

Hidden Markov Models for precipitation

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Joint work with

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Context

- **Part of the project**
 - **“Climate-related risks for energy supply and demand”**
- **Important part is to assess future climate variability**
 - **Based on past observations...**
 - **...and expected behavior of ENSO, IPO, human-induced climate change,...**
- **Aim : developing a stochastic models to simulate realistic scenarios for the future climate. First step:**
 - **Focus on rainfall**
 - **Reproduce past conditions**
- **Simulated rainfall used as input in models of large-scale hydrology and river flows**
 - **Estimate risks related to production of hydroelectricity (60% of NZ electricity)**

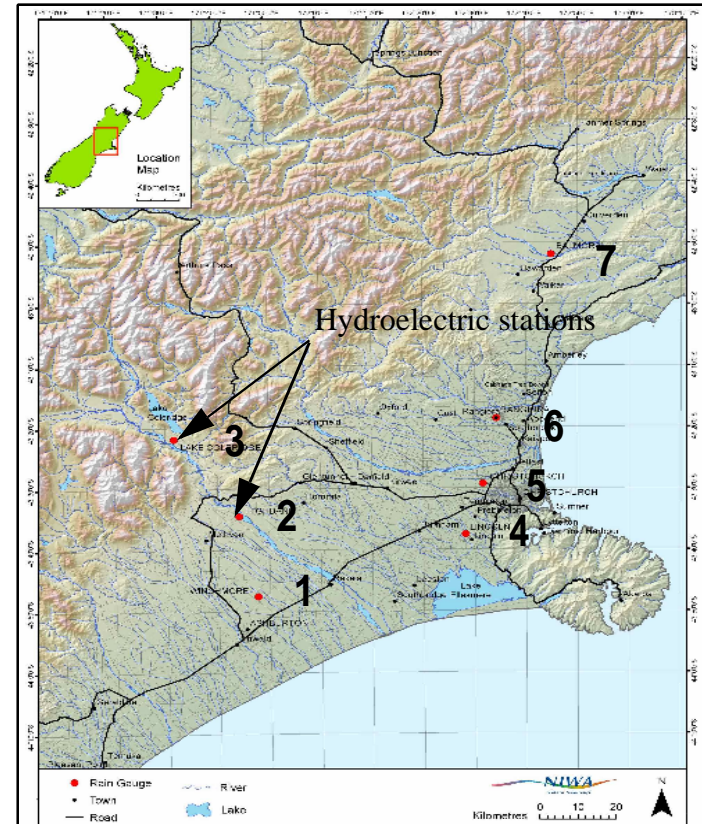
Outline

- **Data**
- **Basic Hidden Markov Model (HMM)**
- **HMM with truncated Gaussian distributions**
- **Conclusion**

Data

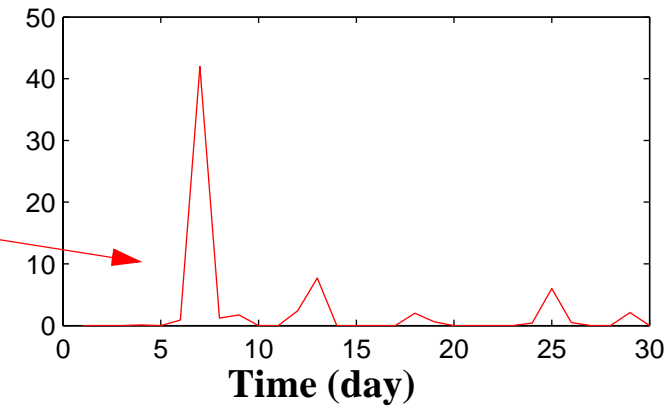
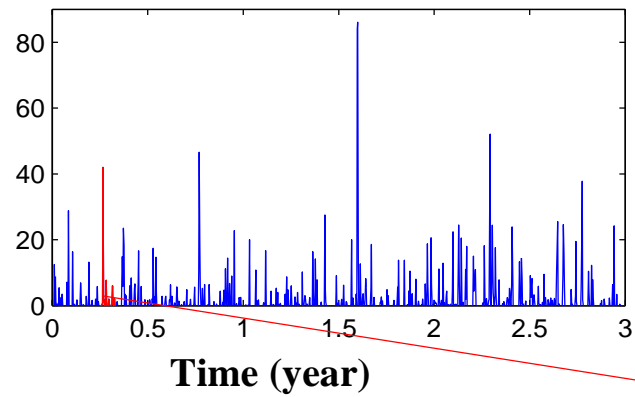
Data

- **Rainfall data in New Zealand**
 - Daily rainfall
 - $K=7$ locations
- $Y_t = (Y_t(1), \dots, Y_t(K))'$
 - $Y_t(k) \in R^+$: rainfall (mm) during day t at location k
- **26 years**
 - Focus on April



Data

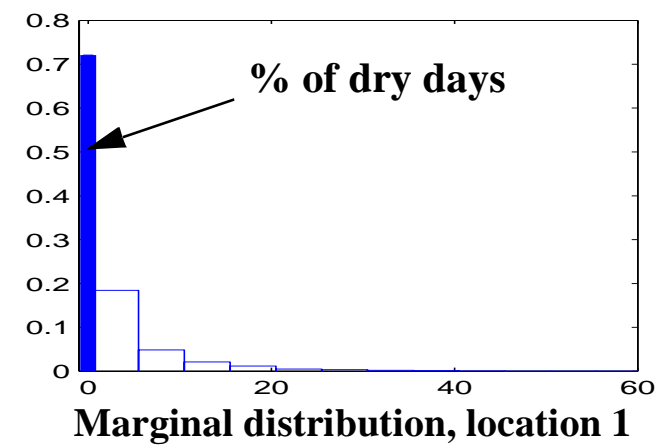
- **Time structure (location 1)**



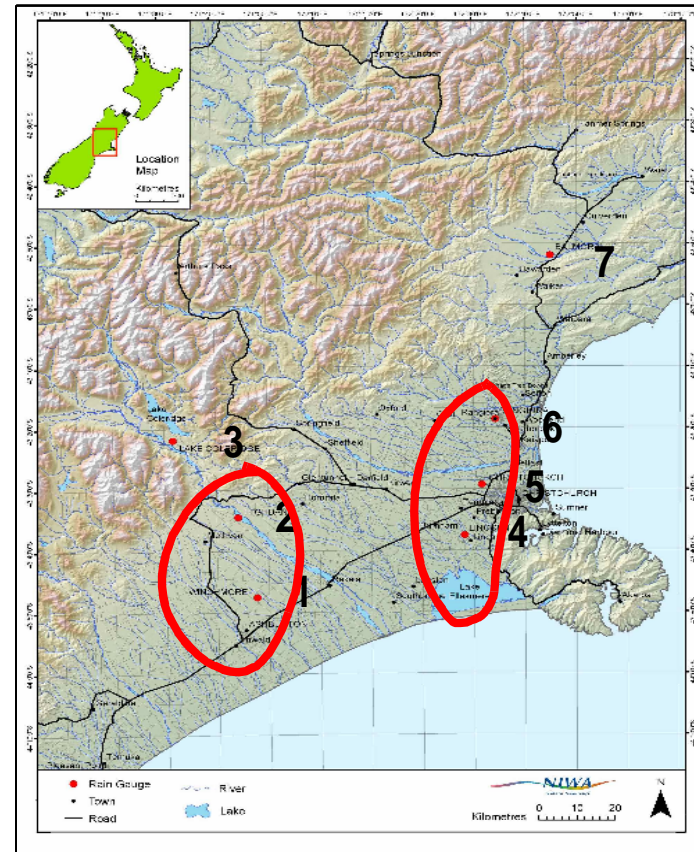
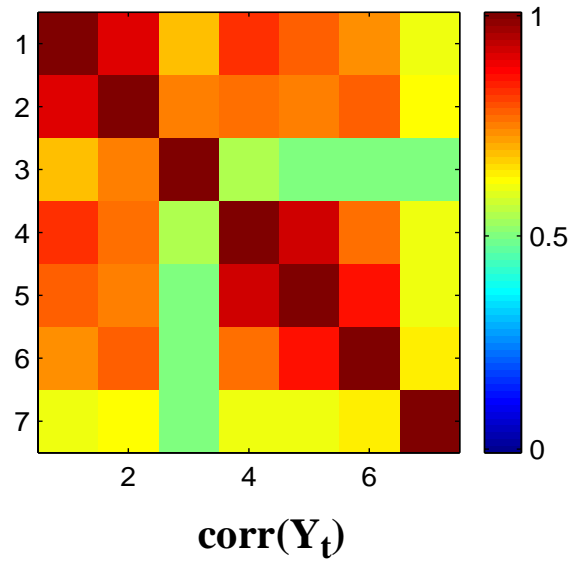
- **Marginal distribution**

- **Two components:**

- . $Y_t(k) = 0$ if no rainfall occurs
- . $Y_t(k) > 0$ if a rainfall occurs

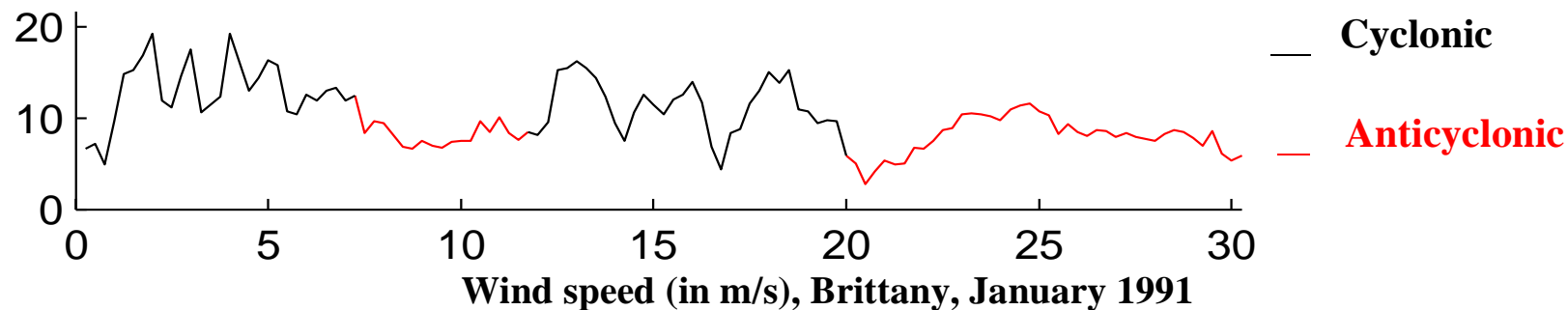


- Spatial structure



Basic HMM: model description (Zucchini & Guttorp (1991))

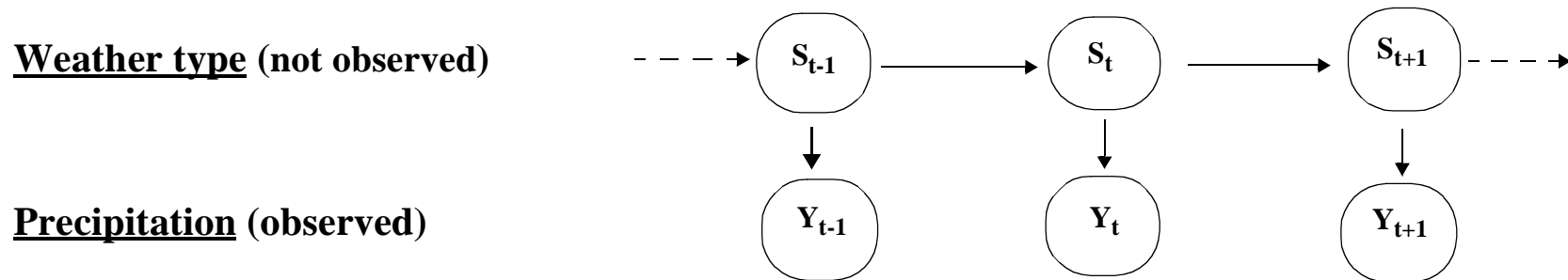
- Existence of “weather types” in meteorological time series
 - Another meteorological time series



- The weather type depends on the position of high pressure systems, frontal systems...
- Introduced as a hidden process $S_t \in \{1 \dots Q\}$

Basic HMM: model description (Zucchini & Guttorp (1991))

- **Existence of “weather types” in meteorological time series**
 - Introduced as a hidden process $S_t \in \{1 \dots Q\}$
- **Time structure: HMM**
 - $P(S_t | S_{t-1} = s_{t-1}, Y_{t-1} = y_{t-1}, \dots, S_0 = s_0, Y_0 = y_0) = P(S_t | S_{t-1} = s_{t-1})$
 - $P(Y_t | S_t = s_t, S_{t-1} = s_{t-1}, Y_{t-1} = y_{t-1}, \dots, S_0 = s_0, Y_0 = y_0) = P(Y_t | S_t = s_t)$



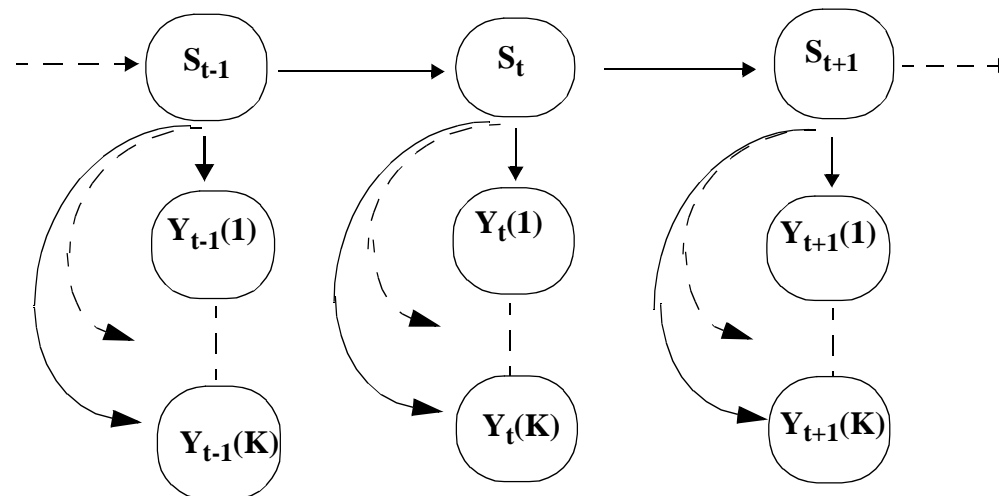
- ...Dynamics induced only by $\{S_t\}$!

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- **Existence of “weather types” in meteorological time series**
 - Introduced as a hidden process $S_t \in \{1 \dots Q\}$
- **Time structure: HMM**
 - ...Dynamics induced only by $\{S_t\}$!
- **Spatial structure: conditional independence**

$$p(Y_t(1), \dots, Y_t(K) | S_t = s_t) = \prod_{k \in \{1 \dots K\}} p(Y_t(k) | S_t = s_t)$$

Weather type (not observed)



Precipitation (observed)

- **Spatial dependence induced only by $\{S_t\}$!**

Basic HMM: model description (Zucchini & Guttorp (1991))

- **Existence of “weather types” in meteorological time series**
 - Introduced as a hidden process $S_t \in \{1 \dots Q\}$
- **Time structure: HMM**
 - ...Dynamics induced only by $\{S_t\}$!
- **Spatial structure: conditional independence**

$$p(Y_t(1), \dots, Y_t(K) | S_t = s_t) = \prod_{k \in \{1 \dots K\}} p(Y_t(k) | S_t = s_t)$$

- **Spatial dependence induced only by $\{S_t\}$!**

$$p(Y_t(k) \in dy | S_t = s) = \begin{cases} 1 - p_k^{(s)} & \text{if } 0 \in dy \\ p_k^{(s)} \gamma(y; \alpha_k^{(s)}, \beta_k^{(s)}) & \text{if } 0 \notin dy \end{cases}$$

- $\gamma(y; \alpha, \beta) = \frac{1}{\Gamma(\alpha) \beta^\alpha} y^{\alpha-1} \exp\left(-\frac{y}{\beta}\right)$
- $p_k^{(s)} \in [0, 1], \alpha_k^{(s)} > 0, \beta_k^{(s)} > 0$

Parameter estimation

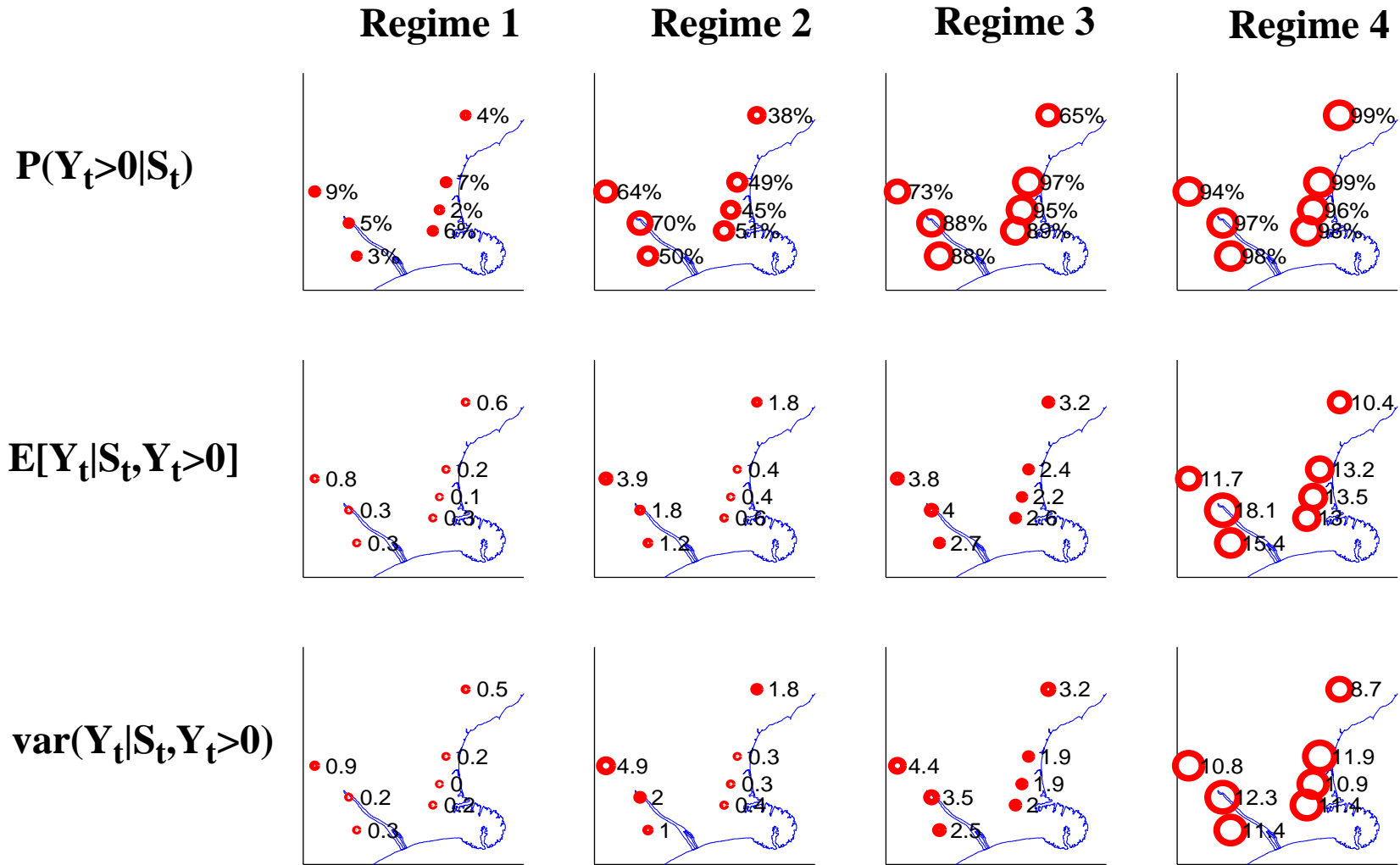
- $3KQ + Q^2 - 1$ parameters
- EM algorithm to compute the Maximum Likelihood Estimates
 - Several random starting values to avoid local extrema
- Model selection
 - First selection with AIC and BIC

Q	1	2	3	4	5	6
AIC	17404	14317	13436	13213	13144	12990
BIC	17502	14523	13760	13663	13731	13722

- Focus on the model with $Q = 4$
 - Easier interpretation than models with $Q \geq 5$
 - Produce “more realistic” synthetic time series than models with $Q \leq 3$

Model validation

- **Meteorological interpretability**
 - **Emission probabilities**



Model validation

- **Meteorological interpretability**
 - **Emission probabilities**
 - **Transition matrix, stationary distribution, mean durations**

0.70	0.15	0.09	0.05
0.49	0.18	0.20	0.12
0.35	0.31	0.17	0.16
0.21	0.29	0.25	0.25

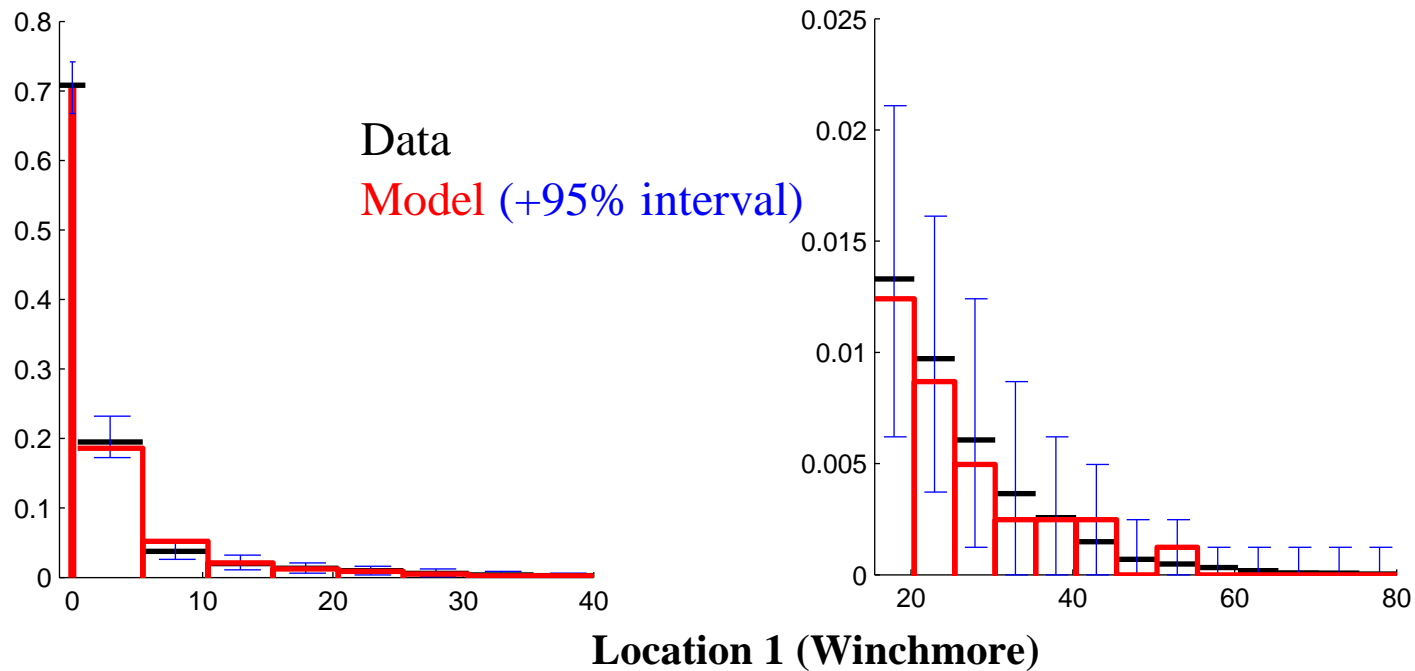
0.56
0.20
0.14
0.10

3.33
1.22
1.20
1.33

- **Summary**
 - Regime 1: dry conditions, “long” persistence**
 - Regime 2 and 3: intermediate patterns, regional differences, higher rainfall in regime 3, short persistence**
 - Regime 4: heavy rainfall**
- **Similar meteorological interpretation for other datasets**

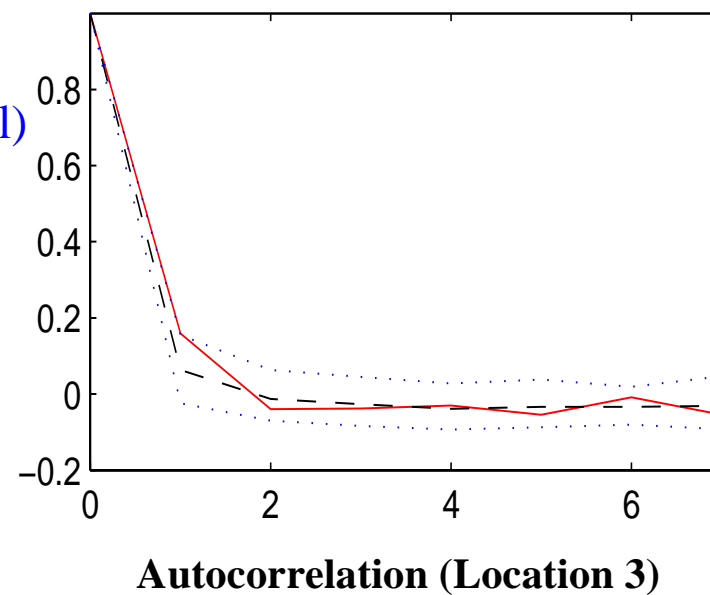
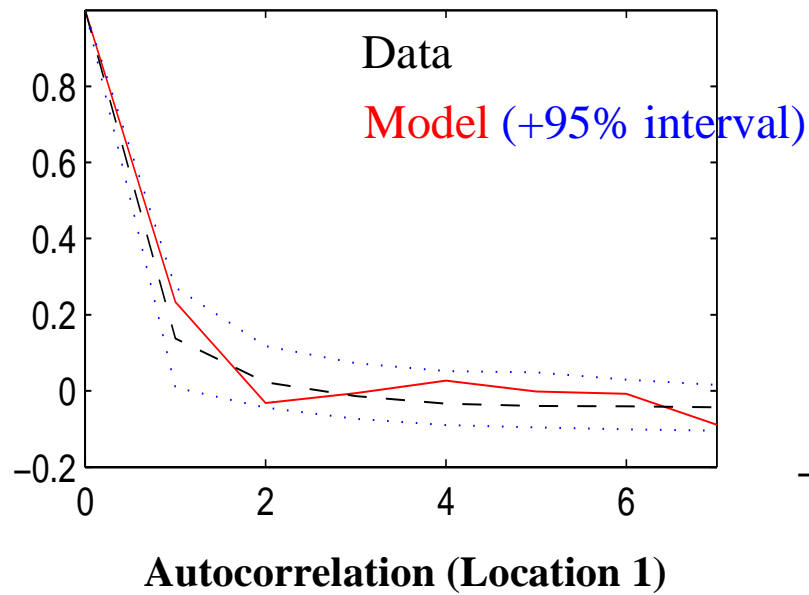
Model validation

- Meteorological interpretability: OK
- Realism of artificial sequences simulated with the model
 - Marginal distribution



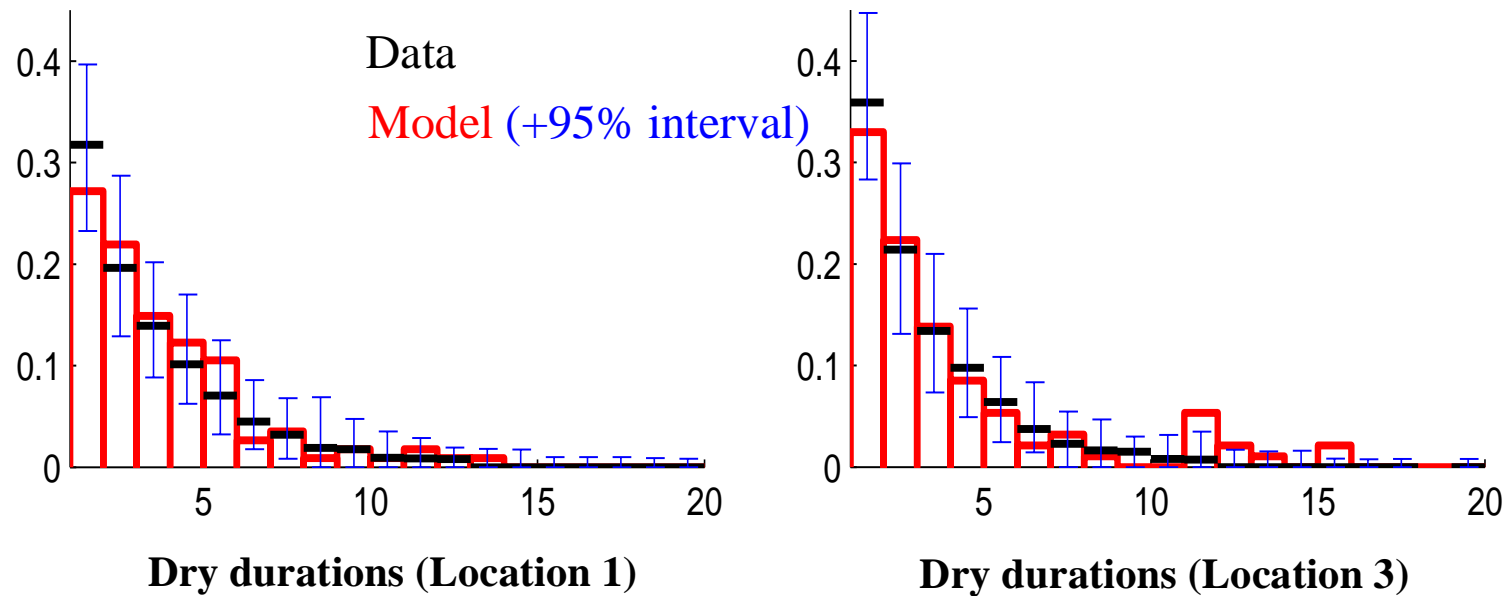
Model validation

- **Meteorological interpretability: OK**
- **Realism of artificial sequences simulated with the model**
 - **Marginal distribution: OK**
 - **Dynamics at the different locations**



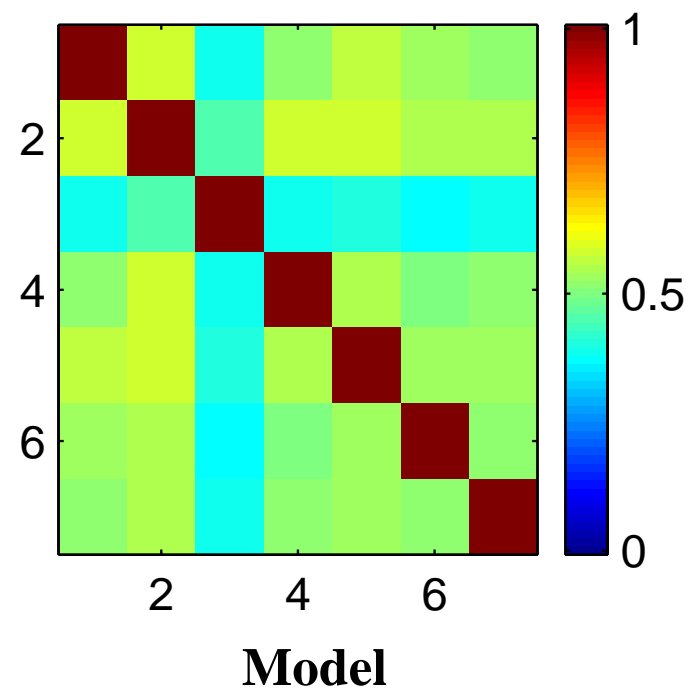
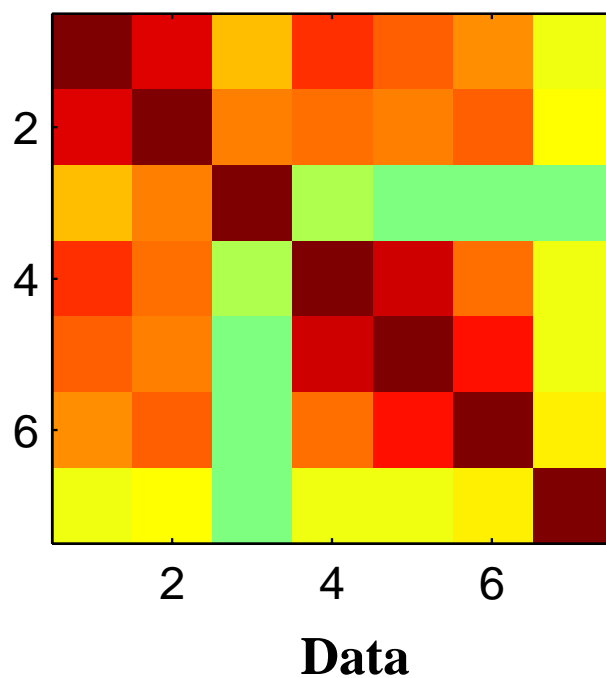
Model validation

- **Meteorological interpretability: OK**
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 - **Marginal distribution: OK**
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Model validation

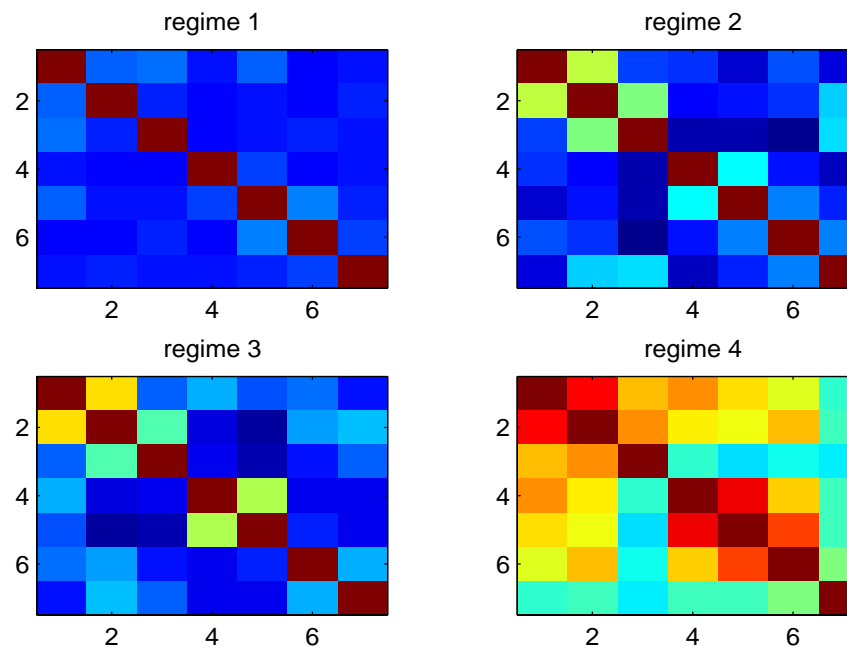
- **Meteorological interpretability: OK**
- **Realism of artificial sequences simulated with the model**
 - **Marginal distribution: OK**
 - **Dynamics at the different locations: ~OK**
 - **Spatial structure**



Model validation

- **Meteorological interpretability: OK**
- **Realism of artificial sequences simulated with the model**
 - **Marginal distribution: OK**
 - **Dynamics at the different locations: ~OK**
 - **Spatial structure: not good!**
- **...Need for a better model!**
 - **Existence of residual spatial structure within the weather types**

**Empirical correlation matrices
in the different weather types
(identified via the Viterbi algo.)**



Model validation

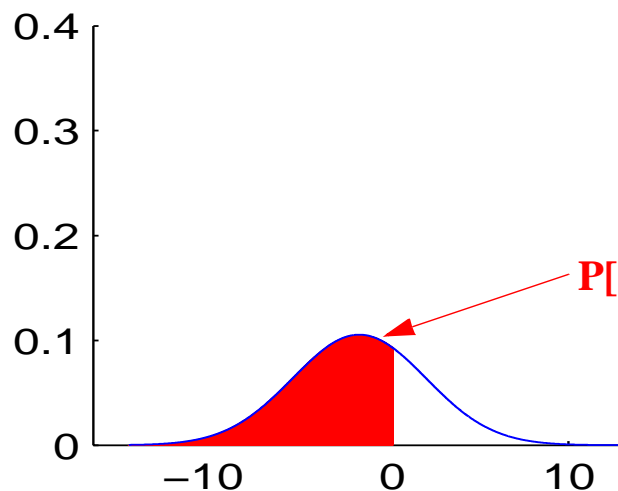
- **Meteorological interpretability: OK**
- **Realism of artificial sequences simulated with the model**
 - **Marginal distribution: OK**
 - **Dynamics at the different locations: ~OK**
 - **Spatial structure: not good!**
- **...Need for a better model!**
 - **Existence of residual spatial structure within the weather types**
- **Introduce spatial structure in the emission probabilities**
 - **Need model for multivariate mixed discrete-continuous distributions**
 - **...Truncated Gaussian random fields**

HMM with truncated Gaussian fields: model description

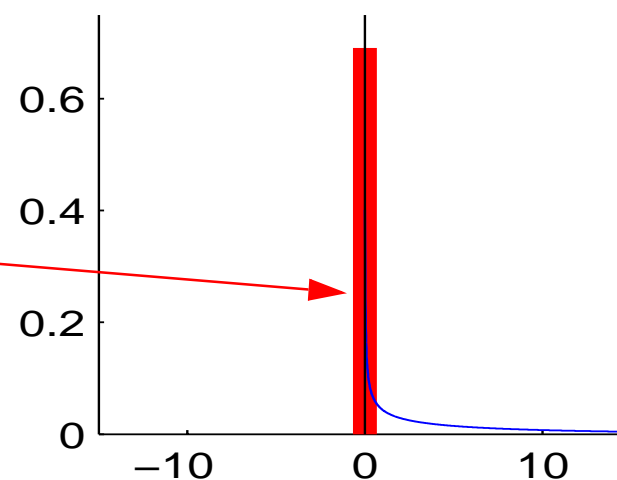
- If $S_t = s$ then

$$Y_t(k) = \begin{cases} 0 & \text{if } W_t(k) \leq 0 \\ W_t(k)^{\beta^{(s)}(k)} & \text{if } W_t(k) > 0 \end{cases}$$

- $W_t = m^{(s)} + H^{(s)}Z_t$ with $Z_t \sim N(O, I)$ i.i.d
- $m^{(s)} \in \mathbb{R}^K$, $\Sigma^{(s)} = H^{(s)}(H^{(s)})' \in \mathbb{R}^{K \times K}$ and $\beta^{(s)} \in (\mathbb{R}^{+*})^K$



pdf of $W \sim N(-1.88, 3.78)$



pdf of $Y = \max(W, 0)^{1.81}$

- **Assumptions on the covariance matrices**

- **HMMCI model** ($Q^2 - 1 + 3QK$ parameters)

$$\Sigma^{(s)}(i, j) = \sigma_i^{(s)} \sigma_j^{(s)} \delta_{i, j} \text{ with } \sigma_j^{(s)} > 0$$

- **HMMdist model** ($Q^2 - 1 + K(3Q + 1)$ parameters)

$$\Sigma^{(s)}(i, j) = \sigma_i^{(s)} \sigma_j^{(s)} \exp(-\lambda^{(s)} d(z_i, z_j)) \text{ with } \sigma_j^{(s)} > 0 \text{ and } \lambda^{(s)} > 0$$

- **HMMloc model** ($Q^2 - 1 + 4QK$ parameters)

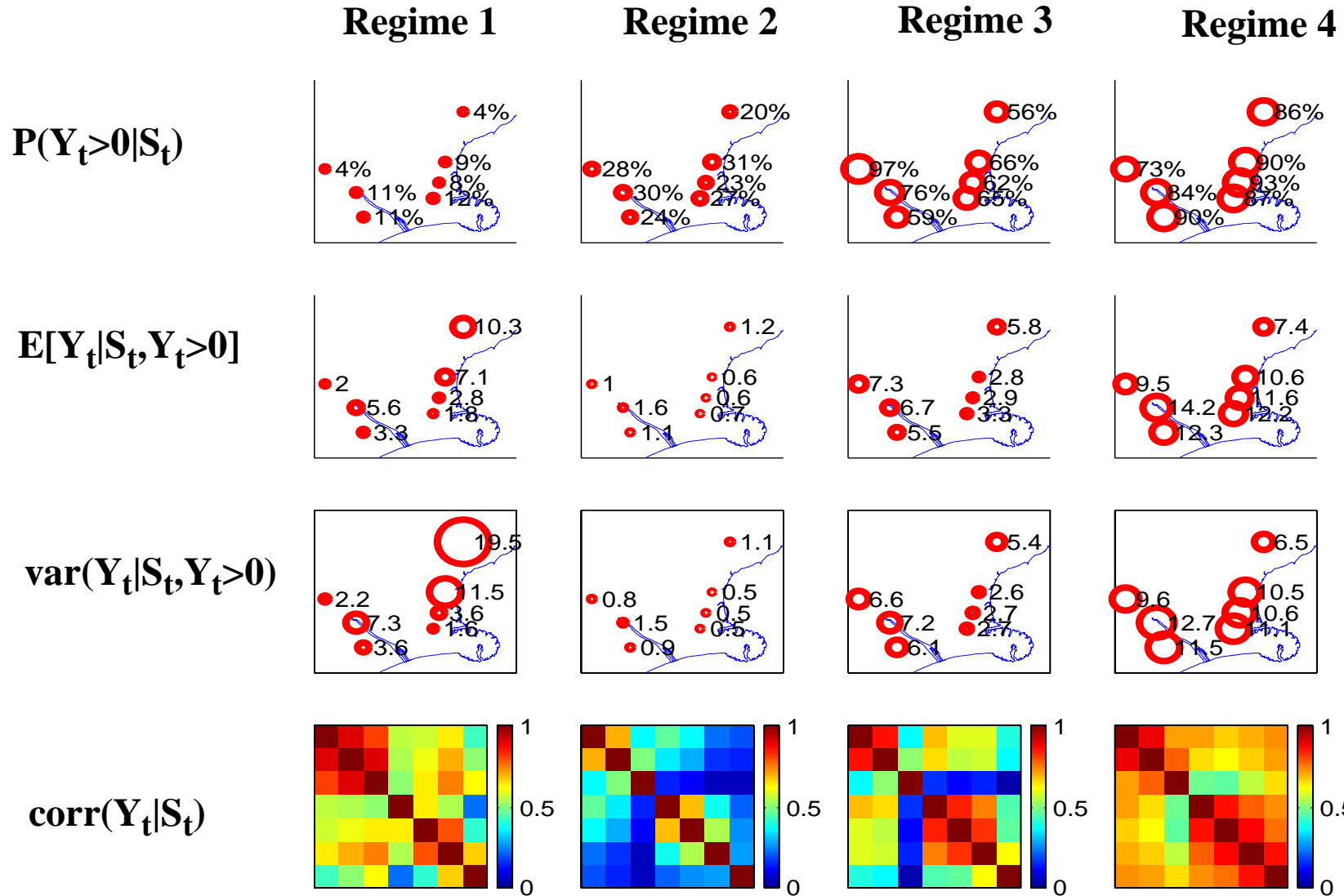
$$\Sigma^{(s)}(i, j) = \sigma_i^{(s)} \sigma_j^{(s)} \exp(-\lambda_i^{(s)} \lambda_j^{(s)} d(z_i, z_j)) \text{ with } \sigma_j^{(s)} > 0 \text{ and } \lambda_i^{(s)} > 0$$

- **Model selection with AIC**

Q	1	2	3	4	5
Basic HMM	17404	14317	13436	13213	13144
HMMCI	17403	14445	13639	13398	13289
HMMdist	13092	12770	12697	12616	12623
HMMloc	12995	12741	12600	12506	12509
HMMfull	12904	12643	12640	12674	12611

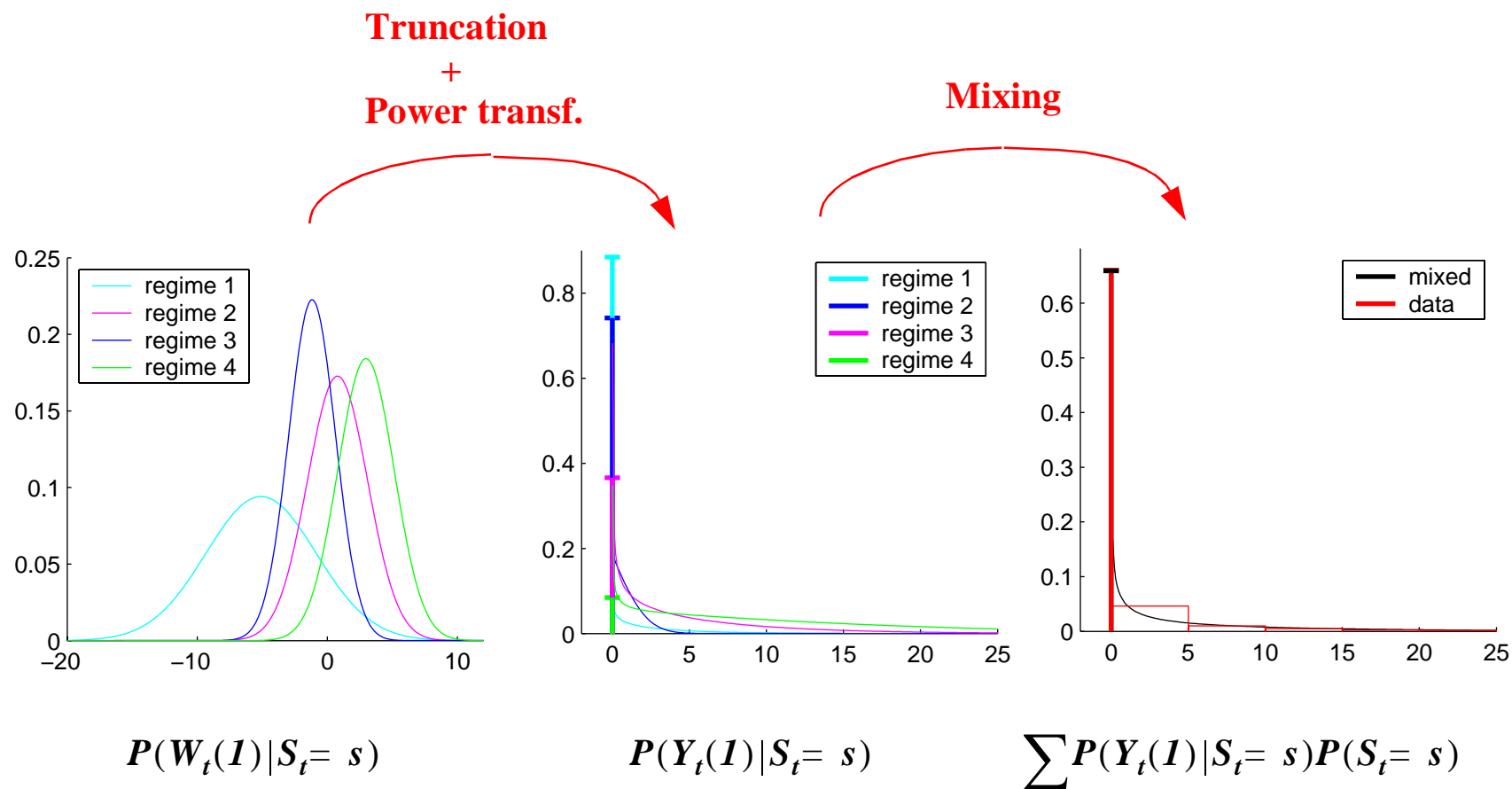
Model validation

- Meteorological interpretability



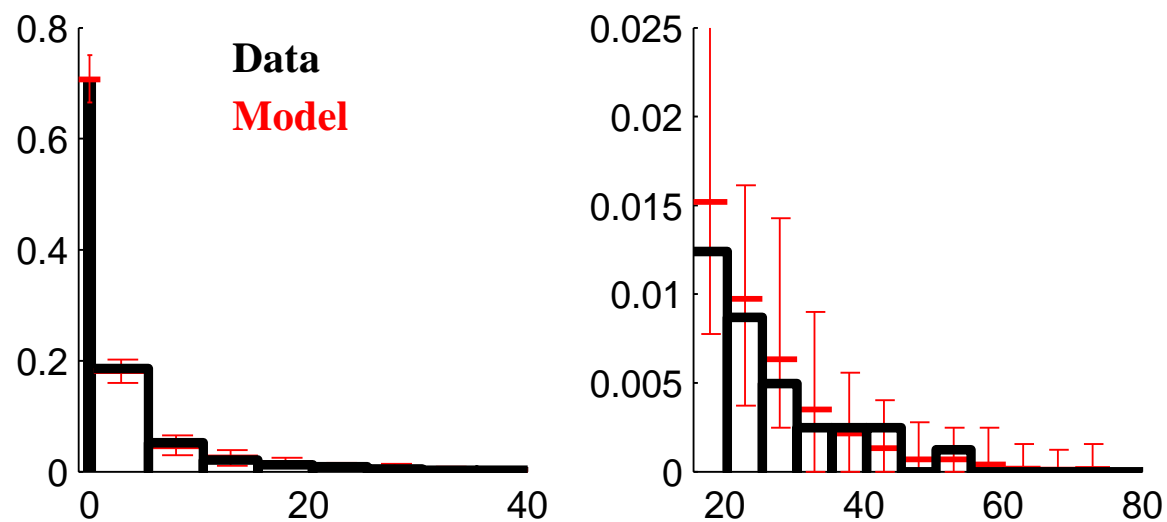
Model validation

- Meteorological interpretability: OK
- Realism of artificial sequences simulated with the model
 - Marginal distribution (Location 1)



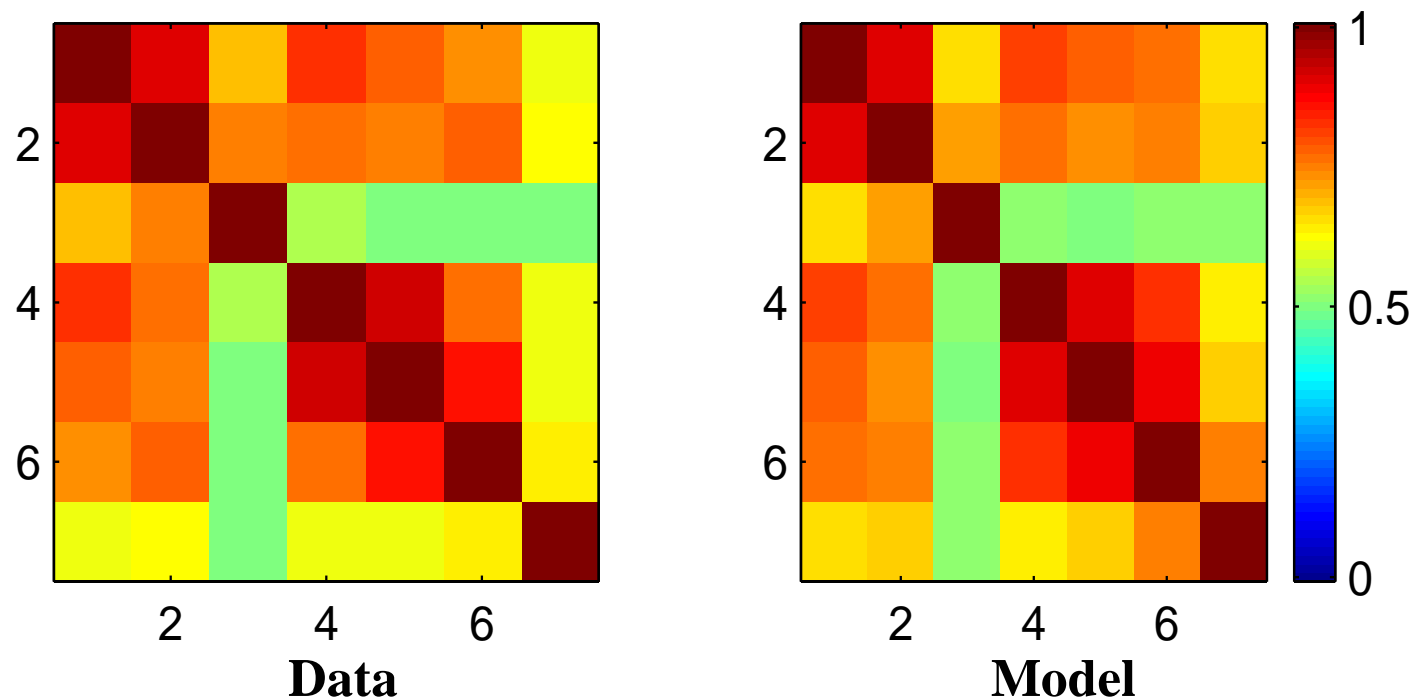
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Model validation

- **Meteorological interpretability: OK**
- **Realism of artificial sequences simulated with the model**
 - **Marginal distribution: OK**
 - **Dynamics at the different locations: ~OK**
 - **Spatial structure: OK**



Parameter estimation

- **Model structure**

Weather type:

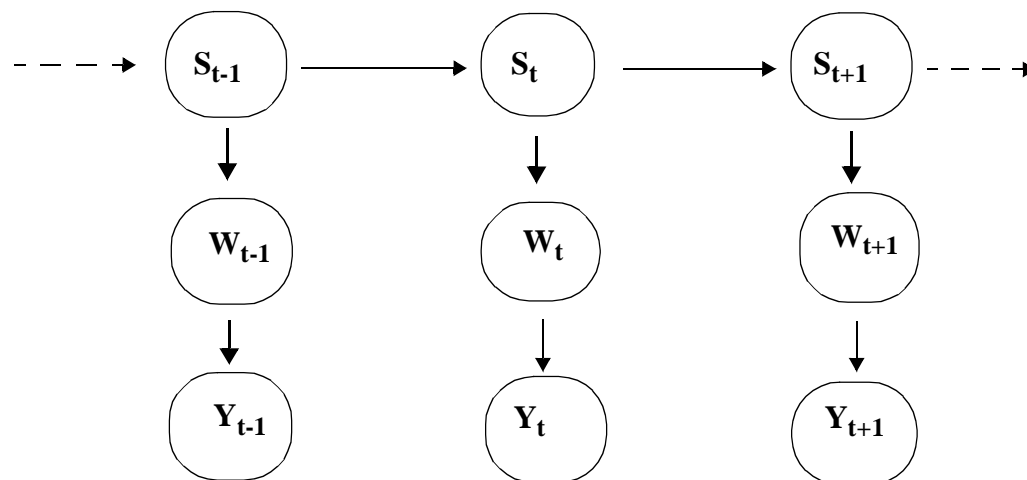
Not observed, finite values

Conditionally Gaussian vector:

Not observed, continuous values

Precipitation:

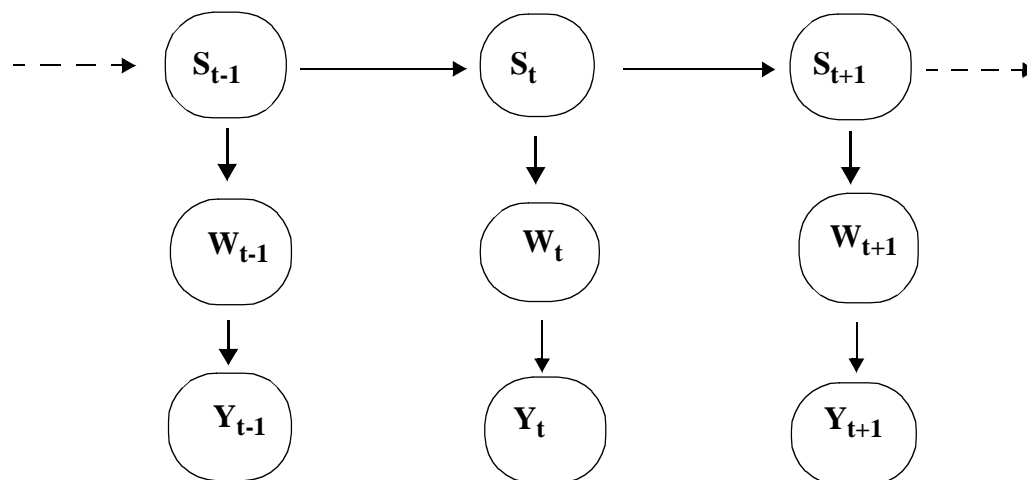
Observed, mixed continuous-discrete



- **Monte-Carlo EM algorithm**

HMMs for rainfall: HMM with truncated Gaussian fields

- **Need to compute the following smoothing probabilities for the M-step**
 - $u_t(s) = p(S_t = s | y_I^T, \theta_n)$
 - $v_t(s, s') = p(S_{t-1} = s, S_t = s' | y_I^T, \theta_n)$
 - $E[W_t | y_I^T, S_t = s, \theta_n]$
 - $E[W_t W_t' | S_t = s, y_I^T, \theta_n]$
- **Several algorithms can be used**
 - **Generic algorithms : Gibbs sampler, particle filter,...**
 - **More efficient algorithms if we take advantage of the specific structure of the model**



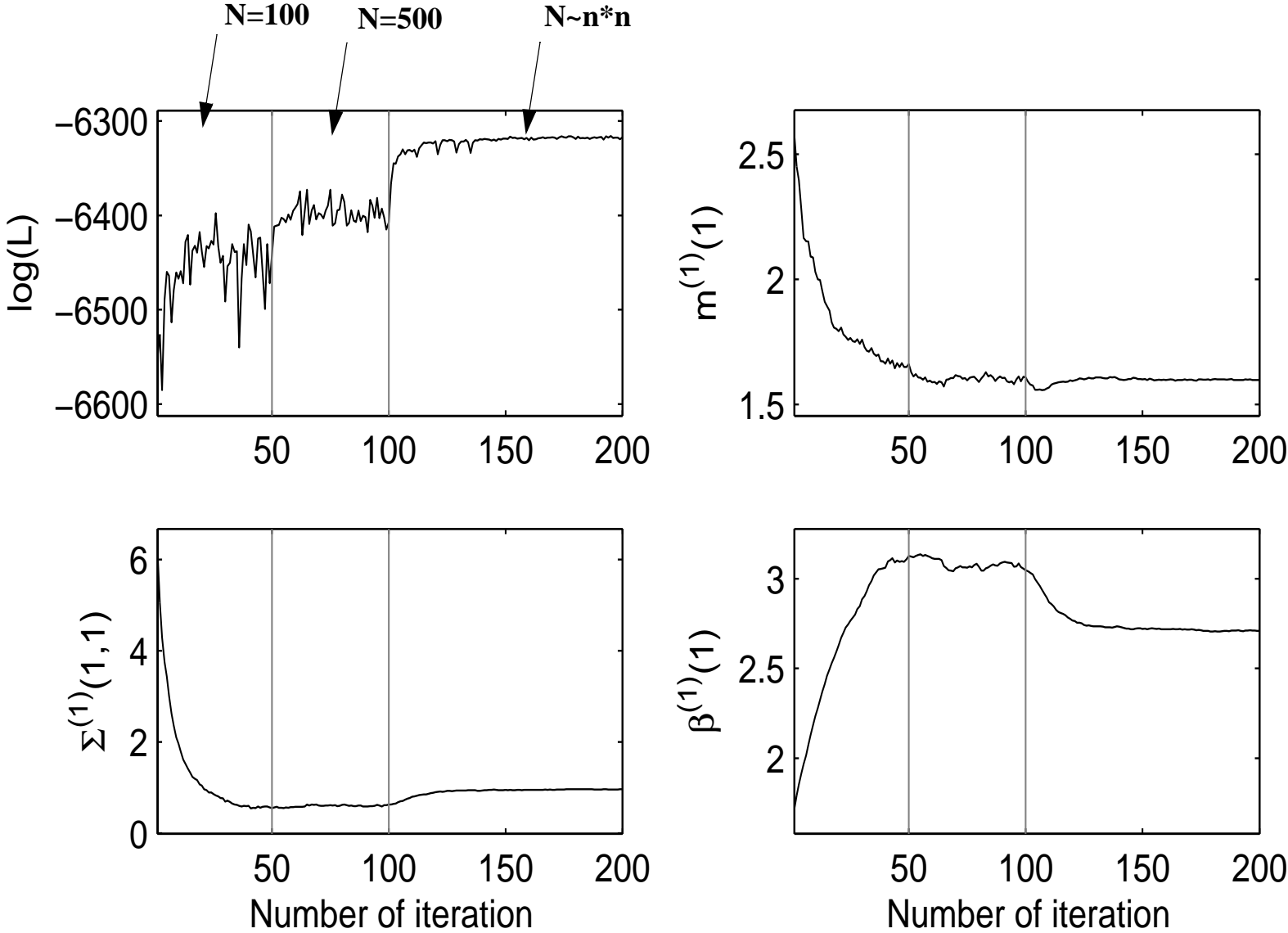
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 - $u_t(s) = p(S_t = s | y_1^T, \theta_n)$
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 - $E[W_t | y_1^T, \theta_n]$
 - $E[W_t W_t' | y_1^T, \theta_n]$
- **Several algorithms can be used**
 - **Generic algorithms : Gibbs sampler, particle filter,...**
 - **More efficient algorithms if we take advantage of the specific structure of the model**
 - **Forward-backward algorithm for the discrete component**
 - **Monte-Carlo integration for the gaussian component (ϕ pdf of $N(m, \Sigma)$)**

$$\int_{l=-\infty}^{\infty} \int_{0}^k \phi(w_1, \dots, w_k, w_{k+1}, \dots, w_K) dw_1 \dots dw_k$$

$$\int_{l=-\infty}^{\infty} \int_{0}^k w_i \phi(w_1, \dots, w_k, w_{k+1}, \dots, w_K) dw_1 \dots dw_k$$

$$\int_{l=-\infty}^{\infty} \int_{0}^k w_i w_j \phi(w_1, \dots, w_k, w_{k+1}, \dots, w_K) dw_1 \dots dw_k$$

HMMs for rainfall: HMM with truncated Gaussian fields



Conclusion

- **Better description of the spatial structure of the data**
- **Some perspectives**
 - **Add an autoregressive part to better describe the local dynamics**
 - **Incorporate seasonal and inter-annual components in the model**
- **Some virtues of HMM**
 - **Distributional versatility**
 - **Ability to model diverse time scales**
 - **Open structure which allows for more physical models**