It can be theoretically motivated that bias and variance affect the expected prediction error. **The goal is to find a balance.**

Performance of LDA vs KNN

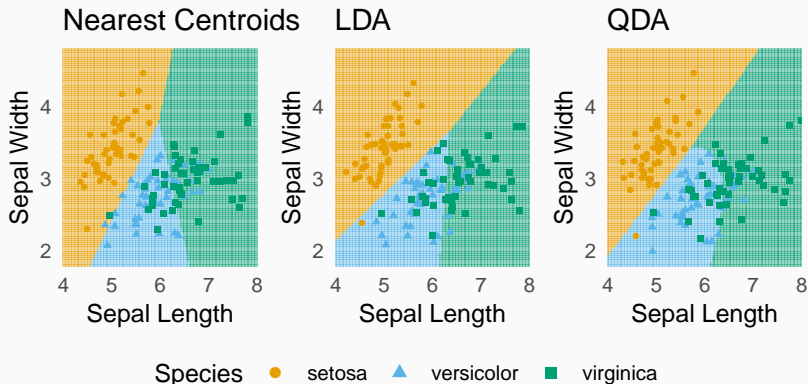
Table 1: Average cross-validation errors for ten folds

	Boundary	
	simple	complex
LDA	0.011	0.092
kNN (k = 3)	0.018	0.021

LDA does better for simple boundaries, while kNN has an advantage for more complicated boundaries.

Choosing a classification method (I)

Remember: We looked at different classification methods for solving the same classification problem



Choosing a classification method (II)

Table 2: Average cross-validation errors for ten folds

NC	LDA	QDA
0.193	0.2	0.22

Quality of a classification result

How to quantify classification quality, When we receive a classification result from our classifier?

Setting:

- ▶ Language/notation comes from medical studies where the presence or absence of a disease/condition is determined
- ▶ Binary classification with classes 0 and 1
- ▶ 0s are interpreted as **negative outcomes** (e.g. not sick = healthy individual) and 1s are interpreted as **positive outcomes** e.g. sick individuals

Confusion matrix

Table 3: Confusion matrix

Predicted class	True class	
	Positive	Negative
Positive	True Positive (TP)	False Positive (FP)
Negative	False Negative (FN)	True Negative (TN)

Measures of classification quality

- ▶ **Accuracy:** $\frac{TP + TN}{TP + FP + FN + TN}$
- ▶ **Precision:** $\frac{TP}{TP + FP}$
- ▶ **Sensitivity/True positive rate (TPR)/Recall:** $\frac{TP}{TP + FN}$
- ▶ **Specificity:** $\frac{TN}{TN + FP}$
- ▶ **False positive rate (FPR)/fall out:** 1 - Specificity

Combined measures

▶ **F_1 score** = $2 \cdot \frac{\text{Precision} \cdot \text{Recall}}{\text{Precision} + \text{Recall}}$

- ▶ **Matthew's correlation coefficient:**

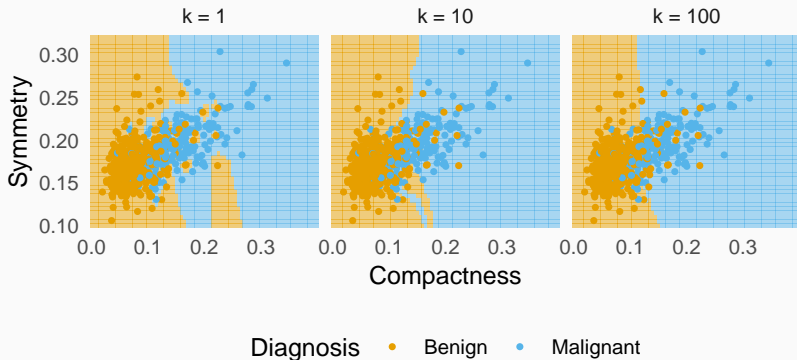
$$MCC = \frac{TP \cdot TN - FP \cdot FN}{\sqrt{(TP + FP)(TP + FN)(TN + FP)(TN + FN)}} \in (-1, 1)$$

where $MCC = 0$ for a random classifier and $MCC < 0$ if worse than random and $MCC > 0$ if better than random. Takes both classes into account.

- ▶ **Receiver Operating Characteristic (ROC) curve:** Trade-off between FPR and TPR. Equal for a random classifier, $TPR < FPR$ for a worse than random classifier and $FPR > TPR$ is better than random
- ▶ **Area under the ROC curve (AUC):** 0.5 for a random classifier and > 0.5 for better classifiers. Maximum 1.

How to choose the best k for kNN? (revisited, I)

Reminder: This motivated our discussion



How to choose the best k for kNN? (revisited, II)

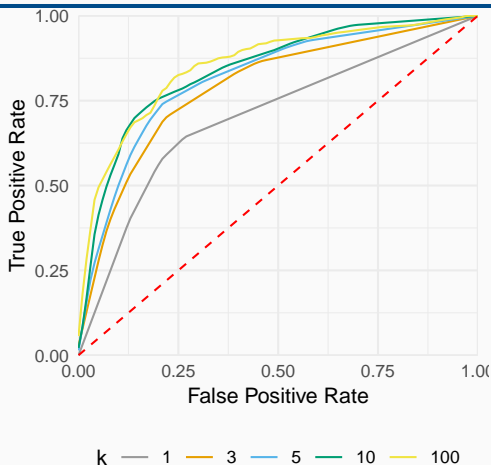


Table 4: Average training and cross-validation errors for five folds

k	R^{tr}	R^{cv}
1	0.000	0.276
3	0.137	0.243
5	0.160	0.228
10	0.182	0.204
100	0.204	0.207

$k = 100$ leads to the best measurable results. Judging from the plots for $k = 1$, $k = 10$ and $k = 100$, kNN is trying to approximate a linear decision boundary and “tries to become a global method”.

Take-home message

- ▶ Cross-validation or splitting data into a training and test set are valuable approaches for model selection and model assessment
- ▶ Method complexity and global/local rules exhibit a bias-variance trade-off
- ▶ There is no single best measurement of classification quality, use multiple!