

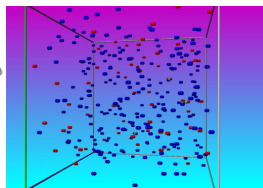
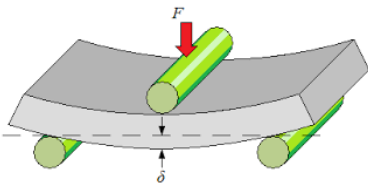
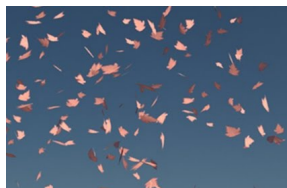
Splitting techniques for solving PDEs

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Partial differential equations (PDEs)

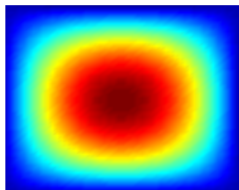


Mathematical model of physical processes

- 1 Complex movement of leaves in the wind. (Navier-Stokes)
- 2 Temperature distribution in this room. (Heat equation)
- 3 Someone leaning at a desk. (Linear elasticity)
- 4 The molecules floating around us. (Schrödinger)
- 5 Electromagnetic field allows surfing the web. (Maxwell)
- 6 Several coupled physical processes. (Systems of PDEs)

Solving PDEs is crucial in industry, academia, environment, ...

Parabolic partial differential equations

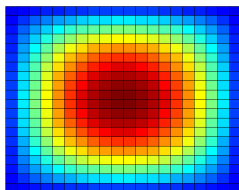


The heat equation:

$$\dot{u} - \Delta u = f, \quad x \in \Omega, \quad u(0) = u_0.$$

- 1 Heat equation, u is temperature and f heat source.
- 2 Smoothing property, infinite speed of propagation, as opposed to waves (audio).
- 3 If $f = f(u)$ the equation is semilinear, leads to different behaviour.
- 4 Allen-Cahn $f(u) = u - u^3$, phase separation in alloys.

Numerical techniques for solving PDEs



The heat equation:

$$\dot{u} - \Delta u = f(u), \quad \text{in } \Omega, \quad u(0) = u_0.$$

- 1 We discretize the domain Ω into finite elements.
- 2 We discretize in time $\dot{u} \approx \frac{u^{n+1} - u^n}{k}$.

$$\frac{u^{n+1} - u^n}{k} - \Delta_h u^{n+1} = P_h f(u^{n+1}),$$

where $u^0 = P_h u_0$, and P_h is some map into the FE space.

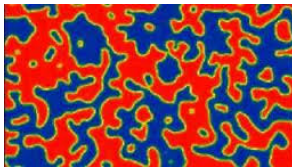
Numerical techniques for solving PDEs

If we were to compute the temperature in a large room of size $16m \times 16m \times 4m$, the algebraic system of equations

$$\frac{u^{n+1} - u^n}{k} - \Delta_h u^{n+1} = P_h f(u^{n+1}),$$

has a huge number of unknowns.

- 1 Grid on centimeter-scale: size $\Delta_h \approx 10^9 \times 10^9$.
- 2 A (non)linear system of 10^9 unknowns need to be solved in every time step.
- 3 This procedure need to be repeated perhaps 10^3 times.
- 4 This is **extremely time consuming** (costly) or impossible on many computers.
- 5 Only development of faster computers is not enough, **numerical analysis is needed!**

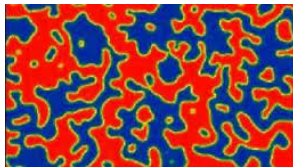


We consider a semilinear heat equation (Allen-Cahn),

$$\dot{u} - \Delta u = f(u), \quad t \in (0, T]$$

In each time step we wish to,

- first solve a pure diffusion problem, $\dot{u} = \Delta u$,
- then a pure reaction problem, $\dot{u} = f(u)$.

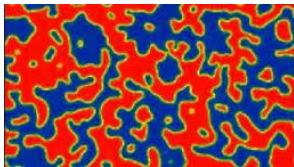


We discretize in time $0 = t_0 < t_1 < \dots < t_n < \dots < t_N = T$.

Given $u_{n-1}^s \approx u(t_{n-1})$, on (t_{n-1}, t_n) , we solve

$$\begin{cases} \dot{u}^d = \Delta u^d \\ u_{n-1}^d = u_{n-1}^s \end{cases} \quad \begin{cases} \dot{u}^r = f(u^r) \\ u_{n-1}^r = u_n^d \end{cases} \quad u_n^s = u_n^r \approx u(t_n).$$

We thereby make a physical split of the equation. This procedure is called exponential splitting or Lie-Trotter splitting (for operators in the 1950s).



- The diffusion equation is the standard heat equation for which very efficient methods exist.
- Another advantage is that the reaction equation does not contain spatial derivatives and can be solved cheaply.
- We can allow different time steps for different subproblems.
- However, the accuracy of the splitting must be controlled.

More advanced splitting techniques

In general we consider an equation,

$$\dot{u} = Au + F(u),$$

where $A = \Delta$ in the previous example.

If we let the solution operators to $\dot{v} = Av$ and $\dot{w} = Fw$ be denoted e^{kA} and e^{kF} where k is the time step size. The Lie-Trotter splitting scheme can be written

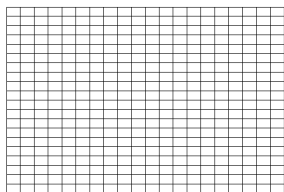
$$u_n^s = e^{kF} e^{kA} u_{n-1}^s$$

A second order (more accurate) splitting scheme is the Strang splitting,

$$u_n^s = e^{\frac{1}{2}kA} e^{kF} e^{\frac{1}{2}kA} u_{n-1}^s,$$

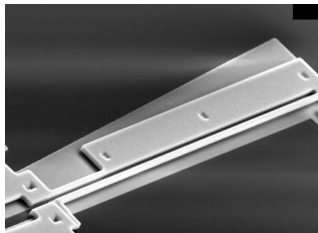
which means half a time step diffusion, a full time step reaction, and half a time step diffusion.

Error analysis



- The error consists of two parts: discretization in space (h) and discretization and splitting in time (k).
- High order methods need high smoothness in the solution.
- The different error sources are not independent.
- Understanding of error is (besides development of the method) the most important task in numerical analysis.

Multiphysics example



We consider temperature (θ), electric potential (ϕ), and displacement (\mathbf{u}) in a micro-electro-mechanical system,

$$\begin{cases} \dot{\theta} - \Delta\theta &= \kappa(\theta)|\nabla\phi|^2 - \nabla \cdot \dot{\mathbf{u}} \\ -\nabla \cdot \kappa(\theta)\nabla\phi &= 0 \\ \ddot{\mathbf{u}} - \nabla \cdot (\boldsymbol{\epsilon}(\mathbf{u}) - \alpha\theta\mathbf{I}) &= \mathbf{f}. \end{cases}$$

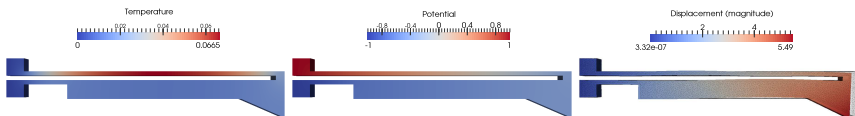
We apply a voltage to the contacts which induces Joule heating giving rise to thermal stresses that bends the device.

Multiphysics example

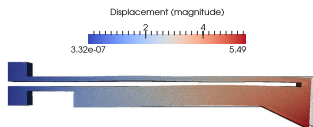
We split the system in each time step into:

- a heat equation,
- an elliptic equation for the electric potential,
- an elastic wave equation.

$$\begin{cases} D_t \theta_n - \Delta \theta_n &= \kappa(\theta_{n-1}) |\nabla \phi_{n-1}|^2 - \nabla \cdot D_t \mathbf{u}_{n-1} \\ -\nabla \cdot \kappa(\theta_n) \nabla \phi_n &= 0 \\ D_t^2 \mathbf{u}_n - \nabla \cdot (\epsilon(\mathbf{u}_n) - \alpha \theta_n \mathbf{l}) &= \mathbf{f}. \end{cases}$$



Multiphysics example



- Splitting techniques are very natural and necessary.
- The error analysis is complicated, not just splitting errors but discretization in time and space, error in data transfer between solvers (possibly different grids, methods), ...
- Errors may trigger numerical instability which destroys convergence.
- Already existence and uniqueness of solution and regularity of solutions is difficult.
- **This situation is typical in real applications.**

Erik's contribution

This is an important field of research with direct applications in many areas of science.

- A theoretical framework for analyzing the error due to splitting for semilinear evolution problems (Paper I).
- An analysis of the combined effect of splitting and spatial error for linear parabolic problems (Paper II).
- An analysis of combining physical and spatial splitting (domain decomposition) (Paper III).
- Real applications where splitting reduces the computational cost (Papers IV and V).