TMA372/MMG800: Partial Differential Equations, 2011–08–24; kl 8.30-13.30.

Telephone: Ida Säfström: 0703-088304

Calculators, formula notes and other subject related material are not allowed.

Each problem gives max 6p. Valid bonus poits will be added to the scores.

Breakings: 3: 15-20p, 4: 21-27p och 5: 28p- For GU studentsG:15-27p, VG: 28p-

For solutions and gradings information see the couse diary in:

http://www.math.chalmers.se/Math/Grundutb/CTH/tma372/1011/index.html

1. Let a(x) > 0, and assume that u and u_h are the solutions of the Dirichlet problem:

(1) (BVP)
$$-(a(x)u'(x))' = f(x), \quad 0 < x < 1 \qquad u(0) = u(1) = 0,$$

and its cG(1) finite element (FEM) approximation, respectively. Prove that there is a constant C_i , depending only on a(x), such that

(2)
$$||u - u_h||_E \le C_i ||hu''||_a.$$

2. Consider the estimate (2). Derive the exact relation that shows how C_i depends on a(x).

3. Consider the two-dimensional Poisson equation with Neumann boundary condition

(3)
$$-\Delta u = f$$
, in $\Omega \subset \mathbf{R}^2$; $-\mathbf{n} \cdot \nabla u = k u$, on $\partial \Omega$,

where k > 0 and **n** is the outward unit normal to $\partial \Omega$ ($\partial \Omega$ is the boundary of Ω).

a) Prove the Poincare inequality:

$$||u||_{L_2(\Omega)} \le C_{\Omega}(||u||_{L_2(\partial\Omega)} + ||\nabla u||_{L_2(\Omega)})$$

b) Use the inequality in a) and show that $||u||_{L_2(\partial\Omega)} \to 0$ as $k \to \infty$.

4. Consider the problem

(4)
$$\begin{cases} -\Delta u = f, & \text{in } \Omega = \{(x_1, x_2) : -1 < x_1 < 2, \ 0 < x_2 < 2\} \\ u = 0, & \text{on } \Gamma = \partial \Omega, \end{cases}$$

where f = 1 for $x_1 < 0$ and f = 2 for $x_1 > 0$.

a) Write down the discrete system $SU = \mathbf{b}$ (S is the stiffness matrix and \mathbf{b} is the load vector) in approximating (4) by cG(1) FEM in the following triangulation:



b) Consider the same problem as in a), replacing the Dirichlet data u = 0 (only) on $x_1 = 2$ by the Neumann data: $\partial_n u = 0$ on $x_1 = 2$, $0 < x_2 < 2$.

5. a) Formulate a relevant minimization problem for the solution of the Poisson equation

(5) $-\Delta u = f$, in $\Omega \in \mathbf{R}^2$, with $\mathbf{n} \cdot \nabla u = b(g - u)$, on $\partial \Omega$,

where f > 0, b > 0 and g are given functions.

b) Derive an a priori error estimate for cG(1) approximation in the corresponding energy-norm. MA

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void!

TMA372/MMG800: Partial Differential Equations, 2011–08–24; kl 8.30-13.30.. Lösningar/Solutions.

1. See Lecture Notes or text book chapter 8.

2. Note that the interpolation theorem is not in the weighted norm. The a(x) dependence of the interpolation constant C_i can be shown as follows:

$$\begin{aligned} \|u' - (\pi_h u)'\|_a &= \left(\int_0^1 a(x)(u'(x) - (\pi_h u)'(x))^2 \, dx\right)^{1/2} \\ &\leq \left(\max_{x \in [0,1]} a(x)^{1/2}\right) \cdot \|u' - (\pi_h u)'\|_{L_2} \leq c_i \left(\max_{x \in [0,1]} a(x)^{1/2}\right) \|hu''\|_{L_2} \\ &= c_i \left(\max_{x \in [0,1]} a(x)^{1/2}\right) \left(\int_0^1 h(x)^2 u''(x)^2 \, dx\right)^{1/2} \\ &\leq c_i \frac{\left(\max_{x \in [0,1]} a(x)^{1/2}\right)}{\left(\min_{x \in [0,1]} a(x)^{1/2}\right)} \cdot \left(\int_0^1 a(x)h(x)^2 u''(x)^2 \, dx\right)^{1/2}. \end{aligned}$$

Thus

(6)
$$C_i = c_i \frac{(\max_{x \in [0,1]} a(x)^{1/2})}{(\min_{x \in [0,1]} a(x)^{1/2})},$$

where c_i is the interpolation constant independent of a(x).

3. a) There is smooth function ϕ such that $\Delta \phi = 1$ so that, using Greens formula

$$\begin{aligned} \|u\|_{\Omega}^{2} &= \int_{\Omega} u^{2} \Delta \phi = \int_{\partial \Omega} u^{2} \partial_{n} \phi - \int_{\Omega} 2u \nabla u \cdot \nabla \phi \\ &\leq C_{1} \|u\|_{\partial \Omega}^{2} + C_{2} \|u\| \|\nabla u\| \leq C_{1} \|u\|_{\partial \Omega}^{2} + \frac{1}{2} \|u\|_{\Omega}^{2} + \frac{1}{2} C_{2}^{2} \|\nabla u\|_{\Omega}^{2}. \end{aligned}$$

This yields

$$\|u\|_{\Omega}^{2} \leq 2C_{1}\|u\|_{\partial\Omega}^{2} + C_{2}^{2}\|\nabla u\|_{\Omega}^{2} \leq C^{2}(\|u\|_{\partial\Omega}^{2} + \|\nabla u\|_{\Omega}^{2}),$$

where $C^2 = \max(2C_1, C_2^2)$, $C_1 = \max_{\partial\Omega} |\partial_n \phi|$, and $C_2 = \max_{\Omega} (2|\nabla \phi|)$. b) Multiply the equation $-\Delta u = f$ by u and integrate over Ω . Partial integration together with the boundary data $-\partial_{\mathbf{n}} u = ku$ and Cauchy's inequality, yields

$$\begin{aligned} \|\nabla u\|_{\Omega}^{2} + k\|u\|_{\partial\Omega}^{2} &= \int_{\Omega} \nabla u \cdot \nabla u + \int_{\partial\Omega} u(-\partial_{\mathbf{n}}u) = \int_{\Omega} u(-\Delta u) = \int_{\Omega} fu \\ &\leq \|u\|_{\Omega}^{\parallel} f\|_{\Omega} \leq C_{\Omega}(\|u\|_{\partial\Omega} + \|\nabla u\|_{\Omega})\|f\|_{\Omega} = \|u\|_{\partial\Omega}C_{\Omega}\|f\|_{\Omega} + \|\nabla u\|_{\Omega}C_{\Omega}\|f\|_{\Omega} \\ &\leq \frac{1}{2}\|u\|_{\partial\Omega}^{2} + \frac{1}{2}\|\nabla u\|_{\Omega}^{2} + C_{\Omega}^{2}\|f\|_{\Omega}^{2}. \end{aligned}$$

Subtracting $\frac{1}{2} \|u\|_{\partial\Omega}^2 + \frac{1}{2} \|\nabla u\|_{\Omega}^2$ from the both sides, we end up with

$$(k-\frac{1}{2})\|u\|_{\partial\Omega}^{2} \leq \frac{1}{2}\|\nabla u\|_{\Omega}^{2} + (k-\frac{1}{2})\|u\|_{\partial\Omega}^{2} \leq C_{\Omega}^{2}\|f\|_{\Omega}^{2},$$

which gives that $||u||_{\partial\Omega} \to 0$ as $k \to \infty$.

4. Let V be the linear function space defined by

 $V_h := \{v : v \text{ is continuous in } \Omega, v = 0, \text{ on } \partial \Omega \}.$

Multiplying the differential equation by $v \in V$ and integrating over Ω we get that

$$-(\Delta u, v) = (f, v), \qquad \forall v \in V.$$

Now using Green's formula we have that

$$-(\Delta u, \nabla v) = (\nabla u, \nabla v) - \int_{\partial \Omega} (n \cdot \nabla u) v \, ds = (\nabla u, \nabla v), \qquad \forall v \in V.$$

Thus the variational formulation is:

$$(\nabla u, \nabla v) = (f, v), \qquad \forall v \in V.$$

Let V_h be the usual finite element space consisting of continuous piecewise linear functions satisfying the boundary condition v = 0 on $\partial \Omega$: The cG(1) method is: Find $U \in V_h$ such that

$$(\nabla U, \nabla v) = (f, v) \qquad \forall v \in V_h$$

With this boundary conditions we have the internal nodes N_1 and N_2 . Making the "Ansatz"



 $U(x) = \sum_{j=1}^{2} \xi_j \varphi_j(x)$, where φ_i are the standard basis functions, we obtain the system of equations $\sum_{j=1}^{2} \xi_j \varphi_j(x) = \int_{-\infty}^{\infty} \int_$

$$\sum_{i=1} \xi_j \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j \, dx = \int_{\Omega} f \varphi_j \, dx, \quad i = 1, 2,$$

or, in matrix form,

$$S\xi = F$$

where $S_{ij} = (\nabla \varphi_i, \nabla \varphi_j)$ is the stiffness matrix and $F_j = (f, \varphi_j)$ is the load vector. We first compute the mass and stiffness matrix for the reference triangle T. The local basis functions are

$$\phi_1(x_1, x_2) = 1 - \frac{x_1}{h} - \frac{x_2}{h}, \qquad \nabla \phi_1(x_1, x_2) = -\frac{1}{h} \begin{bmatrix} 1\\1 \end{bmatrix},$$

$$\phi_2(x_1, x_2) = \frac{x_1}{h}, \qquad \nabla \phi_2(x_1, x_2) = \frac{1}{h} \begin{bmatrix} 1\\0 \end{bmatrix},$$

$$\phi_3(x_1, x_2) = \frac{x_2}{h}, \qquad \nabla \phi_3(x_1, x_2) = \frac{1}{h} \begin{bmatrix} 0\\1 \end{bmatrix}.$$

Hence, with $|T| = \int_T dz = h^2/2$,

$$s_{11} = (\nabla \phi_1, \nabla \phi_1) = \int_T |\nabla \phi_1|^2 \, dx = \frac{2}{h^2} |T| = 1.$$

Similarly we can compute the other elements and obtain

$$s = \frac{1}{2} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$$

We can now assemble the global matrix S from the local one s:

$$S_{11} = 8s_{22} = 4, \qquad S_{12} = 2s_{12} = -1, \\ S_{21} = 2s_{12} = -1, \qquad S_{22} = 2s_{11} + 4s_{22} = 2 + 2 = 4$$

As for the load vector we have

$$\int_{\Omega} f\varphi_1 = \int_{x_1 < 0} \varphi_1 + 2 \int_{x_1 > 0} \varphi_1 = 4 \cdot \frac{1}{3} \cdot \frac{1}{2} + 2 \cdot 4 \cdot \frac{1}{3} \cdot \frac{1}{2} = 2/3 + 4/3 = 2.$$
$$\int_{\Omega} f\varphi_2 = 2 \int_{x_1 > 0} \varphi_2 = 2 \cdot 6 \cdot \frac{1}{3} \cdot \frac{1}{2} = 2$$

Thus the equation system is given by

$$\left[\begin{array}{cc} 4 & -1 \\ -1 & 4 \end{array}\right] \left[\begin{array}{c} \xi_1 \\ \xi_2 \end{array}\right] = \left[\begin{array}{c} 2 \\ 2 \end{array}\right].$$

b) With the Neumann boundary data we obtain an addition node at $N_3 = (2, 1)$ with the obvious corresponding basis function φ_3 which gives rise to an additional row and an additional column viz,

$$\int_{\Omega} \nabla \varphi_3 \cdot \nabla \varphi_3 = 2, \quad \int_{\Omega} \nabla \varphi_2 \cdot \nabla \varphi_3 = \int_{\Omega} \nabla \varphi_3 \cdot \nabla \varphi_2 = -1 \quad \int_{\Omega} f \varphi_3 = 2 \cdot \frac{1}{2}.$$

Consequently the corresponding system reads as

$$\begin{bmatrix} 4 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2/3 \end{bmatrix}$$

5. a) Multiply the equation by v, integrate over Ω , partial integrate, and use the boundary data to obtain

$$\int_{\Omega} fv = -\int_{\Omega} (\Delta u)v = -\int_{\Gamma} (\mathbf{n} \cdot \nabla u)v + \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Gamma} buv - \int_{\Gamma} bgv + \int_{\Omega} \nabla u \nabla v,$$

where $\Gamma := \partial \Omega$. This can be rewritten as

$$\underbrace{\int_{\Omega} \nabla u \cdot \nabla v + \int_{\Gamma} buv}_{:=a(u,v)} = \underbrace{\int_{\Omega} fv + \int_{\Gamma} bgv}_{:=l(v)}.$$

Let now

$$F(w) = \frac{1}{2} = a(w, w) - l(w) = \frac{1}{2} \int_{\Omega} \nabla w \cdot \nabla w + \int_{\Gamma} bww - \int_{\Omega} fv + \int_{\Gamma} bgv,$$

and choose w = u + v, then

$$F(w) = F(u+v) = F(u) + \underbrace{\int_{\Omega} \nabla u \cdot \nabla v + \int_{\Gamma} buv - \int_{\Omega} fv + \int_{\Gamma} bgv}_{=0} + \underbrace{\frac{1}{2} \int_{\Omega} \nabla v \cdot \nabla v + \frac{1}{2} \int_{\Gamma} bvv}_{\geq 0} \geq F(u).$$

This gives $F(u) \leq F(w)$ for arbitrary w.

b) Make the discrete ansatz $U = \sum_{j=1}^{M} U_j \varphi_j$, and set $v = \varphi_i$, i = 1, 2, ..., M in the variational formulation. Then we get the equation system AU = B, where U is the column vector with entries U_j , B is the load vector with elements

$$B_j = \int_{\Omega} f\varphi_i + \int_{\Gamma} bg\varphi_i,$$

and A is the matrix with elements

$$A_{ij} = \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j + \int_{\Gamma} b \varphi_i \varphi_j.$$

Here $\varphi_j = \varphi_j(x)$ is the basis function (*hat-functions*) for the set of all piecewise linear polynomials functions on a triangulation of the domain Ω .

Finally for the energy-norm $||v|| = a(v, v)^{1/2}$, using the definition for U = U(x), and the Galerkin orthogonality, we estimate the error e = u - U as

$$||e||^{2} = a(e, e) = a(e, u - U) = a(e, u) - a(e, U) = a(e, u)$$
$$= a(e, u) - a(e, v) = a(e, u - v) \le ||e|| ||u - v||.$$

This gives $||u - U|| = ||e|| \le ||u - v||$, for arbitrary piecewise linear function v, due to the fact that for such U and v Galerkin orthogonality gives a(e, U) = 0 and a(e, v) = 0: Just notice that both U and v are the linear combination of the basis functions φ_j for which according to the definition of U we have that

$$a(e,\varphi_j) = a(u,\varphi_j) - a(U,\varphi_j) = l(\varphi_j) - l(\varphi_j) = 0.$$

In particular, we may chose the piecewise linear function v to be the interpolant u and hence get

$$||u - U|| \le ||u - v|| \le C ||hD^2u||,$$

where h is the mesh size and C is an interpolation constant independent of h and u.

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