Chapter 15. The Poisson Equation

Solve the Poisson equation

$$\begin{cases}
-\Delta u = f & \text{in } \Omega \\
u = 0 & \text{on } \partial\Omega,
\end{cases}$$

where Ω is a bounded domain in \mathbb{R}^2 , with polygonal boundary $\Gamma = \partial \Omega$.

To derive stability estimates we multiply the equation by u and integrate over Ω to obtain

$$-\int_{\Omega} (\Delta u) u dx = \int_{\Omega} f \ u dx, \quad x \in \Omega \text{ and } u \in V.$$

Using Green's formula and the boundary condition: u = 0 on Γ , we get that

(1)
$$\|\nabla u\|^2 = \int_{\Omega} fu \le \|f\| \|u\|,$$

where $\|\cdot\|$ denotes the usual $L_{2(\Omega)}$ -norm.

Poincaré inequality (2D-version):

$$||u|| \le C_{\Omega} ||\nabla u||$$

Proof. Let φ be a function such that $\Delta \varphi = 1$ in Ω , and $2|\nabla \varphi| \leq C_{\Omega}$ in Ω , (such a function exists), then again by the use of Green's formula and the boundary condition we get

$$||u||^2 = \int_{\Omega} u^2 \Delta \varphi = -\int_{\Omega} 2u (\nabla u \cdot \nabla \varphi) \le C_{\Omega} ||u|| \, ||\nabla u||.$$

Thus

$$||u|| \le C_{\Omega} ||\nabla u||.$$

Now combining with formula (1) we get that the following weak stability estimate:

Exercise: Derive corresponding estimates for following problem:

$$\begin{cases}
-\Delta u + u = f, & \text{in } \Omega \\
\frac{\partial u}{\partial n} = 0, & \text{on } \Gamma = \partial \Omega
\end{cases}$$

Error estimates for FEM for the Poisson equation:

$$\begin{cases}
-\Delta u = f, & \text{in } \Omega \\
u = 0, & \text{on } \Gamma = \partial \Omega
\end{cases}$$

where $\Omega \subset \mathbb{R}^d$, d = 1, 2, 3, with following <u>variational formulation</u>:

Find U(x) such that u(x) = 0 on $\Gamma = \partial \Omega$ and

$$(V): \int_{\Omega} \nabla u \cdot \nabla v \, dx = \int_{\Omega} f v \, dx$$
 for all v such that $v = 0$ on Γ .

<u>FEM</u>: Let $\mathcal{T} = \{K : \cup K = \Omega\}$ be a triangulation of Ω and $\varphi_j, j = 1, 2, ..., n$ be the corresponding basis functions, such that $\varphi_j(x)$ is continuous, linear in x on each K and

$$\varphi_j(N_i) = \begin{cases} 1 & \text{for } i = j \\ 0 & \text{for } i \neq j \end{cases}$$

where N_1, N_2, \ldots, N_n are the inner nodes in the triangulation.

Now we set the approximate solution:

$$U(x) = U_1 \varphi_1(x) + U_2 \varphi_2(x) + \ldots + U_n \varphi_n(x),$$

and seek the coefficients $U_i = U(N_i)$, i.e., the nodal values of U(x), at the nodes N_i , $1 \le i \le n$, so that

(FEM)
$$\int_{\Omega} \nabla U \cdot \nabla \varphi_j \, dx = \int_{\Omega} f \cdot \varphi_j \, dx, \quad j = 1, 2, \dots n$$
 or equivalently

$$(V_h^0) \qquad \int_{\Omega} \nabla U \cdot \nabla v \, dx = \int_{\Omega} f \cdot v \, dx, \quad \forall v \in V_h^0.$$

Recall that

 $V_h^0 = \{v(x) : v \text{ is continuous, piecewise linear in } x \text{ (on } \mathcal{T}), \text{ and } v = 0 \text{ on } \Gamma = \partial \Omega\}.$

Note that for $v \in V_h^0$ we have

$$v(x) = v(N_1)\varphi_1(x) + v(N_2)\varphi_2(x) + \ldots + v(N_n)\varphi_n(x).$$

For the error e = u - U we have $\nabla e = \nabla u - \nabla U = \nabla (u - U)$. We observe that subtracting the formula (V_h^0) from the (V); we obtain the Galerkin Orthogonality:

(4)
$$\int_{\Omega} (\nabla u - \nabla U) \nabla v \, dx = \int_{\Omega} \nabla e \cdot \nabla v \, dx = 0, \qquad \forall v \in V_h^0.$$

On the other hand we may write

$$\|\nabla e\|^2 = \int_{\Omega} \nabla e \cdot \nabla e \, dx = \int_{\Omega} \nabla e \cdot \nabla (u - U) \, dx = \int_{\Omega} \nabla e \cdot \nabla u \, dx - \int_{\Omega} \nabla e \cdot \nabla U \, dx,$$

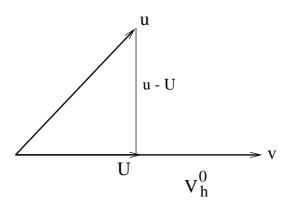
where using the Galerkin orthogonality (4), since $U(x) \in V_h^0$ we have the last integral above: $\int_{\Omega} \nabla e \cdot \nabla U \, dx = 0$. Thus inserting $\int_{\Omega} \nabla e \cdot \nabla v \, dx = 0$, $\forall v \in V_h^0$ we have that

$$\|\nabla e\|^2 = \int_{\Omega} \nabla e \cdot \nabla u dx - \int_{\Omega} \nabla e \cdot \nabla v dx = \int_{\Omega} \nabla e \cdot \nabla (u - v) dx \leq \|\nabla e\| \cdot \|\nabla (u - v)\|.$$

Hence

(5)
$$\|\nabla(u-U)\| \le \|\nabla(u-v)\|, \quad \forall v \in V_h^0,$$

that is, U is closer to u than any other v in V_h^0 .



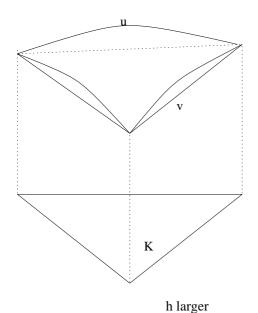
In other words the error u-U is orthogonal to V_h^0 .

It is possible to show that there is a $v \in V_h^0$ (an interpolant), such that

(6)
$$\|\nabla(u-v)\| \le C\|h\,D^2u\|,$$

where h = h(x) = diam(K) for $x \in K$ and C is a constant, independent of h.

This is the case, for example, if v interpolates u at the nodes N_i







h smaller





Combining (5) and (6) we get

(7)
$$\|\nabla e\| = \|\nabla(u - U) \le C\|h D^2 u\|,$$

which is indicating that the error is small if h(x) is sufficiently small depending on D^2u :

Estimate of the error e = u - U:

Let φ be the solution of the dual problem

$$\begin{cases}
-\Delta \varphi = e, & \text{in } \Omega \\
\varphi = 0, & \text{on } \partial \Omega
\end{cases}$$

Then

(8)
$$\begin{aligned} \|e\|^2 &= \int_{\Omega} e(-\Delta \varphi) dx = \{ \text{Green's formula} \} = \int_{\Omega} \nabla e \cdot \nabla \varphi \ dx, \\ &= \{ \text{Galerkin orthogonality} \} = \int_{\Omega} \nabla e \cdot \nabla (\varphi - v) \ dx \\ &\leq \|\nabla e\| \cdot \|\nabla (\varphi - v)\|, \quad \forall v \in V_h^0. \end{aligned}$$

We now choose v such that

(9)
$$\|\nabla(\varphi - v)\| \le C\|h \cdot D^2\varphi\| \le C \max_{\Omega} h \cdot \|D^2\varphi\|.$$

<u>Lemma:</u> Assume that Ω has no re-intrents. We have for $u \in H^2(\Omega)$; with u = 0 or $(\frac{\partial u}{\partial n} = 0)$ on $\partial \Omega$. that

$$||D^2u|| < c_{\Omega} \cdot ||\Delta u||,$$

where

$$D^2 u = (u_{xx}^2 + 2u_{xy}^2 + u_{yy}^2)^{1/2}.$$

We postpone the proof of this lemma and first derive the error estimate:

Applying the lemma to φ , we get

$$||D^2\varphi|| \le C_{\Omega} \cdot ||\Delta\varphi|| = C_{\Omega}||e||$$

Now (7)-(10) implies that

$$||e||^{2} \leq (8) \leq ||\nabla e|| \cdot ||\nabla(\varphi - v)|| \leq (9) \leq ||\nabla e|| \cdot C \max_{\Omega} h ||D^{2}\varphi||$$

$$\leq (10) \leq ||\nabla e|| \cdot C \max_{\Omega} hC_{\Omega}||e|| \leq (7) \leq C^{2} C_{\Omega} \max_{\Omega} h||e|| ||h|D^{2}u||.$$

Thus we have obtained the following a priori error estimate:

$$||e|| = ||u - U|| \le C^2 C_{\Omega} (\max_{\Omega} h) \cdot ||h| D^2 u||,$$

which using the Lemma, for a uniform (constant h), can be written as an stability estimate viz,

$$||u - U|| \le C^2 C_{\Omega}^2 (\max_{\Omega} h)^2 ||f||.$$

A posteriori error estimate. For simplicity we consider a one dimensional case with $\Omega = (0, 1)$ and study the problem:

(11)
$$\begin{cases} -\varphi''(x) = e(x), & 0 < x < 1, \\ \varphi(0) = \varphi(1) = 0, & e(x) = u(x) - U(x). \end{cases}$$

Using (11) the L2-norm of the error can be written as:

$$||e||^2 = \int_{\Omega} e \cdot e \, dx = \int_{\Omega} e(-\varphi'') dx = \int_{\Omega} e' \cdot \varphi' \, dx.$$

Thus, using the one-dimensional version of the Galerkin orthogonality: $\int_{\Omega} e' \cdot v' dx = 0$, and the boundary data: $\varphi(0) = \varphi(1) = 0$ (in a partial integration) we can write

$$||e||^{2} = \int_{\Omega} e' \cdot \varphi' dx - \int_{\Omega} e' \cdot v' dx = \int_{\Omega} e' \cdot (\varphi - v)' dx = \int_{\Omega} (-e'')(\varphi - v) dx =$$

$$\leq ||h^{2}r|| \cdot ||h^{-2}(\varphi - v)|| \leq C \cdot ||h^{2}r|| \cdot ||\varphi''|| \leq C \cdot ||h^{2}r|| \cdot ||e||,$$

where we use the fact that the -e'' = -u'' + U'' = f + U'' is the residual r and v is an interpolant of φ . Thus, for this problem, the final a posteriori error estimate is:

$$||u - U|| \le C ||h^2 r||.$$

Observe that for piecewise linear approximations U'' = 0 on each element K and hence $r \equiv f$ and our a posteriori error estimate above can be viewed as a stability estimate viz,

$$||e|| \le C ||h^2 f||.$$

Exercise 1: Show that $||(u-U)'|| \le C||hr||$

Exercise 2: Verify that for v being the interpolant of φ , we have

$$||h^{-2}(\varphi - v)|| \le C ||\varphi''||, \text{ and}$$

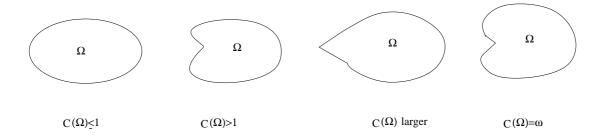
 $||h^{-1}(\varphi - v)|| \le C ||\varphi'||$

Exercise 3: Derive the corresponding estimate to (12) in the 2-dimensional case (d=2).

Note that now is $\nabla e(\varphi - v) \neq 0$ on the enter-element boundaries.

Now we return to the proof of Lemma 1:

First note that for convex Ω , the constant $C_{\Omega} \leq 1$ in lemma 1, otherwise the constant $C_{\Omega} > 1$ and increases from left to right for the Ω :s below.



Proof. Let Ω be a rectangular domain and set u=0 on $\partial\Omega$. We have then

$$\|\Delta u\|^2 = \int_{\Omega} (u_{xx} + u_{yy})^2 dx dy = \int_{\Omega} (u_{xx}^2 + 2u_{xx}u_{yy} + u_{yy}^2) dx dy.$$

Further applying Green's formula: $\int_{\Omega} (\Delta u) v \, dx = \int_{\Gamma} (\nabla u \cdot n) v \, ds - \int_{\Omega} \nabla u \cdot \nabla v \, dx$ to our rectangular domain Ω we have

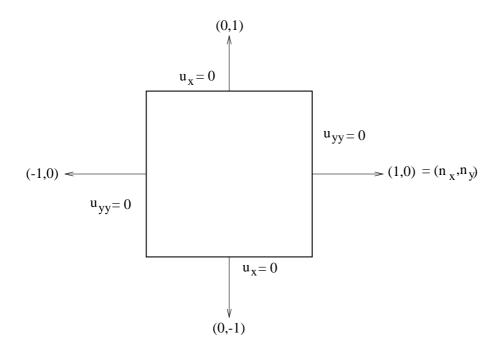
(13)
$$\int_{\Omega} u_{xx} u_{yy} dx dy = \int_{\partial \Omega} u_{x} (u_{yy} \cdot n_{x}) ds - \int_{\Omega} u_{x} \underbrace{u_{yyx}}_{=u_{xyy}} dx dy$$

using Green's formula once again (with " $v=u_x$ ", " $\Delta u=u_{xyy}$ ") we have

$$\int_{\Omega} u_x u_{xyy} dx dy = \int_{\partial \Omega} u_x (u_{yx} \cdot n_y) ds - \int_{\Omega} u_{xy} u_{xy} dx dy,$$

which inserting in (13) gives that

$$\int_{\Omega} u_{xx} u_{yy} \, dx dy = \int_{\partial \Omega} (u_x u_{yy} n_x - u_x u_{yx} n_y) ds + \int_{\Omega} u_{xy} u_{xy} \, dx dy.$$



Now, as we can see from the figure that $(u_x u_{yy} n_x - u_x u_{yx} n_y) = 0$, on $\partial \Omega$ and hence we have

$$\int_{\Omega} u_{xx} u_{yy} dx dy = \int_{\Omega} u_{xy} u_{xy} dx dy = \int_{\Omega} u_{xy}^2 dx dy.$$

Thus, in this case,

$$\|\Delta u\|^2 = \int_{\Omega} (u_{xx} + u_{yy})^2 dx dy = \int_{\Omega} (u_{xx}^2 + 2u_{xy}^2 + u_{yy}^2) dx dy = \|D^2 u\|^2,$$

and the proof is complete. \Box