Rigidity for measurable sets

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The problem

Characterize sets $\Omega \subset \mathbb{R}^d$, with $|\Omega| < +\infty$, such that, for a given radius r > 0,

 $|\Omega \cap B_r(x)| = c > 0$ for $x \in \partial \Omega$



OUTLINE

- I. *Historical overview*: from 1932 to 2018
- II. The main result: rigidity for arbitrary measurable sets
- III. A look at the proof: rebuild of moving planes methods in a measure theoretic framework
- IV. Further remarks and open questions

[Cimmino '32] Is it possible to characterize C^0 surfaces Γ in \mathbb{R}^3 such that, for any sufficiently small radius r > 0,

$$\mathscr{H}^2(\Gamma^+ \cap \partial B_r(x)) = \mathscr{H}^2(\Gamma^- \cap \partial B_r(x)) = 2\pi r^2 \qquad \forall x \in \Gamma?$$

[Nitsche '95]

The only (smooth) surfaces with this property are the plane and the helicoid. [Meeks-Rosenberg '05]

The plane and the helicoid are the unique simply connected minimal surfaces embedded in $\mathbb{R}^3.$

Reprise in the first 2000s

• The Matzoh Ball Soup Problem: Klamkin 1964, Zalcman 1987 solved by Alessandrini in 1990

$$u_t = \Delta u$$
 in $\Omega \times (0, \infty)$.

Initially, u = 0. On the boundary u = 1. The sphere is the only bounded solid having the property of invariant equipotential surfaces. [Magnanini-Sakaguchi '02] only one surface is enough.

 ∂U is isothermal ⇔ U is B-dense [Magnanini-Prajapat-Sakaguchi '06] i.e.

$$|U \cap (x+rB)| = c(r)$$
 $\forall x \in \partial U$, $\forall r_0 > r > 0$.

• Theorem [Magnanini-Marini '16] U, K convex,

If U with $|U| \in (0, +\infty)$ is K-dense, then U and K are homothetic ellipsoids.

Relationship with the mean curvature

• Expansion [Hulin-Troyanov '03]

$$|\Omega \cap B_r(x)| = \frac{1}{2}\omega_d r^d - \frac{d-1}{2(d+1)}\omega_{d-1}H_{\Omega}(x)r^{d+1} + O(r^{d+2}),$$

- Applications in Geometry Processing: integral invariant estimator of the mean curvature.
- Theorem [Alexandrov '58, Delgadino-Maggi '19]
 - Balls are the unique bounded connected C^2 sets in \mathbb{R}^d having constant mean curvature.
 - Finite unions of equal balls are the unique sets of finite Lebesgue measure and finite perimeter in \mathbb{R}^d having constant distributional mean curvature.

Rigidity of measurable sets: r-criticality

By definition, for a FIXED positive radius r > 0 we say that Ω is *r*-critical if,

 $|\Omega \cap B_r(x)| = c \qquad \forall x \in \partial^* \Omega$

where $\partial^* \Omega$ is the essential boundary of Ω , i.e. the set of points $x \in \mathbb{R}^d$ such that

$$\limsup_{\rho\to 0} \frac{|\Omega\cap B_\rho(x)|}{\rho^d} > 0 \qquad \text{and} \qquad \limsup_{\rho\to 0} \frac{|(\mathbb{R}^d\setminus\Omega)\cap B_\rho(x)|}{\rho^d} > 0\,.$$

• Remark: $\partial^* \Omega \subseteq \partial \Omega$.

The variational interpretation

• Constant mean curvature sets are stationary for the isoperimetric inequality [De Giorgi '58]

$$\frac{\operatorname{Per}(\Omega)^{\frac{1}{d-1}}}{|\Omega|^{\frac{1}{d}}} \geq \frac{\operatorname{Per}(B)^{\frac{1}{d-1}}}{|B|^{\frac{1}{d}}}$$

• r-critical sets are stationary for the rearrangement inequality [Riesz '30]

$$\int_{\Omega} \int_{\Omega} h(x-y) \, dx \, dy \leq \int_{\Omega^*} \int_{\Omega^*} h(x-y) \, dx \, dy$$

holding for any radially symmetric, decreasing, nonnegative function h, when one chooses $h = \chi_{B_r(0)}$.

Equivalently: $2|\Omega \cap B_r(x)| - \omega_d r^d = |\Omega \cap B_r(x)| - |\Omega^c \cap B_r(x)| \Rightarrow$ *r*-critical sets are stationary for the nonlocal *r*-perimeter

$$r - \operatorname{Per}(\Omega) = \int_{\Omega} \int_{\Omega^c} \chi_{|x-y| < r} \, dx \, dy$$

[Chambolle-Morini-Ponsiglione '15, Mazon-Rossi-Toledo '19] .

The nonlocal side

Fractional perimeter [Caffarelli-Souganidis '08, Caffarelli-Roquejoffre-Savin '10]

$$P_s(\Omega) = \int_{\Omega} \int_{\Omega^c} \frac{1}{|x-y|^{d+2s}} \, dx \, dy \qquad s \in (0, 1/2)$$

is minimized by balls under volume constraint [Frank-Seiringer '08].

Critical sets have constant fractional mean curvature

$$H_{\Omega,s}(x) := \frac{1}{\omega_{d-2}} PV \int_{\mathbb{R}^d} \frac{\chi_{\Omega^c}(y) - \chi_{\Omega}(y)}{|y-x|^{d+2s}} \, dy$$

Theorem [Ciraolo-Figalli-Maggi-Novaga, Cabré-Fall-Solá Morales-Weth '18] If Ω is a bounded open set of class $C^{1,2s}$ and $H_{\Omega,s} = c$ on $\partial\Omega$, then Ω is a ball. Why our problem is different: the kernel equals χ_{B_r} !

- Bounded kernel allows to deal with measurable sets.
- The flatness (level sets of positive measure): a point can not distinguish how far is from the center of a kernel!
- Compactly supported kernel produces short-range non-local effects.
- Discontinuous kernel enhances the need for some "transmission condition", companion to *r*-criticality.

The companion condition: *r*-nondegeneracy

By definition, we say that Ω is not r-degenerate if



- A sufficient condition is: $\inf_{x \in \mathscr{U}_{\varepsilon}(\partial^*\Omega)} |D\chi_{B_r(x)}|(\Omega^{(1)}) > 0.$
- Any open connected set is not *r*-degenerate for any r < diameter.

Theorem [B.-Fragalà '21]

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Let Ω be a measurable set with finite Lebesgue measure in \mathbb{R}^d , and let r > 0. Assume that Ω is *r*-critical and is not *r*-degenerate, i.e.

$$\begin{split} |\Omega \cap B_r(x)| &= c > 0 \quad \forall x \in \partial^* \Omega, \qquad \inf_{x_1, x_2 \in \partial^* \Omega} \frac{\left|\Omega \cap (B_r(x_1) \Delta B_r(x_2))\right|}{\|x_1 - x_2\|} > 0. \end{split}$$

Then Ω is equivalent to a finite union of equal balls of radius $R > \frac{r}{2}$, t mutual distance larger than or equal to r .

• Bubbling is tuned by the initial choice of r.

• The analogue result holds true with ellipsoids in place of balls.

Some sets which escape from rigidity (though being *r*-critical)

Sets of infinite measure

• Halfspaces or strips:



Sets which are *r*-degenerate

• Small sets: any measurable set Ω with diam $(\Omega) \leq r$.



Small sets at large distance: the union of two measurable sets Ω₁, Ω₂ of equal measure, with diam(Ω_i) ≤ r and dist(Ω₁,Ω₂) ≥ r.



 Spaced small sets at small distance: the union of a family of measurable sets of equal measure suitably "equidistributed" along a circle in ℝ².



Rigidity for sets enjoying some regularity

Corollary (the case of open sets)

Let Ω be an open set with finite Lebesgue measure in $\mathbb{R}^d,$ and let r>0. Assume that

$$|\Omega \cap B_r(x)| = c \quad \forall x \in \partial \Omega.$$

If Ω is connected and $r < \operatorname{diam}(\Omega)$, then Ω is a ball.

If Ω has multiple components Ω_i and $r < \inf_i \{\operatorname{diam}(\Omega_i)\}$, then Ω is a finite union of equal balls of radius $R > \frac{r}{2}$, at distance larger than or equal to r.

Corollary (the case of sets with finite perimeter)

Let Ω be set with finite Lebesgue measure and finite perimeter in \mathbb{R}^d , and let r > 0. Assume that

$$|\Omega \cap B_r(x)| = c$$
 for \mathscr{H}^{d-1} -a.e. $x \in \mathscr{F}\Omega$.

If Ω is indecomposable and $r < \operatorname{diam}(\Omega)$, then Ω is a ball.

If Ω has multiple components Ω_i and $r < \inf_i \{ \operatorname{diam}(\Omega_i) \}$, then Ω is a finite union of equal balls of radius $R > \frac{r}{2}$, at distance larger than or equal to r.

- $\mathscr{F}\Omega$ is the reduced boundary, i.e. the collection of points $x \in \operatorname{supp}(D\chi_{\Omega})$ such that the generalized normal exists
- Ω is indecomposable if it is not possible to find a partition (Ω_1, Ω_2) of Ω such that $|\Omega_1| > 0$, $|\Omega_2| > 0$ and $Per(\Omega) = Per(\Omega_1) + Per(\Omega_2)$



The method of moving planes

- Alexandrov idea: if the mean curvature of ∂Ω is constant, Ω has a plane of symmetry in every direction. This can be proved by moving a given plane H₀ to parallel positions H_t and "reflecting as far as possible".
- Applied to overdetermined PDEs [Serrin 71, Gidas-Ni-Nirenberg '79, Caffarelli-Gidas-Spruck 89, Berestycki-Nirenberg '91]

$$\begin{cases} -\Delta u = 1 & \text{in } \Omega, \\ u = 0 & \text{on } \partial \Omega \\ \frac{\partial u}{\partial n} = \text{constant} & \text{on } \partial \Omega \end{cases}$$

then $\boldsymbol{\Omega}$ has to be a ball.

How it works

• *Start*: For $t \ll 1$, the reflection \Re_t of the cap Ω_t is contained in Ω .



• *Stop*: At the stopping time: 1) interior tangency 2) orthogonality. Crucial fact: the boundary is locally the graph of a function *u*, and

$$\mathcal{H}_\Omega = rac{1}{d-1} {
m div} \Big(rac{
abla u}{\sqrt{1+|
abla u|^2}} \Big) \quad \Rightarrow \quad {
m a \ PDE \ can \ be \ exploited}$$



• Conclusion: Ω has a plane of symmetry in every direction \Rightarrow it is a ball.

Obstacles in the measurable setting

• Start: For $t \ll 1$, \mathscr{R}_t is not contained into Ω



• *Stop*: For nonsmooth sets, tangency and orthogonality make no sense. (No local graphicality and no PDE!)



• Conclusion: multiple balls have not a plane of symmetry in every direction.

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Rebuilding of the main steps

 Start : For t ≪ 1, 𝔐_t ⊂ Ω and Ω_t ∪ 𝔐_t is Steiner symmetric about H_t. By contradiction, using r-criticality and r-nondegeneracy.



• Stop: Replace interior tangency and orthogonality by:

- Away contact:
$$p \in \left[\overline{\partial^* \mathscr{R}_t} \cap \overline{\partial^* \Omega}\right] \setminus H_t$$

- Close contact: $q = \lim q_{1,n} = \lim q_{2,n} \in H_t, \ q_{i,n} \in \overline{\partial^*\Omega} \cap \{q + t\nu : t \in \mathbb{R}\}$



• Away contact implies local symmetry (based on symmetry inside *r*-moons, and on a ping-pong game)



 Close contact is not possible without away contact (based on a local analysis which exploits nondegeneracy)



• Conclusion

Under some connectedness hyp: Ω is symmetric about H_t

 $\Rightarrow \Omega$ is a ball since it has a plane of symmetry in every direction

Otherwise: $\Omega = \Omega^s \sqcup \Omega^{ns}$, with Ω^s open (the Steiner symmetric part of Ω) $\Rightarrow \Omega^s$ is a finite union of balls of equal radii, while Ω^{ns} is negligible.



- What about decreasing radial kernels h other than $\chi_{B_r(0)}$?
- What about measuring area intersection with spheres

$$\forall x \in \partial \Omega, \quad \mathscr{H}^{d-1}(\partial B_r(x) \cap \Omega) = c?$$

• What is our motivation?

Polygonal isoperimetric inequalities...

Thank you for your attention!