Mathematic Chalmers & GU

$TMA372/MMG800: Partial\ Differential\ Equations,\ 2009-08-26;\ kl\ 8.30-13.30.$

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Calculators, formula notes and other subject related material are not allowed.

Each problem gives max 8p. Valid bonus poits will be added to the scores.

Breakings: 3: 20-29p, 4: 30-39p och 5: 40p- GU ${\bf G}{:}20\text{-}39p,\,{\bf VG}{:}$ 40p-

1. Consider the boundary value problem:

(1)
$$\begin{cases} -(a(x)u'(x))' = f(x), & \text{for } 0 < x < 1, \\ u(0) = 0, & a(1)u'(1) = g_1, \end{cases}$$

Formulate a finite element method for this problem and show the a posteriori error estimate:

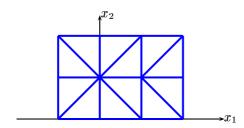
$$||(u-U)'||_a \le C_i ||hR(U)||_{1/a}.$$

- **2.** a) Let a(x) = 1 for x < 1/2, a(x) = 2 for $x \ge 1/2$ and $g_1 = -2$. Formulate a finite element method for (1). Dervie the matrix equation AU = b arising in discretizing the problem by cG(1) FEM in a uniform partition of I = (0,1) into 4 intervals. Compute, explicitly, only the matrix elements a_{22} and a_{34} and the vector element b_4 .
- b) Show, using (2), that the above finite element approximation is actually exact, i.e., u U = 0.
- 3. Consider the problem

(3)
$$\begin{cases} -\Delta u = f, & \text{in } \Omega = \{(x_1, x_2) : -1 < x_1 < 2, 0 < x_2 < 2\} \\ u = 0, & \text{on } \Gamma = \partial \Omega, \end{cases}$$

where f = 1 for $x_1 < 0$ and f = 2 for $x_1 > 0$.

a) Write down the discrete system SU = b (S is the stiffness matrix and b is the load vextor) in approximating (3) using cG(1) FEM in the following triangulation:



- b) Consider the same problem as in a), replacing the Dirichlet u=0 (only) on $x_1=2$ by the Neuman data: $\partial_n u=0$ on $x_1=2,\ 0< x_2<2$.
- **4.** Let $M \in (0,1)$. Consider the problem

(4)
$$(1 - M^2)u_{xx} + u_{yy} = f, \qquad (x, y) \in \mathbb{R}^2.$$

Determine the solution u for $f(x) = g(x)\delta(x)$ where δ is the Dirac δ function and

$$g(x) = \left\{ \begin{array}{ll} 1, & |x| < 1 \\ 0, & |x| \ge 1. \end{array} \right.$$

Hint: The fundamental solution for $-\Delta$ in \mathbb{R}^2 is given by $E(x,y) = \frac{1}{2\pi} \log \frac{1}{\sqrt{x^2 + y^2}}$.

5. Formulate and prove the Lax-Milgram theorem.

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TMA372/MMG800: Partial Differential Equations, 2009–08–26; kl 8.30-13.30.. Lösningar/Solutions.

1. Define the continuous and discrete function spaces

$$V = \{v : \int_0^1 [(v')^2 + v^2] \, dx < \infty, \quad v(0) = 0\},$$

and

 $V_h = \{v \in V : v \text{is piecewise linear and continuous on the partition of } I = [0, 1]\},$

Multiply the differential equation by a test function $v \in V$ and integrate over I. Partial integration yields the variational formulation: Find $u \in V$ such that

$$\int_0^1 au'v' \, dx = g_1 v(1), \qquad \forall v \in V.$$

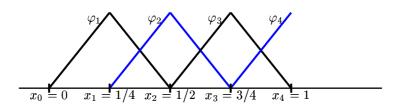
The corresponding finite element method is: Find $U \in V_h$ such that

$$\int_0^1 aU'v' \, dx = g_1 v(1), \qquad \forall v \in V_h.$$

For the inequality (2), se lecture notes.

2. a) A uniform partition for I=(0,1) into 4 subintervals $I_1=(0,1/4),\ I_2=(1/4,1/2),\ I_3=(1/2,3/4)$ and $I_4=(3/4,1)$ would have the piecewise linear basis functions $\{\varphi_j\}_{j=1}^4$, where for V_h defined by $\varphi_j\in V_h$ and

$$\varphi_j(x_i) = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$



With the ansatz $U(x) = \sum_{j=1}^4 U_j \varphi_j(x)$ the FEM, in the basis functions $\{\varphi_j\}_{j=1}^4$, can be formulated as follows: Find $U \in V_h$ such that

$$\int_0^1 aU'\varphi_i' \, dx = g_1\varphi_i(1), \qquad i = 1, 2, 3, 4.$$

Inserting the ansatz for U yields

$$\sum_{i=1}^{4} U_j \int_0^1 a\varphi_j' \varphi_i' \, dx = g_1 \varphi_i(1), \qquad i = 1, 2, 3, 4.$$

In this way we obtain a matrix problem AU = b with the element of A giver by

$$a_{ij} = \int_0^1 a \varphi_j' \varphi_i' \, dx, \qquad ext{and} \quad b_i = g_1 \varphi_i(1).$$

With a(x) and g_1 given as in the problem and h = 1/4 we have that

$$a_{22} = \int_{1/4}^{1/2} 1 \cdot \frac{1}{h} \cdot \frac{1}{h} \, dx + \int_{1/2}^{3/4} 2 \cdot \left(\frac{-1}{h}\right) \cdot \left(\frac{-1}{h}\right) dx = 12,$$

and

$$a_{34} = \int_{3/4}^{1} 2 \cdot \frac{1}{h} \cdot \left(\frac{-1}{h}\right) dx = -8,$$
 and $b_4 = (-2) \cdot 1 = -2.$

b) Due to the fact tha a(x) is chosen to br piecewise constant and $U \in V_h$ we get R(U) = a'U' + aU'' = 0. Thus by (2)

$$||e'||_a \le 0 \Longrightarrow e(x) = C.$$

Now since e is continuous and e(0) = 0, hence e(x) = 0.

3. Let V be the linear function space defined by

$$V_h := \{v : v \text{ is continuous in } \Omega, v = 0, \text{ on } \partial\Omega\}.$$

Multiplying the differential equation by $v \in V$ and integrating over Ω we get that

$$-(\Delta u, v) = (f, v), \qquad \forall v \in V.$$

Now using Green's formula we have that

$$-(\Delta u, \nabla v) = (\nabla u, \nabla v) - \int_{\partial \Omega} (n \cdot \nabla u) v \, ds = (\nabla u, \nabla v), \qquad \forall v \in V.$$

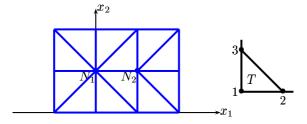
Thus the variational formulation is:

$$(\nabla u, \nabla v) = (f, v), \quad \forall v \in V$$

Let V_h be the usual finite element space consisting of continuous piecewise linear functions satisfying the boundary condition v=0 on $\partial\Omega$: The cG(1) method is: Find $U\in V_h$ such that

$$(\nabla U, \nabla v) = (f, v) \quad \forall v \in V_h$$

With this boundary conditions we have the internal nodes N_1 and N_2 . Making the "Ansatz"



 $U(x) = \sum_{j=1}^{2} \xi_{j} \varphi_{j}(x)$, where φ_{i} are the standard basis functions, we obtain the system of equations

$$\sum_{i=1}^{2} \xi_{j} \int_{\Omega} \nabla \varphi_{i} \cdot \nabla \varphi_{j} \, dx = \int_{\Omega} f \varphi_{j} \, dx, \quad i = 1, 2,$$

or, in matrix form,

$$S\mathcal{E} = F$$

where $S_{ij} = (\nabla \varphi_i, \nabla \varphi_j)$ is the stiffness matrix and $F_j = (f, \varphi_j)$ is the load vector. We first compute the mass and stiffness matrix for the reference triangle T. The local basis functions are

$$\phi_1(x_1, x_2) = 1 - \frac{x_1}{h} - \frac{x_2}{h}, \qquad \qquad \nabla \phi_1(x_1, x_2) = -\frac{1}{h} \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$

$$\phi_2(x_1, x_2) = \frac{x_1}{h}, \qquad \qquad \nabla \phi_2(x_1, x_2) = \frac{1}{h} \begin{bmatrix} 1 \\ 0 \end{bmatrix},$$

$$\phi_3(x_1, x_2) = \frac{x_2}{h}, \qquad \qquad \nabla \phi_3(x_1, x_2) = \frac{1}{h} \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

Hence, with $|T| = \int_T dz = h^2/2$,

$$s_{11} = (
abla \phi_1,
abla \phi_1) = \int_T |
abla \phi_1|^2 \, dx = rac{2}{h^2} |T| = 1.$$

Similarly we can compute the other elements and obtain

$$s = \frac{1}{2} \left[\begin{array}{ccc} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{array} \right].$$

We can now assemble the global matrix S from the local one s:

$$S_{11} = 8s_{22} = 4,$$
 $S_{12} = 2s_{12} = -1,$ $S_{21} = 2s_{12} = -1,$ $S_{22} = 2s_{11} + 4s_{22} = 2 + 2 = 4$

As for the load vector we have

$$\int_{\Omega} f \varphi_1 = \int_{x_1 < 0} \varphi_1 + 2 \int_{x_1 > 0} \varphi_1 = 4 \cdot \frac{1}{3} \cdot \frac{1}{2} + 2 \cdot 4 \cdot \frac{1}{3} \cdot \frac{1}{2} = 2/3 + 4/3 = 2.$$

$$\int_{\Omega} f \varphi_2 = 2 \int_{x_1 > 0} \varphi_2 = 2 \cdot 6 \cdot \frac{1}{3} \cdot \frac{1}{2} = 2$$

Thus the equatuion system is given by

$$\left[\begin{array}{cc} 4 & -1 \\ -1 & 4 \end{array}\right] \left[\begin{array}{c} \xi_1 \\ \xi_2 \end{array}\right] = \left[\begin{array}{c} 2 \\ 2 \end{array}\right].$$

b) With the Neumann boundary data we obtain an addition node at $N_3 = (2, 1)$ with the obvious corresponding basis function φ_3 which gives rize to an additional row and an additional column viz,

$$\int_{\Omega} \nabla \varphi_3 \cdot \nabla \varphi_3 = 2, \quad \int_{\Omega} \nabla \varphi_2 \cdot \nabla \varphi_3 = \int_{\Omega} \nabla \varphi_3 \cdot \nabla \varphi_2 = -1 \quad \int_{\Omega} f \varphi_3 = 2 \cdot \frac{1}{2}.$$

Consequently the corresponding system reads as

$$\begin{bmatrix} 4 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2/3 \end{bmatrix}.$$

4. Notre that M < 1. The substitution of variables

$$\left\{ \begin{array}{l} x_1' = \frac{1}{\sqrt{1 - M^2}} x_1 \\ x_2' = x_2 \end{array} \right. \Longrightarrow \left\{ \begin{array}{l} \frac{\partial}{\partial x_1} = \frac{1}{\sqrt{1 - M^2}} \frac{\partial}{\partial x_1'}, \\ \frac{\partial^2}{\partial x_1^2} = \frac{1}{1 - M^2} \frac{\partial^2}{\partial x_1'^2}, \end{array} \right. \qquad \left. \begin{array}{l} \frac{\partial}{\partial x_2} = \frac{\partial}{\partial x_2'} \\ \frac{\partial^2}{\partial x_2^2} = \frac{\partial^2}{\partial x_2'^2} \end{array} \right. \Longrightarrow u_{x_1' x_1'} + u_{x_2' x_2'} = f(x_1', x_2').$$

Here $f(x'_1, x'_2) = g(x'_1)\delta(x'_2)$ and

$$g(x_1') = \left\{ egin{array}{ll} 1, & |x_1'| < rac{1}{\sqrt{1-M^2}} \ 0, & |x_1'| > rac{1}{\sqrt{1-M^2}} \end{array}
ight. \quad ext{and} \quad -\Delta' = -f.$$

Thus

$$u(z') = \frac{1}{2\pi} \int_{\mathbb{R}^2} \left(-f(x') \right) \log \left(\frac{1}{|z' - x'|} \right) dx' = -\frac{1}{2\pi} \int_{\mathbb{R}} g(x_1') \log \left(\frac{1}{|(z_1', z_2') - (x_1', 0)|} \right) dx_1',$$

and hence

$$u(z') = \frac{1}{2\pi} \int_{-\frac{1}{\sqrt{1-M^2}}}^{\frac{1}{\sqrt{1-M^2}}} \log \left(|(z_1', z_2') - (x_1', 0)| \right) dx_1'$$

so that

$$u(z_1', z_2') = u\left(\frac{z_1}{\sqrt{1 - M^2}}, z_2\right)$$
 gives $u = u(z_1, z_2).$

5. See lecture notes

ΜA