

**TMA371 Partial Differential Equations TM, 1999-12-21. Solutions**

1. Consider

$$(1) \quad \begin{cases} -\Delta u = 1, & \text{on } \Omega = (0, 1) \times (0, 1), \\ \frac{\partial u}{\partial n} = 0, & \text{for } x \in \Gamma_2 : x_1 = 1, \\ u = 0, & \text{for } x \in \Gamma_1 := \partial\Omega \setminus \{x_1 = 1\}, \end{cases}$$

Define

$$V = \{v : v \in H^1(\Omega), v = 0 \text{ on } \Gamma_1\}.$$

Multiply the equation by  $v \in V$  and integrate over  $\Omega$ ; using Green's formula

$$\int_{\Omega} \nabla u \cdot \nabla v - \int_{\Gamma} \frac{\partial u}{\partial n} v = \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} v,$$

where we have used  $\Gamma = \Gamma_1 \cup \Gamma_2$  and the fact that  $v = 0$  on  $\Gamma_1$  and  $\frac{\partial u}{\partial n} = 0$  on  $\Gamma_2$ .

Variational formulation:

Find  $u \in V$  such that

$$\int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} v, \quad \forall v \in V.$$

FEM: cG(1):

Find  $U \in V_h$  such that

$$(2) \quad \int_{\Omega} \nabla U \cdot \nabla v = \int_{\Omega} v, \quad \forall v \in V_h \subset V,$$

where

$V_h = \{v : v \text{ is piecewise linear and continuous in } \Omega, v = 0 \text{ on } \Gamma_1, \text{ on above mesh } \}$ .

A set of bases functions for the finite dimensional space  $V_h$  can be written as  $\{\varphi_i\}_{i=1}^4$ , where

$$\begin{cases} \varphi_i \in V_h, & i = 1, 2, 3, 4 \\ \varphi_i(N_j) = \delta_{ij}, & i, j = 1, 2, 3, 4. \end{cases}$$

Then the equation (2) is equivalent to: Find  $U \in V_h$  such that

$$(3) \quad \int_{\Omega} \nabla U \cdot \nabla \varphi_i = \int_{\Omega} \varphi_i, \quad i = 1, 2, 3, 4.$$

Set  $U = \sum_{j=1}^4 \xi_j \varphi_j$ . Invoking in the relation (3) above we get

$$\sum_{j=1}^4 \xi_j \int_{\Omega} \nabla \varphi_j \cdot \nabla \varphi_i = \int_{\Omega} \varphi_i, \quad i = 1, 2, 3, 4.$$

Now let  $a_{ij} = \int_{\Omega} \nabla \varphi_j \cdot \nabla \varphi_i$  and  $b_i = \int_{\Omega} \varphi_i$ , then we have that

$$A\xi = b, \quad A \text{ is the stiffness matrix } b \text{ is the load vector.}$$

Below we compute  $a_{ij}$  and  $b_i$

$$b_i = \int_{\Omega} \varphi_i = \begin{cases} 6 \cdot \frac{1}{3} \cdot \frac{1/4 \cdot 1/2}{2} \cdot 1 = 1/8, & i = 1, 2, 3 \\ 3 \cdot \frac{1}{3} \cdot \frac{1/4 \cdot 1/2}{2} \cdot 1 = 1/16, & i = 4 \end{cases}$$

and

$$a_{ii} = \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_i = \begin{cases} 2 \cdot (\frac{5}{4} + 1 + \frac{1}{4}) = 5, & i = 1, 2, 3 \\ \frac{5}{4} + 1 + \frac{1}{4} = 5/2, & i = 4 \end{cases}$$

Further

$$a_{i,i+1} = \int_{\Omega} \nabla \varphi_{i+1} \cdot \nabla \varphi_i = 2 \cdot (-1) = -2 = a_{i+1,i}, \quad i = 1, 2, 3,$$

and

$$a_{ij} = 0, \quad |i - j| > 1.$$

Thus we have

$$A = \begin{pmatrix} 5 & -2 & 0 & 0 \\ -2 & 5 & -2 & 0 \\ 0 & -2 & 5 & -2 \\ 0 & 0 & -2 & 5/2 \end{pmatrix} \quad b = \frac{1}{16} \begin{pmatrix} 2 \\ 2 \\ 2 \\ 1 \end{pmatrix}.$$

**2.** For the proof of the Lax-Milgram theorem see the book, Chapter 21.

As for the given case:  $I = (0, 1)$ ,  $f \in L_2(I)$ ,  $V = H^1(I)$  and

$$a(v, w) = \int_I v' w' dx + v(0)w(0), \quad L(v) = \int_I f v dx,$$

it is trivial to show that  $a(\cdot, \cdot)$  is bilinear and  $b(\cdot)$  is linear. We have that

$$(4) \quad a(v, v) = \int_I (v')^2 dx + v(0)^2 \geq \frac{1}{2} \int_I (v')^2 dx + \frac{1}{2} v(0)^2 + \frac{1}{2} \int_I (v')^2 dx.$$

Further

$$v(x) = v(0) + \int_0^x v'(y) dy, \quad \forall x \in I$$

implies

$$\begin{aligned} v^2(x) &\leq 2 \left( v(0)^2 + \left( \int_0^x v'(y) dy \right)^2 \right) \\ &\leq \{C - S\} \leq 2v(0)^2 + 2 \int_0^1 v'(y)^2 dy, \end{aligned}$$

so that

$$\frac{1}{2} v(0)^2 + \frac{1}{2} \int_0^1 v'(y)^2 dy \geq \frac{1}{4} v^2(x), \quad \forall x \in I.$$

Integrating over  $x$  we get

$$(5) \quad \frac{1}{2} v(0)^2 + \frac{1}{2} \int_0^1 v'(y)^2 dy \geq \frac{1}{4} \int_I v^2(x) dx.$$

Now combining (4) and (5) we get

$$\begin{aligned} a(v, v) &\geq \frac{1}{4} \int_I v^2(x) dx + \frac{1}{2} \int_I (v')^2(x) dx \\ &\geq \frac{1}{4} \left( \int_I v^2(x) dx + \int_I (v')^2(x) dx \right) = \frac{1}{4} \|v\|_V^2, \end{aligned}$$

so that we can take  $\kappa_1 = 1/4$ . Further

$$\begin{aligned} |a(v, w)| &\leq \left| \int_I v' w' dx \right| + |v(0)w(0)| \\ &\leq \{C - S\} \leq \|v'\|_{L_2(I)} \|w'\|_{L_2(I)} + |v(0)| |w(0)| \\ &\leq \|v\|_V \|w\|_V + |v(0)| |w(0)|. \end{aligned}$$

Now we have that

$$(6) \quad v(0) = - \int_0^x v'(y) dy + v(x), \quad \forall x \in I,$$

and by the Mean-value theorem for the integrals:  $\exists \xi \in I$  so that  $v(\xi) = \int_0^1 v(y) dy$ . Choose  $x = \xi$  in (6) then

$$\begin{aligned} |v(0)| &= \left| - \int_0^\xi v'(y) dy + \int_0^1 v(y) dy \right| \\ &\leq \int_0^1 |v'| dy + \int_0^1 |v| dy \leq \{C - S\} \\ &\leq \|v'\|_{L_2(I)} + \|v\|_{L_2(I)} \leq 2\|v\|_V, \end{aligned}$$

implies that

$$|v(0)| |w(0)| \leq 4\|v\|_V \|w\|_V,$$

and consequently

$$|a(u, w)| \leq \|v\|_V \|w\|_V + 4\|v\|_V \|w\|_V = 5\|v\|_V \|w\|_V,$$

so that we can take  $\kappa_2 = 5$ . Finally

$$|L(v)| = \left| \int_I f v dx \right| \leq \|f\|_{L_2(I)} \|v\|_{L_2(I)} \leq \|f\|_{L_2(I)} \|v\|_V,$$

taking  $\kappa_3 = \|f\|_{L_2(I)}$  all the conditions in the Lax-Milgram theorem are fulfilled.

**3. a)** Multiply the equation by  $\dot{u}$  and integrate to obtain

$$\begin{aligned} (\ddot{u}, \dot{u}) - (\Delta u, \dot{u}) + (u, \dot{u}) &= 0, \\ (\ddot{u}, \dot{u}) + (\nabla u, \nabla \dot{u}) + (u, \dot{u}) &= 0, \\ \frac{1}{2} \frac{d}{dt} (\|\dot{u}\|^2 + \|\nabla u\|^2 + \|u\|^2) &= 0, \\ \frac{1}{2} (\|\dot{u}(t)\|^2 + \|\nabla u(t)\|^2 + \|u(t)\|^2) &= \frac{1}{2} (\|u_1\|^2 + \|\nabla u_0\|^2 + \|u_0\|^2). \end{aligned}$$

This means that the energy  $E = \frac{1}{2} (\|\dot{u}(t)\|^2 + \|\nabla u(t)\|^2 + \|u(t)\|^2)$  is conserved.

b) Set  $v_1 = \dot{u}$ ,  $v_2 = u$ . Then

$$\begin{aligned} \dot{v}_1 - \Delta v_2 + v_2 &= 0, \\ \dot{v}_2 - v_1 &= 0. \end{aligned}$$

Now we have a system  $\dot{v} + Av = 0$  of first order in  $t$  and we can use various techniques developed for such systems, for example, we can apply standard time-discretization methods such as  $dG(0)$  or  $cG(1)$ .

4. Multiplication by  $u$  gives

$$\varepsilon \|u'\|^2 + \int_0^1 \alpha u' u \, dx + \|u\|^2 = (f, u) \leq \|f\| \|u\| \leq \frac{1}{2} \|f\|^2 + \frac{1}{2} \|u\|^2.$$

Here

$$(7) \quad \begin{aligned} \int_0^1 \alpha u' u \, dx &= \frac{1}{2} \int_0^1 \alpha \frac{d}{dx} u^2 \, dx \\ &= \frac{1}{2} \alpha(1) u(1)^2 - \frac{1}{2} \int_0^1 \alpha' u^2 \, dx \geq 0, \end{aligned}$$

and hence

$$\varepsilon \|u'\|^2 + \frac{1}{2} \|u\|^2 \leq \frac{1}{2} \|f\|^2.$$

This proves

$$(8) \quad \sqrt{\varepsilon} \|u'\| \leq \|f\|, \quad \|u\| \leq \|f\|.$$

Multiply the equation by  $\alpha u'$  and integrate over  $x$  to obtain

$$-\varepsilon \int_0^1 u'' \alpha u' \, dx + \|\alpha u'\|^2 + \int_0^1 \alpha u' u \, dx \leq \frac{1}{2} \|f\|^2 + \frac{1}{2} \|\alpha u'\|^2.$$

Hence by (7)

$$\begin{aligned} \|\alpha u'\|^2 &\leq \|f\|^2 + \varepsilon \int_0^1 \alpha \frac{d}{dx} (u')^2 \, dx \\ &= \|f\|^2 - \varepsilon \alpha(0) u'(0)^2 - \varepsilon \int_0^1 \alpha' (u')^2 \, dx \\ &\leq \|f\|^2 + \|\alpha'\| \varepsilon \|u'\|^2 \leq \|f\|^2 + C \varepsilon \|u'\|^2. \end{aligned}$$

Using also (8) we conclude

$$(9) \quad \|\alpha u'\| \leq C \|f\|.$$

Finally, by the differential equation and (8) and (9) we get

$$\varepsilon \|u''\| = \|f - \alpha u' - u\| \leq \|f\| + \|\alpha u'\| + \|u\| \leq C \|f\|.$$

5. We have, using the hint, that

$$\begin{aligned} \|v\|^2 &= \int_0^1 v^2 \, dx = \int_0^{1/2} v^2 \, dx + \int_{1/2}^1 v^2 \, dx \\ &= [(x - 1/2)v(x)^2]_0^{1/2} + [(x - 1/2)v(x)^2]_{1/2}^1 - \int_0^1 (x - 1/2)2v(x)v'(x) \, dx \\ &\leq \frac{1}{2}v(0)^2 + \frac{1}{2}v(1)^2 + \|v\| \|v'\| \leq \frac{1}{2}(v(0)^2 + v(1)^2 + \|v'\|^2) + \frac{1}{2}\|v\|^2, \end{aligned}$$

and the proof is complete.

MA