

Lecture 9

Global and local error bounds

Chapter 9.1-9.3

We consider the Poisson equation on weak form: Find $u \in H^1(\Omega)$ st

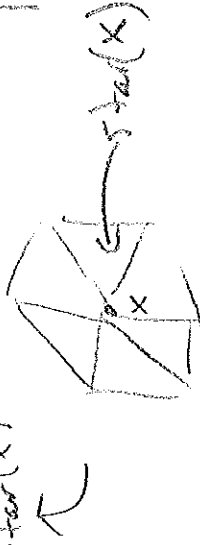
$$a(u, v) = \int_{\Omega} \alpha \nabla u \cdot \nabla v \, dx = \int_{\Omega} f \cdot v \, dx \quad \forall v \in V$$

$$0 < \alpha_0 \leq \alpha(x) \leq \alpha_1, \quad x \in \Omega,$$

We assume α and f to be

piece smooth on a non-degenerate family of simplicial meshes $\{\mathcal{T}_h\}_{0 \leq h \leq h_0}$

$$\text{and } h(x) = \max_{K \in \mathcal{T}_h(x)} h_K$$



We have $h(x) \geq \text{diam}(K) \quad \forall x \in K$ 1/5
and $h|_K \leq C \text{diam}(K)$ since the meshes are non-degenerate.

Similarly we assume $\max_{x \in K} \alpha(x) \leq C \min_{x \in K} \alpha(x) \quad \forall K \in \mathcal{T}_h$.

We let V_h be the space of piecewise polynomials of degree k , with interpolant (nodal) I_h . From Thm 4.4, 4 assuming sufficient smoothness on u

$$\|u - I_h u\|_{H^1(\Omega)}^2 \leq \sum_{|S|=k} \int_K h^{2k-2} |D^S u|^2 \, dx \quad \forall K \in \mathcal{T}_h$$

In energy norm under the assumption on α and optimality of $u_h \in V_h$

$$\|u - u_h\|_E \leq C \left(\sum_{|S|=k} \int_{\Omega} \alpha(x) h(x)^{2k-2} |D^S u|^2 \, dx \right)^{1/2}$$

Theorem 9.1.7

We have $\|u - u_h\|_E \leq C \|\sqrt{\sigma} h^{k-1} |\nabla_k u|\|_{L^2(\Omega)}$

where $|\nabla_k u|(x) = \left(\sum_{|\alpha|=k} |D^\alpha u(x)|^2 \right)^{1/2}$,

C is independent of σ and h .

L^2 estimate is given by a duality argument, let $w \in H_0^1(\Omega)$ solve $a(v, w) = (v, u - u_h) \quad \forall v \in H_0^1(\Omega)$.

$$\begin{aligned} \|u - u_h\|_{L^2(\Omega)}^2 &= a(u - u_h, w - I_h w) = \\ &= \left(\int_{\Omega} \sigma^{2-\lambda} (h \nabla(u - u_h))^2 dx \right)^{1/2} \left(\int_{\Omega} \sigma^\lambda |\nabla w - I_h w|^2 dx \right)^{1/2} \\ &\leq C \left(\int_{\Omega} \sigma^{2-\lambda} (h \nabla(u - u_h))^2 dx \right)^{1/2} \left(\int_{\Omega} \sigma^\lambda |\nabla_2 w|^2 dx \right)^{1/2}, \\ 0 \leq \lambda \leq 2 &\text{ is arbitrary.} \end{aligned}$$

A priori information gives (under additional information on σ, Ω)

$$|\nabla_2 w| \leq C \|u - u_h\|$$

Theorem 9.1.8

(f) $|\nabla_2 w| \leq C \|u - u_h\|$ it holds

$$\|u - u_h\|_{L^2(\Omega)} \leq C \left(\sum_{\mathcal{T}_h} \sigma(x)^2 h(x)^2 |\nabla(u - u_h)|^2 dx \right)^{1/2},$$

C depends on σ .

Given the bound in energy norm it holds.

Theorem 9.1.10

There is a constant $\mu > 0$ s.t. if μh mesh size variation $\|\nabla u\|_{L^\infty(\Omega)} < \mu h$

then $\|u - u_h\|_{L^2(\Omega)} \leq C \|\sqrt{\sigma} h^2 |\nabla_2 u|\|_{L^2(\Omega)}$

Note that $\|\nabla u\|_{L^\infty(\Omega)}$ still allows for strong mesh gradings, e.g. geometric grading.

Error estimators 9.2

Lemma 9.2.1

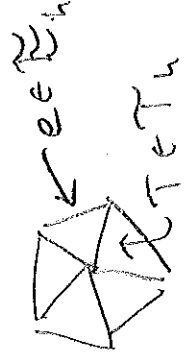
It holds

$$a(u-u_h, v) = R(v), \quad \forall v \in V$$

where $R \in V'$ is the residual

$$R(v) := \sum_{T \in \mathcal{T}_h} \int_T (f + \nabla \cdot (\alpha \nabla u_h)) v dx + \sum_{e \in \mathcal{E}_h} \int_e [\alpha n_e \cdot \nabla u_h]_{n_e} v ds \quad \forall v \in V$$

where n_e denotes a unit normal to e .



This follows from integration by parts, see Lecture 1.

Remember $[\phi]_n(x) := \lim_{\epsilon \rightarrow 0} \phi(x+\epsilon n) - \phi(x-\epsilon n)$

We note that K has two $3/5$ disjoint parts:

1) $R_A|_T = f + \nabla \cdot \alpha \nabla u_h|_T, R_A \in L_1(u_h)$

2) $R_D(v) := \sum_e \int_e [\alpha n_e \cdot \nabla u_h] v ds \quad \forall v \in V$
the "jump" term.

By letting $v = u - u_h$ we get

$$\alpha \|u - u_h\|_{H^1(\Omega)}^2 \leq \|R(u - u_h)\|_{H^1(\Omega)} \cdot \|u - u_h\|_{H^1(\Omega)}$$

recall $\|r\|_{H^1} := \sup_{z \in \mathcal{E}_h(\Omega)} \frac{r(z)}{\|z\|_{H^1(\Omega)}}$

i.e. $\|u - u_h\|_{H^1(\Omega)} \in C \|R\|_{H^1(\Omega)}$

Negative norms are difficult to compute. (also from Lecture 1)

$$\|u - u_h\|_{H^1(\Omega)} \leq C \left(\sum_{T \in \mathcal{T}_h} \int_T \epsilon_T(u_h)^2 \right)^{1/2}$$

$$\epsilon_T(u_h) := h_T^2 \|R_A\|_{L^2(T)}^2 + \sum_{e \in \partial T} h_e \|\epsilon_T \cdot \nabla u_h\|_{L^2(e)}^2$$

Local error estimate 9.3

We have global bounds of $u-u_h$.

We seek local bounds to make sure the error $u-u_h|_T$ and the error indicator $\mathcal{E}_T(u)$ are correlated.

We have $a(u-u_h, v) = (R_A, v)$

$\forall v \in H_0^1(T)$

Therefore

$$\left| \int_T R_A v dx \right| \leq \alpha_1 |u-u_h|_{H^1(T)} |v|_{H^1(T)}$$

makes

jumps vanish.

$$\text{and } \alpha_1 |u-u_h|_{H^1(T)} \geq \sup_{0 \neq v \in H_0^1(T)} \frac{\left| \int_T R_A v dx \right|}{|v|_{H^1(T)}}$$

We assume f and α to be piecewise polynomials. This means that R_A is piecewise polynomial

It holds

$$\frac{\sum_T \nu P dx}{\sup_{v \in H_0^1(T)} |v|_{H^1(T)}} \geq C h_T \|P\|_{L^2(T)}$$

(constant $\cdot h_T^r$)

Where C depends on the degree of P .
(polynomial)
and the characteristics of the mesh.

With $P = R_A$ we get

$$\alpha_1 |u-u_h|_{H^1(T)} \geq C h_T \|R_A\|_{L^2(T)}$$

Local Lower bound.

We turn to the jump term.

$$a(e_h, v) = \sum_e [\alpha n \cdot \tau_{un}] \nu ds \quad \forall v \in V_e$$

$$\text{where } V_e = \{ v \in H_0^1(T_e) : \sum_{T \in \mathcal{T}_e} \nu P dx = \sum_{T \in \mathcal{T}_e} \nu P dx = 0 \}$$



Polynomials of degree r which R_A is.

$$\text{Then } \left| \sum_e [\alpha n \cdot \tau_{un}] \nu ds \right| \leq \alpha_1 |u-u_h|_{H^1(T_e)}$$

$$\text{and } \alpha_1 |u-u_h|_{H^1(T_e)} \geq \sup_{0 \neq v \in V_e} \frac{\left| \sum_e [\alpha n \cdot \tau_{un}] \nu ds \right|}{|v|_{H^1(T_e)}}$$

Since $[x_n, v_n]$ is a polynomial on the edge e it can be shown

$$\sup_{0 \neq v \in H_0^1(\tau_e)} \frac{|\int_e [x_n, v_n] v \, ds|}{|v|_{H^1(\tau_e)}} \geq c h_e^2 \| [x_n, v_n] \|_{L^2(\tau_e)}^2$$

Combining these results gives us

Theorem 9.3.6 Suppose α and f are piecewise polynomials,

then the local lower bound

$$\alpha_1 |u - u_h|_{H^1(\tau_e)} \geq \epsilon_e(u_h)$$

$$\text{where } \epsilon_e(u_h)^2 = \sum_{T \in \mathcal{T}_e} h_T^2 \|f + \nabla \cdot \mathbf{r}(u_h)\|_{L^2(T)}^2 + h_e \| [x_n, v_n] \|_{L^2(\tau_e)}^2$$

Squaring and summing gives a global lower bound

Theorem 9.3.7

$$\alpha_1 \|u - u_h\|_{H^1(\Omega)} \geq c \left(\sum_{e \in \mathcal{E}_h} \epsilon_e(u_h)^2 \right)^{1/2}$$

Note that the reverse of 9.3.6 is not true. The local bound tells us that it is reasonable to refine an element with high error indicator $\epsilon_e(u_h)$.