# MVE165/MMG630, Applied Optimization Lecture 3 Sensitivity analysis; duality; interpretation; post-optimal analysis

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#### A general linear program in standard form

► A linear program with n non-negative variables, m equality constraints (m < n), and non-negative right hand sides:</p>

maximize 
$$z = \sum_{\substack{j=1 \ n}}^{n} c_j x_j$$
  
subject to  $\sum_{\substack{j=1 \ n}}^{n} a_{ij} x_j = b_i, \quad i = 1, \dots, m,$   
 $x_j \ge 0, \quad j = 1, \dots, n.$ 

On matrix form it is written as:

where  $\mathbf{x} \in \Re^n$ ,  $\mathbf{A} \in \Re^{m \times n}$ ,  $\mathbf{b} \in \Re^m_+$  ( $\mathbf{b} \ge \mathbf{0}^m$ ), and  $\mathbf{c} \in \Re^n$ .

## General derivation of the simplex method (Ch. 4.8)

• B = set of basic variables, N = set of non-basic variables

$$\Rightarrow |B| = m$$
 and  $|N| = n - m$ 

- ▶ Partition matrix/vectors:  $\mathbf{A} = (\mathbf{B}, \mathbf{N})$ ,  $\mathbf{x} = (\mathbf{x}_B, \mathbf{x}_N)$ ,  $\mathbf{c} = (\mathbf{c}_B, \mathbf{c}_N)$
- The matrix B (N) contains the columns of A corresponding to the index set B (N) — Analogously for x and c
- Rewrite the linear program:

$$\begin{bmatrix} \text{maximize } z = \mathbf{c}^{\mathrm{T}} \mathbf{x} \\ \text{subject to } \mathbf{A} \mathbf{x} = \mathbf{b}, \\ \mathbf{x} \ge \mathbf{0}^{n} \end{bmatrix} = \begin{bmatrix} \text{maximize } z = \mathbf{c}_{B}^{\mathrm{T}} \mathbf{x}_{B} + \mathbf{c}_{N}^{\mathrm{T}} \mathbf{x}_{N} \\ \text{subject to } \mathbf{B} \mathbf{x}_{B} + \mathbf{N} \mathbf{x}_{N} = \mathbf{b}, \\ \mathbf{x}_{B} \ge \mathbf{0}^{m}, \ \mathbf{x}_{N} \ge \mathbf{0}^{n-m} \end{bmatrix}$$

• Substitute:  $\mathbf{x}_B = \mathbf{B}^{-1}\mathbf{b} - \mathbf{B}^{-1}\mathbf{N}\mathbf{x}_N \Longrightarrow$ 

$$\begin{array}{ll} \text{maximize} & z = \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{b} + [\mathbf{c}_N^{\mathrm{T}} - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N}] \mathbf{x}_N \\ \text{subject to} & \mathbf{B}^{-1} \mathbf{b} - \mathbf{B}^{-1} \mathbf{N} \mathbf{x}_N \geq \mathbf{0}^m, \\ & \mathbf{x}_N \geq \mathbf{0}^{n-m} \end{array}$$

Optimality condition (for maximization)

The basis *B* is optimal if  $\mathbf{c}_N^{\mathrm{T}} - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N} \leq \mathbf{0}^{n-m}$ (marginal values = reduced costs  $\leq 0$ )

If not, choose as entering variable  $j \in N$  the one with the largest value of the reduced cost  $c_j - \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{A}_j$ 

#### Feasibility condition

For all  $i \in B$  it holds that  $x_i = (\mathbf{B}^{-1}\mathbf{b})_i - (\mathbf{B}^{-1}\mathbf{A}_j)_i x_j$ 

Choose the leaving variable  $i^* \in B$  according to

$$i^* = \arg\min_{i\in B} \left\{ \left. \frac{(\mathbf{B}^{-1}\mathbf{b})_i}{(\mathbf{B}^{-1}\mathbf{A}_j)_i} \right| (\mathbf{B}^{-1}\mathbf{A}_j)_i > 0 \right\}$$

#### In the simplex tableau we have

basis	-z	<b>x</b> <sub>B</sub>	× <sub>N</sub>	S	RHS
-z	1	0	$\mathbf{c}_{N}^{\mathrm{T}}-\mathbf{c}_{B}^{\mathrm{T}}\mathbf{B}^{-1}\mathbf{N}$	$-\mathbf{c}_B^{\mathrm{T}}\mathbf{B}^{-1}$	$-\mathbf{c}_B^{\mathrm{T}}\mathbf{B}^{-1}\mathbf{b}$
<b>x</b> <sub>B</sub>	0	I	$B^{-1}N$	$\mathbf{B}^{-1}$	$B^{-1}b$

- ► s denotes possible slack variables (columns for s are copies of certain columns for (x<sub>B</sub>, x<sub>N</sub>))
- The computations performed by the simplex algorithm involve matrix inversions and updates of these
- A non-basic (basic) variable enters (leaves) the basis ⇒ one column, A<sub>j</sub>, of B is replaced by another, A<sub>k</sub>
- ▶ Row operations  $\Leftrightarrow$  Updates of  $\mathbf{B}^{-1}$  (and  $\mathbf{B}^{-1}\mathbf{N}$ ,  $\mathbf{B}^{-1}\mathbf{b}$ , and  $\mathbf{c}_B^{\mathrm{T}}\mathbf{B}^{-1}$ )
- ⇒ Efficient numerical computations are crucial for the performance of the simplex algorithm

## Derivation of duality (Ch. 6.1)

A linear program with optimal value z\*

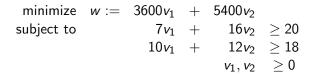
- ► How large can *z*<sup>\*</sup> be?

Compute upper estimates of z<sup>\*</sup>, e.g.

- Multiply (1) by  $3 \Rightarrow 21x_1 + 30x_2 \le 10800 \Rightarrow z^* \le 10800$
- Multiply (2) by  $1.5 \Rightarrow 24x_1 + 18x_2 \le 8100 \Rightarrow z^* \le 8100$
- Combine:  $0.6 \times (1) + 1 \times (2) \Rightarrow 20.2x_1 + 18x_2 \le 7560 \Rightarrow z^* \le 7560$
- Do better than guess—compute optimal weights!
- ▶ Value of estimate:  $w = 3600v_1 + 5400v_2 \rightarrow \min$

 $\blacktriangleright \text{ Constraints on weights: } \left[ \begin{array}{cc} 7v_1 + 16v_2 & \geq 20\\ 10v_1 + 12v_2 & \geq 18\\ v_1, v_2 & \geq 0 \end{array} \right]$ 

## The best (lowest) possible upper estimate of $z^*$



► A linear program!

It is called the dual of the original linear program

#### The lego model—the market problem

Consider the lego problem

maximize	Ζ	=	$1600x_1$	+	1000 <i>x</i> <sub>2</sub>		
subject to			$2x_1$	+	<i>x</i> <sub>2</sub>	$\leq$	6
			$2x_1$	+	$2x_2$	$\leq$	8
					$x_1, x_2$	$\geq$	0

- Option: Sell blocks instead of making furniture
- $v_1(v_2) =$ price of a large (small) block
- Market wish to minimize payment: minimize  $6v_1 + 8v_2$
- I sell if prices are high enough:
  - ►  $2v_1 + 2v_2 \ge 1600$
  - ▶  $v_1 + 2v_2 \ge 1000$
  - ▶  $v_1, v_2 \ge 0$

- otherwise better to make tables
- otherwise better to make chairs
- prices are naturally non-negative

#### Linear programming duality

 To each primal linear program corresponds a dual linear program

$$\begin{array}{lll} \mbox{[Primal]} & \mbox{minimize} & z = \mathbf{c}^{\mathrm{T}}\mathbf{x}, \\ & \mbox{subject to} & \mathbf{A}\mathbf{x} = \mathbf{b}, \\ & \mathbf{x} \geq \mathbf{0}^n, \end{array} \\ \mbox{[Dual]} & \mbox{maximize} & w = \mathbf{b}^{\mathrm{T}}\mathbf{y}, \\ & \mbox{subject to} & \mathbf{A}^{\mathrm{T}}\mathbf{y} \leq \mathbf{c}. \end{array}$$

► On component form: [Primal] minimize  $z = \sum_{j=1}^{n} c_j x_j$ subject to  $\sum_{j=1}^{n} a_{ij} x_j = b_i$ , i = 1, ..., m,  $x_j \ge 0$ , j = 1, ..., n, [Dual] maximize  $w = \sum_{j=1}^{n} b_i y_i$ subject to  $\sum_{i=1}^{m} a_{ij} y_i \le c_j$ , j = 1, ..., n.

## In practice ...

A primal linear program

The corresponding dual linear program

## Rules for constructing the dual program (Ch. 6.2)

maximization	$\Leftrightarrow$	minimization
dual program	$\Leftrightarrow$	primal program
primal program	$\Leftrightarrow$	dual program
constraints		variables
$\geq$	$\Leftrightarrow$	$\leq$ 0
$\leq$	$\Leftrightarrow$	$\geq$ 0
=	$\Leftrightarrow$	free
variables		constraints
$\geq$ 0	$\Leftrightarrow$	$\geq$
$\leq$ 0	$\Leftrightarrow$	$\leq$
free	$\Leftrightarrow$	=

The dual of the dual of any linear program equals the primal

## Duality properties (Ch. 6.3)

Weak duality: Let x be a feasible point in the primal (minimization) and y be a feasible point in the dual (maximization). Then,

$$z = \mathbf{c}^{\mathrm{T}} \mathbf{x} \ge \mathbf{b}^{\mathrm{T}} \mathbf{y} = w$$

- Strong duality: In a pair of primal and dual linear programs, if one of them has an optimal solution, so does the other, and their optimal values are equal.
- ► Complementary slackness: If x is optimal in the primal and y is optimal in the dual, then x<sup>T</sup>(c - A<sup>T</sup>y) = y<sup>T</sup>(b - Ax) = 0.

If **x** is feasible in the primal, **y** is feasible in the dual, and  $\mathbf{x}^{\mathrm{T}}(\mathbf{c} - \mathbf{A}^{\mathrm{T}}\mathbf{y}) = \mathbf{y}^{\mathrm{T}}(\mathbf{b} - \mathbf{A}\mathbf{x}) = 0$ , then **x** and **y** are optimal for their respective problems.

primal (dual) problem	$\iff$	dual (primal) problem
unique and non-degenerate solution	$\Leftrightarrow$	unique and non-degenerate solution
unbounded solution	$\Rightarrow$	no feasible solutions
no feasible solutions	$\Rightarrow$	unbounded solution <b>or</b> no feasible solutions
degenerate solution	$\Leftrightarrow$	alternative solutions

HOMEWORK!

Formulate and solve graphically the dual of:

$$\begin{array}{rll} \mbox{minimize} & z = & 6x_1 & +3x_2 & +x_3 \\ \mbox{subject to} & & 6x_1 & -3x_2 & +x_3 & \geq 2 \\ & & 3x_1 & +4x_2 & +x_3 & \geq 5 \\ & & & x_1, x_2, x_3 & \geq 0 \end{array}$$

- Then find the optimal primal solution
- Verify that the dual of the dual equals the primal

## Sensitivity analysis (Ch. 5)

- How does the optimum change when the right hand sides (resources, e.g.) change?
- When the objective coefficients (prices, e.g.) change?
- Assume that the basis *B* is optimal:

$$\begin{array}{ll} \text{maximize} & z = \mathbf{c}_B^{^{\mathrm{T}}} \mathbf{B}^{-1} \mathbf{b} + [\mathbf{c}_N^{^{\mathrm{T}}} - \mathbf{c}_B^{^{\mathrm{T}}} \mathbf{B}^{-1} \mathbf{N}] \mathbf{x}_N \\ \text{subject to} & \mathbf{B}^{-1} \mathbf{b} - \mathbf{B}^{-1} \mathbf{N} \mathbf{x}_N \geq \mathbf{0}^m, \\ & \mathbf{x}_N \geq \mathbf{0}^{n-m} \end{array}$$

 $\mathbf{x}_B = \mathbf{B}^{-1}\mathbf{b} - \mathbf{B}^{-1}\mathbf{N}\mathbf{x}_N$ 

- Suppose **b** changes to  $\mathbf{b} + \Delta \mathbf{b}$
- $\Rightarrow$  New optimal value:

$$z^{\text{new}} = \mathbf{c}_B^{\text{T}} \mathbf{B}^{-1} (\mathbf{b} + \Delta \mathbf{b}) = z + \mathbf{c}_B^{\text{T}} \mathbf{B}^{-1} \Delta \mathbf{b}$$

- The current basis is feasible if  $\mathbf{B}^{-1}(\mathbf{b} + \Delta \mathbf{b}) \ge 0$
- If not: negative values will occur in the right hand side
- ► The reduced costs are unchanged (negative, at optimum) ⇒ this can be resolved using the *dual simplex method*

Consider the linear program

minimize	z =	$-x_1$	$-2x_{2}$	
subject to		$-2x_{1}$	$+x_{2}$	$\leq 2$
		$-x_{1}$	$+2x_{2}$	$\leq$ 7
Draw graph!!		$x_1$		$\leq$ 3
			$x_1, x_2$	$\geq$ 0

The optimal solution is given by

basis	- <i>z</i>	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	<i>s</i> <sub>1</sub>	<i>s</i> <sub>2</sub>	<b>s</b> 3	RHS
-z	1	0	0	0	1	2	13
<i>x</i> <sub>2</sub>	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	5
<i>x</i> <sub>1</sub>	0	1	0	0	ō	ī	3
<i>s</i> <sub>1</sub>	0	0	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	3

Change the right hand side according to

▶ The change in the right hand side is given by  $\mathbf{B}^{-1}(0, \delta, 0)^{\mathrm{T}} = (\frac{1}{2}\delta, 0, -\frac{1}{2}\delta)^{\mathrm{T}} \Rightarrow$  new optimal tableau:

basis	-z	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	$s_1$	<i>s</i> <sub>2</sub>	<i>s</i> 3	RHS
-z	1	0	0	0	1	2	$13 + \delta$
<i>x</i> <sub>2</sub>	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	$5 + \frac{1}{2}\delta$
<i>x</i> <sub>1</sub>	0	1	0	0	ō	ī	3
$s_1$	0	0	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	$3-\frac{1}{2}\delta$

• The current basis is feasible if  $-10 \le \delta \le 6$ 

#### Suppose δ = 8:

-							
basis	- <i>Z</i>	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	$s_1$	<i>s</i> <sub>2</sub>	<i>s</i> 3	RHS
-z	1	0	0	0	1	2	21
<i>x</i> <sub>2</sub>	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	9
$x_1$	0	1	0	0	Ō	Ī	3
<i>s</i> <sub>1</sub>	0	0	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	-1

- Dual simplex iteration:
- $s_1 = -1$  has to leave the basis
- Find the smallest ratio between reduced costs (for non-basic columns) and (negative) elements in the "s<sub>1</sub>-row" (to stay optimal)
- s<sub>2</sub> will enter the basis New optimal tableau:

basis	-z	$x_1$	<i>x</i> <sub>2</sub>	$s_1$	<i>s</i> <sub>2</sub>	<i>s</i> <sub>3</sub>	RHS
-z	1	0	0	2	0	5	19
<i>x</i> <sub>2</sub>	0	0	1	1	0	2	8
$x_1$	0	1	0	0	0	1	3
<i>s</i> <sub>2</sub>	0	0	0	-2	1	-3	2

## Changes in the objective coefficients

Suppose **c** changes to 
$$\mathbf{c} + \Delta \mathbf{c}$$

The new optimal value:

$$z^{\text{new}} = (\mathbf{c}_B + \Delta \mathbf{c}_B)^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{b} = z + \Delta \mathbf{c}_B^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{b}$$

► The current basis is optimal if  

$$(\mathbf{c}_N + \Delta \mathbf{c}_N)^{\mathrm{T}} - (\mathbf{c}_B + \Delta \mathbf{c}_B)^{\mathrm{T}} \mathbf{B}^{-1} \mathbf{N} \leq \mathbf{0}$$

If not: more simplex iterations to find the optimal solution

## Changes in the objective coefficients

Change the objective according to

► The changes in the reduced costs are given by  $-(\delta, 0, 0)\mathbf{B}^{-1}\mathbf{N} = (-\frac{1}{2}\delta, -\frac{1}{2}\delta) \Rightarrow$  new optimal tableau:

b	asis	- <i>z</i>	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	<i>s</i> <sub>1</sub>	<i>s</i> <sub>2</sub>	<i>s</i> 3	RHS
_	-z	1	0	0	0	$1-\frac{1}{2}\delta$	$2-\frac{1}{2}\delta$	$13-5\delta$
	<i>x</i> <sub>2</sub>	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	5
	$x_1$	0	1	0	0	Ō	$\overline{1}$	3
	$s_1$	0	0	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	3
. –								

• The current basis is optimal if  $\delta \leq 2$ 

#### Changes in the objective coefficients

Suppose  $\delta = 4$ : new tableau:

basis	-z	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	$s_1$	<i>s</i> <sub>2</sub>	<i>s</i> 3	RHS
- <i>z</i>	1	0	0	0	-1	0	-7
<i>x</i> <sub>2</sub>	0	0	1	0	$\frac{1}{2}$	$\frac{1}{2}$	5
$x_1$	0	1	0	0	Ō	1	3
<i>s</i> <sub>1</sub>	0	0	0	1	$-\frac{1}{2}$	$\frac{3}{2}$	3

• Let  $s_2$  enter and  $x_2$  leave the basis. New optimal tableau:

basis	- <i>z</i>	<i>x</i> <sub>1</sub>	<i>x</i> <sub>2</sub>	$s_1$	<i>s</i> <sub>2</sub>	<i>s</i> 3	RHS
-z	1	0	2	0	0	1	3
<i>s</i> <sub>2</sub>	0	0	2	0	1	1	10
$x_1$	0	1	0	0	0	1	3
<i>s</i> <sub>1</sub>	0	0	1	1	0	2	8