

Geometric Numerical Integration, Serie 6

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Exercise 18: Complete the proof of the following Theorem from the lecture.

Let $f(y)$ be analytic in $B_{2R}(y_0)$, let the coefficients $d_j(y)$ of the numerical scheme be analytic in $B_R(y_0)$ and assume that

$$\|f(y)\| \leq M \quad \text{for} \quad \|y - y_0\| \leq 2R$$

and

$$\|d_j(y)\| \leq \mu M \left(\frac{2\kappa M}{R}\right)^{j-1} \quad \text{for} \quad \|y - y_0\| \leq R$$

hold. If $h \leq h_0/4$ with $h_0 = R/(e\eta M)$, then there exists $N = N(h)$ (namely N equals the largest integer satisfying $hN \leq h_0 < h(N+1)$) such that the difference between the numerical solution $y_1 = \Phi_h(y_0)$ and the exact solution $\varphi_{N,t}(y_0)$ of the truncated modified equation satisfies

$$\|\Phi_h(y_0) - \varphi_{N,h}(y_0)\| \leq h\gamma M e^{-h_0/h}$$

where $\gamma = e(2 + 1.65\eta + \mu)$ depends only on the method.

The proof proceeded in the following steps, where all parts except for part (d) were done in the lecture.

(a) Show that for $g(h) := \Phi_h(y_0) - \varphi_{N,h}(y_0)$ the bound

$$\|g(h)\| \leq \left(\frac{h}{\varepsilon}\right)^{N+1} \max_{|z| \leq \varepsilon} \|g(z)\|$$

holds for $0 \leq h \leq \varepsilon := eh_0/N$.

(b) Split the error in two parts,

$$\|g(z)\| \leq \|\Phi_z(y_0) - y_0\| + \|\varphi_{N,z}(y_0) - y_0\|,$$

which are estimated separately in the following two steps of the proof.

(c) Show that

$$\|\Phi_z(y_0) - y_0\| \leq \varepsilon M(1 + \mu)$$

holds.

(d) Show that

$$\|\varphi_{N,z}(y_0) - y_0\| \leq \varepsilon M(1 + 1.65\eta)$$

for $\varphi_{N,z}(y_0) \in B_{R/2}(y_0)$.

(e) Finally combine both bounds to obtain the desired result.

Exercise 19:

Consider a differential equation

$$y'(t) = f(y(t)), \quad y(0) = y_0,$$

which possesses the invariant $I(y)$. We solve this equation numerically with a scheme $\Phi_h(y)$, that also conserves the invariant. Show that the modified equation conserves $I(y)$ as well.

Hint: Show via induction that $\nabla I(y)f_j(y) = 0$, $j = 1, \dots, r$ holds. For this purpose let $\varphi_{r,t}^{(h)}$ be the flow of the truncated modified equation $\tilde{y}' = f(\tilde{y}) + hf_2(\tilde{y}) + \dots + h^{r-1}f_r(\tilde{y})$, $\tilde{y}(0) = y_0$.

Programming Exercise 7:

- (a) Show that for a nonsymplectic method of order r applied to a Hamilton system the error in the energy grows linearly with the time, namely

$$H(y_n) - H(y_0) = \mathcal{O}(th^r),$$

where $t = nh$.

Hint: Use that the local error of the method is of the order h^{r+1} .

- (b) Consider the pendulum equation given by the Hamiltonian

$$H(p, q) = \frac{p^2}{2} - \cos(q)$$

with initial condition $(p_0, q_0) = (2.5, 0)$. Solve this equation with the explicit and the symplectic Euler method on the time interval $[0, T] = [0, 50]$ using the time step size $h = 0.005$. Plot the error in the energy H of both methods over time.

Programming Exercise 8:

Consider the pendulum equation given by the Hamilton function

$$H(p, q) = \frac{p^2}{2} - \cos(q).$$

- (a) Let K be a compact subset of $\{(x, y) \in \mathbb{R}^2; |x| \leq c\}$. Show that

$$\|f(p, q)\| \leq \sqrt{(c + 2R)^2 + e^{4R}} = M$$

for $f(p, q) = -J\nabla H(p, q)$ and $\|(p, q) - (p_0, q_0)\| \leq 2R$ with $(p_0, q_0) \in K$.

- (b) Now choose $c = 2$ and $R = 1/2$ and compute the corresponding time step size h_0 for the midpoint rule to obtain good energy conservation.
(c) Numerically compute the solution of the pendulum equations with the different initial conditions

$$(p_0, q_0) = (0, -1.5), \quad (0, -2.5), \quad (1.5, -\pi), \quad (2.5, -\pi).$$

Therefore use the midpoint rule with the time step size h_0 computed in the previous part on the time interval $[0, 200.000h_0]$ and plot the components p and q against each other. What happens to the results, if the time step size is increased?

Programming Exercise 9: *Oscillatory example – Fermi-Pasta-Ulam problem*

Consider the equation

$$x''(t) = -\omega^2 x(t), \quad \omega \gg 1$$

with initial conditions $x(0) = x_0$ and $x'(0) = x'_0$.

- (a) Show, that the exact solution of the system is given by

$$\begin{pmatrix} \omega x(t) \\ x'(t) \end{pmatrix} = \begin{pmatrix} \cos \omega t & \sin \omega t \\ -\sin \omega t & \cos \omega t \end{pmatrix} \begin{pmatrix} \omega x_0 \\ x'_0 \end{pmatrix}.$$

- (b) We consider the midpoint rule

$$y_{n+1} = y_n + hf\left(\frac{y_n + y_{n+1}}{2}\right)$$

for $y' = f(y)$ as well as the Störmer-Verlet method

$$\begin{aligned} x'_{n+1/2} &= x'_n + \frac{h}{2}g(x_n) \\ x_{n+1} &= x_n + hx'_{n+1/2} \\ x'_{n+1} &= x'_{n+1/2} + \frac{h}{2}g(x_{n+1}) \end{aligned}$$

for $x'' = g(x)$. Compute one step of each method applied to the above problem. Note that for the midpoint rule, the problem needs to be rewritten as a first order system. Analyze the stability of the methods with respect to the time step size h .

Hint: Write the numerical solution as

$$\begin{pmatrix} \omega x_{n+1} \\ x'_{n+1} \end{pmatrix} = M(h\omega) \begin{pmatrix} \omega x_n \\ x'_n \end{pmatrix}$$

and consider the eigenvalues of $M(h\omega)$.

(c) The Hamiltonian of the Fermi-Pasta-Ulam problem in the scaled expansions of the springs is given by

$$\begin{aligned} H(y, x) = & \frac{1}{2} \sum_{i=1}^m (y_{0i}^2 + y_{1i}^2) + \frac{\omega^2}{2} \sum_{i=1}^m x_{1i}^2 \\ & + \frac{1}{4} (x_{01} - x_{11})^4 + \frac{1}{4} \sum_{i=1}^{m-1} (x_{0i+1} - x_{1i+1} - x_{0i} - x_{1i})^4 + \frac{1}{4} (x_{0m} + x_{1m})^4, \end{aligned}$$

the oscillatory energy of the stiff springs is given by

$$I_j(x_{1j}, y_{1j}) = \frac{1}{2} (y_{1j}^2 + \omega^2 x_{1j}^2)$$

and the total oscillatory energy is $I = I_1 + \dots + I_m$. Consider for $m = 3$ and $\omega = 50$ the initial values

$$\begin{aligned} x_{01}(0) = 1, \quad y_{01}(0) = 1, \quad x_{11}(0) = \omega^{-1}, \quad y_{11}(0) = 1 \\ x_{0i}(0) = y_{0i}(0) = x_{1i}(0) = y_{1i}(0) = 0, \quad i = 2, 3. \end{aligned}$$

Solve this problem numerically on the time interval $[0, 225]$ with

- (i) the implicit midpoint rule,
- (ii) the symplectic Euler method and
- (iii) the Störmer-Verlet method.

Employ the time step sizes $h = 0.001$ and $h = 0.03$ and plot the shifted Hamiltonian $H(y, x) - 0.8$ as well as the total oscillatory energy I and the energies of the three stiff springs $I_j, j = 1, 2, 3$.