

1. Consider the initial value problem

$$\begin{cases} \dot{u}(t) + au(t) = 0, & t > 0, \\ u(0) = u_0, & a > 0, \quad (a = \text{constant}). \end{cases}$$

Assume a constant time step k and verify the iterative formulas for $dG(0)$ and $cG(1)$ approximations U and \tilde{U} respectively: i.e.

$$U_n = \left(\frac{1}{1+ak}\right)^n u_0, \quad \tilde{U}_n = \left(\frac{1-ak/2}{1+ak/2}\right)^n u_0.$$

2. Let $\mathcal{T}_h : x_0 = 0, x_1 = 1/3, x_2 = 2/3, x_3 = 1$ be a partition of the interval $[0,1]$. Write down the equation system $A\xi = b$ (determine A and b) for the piecewise linear Galerkin approximation on \mathcal{T}_h for the problem:

$$\begin{cases} -u''(x) + 18u(x) = 6, & \text{for } x \in (0, 1) \\ u'(0) = -1, \quad u(1) = 0. \end{cases}$$

3. Prove an a priori and an a posteriori error estimate (in the H^1 -norm: $\|u\|_{H^1}^2 := \|u'\|^2 + 2\|u\|^2$) for a finite element method for the problem

$$\begin{cases} -u''(x) + 2xu'(x) + 3u(x) = f(x), & \text{for } x \in (0, 1) \\ u(0) = u(1) = 0. \end{cases}$$

4. Prove that if $u = 0$ on the boundary of the unit square Ω , then

$$\left(\int_{\Omega} |u|^2 dx\right)^{1/2} \leq \left(\int_{\Omega} |\nabla u|^2 dx\right)^{1/2}, \quad (\text{Poincare inequality in 2D}).$$

5. Consider the boundary value problem

$$\begin{cases} -\Delta u = 0, & \text{in a bounded domain } \Omega \subset \mathbb{R}^d, \quad d = 2, 3. \\ \frac{\partial u}{\partial n} + u = g, & \text{on } \Gamma = \partial\Omega. \end{cases}$$

a) Prove the L_2 stability estimate

$$\|\nabla u\|_{L_2(\Omega)} + \frac{1}{2}\|u\|_{L_2(\Gamma)} \leq \frac{1}{2}\|g\|_{L_2(\Gamma)}.$$

b) Verify the conditions on Riesz/Lax-Milgram theorem for this problem.

2

void!

TMA372/MMG800: Partial Differential Equations, 2009–01–13; kl 8.30-13.30..
Lösningar.

1. See the Book and Lecture notes.

2. Multiply the equation with a test function $v \in H^1_{\underline{=}} = \{v : \|v\| + \|v'\| < \infty, \quad v(1) = 0\}$. Partial integration over $I = (0, 1)$ yields

$$\int_0^1 u'(x)v'(x) dx - [u'(x)v(x)]_{x=0}^{x=1} + 18 \int_0^1 u(x)v(x) dx = 6 \int_0^1 v(x) dx.$$

Using the boundary data we get the *variational formulation*: Find $u \in H^1_0(I)$ such that

$$(1) \quad \int_0^1 u'(x)v'(x) dx + 18 \int_0^1 u(x)v(x) dx = 6 \int_0^1 v(x) dx + v(0)$$

A *Finite element Method* with piecewise linear approximation is formulated as: Find $U \in V_h^0$ such that

$$(2) \quad \int_0^1 U'(x)v'(x) dx + 18 \int_0^1 U(x)v(x) dx = 6 \int_0^1 v(x) dx + v(0), \quad \forall v \in V_h^0 \subset H^1(I),$$

where

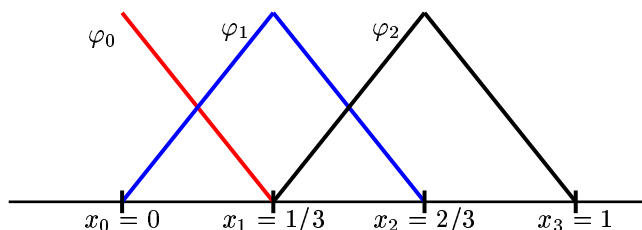
$$V_h^0 = \{v : v \text{ piecewise linear and continuous on the partition } \mathcal{T}_h, \quad v(1) = 0\}.$$

For the partition \mathcal{T}_h , and with the Neumann boundary data at $x = 0 : u'(0) = -1$, and the Dirichlet data at $x = 1 : u(1) = 0$ our bases functions are as follows:

$$\varphi_0(x) = \begin{cases} 1 - 3x, & 0 \leq x \leq 1/3 \\ 0, & 1/3 \leq x \leq 1. \end{cases} \quad \varphi_1(x) = \begin{cases} 3x, & 0 \leq x \leq 1/3 \\ 2 - 3x, & 1/3 \leq x \leq 2/3 \\ 0, & 2/3 \leq x \leq 1 \end{cases}$$

and

$$\varphi_2(x) = \begin{cases} 0, & 0 \leq x \leq 1/3 \\ 3x - 1, & 1/3 \leq x \leq 2/3 \\ 3 - 3x, & 2/3 \leq x \leq 1 \end{cases}$$



In this base we may use the ansatz $U(x) = \sum_{j=0}^2 \xi_j \varphi_j(x)$ in (4) and choose $v(x) = \varphi_i(x)$, $i = 0, 1, 2$. Then the finite element method (4) can be rewritten as

$$\sum_{j=0}^2 \xi_j \int_0^1 \varphi'_i(x)\varphi'_j(x) dx + 18 \sum_{j=0}^2 \xi_j \int_0^1 \varphi_i(x)\varphi_j(x) dx = 6 \int_0^1 \varphi_i(x) dx + \varphi_i(0), \quad i = 0, 1, 2,$$

or as a linear system of equations $A\xi = b$, $A = (a_{ij})$, with

$$a_{ij} = \int_0^1 \varphi_i'(x)\varphi_j'(x) dx + 18 \sum_{j=0}^2 \xi_j \int_0^1 \varphi_i(x)\varphi_j(x) dx, \quad i, j = 0, 1, 2.$$

$$b = (b_i), \quad b_i = 6 \int_0^1 \varphi_i(x) dx + \varphi_i(0), \quad i, j = 0, 1, 2.$$

Observe that the Neumann boundary condition $u'(0) = -1$, would yield a *half-base* function φ_0 at $x = 0$, and therefore compared to the standard case, the values of the first diagonal elements in both mass and stiffness matrices M and S are half of the values in the Dirichlet boundary value case. Thus we end up with the equation system

$$\frac{1}{h} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} + 18h \begin{pmatrix} 1/3 & 1/6 & 0 \\ 1/6 & 2/3 & 1/6 \\ 0 & 1/6 & 1/3 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} = 6 \begin{pmatrix} 1/6 \\ 2/6 \\ 2/6 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Finally with $h = 1/3$ we end up with

$$A = \begin{pmatrix} 3 & -3 & 0 \\ -3 & 6 & -3 \\ 0 & -3 & 6 \end{pmatrix} + 18 \frac{1}{3} \begin{pmatrix} 1/3 & 1/6 & 0 \\ 1/6 & 2/3 & 1/6 \\ 0 & 1/6 & 2/3 \end{pmatrix} = \begin{pmatrix} 5 & -2 & 0 \\ -2 & 10 & -2 \\ 0 & -2 & 10 \end{pmatrix}, \quad b = \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix}.$$

3. We multiply the differential equation by a test function $v \in H_0^1(I)$, $I = (0, 1)$ and integrate over I . Using partial integration and the boundary conditions we get the following *variational problem*: Find $u \in H_0^1(I)$ such that

$$(3) \quad \int_I (u'v' + 2xu'v + 3uv) = \int_I fv, \quad \forall v \in H_0^1(I).$$

A *Finite Element Method* with $cG(1)$ reads as follows: Find $U \in V_h^0$ such that

$$(4) \quad \int_I (U'v' + 2xU'v + 3Uv) = \int_I fv, \quad \forall v \in V_h^0 \subset H_0^1(I),$$

where

$$V_h^0 = \{v : v \text{ is piecewise linear and continuous in a partition of } I, v(0) = v(1) = 0\}.$$

Now let $e = u - U$, then (3)-(4) gives that

$$(5) \quad \int_I (e'v' + 2xe'v + 3ev) = 0, \quad \forall v \in V_h^0.$$

A *posteriori error estimate*: We note that using $e(0) = e(1) = 0$, we get

$$(6) \quad \int_I 2xe'e = \int_I x \frac{d}{dx}(e^2) = (xe^2)|_0^1 - \int_I e^2 = - \int_I e^2,$$

so that using variational formulation (3) to replace the terms involving continuous solution u and the finite element method (4) to insert the interpolant $\pi_h e$ of the error we can compute

$$(7) \quad \begin{aligned} \|e\|_{H^1}^2 &= \int_I (e'e' + 2ee) = \int_I (e'e' + 2xe'e + 3ee) \\ &= \int_I ((u - U)'e' + 2x(u - U)'e + 3(u - U)e) = \{v = e \text{ in (3)}\} \\ &= \int_I fe - \int_I (U'e' + 2xU'e + 3Ue) = \{v = \pi_h e \text{ in (4)}\} \\ &= \int_I f(e - \pi_h e) - \int_I (U'(e - \pi_h e)' + 2xU'(e - \pi_h e) + 3U(e - \pi_h e)) \\ &= \{P.I. \text{ on each subinterval}\} = \int_I \mathcal{R}(U)(e - \pi_h e), \end{aligned}$$

where $\mathcal{R}(U) := f + U'' - 2xU' - 3U = f - 2xU' - 3U$, (for approximation with piecewise linears, $U \equiv 0$, on each subinterval). Thus (7) implies that

$$\begin{aligned} \|e\|_{H^1}^2 &\leq \|h\mathcal{R}(U)\| \|h^{-1}(e - \pi_h e)\| \\ &\leq C_i \|h\mathcal{R}(U)\| \|e'\| \leq C_i \|h\mathcal{R}(U)\| \|e\|_{H^1}, \end{aligned}$$

where C_i is an interpolation constant, and hence we have with $\|\cdot\| = \|\cdot\|_{L_2(I)}$ that

$$\|e\|_{H^1} \leq C_i \|h\mathcal{R}(U)\|.$$

A priori error estimate: We use (6) and write

$$\begin{aligned} \|e\|_{H^1}^2 &= \int_I (e'e' + 2ee) = \int_I (e'e' + 2xe'e + 3ee) \\ &= \int_I (e'(u - U)' + 2xe'(u - U) + 3e(u - U)) = \{v = U - \pi_h u \text{ in (5)}\} \\ &= \int_I (e'(u - \pi_h u)' + 2xe'(u - \pi_h u) + 3e(u - \pi_h u)) \\ &\leq \|(u - \pi_h u)'\| \|e'\| + 2\|u - \pi_h u\| \|e'\| + 3\|u - \pi_h u\| \|e\| \\ &\leq \{(u - \pi_h u)'\| + 4\|u - \pi_h u\|\} \|e\|_{H^1} \\ &\leq C_i \{\|hu''\| + \|h^2 u''\|\} \|e\|_{H^1}, \end{aligned}$$

this gives that

$$\|e\|_{H^1} \leq C_i \{\|hu''\| + \|h^2 u''\|\},$$

which is the a priori error estimate.

4. This is inspired from the proof of the Poincare inequality in the 1D case: We have, due to the vanishing boundary data, that

$$\begin{aligned} |u(x)| &= |u(x_1, x_2) - u(0, x_2)| = \left| \int_0^{x_1} \frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) d\bar{x}_1 \right| \\ &= \left| \int_0^{x_1} 1 \cdot \frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) d\bar{x}_1 \right| \leq \{\text{Cauchy's inequality}\} \\ &\leq \left(\int_0^{x_1} 1^2 d\bar{x}_1 \right)^{1/2} \cdot \left(\int_0^{x_1} \left(\frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) \right)^2 d\bar{x}_1 \right)^{1/2} \\ &\leq \left(\int_0^1 \left(\frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) \right)^2 d\bar{x}_1 \right)^{1/2}. \end{aligned}$$

This implies that

$$\begin{aligned} \int_{\Omega} |u|^2 dx &\leq \int_{\Omega} \left(\int_0^1 \left(\frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) \right)^2 d\bar{x}_1 \right) dx \\ &= \int_0^1 \int_0^1 \left(\int_0^1 \left(\frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) \right)^2 d\bar{x}_1 \right) dx_1 dx_2 \\ &= \int_0^1 \left(\int_0^1 \left(\frac{\partial}{\partial \bar{x}_1} u(\bar{x}_1, x_2) \right)^2 d\bar{x}_1 \right) dx_2 = \int_0^1 \int_0^1 \left(\frac{\partial}{\partial x_1} u(x_1, x_2) \right)^2 dx_1 dx_2 \\ &= \int_{\Omega} \left(\frac{\partial}{\partial x_1} u(x_1, x_2) \right)^2 dx \leq \int_{\Omega} |\nabla u|^2 dx, \end{aligned}$$

which gives the desired result:

$$\left(\int_{\Omega} |u|^2 dx \right)^{1/2} \leq \left(\int_{\Omega} |\nabla u|^2 dx \right)^{1/2}.$$

5. a) Using Greens formula we have that

$$\int_{\Omega} |\nabla u|^2 = \int_{\Omega} \nabla u \cdot \nabla u = - \int_{\Omega} (\Delta u)u + \int_{\partial\Omega} \frac{\partial u}{\partial n} u = \int_{\partial\Omega} (g - u)u,$$

where, in the last equality, we have used both equation and the data. In other words

$$\|\nabla u\|_{L_2(\Omega)}^2 + \|u\|_{L_2(\Gamma)}^2 = \int_{\partial\Omega} gu \leq \|g\|_{L_2(\Gamma)}^2 \|u\|_{L_2(\Gamma)}^2 \leq \frac{1}{2} \|g\|_{L_2(\Gamma)}^2 + \frac{1}{2} \|u\|_{L_2(\Gamma)}^2,$$

which gives the desired estimate.

b) To show the Riesz/Lax-Milgram conditions we introduce the notation

$$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v + \int_{\partial\Omega} uv, \quad \text{and} \quad L(v) = \int_{\partial\Omega} gv.$$

Then $a(u, v)$ is a scalar product with the corresponding norm $\|v\|_a = a(v, v)^{1/2}$. For instance we have that $\|v\|_a = 0$, only if $v = 0$:

$$0 = \|v\|_a^2 = a(v, v) = \int_{\Omega} |\nabla v|^2 + \int_{\partial\Omega} v^2 \geq \alpha \int_{\Omega} v^2, \quad \text{for some } \alpha > 0 \Rightarrow v = 0.$$

Further $L(v)$ is bounded in this norm, e.g. if $\|g\|_{\partial\Omega} < \infty$, then

$$|L(v)| \leq \|g\|_{\partial\Omega} \|v\|_{\partial\Omega} \leq \|g\|_{\partial\Omega} \|v\|_a.$$

We can also apply Riesz theorem in the sense that there exists u such that

$$a(u, v) = L(v), \quad \forall v,$$

and u is uniquely determined by

$$\|u\|_a = \|g\|_{\partial\Omega}.$$

Moreover since

$$a(u, v) = - \int_{\Omega} \Delta u v + \int_{\partial\Omega} \left(\frac{\partial u}{\partial n} + u \right) v,$$

we have that

$$\Delta u = 0, \quad \text{in } \Omega \quad \text{and} \quad \frac{\partial u}{\partial n} + u = g \quad \text{on } \Gamma.$$

MA