

**MVE455: Partial Differential Equations, 2018–03–12, 14:00-18:00**

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*Calculators, formula notes and other subject related material are not allowed.*

Each problem gives max 6p. Valid bonus points will be added to the scores.

Breakings: **3:** 10-15p, **4:** 16-20p och **5:** 21p-

For solutions and information about gradings see the course diary in:

<http://www.math.chalmers.se/Math/Grundutb/CTH/mve455/1718/coursediary>

1.  $\pi_1 f$  is the linear interpolant of a twice continuously differentiable function  $f$  on  $I$ . Use Lagrange interpolation error formula and prove that

$$\|f - \pi_1 f\|_{L_1(I)} \leq (b - a)^2 \|f''\|_{L_1(I)}, \quad I = (a, b).$$

2. Consider the heat equation for  $\Omega \subset \mathbb{R}^2$  with boundary  $\partial\Omega = \Gamma$ ,

$$(1) \quad \begin{cases} u_t(x, t) - \Delta u(x, t) = 0, & \text{for } x \in \Omega, \quad 0 < t \leq T, \\ u(x, t) = 0, & \text{for } x \in \Gamma, \quad 0 < t \leq T, \\ u(x, 0) = u_0(x), & \text{for } x \in \Omega, \end{cases}$$

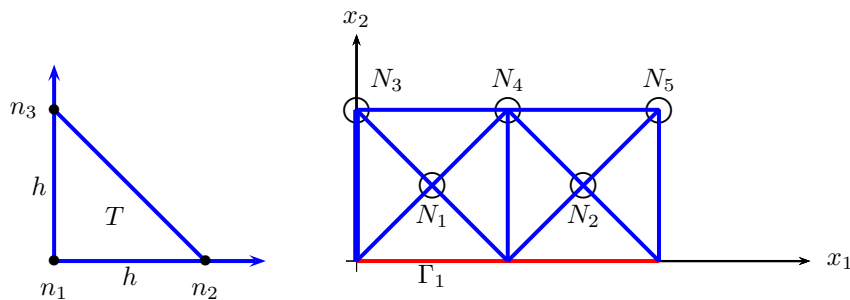
Let  $\tilde{u}$  be the solution of (1) with a modified initial data  $\tilde{u}_0(x) = u_0(x) + \varepsilon(x)$ .

- a) Show that  $w := \tilde{u} - u$  solves (1) with data  $w_0(x) = \varepsilon(x)$  ( and  $f = 0$ ). Derive stability estimates for  $w$ , i.e. estimate  $\|w(T)\|^2 + 2 \int_0^T \|\nabla w\|^2 dt$  by  $\|w_0\|^2$ .
- b) Use stability estimate for  $w$  to prove that the solution of (1) is unique.

3. Prove an a posteriori error estimate for the cG(1) finite element method for

$$-u''(x) + u'(x) = f, \quad 0 < x < 1; \quad u(0) = u(1) = 0.$$

4. Formulate the cG(1) piecewise continuous Galerkin method in  $\Omega$  (see fig. below) for the problem  $-\Delta u(x) = 1$ , for  $x \in \Omega$ ,  $u(x) = 0$ , for  $x \in \Gamma_1$ , and  $\nabla u(x) \cdot \mathbf{n}(x) = 1$  for  $x \in \partial\Omega \setminus \Gamma_1$ , where  $\mathbf{n}(x)$  is the outward unit normal to  $\partial\Omega$  at  $x \in \partial\Omega$ . Determine the coefficient matrix and load vector for the resulting equation system using the mesh as in the fig. with nodes at  $N_1, N_2, N_3, N_4$  and  $N_5$  and a uniform mesh size  $h$ . Hint: First compute the matrix for the standard element  $T$ .



5. Consider the heat equation (1) in problem 2 above. Prove the following stability estimates

$$\max \left( \|u\|(t)^2 + 2 \int_0^t \|\nabla u\|(s)^2 ds \right) \leq \|u_0\|^2.$$

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void!

1. Let  $\lambda_0(x) = \frac{\xi_1 - x}{\xi_1 - x_0}$  and  $\lambda_1(x) = \frac{x - \xi_0}{\xi_1 - x_0}$  be two linear base functions. Then by the integral form of the Taylor formula we may write

$$\begin{cases} f(\xi_0) = f(x) + f'(x)(\xi_0 - x) + \int_x^{\xi_0} (\xi_0 - y)f''(y) dy, \\ f(\xi_1) = f(x) + f'(x)(\xi_1 - x) + \int_x^{\xi_1} (\xi_1 - y)f''(y) dy, \end{cases}$$

Therefore

$$\begin{aligned} \Pi_1 f(x) &= f(\xi_0)\lambda_0(x) + f(\xi_1)\lambda_1(x) \\ &= f(x) + \lambda_0(x) \int_x^{\xi_0} (\xi_0 - y)f''(y) dy + \lambda_1(x) \int_x^{\xi_1} (\xi_1 - y)f''(y) dy \end{aligned}$$

and by the triangle inequality we get

$$\begin{aligned} |f(x) - \Pi_1 f(x)| &= \left| \lambda_0(x) \int_x^{\xi_0} (\xi_0 - y)f''(y) dy + \lambda_1(x) \int_x^{\xi_1} (\xi_1 - y)f''(y) dy \right| \\ &\leq |\lambda_0(x)| \left| \int_x^{\xi_0} (\xi_0 - y)f''(y) dy \right| + |\lambda_1(x)| \left| \int_x^{\xi_1} (\xi_1 - y)f''(y) dy \right| \\ &\leq |\lambda_0(x)| \int_x^{\xi_0} |\xi_0 - y| |f''(y)| dy + |\lambda_1(x)| \int_x^{\xi_1} |\xi_1 - y| |f''(y)| dy \\ &\leq |\lambda_0(x)| \int_x^{\xi_0} (b - a) |f''(y)| dy + |\lambda_1(x)| \int_x^{\xi_1} (b - a) |f''(y)| dy \\ &\leq (b - a) (|\lambda_0(x)| + |\lambda_1(x)|) \int_a^b |f''(y)| dy \\ &= (b - a) (\lambda_0(x) + \lambda_1(x)) \int_a^b |f''(y)| dy = (b - a) \int_a^b |f''(y)| dy. \end{aligned}$$

Consequently

$$\int_a^b |f(x) - \Pi_1 f(x)| dx \leq \int_a^b (b - a) \left( \int_a^b |f''(y)| dy \right) dx = (b - a)^2 \|f''\|_{L_1(I)}.$$

2. We have that

$$(2) \quad \begin{cases} u_t - \Delta u = f, & \text{in } \Omega, \quad 0 < t \leq T, \\ u(x, t) = 0, & \text{on } \Gamma, \quad 0 < t \leq T, \\ u(x, 0) = u_0(x), & \text{in } \Omega, \end{cases}$$

and

$$(3) \quad \begin{cases} \tilde{u}_t - \Delta \tilde{u} = f, & \text{in } \Omega, \quad 0 < t \leq T, \\ \tilde{u}(x, t) = 0, & \text{on } \Gamma, \quad 0 < t \leq T, \\ \tilde{u}(x, 0) = u_0(x) + \varepsilon(x), & \text{in } \Omega, \end{cases}$$

Now we study  $w = \tilde{u} - u$ . (Propagation of disturbance).

a) Through subtracting (2) from (3) we get the differential equation for  $w$ :

$$(4) \quad \begin{cases} w_t - \Delta w = 0, & \text{in } \Omega, \quad 0 < t \leq T, \\ w(x, t) = 0, & \text{on } \Gamma, \quad 0 < t \leq T, \\ w(x, 0) = \varepsilon(x), & \text{in } \Omega, \end{cases}$$

By the stability estimates for the heat equation we have that

$$(5) \quad \|w(T)\| + 2 \int_0^T \|\nabla w\|^2 dt \leq \|\varepsilon\|^2. \quad (\text{No growth of disturbance}).$$

b) To prove uniqueness for (2), take  $\varepsilon = 0$  in (4) and prove that  $w \equiv 0$ . This is obvious from (5):

$$\|w(T)\| + 2 \int_0^T \|\nabla w\|^2 dt \leq 0,$$

where both  $\|w(T)\| \geq 0$  and  $\|\nabla w\|^2 \geq 0$ . Thus  $w \equiv 0$ , so the uniqueness is proved.

**3.** (a) We multiply the differential equation by a test function  $v \in H_0^1(I)$ ,  $I = (0, 1)$  and integrate over  $I$ . Using partial integration and the boundary conditions we get the following *variational problem*: Find  $u \in H_0^1(I)$  such that

$$(6) \quad \int_I (u'v' + u'v) = \int_I fv, \quad \forall v \in H_0^1(I).$$

A *Finite Element Method* with  $cG(1)$  reads as follows: Find  $U \in V_h^0$  such that

$$(7) \quad \int_I (U'v' + U'v) = \int_I fv, \quad \forall v \in V_h^0 \subset H_0^1(I),$$

where

$$V_h^0 = \{v : v \text{ is piecewise linear and continuous in a partition of } I, v(0) = v(1) = 0\}.$$

Now let  $e = u - U$ , then (1)-(2) gives that

$$(8) \quad \int_I (e'v' + e'v) = 0, \quad \forall v \in V_h^0.$$

We note that using  $e(0) = e(1) = 0$ , we get

$$(9) \quad \int_I e'e = \int_I \frac{1}{2} \frac{d}{dx} (e^2) = \frac{1}{2} (e^2)|_0^1 = 0.$$

Further, using Poicare inequality we have

$$\|e\|^2 \leq \|e'\|^2.$$

*A priori error estimate*: We use Poicare inequality and (9) to get

$$\begin{aligned} \|e\|_{H^1}^2 &= \int_I (e'e' + ee) \leq 2 \int_I e'e' = 2 \int_I (e'e' + e'e) = 2 \int_I (e'(u-U)' + e'(u-U)) \\ &= 2 \int_I (e'(u - \pi_h u)' + e'(u - \pi_h u)) + 2 \int_I (e'(\pi_h u - U)' + e'(\pi_h u - U)) \\ &= \{v = U - \pi_h u \text{ in (6)}\} = 2 \int_I (e'(u - \pi_h u)' + e'(u - \pi_h u)) \\ &\leq 2\|(u - \pi_h u)'\| \|e'\| + 2\|u - \pi_h u\| \|e'\| \\ &\leq 2C_i \{\|hu''\| + \|h^2 u''\|\} \|e\|_{H^1}, \end{aligned}$$

this gives that

$$\|e\|_{H^1} \leq C_i \{\|hu''\| + \|h^2 u''\|\},$$

which is the a priori error estimate.

A posteriori error estimate:

$$\begin{aligned}
\|e\|_{H^1}^2 &= \int_I (e'e' + ee) \leq 2 \int_I e'e' = 2 \int_I (e'e' + e'e) \\
&= 2 \int_I ((u-U)'e' + (u-U)'e) = \{v = e \text{ in (4)}\} \\
(10) \quad &= 2 \int_I fe - \int_I (U'e' + U'e) = \{v = \pi_h e \text{ in (5)}\} \\
&= \int_I f(e - \pi_h e) - \int_I (U'(e - \pi_h e)' + U'(e - \pi_h e)) \\
&= \{P.I. \text{ on each subinterval}\} = \int_I \mathcal{R}(U)(e - \pi_h e),
\end{aligned}$$

where  $\mathcal{R}(U) := f + U'' - U' = f - U'$ , (for approximation with picewise linears,  $U \equiv 0$ , on each subinterval). Thus (5) implies that

$$\begin{aligned}
\|e\|_{H^1}^2 &\leq \|h\mathcal{R}(U)\| \|h^{-1}(e - \pi_h e)\| \\
&\leq C_i \|h\mathcal{R}(U)\| \|e'\| \leq C_i \|h\mathcal{R}(U)\| \|e\|_{H^1},
\end{aligned}$$

where  $C_i$  is an interpolation constant, and hence we have with  $\|\cdot\| = \|\cdot\|_{L_2(I)}$  that

$$\|e\|_{H^1} \leq C_i \|h\mathcal{R}(U)\|.$$

4. Let  $V$  be the linear function space defined by

$$V := \{v : \int_{\Omega} (v^2 + |\nabla v|^2) dx < \infty, \quad v = 0, \text{ on } \Gamma_1\}.$$

Multiplying the differential equation by  $v \in V$  and integrating over  $\Omega$  we get that

$$-(\Delta u, v) = (1, v), \quad \forall v \in V.$$

Now using Green's formula and the boundary conditions we have that

$$-(\Delta u, \nabla v) = (\nabla u, \nabla v) - \int_{\partial\Omega} (n \cdot \nabla u) v ds = (\nabla u, \nabla v) - \int_{\partial\Omega \setminus \Gamma_1} v ds, \quad \forall v \in V.$$

Thus the variational formulation is:

$$\int_{\Omega} \nabla u \cdot \nabla v dx = \int_{\Omega} v dx + \int_{\partial\Omega \setminus \Gamma_1} v ds, \quad \forall v \in V.$$

Let  $V_h$  be the usual finite element space consisting of continuous piecewise linear functions satisfying the boundary condition  $v = 0$  on  $\Gamma_1$ :

$$V_h := \{v : v \text{ is continuous piecewise linear in } \Omega, \quad v = 0, \text{ on } \Gamma_1\}.$$

The  $cG(1)$  method is: Find  $U \in V_h$  such that

$$\int_{\Omega} \nabla U \cdot \nabla v dx = \int_{\Omega} v dx + \int_{\partial\Omega \setminus \Gamma_1} v ds, \quad \forall v \in V_h$$

Making the "Ansatz"  $U(x) = \sum_{j=1}^5 \xi_j \varphi_j(x)$ , where  $\varphi_i$  are the standard basis functions, we obtain the system of equations

$$\sum_{j=1}^4 \xi_j \left( \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j dx \right) = \int_{\Omega} \varphi_i dx + \int_{\partial\Omega \setminus \Gamma_1} \varphi_i ds, \quad i = 1, 2, 3, 4, 5,$$

or, in matrix form,

$$S\xi = \mathbf{b}, \quad S_{ij} = (\nabla \varphi_i, \nabla \varphi_j),$$

where  $S$  is the stiffness matrix, and  $\mathbf{b} = \mathbf{b}_1 + \mathbf{b}_2$  is the load vector with components

$$\mathbf{b}_{1,i} = \int_{\Omega} \varphi_i dx, \quad \text{and} \quad \mathbf{b}_{2,i} = \int_{\partial\Omega \setminus \Gamma_1} \varphi_i ds.$$

We first compute stiffness matrix for the reference triangle  $T$ . The local basis functions are

$$\begin{aligned}
\phi_1(x_1, x_2) &= 1 - \frac{x_1}{h} - \frac{x_2}{h}, & \nabla\phi_1(x_1, x_2) &= -\frac{1}{h} \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \\
\phi_2(x_1, x_2) &= \frac{x_1}{h}, & \nabla\phi_2(x_1, x_2) &= \frac{1}{h} \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \\
\phi_3(x_1, x_2) &= \frac{x_2}{h}, & \nabla\phi_3(x_1, x_2) &= \frac{1}{h} \begin{bmatrix} 0 \\ 1 \end{bmatrix}.
\end{aligned}$$

Hence, with  $|T| = \int_T dz = h^2/2$ ,

$$\begin{aligned}
s_{11} &= (\nabla\phi_1, \nabla\phi_1) = \int_T |\nabla\phi_1|^2 dx = \frac{2}{h^2}|T| = 1, \\
s_{12} &= (\nabla\phi_1, \nabla\phi_2) = \int_T |\nabla\phi_1|^2 dx = -\frac{1}{h^2}|T| = -1/2, & s_{13} &= -1/2 \\
s_{22} &= (\nabla\phi_2, \nabla\phi_2) = \int_T |\nabla\phi_2|^2 dx = \frac{1}{h^2}|T| = 1/2, & s_{23} &= (\nabla\phi_2, \nabla\phi_3) = 0, \\
s_{33} &= (\nabla\phi_3, \nabla\phi_3) = \int_T |\nabla\phi_3|^2 dx = \frac{1}{h^2}|T| = 1/2,
\end{aligned}$$

Thus using the symmetry we have the local stiffness matrix as

$$s = \frac{1}{2} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}.$$

We can now assemble the global matrix  $S$  from the local  $s$ , using the character of our mesh, viz:

$$\begin{aligned}
S_{11} &= 4s_{11} = 4, & S_{12} &= 0 & S_{13} &= S_{14} = 2s_{12} = -1 & S_{15} &= 0 \\
S_{22} &= 4s_{11} = 4 & S_{23} &= 0 & S_{24} &= S_{25} = 2s_{12} = -1 \\
S_{33} &= 2s_{22} = 1, & S_{34} &= s_{23} = 0, & S_{35} &= 0 \\
&& & & S_{44} &= 4s_{22} = 2, & S_{45} &= s_{23} = 0 \\
&& & & & & S_{55} &= 2s_{22} = 1
\end{aligned}$$

The remaining matrix elements are obtained by symmetry  $S_{ij} = S_{ji}$ . Hence,

$$S = \begin{bmatrix} 4 & 0 & -1 & -1 & 0 \\ 0 & 4 & 0 & -1 & -1 \\ -1 & 0 & 1 & 0 & 0 \\ -1 & -1 & 0 & 2 & 0 \\ 0 & -1 & 0 & 0 & 1 \end{bmatrix}.$$

As for the load vector we note that

$$\begin{aligned}
\mathbf{b}_{1,1} &= \int_{\Omega} \varphi_1 = 4 \cdot \frac{1}{3} \cdot \frac{h^2}{2} \cdot 1 = 4 \frac{h^2}{6}, \\
\mathbf{b}_{1,2} &= 4 \cdot \frac{1}{3} \cdot \frac{h^2}{2} \cdot 1 = 4 \frac{h^2}{6}, \\
\mathbf{b}_{1,3} &= 2 \cdot \frac{1}{3} \cdot \frac{h^2}{2} \cdot 1 = 2 \frac{h^2}{6}, \\
\mathbf{b}_{1,4} &= 4 \cdot \frac{1}{3} \cdot \frac{h^2}{2} \cdot 1 = 4 \frac{h^2}{6}, \\
\mathbf{b}_{1,5} &= 2 \cdot \frac{1}{3} \cdot \frac{h^2}{2} \cdot 1 = 2 \frac{h^2}{6},
\end{aligned} \tag{11}$$

$$\mathbf{b}_{2,1} = \mathbf{b}_{2,2} = 0, \mathbf{b}_{2,3} = \mathbf{b}_{2,4} = \mathbf{b}_{2,5} \int_{\partial\Omega} \varphi_i = 2 \cdot \frac{1}{2}(h \cdot 1) = h. \tag{12}$$

Hence the load vector  $\mathbf{b}$  is:

$$\mathbf{b} = \frac{h^2}{6} \begin{bmatrix} 4 \\ 4 \\ 2 \\ 4 \\ 2 \end{bmatrix} + h \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

5. See the Lecture Notes.

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