

DFT and the Z-transform of $\textcircled{12}$ and $\textcircled{12}$

Recall $y = \textcircled{12}x = (\dots, x_{-2}, x_0, y_2, \dots)$

$$y_k = x_{2k}$$

$$\begin{aligned} \Rightarrow Y(z) &= \sum_{k=-\infty}^{\infty} x_{2k} z^{-k} = \sum_{k=-\infty}^{\infty} x_{2k} z^{-k} \\ &= \sum_{k=-\infty}^{\infty} x_{2k} (z^{1/2})^{-2k} \\ &= \frac{1}{2} \left(\sum_{k=-\infty}^{\infty} x_{2k} (z^{1/2})^{-2k} + \sum_{k=-\infty}^{\infty} x_{2k+1} (z^{1/2})^{-(2k+1)} \right) \\ &\quad + \frac{1}{2} \left(\sum_{k=-\infty}^{\infty} x_{2k} (z^{1/2})^{-2k} + \sum_{k=-\infty}^{\infty} x_{2k+1} (-z^{1/2})^{-2k+1} \right) \\ &= \frac{1}{2} \left(X(z^{1/2}) + X(-z^{1/2}) \right) \end{aligned}$$

And with $z = e^{i\omega}$, $z^{1/2} = e^{i\omega/2}$, $-z^{1/2} = e^{i(\frac{\omega}{2} + \pi)}$

we get the DFT:

$$Y(\omega) = \frac{1}{2} \left(X\left(\frac{\omega}{2}\right) + X\left(\frac{\omega}{2} + \pi\right) \right)$$

The term $X\left(\frac{\omega}{2} + \pi\right)$ is an "alias component",

which can be removed with a "perfect filter" H^*, G^* .

Upsampling $y = \textcircled{12}x = (\dots, 0, y_0, 0, y_1, 0, \dots)$

$$\text{Then } Y(z) = \sum_{k=-\infty}^{\infty} y_k z^{-k} = \sum_{k=-\infty}^{\infty} y_{2k} z^{-2k} = \sum_{k=-\infty}^{\infty} x_k z^{-2k} = X(z^2)$$

$$\text{and } Y(\omega) = X(2\omega).$$

It is clear then that

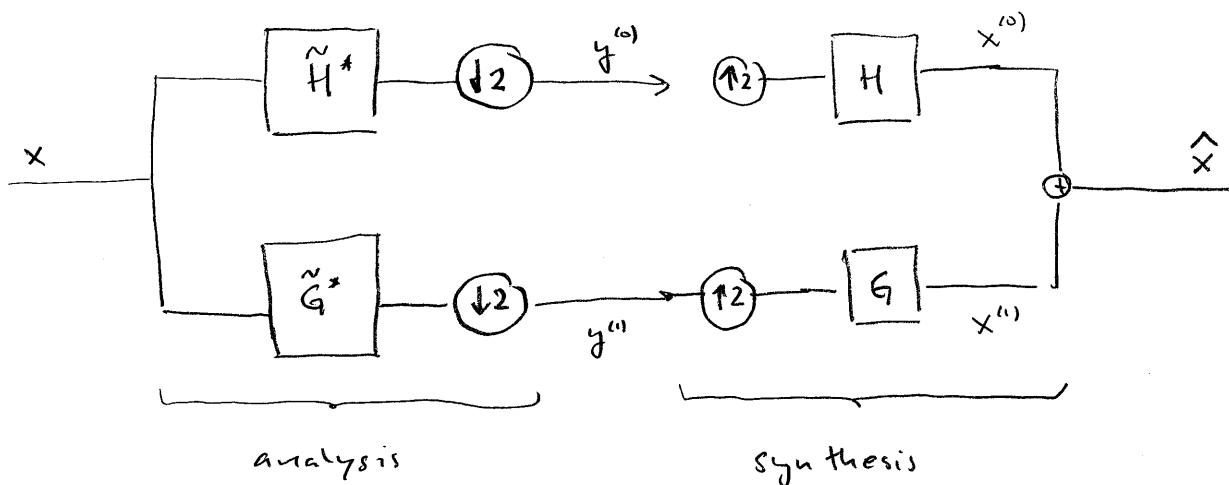
$\textcircled{\downarrow} \textcircled{2}$ $\textcircled{\uparrow} \textcircled{2}$ $x = x$, but $u = \textcircled{\uparrow} \textcircled{2} \textcircled{\downarrow} \textcircled{2} x \neq x$ in general.

$$\begin{aligned} U(z) &= \sum_{k=-\infty}^{\infty} u_k z^{-k} = \sum_{k=-\infty}^{\infty} x_{2k} z^{-2k} \\ &= \frac{1}{2} \left[\sum_{k=-\infty}^{\infty} x_{2k} z^{-2k} + \sum_{k=-\infty}^{\infty} x_{2k+1} z^{-(2k+1)} \right] \\ &\quad + \frac{1}{2} \left[\sum_{k=-\infty}^{\infty} x_{2k} z^{-2k} - \sum_{k=-\infty}^{\infty} x_{2k+1} z^{-(2k+1)} \right] \\ &= \frac{1}{2} (X(z) + X(-z)), \end{aligned}$$

which is the same as

$$U(\omega) = \frac{1}{2} (X(\omega) + X(\omega + \pi)).$$

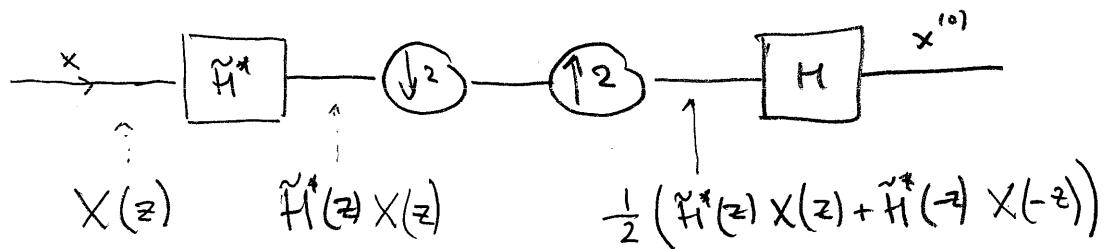
Perfect reconstruction



A filter bank. In the analysis part, the signal is split into a high frequency part and a low filter part, which gives the signals $y^{(0)}$ and $y^{(1)}$.

These then pass the synthesis part to make a reconstruction of the signal. If $\hat{x} = x$, we have achieved "perfect reconstruction".

Expressed in terms of the z-transform, we have,
for the high-frequency part.



so that

$$X^{(0)}(z) = \frac{1}{2} H(z) \left[X(z) H^*(z) + X(-z) H^*(-z) \right]$$

and similarly

$$X^{(1)}(z) = \frac{1}{2} G(z) \left[X(z) \tilde{H}^*(z) + X(-z) \tilde{H}^*(-z) \right]$$

which gives

$$\begin{aligned} \hat{X}(z) &= \frac{1}{2} \left[H(z) H^*(z) + G(z) \tilde{H}^*(z) \right] X(z) \\ &\quad + \frac{1}{2} \left[H(z) H^*(-z) + G(z) \tilde{H}^*(-z) \right] X(-z) \end{aligned}$$

We therefore achieve perfect reconstruction if and only if the following system is satisfied:

$$\left\{ \begin{array}{l} H(z) H^*(z) + G(z) \tilde{H}^*(z) = 2 \\ H(z) H^*(-z) + G(z) \tilde{H}^*(-z) = 0 \end{array} \right.$$

How can we construct such filters?

The "product filters" are obtained by the

ansatz $G(z) = -z^{-L} H^*(-z)$ L odd

$$\tilde{G}(z) = -z^L H^*(-z)$$

Recall that the $*$ -marked filters are time reversed, so

$$G^*(z) = \sum_{k=-\infty}^{\infty} g_k^* z^{-k} = \sum_{k=\infty}^{\infty} g_k (\frac{1}{z})^{-k} = G(\frac{1}{z})$$

and therefore

$$\tilde{G}^*(-z) = -\left(-\frac{1}{z}\right)^L H^*\left(\frac{1}{z}\right) = \left(\frac{1}{z}\right)^L H(z)$$

Therefore

$$H(z) \tilde{H}^*(-z) + G(z) \tilde{G}^*(-z) = H(z) \tilde{H}^*(-z) - z^{-L} H^*(-z) \left(\frac{1}{z}\right)^L H(z) = 0$$

and

$$\begin{aligned} H(z) \tilde{H}^*(z) + G(z) \tilde{G}^*(z) &= \\ &= H(z) \tilde{H}^*(z) - z^{-L} \tilde{H}^*(-z) \cdot \left(\frac{1}{z}\right)^L H(-z) \\ &= H(z) \tilde{H}^*(z) + \tilde{H}^*(-z) H(-z). \end{aligned}$$

The condition for perfect reconstruction is now given in terms of H and \tilde{H} :

$$\boxed{H(z) \tilde{H}^*(z) + \tilde{H}^*(-z) H(-z) = 2}$$

And a product filter is defined by

$$P(z) = H(z) \tilde{H}^*(z).$$

The perfect reconstruction condition becomes

$$P(z) + P(-z) = 2, \text{ i.e.}$$

$$2P_0 + 2 \sum_{k=-\infty}^{\infty} P_{2k} z^{-2k} = 2.$$

It follows that $P_0 = 1$, $P_{2n} = 0$ ($n \neq 0$), and

P_{2k+1} can be chosen arbitrary.

Given $P(z)$ we can choose $H(z)$ and $\tilde{H}(z)$, but this may be done in many different ways.

Orthogonal Filter banks

Filters that satisfy $H(z) = \tilde{f}(z)$, $G(z) = \tilde{g}(z)$

are called orthogonal. Then

$$P(z) = H(z)\tilde{H}^*(z) = H(z)H\left(\frac{1}{z}\right).$$

In the DFT-version:

$$P(\omega) = H(\omega)\overline{H(\omega)} = |H(\omega)|^2 \geq 0.$$

Then $P(\omega)$ is even, and real valued which implies that the coefficients are symmetric, and perfect reconstruction follows from $|H(\omega)|^2 + |H(\omega+\pi)|^2 = 2$.

Why are these called orthogonal?

Recall that in the example, we had

$$\varphi_k = \begin{cases} \frac{1}{\sqrt{2}} & k=0,1 \\ 0 & \text{otherwise} \end{cases} \quad \psi_k = \begin{cases} \frac{1}{\sqrt{2}} & k=0 \\ -\frac{1}{\sqrt{2}} & k=1 \\ 0 & \text{otherwise} \end{cases}$$

and we constructed basis functions

$$\varphi_k^{(2n)} = \varphi_{k-2n}, \quad \varphi_n^{(2n+1)} = \varphi_{k-2n-1}, \quad \text{and the}$$

$$y_n^{(0)} = \langle x, \varphi^{(2n)} \rangle \quad y_n^{(1)} = \langle x, \varphi^{(2n+1)} \rangle, \quad \text{and in}$$

the end:

$$x = \sum \langle x, \varphi^{(2n)} \rangle \varphi^{(2n)} + \sum \langle x, \varphi^{(2n+1)} \rangle \varphi^{(2n+1)}$$

Biorthogonal bases

Sometimes it is advantageous to work with "biorthogonal" bases, which corresponds to expansions of the form

$$x = \sum_n \langle x, \varphi^{(2n)} \rangle \varphi^{(2n)} + \sum_n \langle x, \varphi^{(2n+1)} \rangle \varphi^{(2n+1)}$$

The basis functions must then satisfy

$$\langle \varphi^{(2k)}, \varphi^{(2n)} \rangle = \delta_{kn}$$

$$\langle \varphi^{(2kn)}, \varphi^{(2n+1)} \rangle = \delta_{kn}$$

$$\langle \varphi^{(2k)}, \varphi^{(2n+1)} \rangle = \langle \varphi^{(2kn)}, \varphi^{(2n+1)} \rangle = 0.$$

We will return to that when discussing multi resolution analysis.

Design of filter banks

This can be done in three steps:

1) Find $P(z)$ that satisfies the condition for perfect reconstruction

2) Factorize $P(z)$:

$$P(z) = H(z) \tilde{H}^*(z).$$

3) Define the high pass filters by

$$G(z) = -z^{-L} \tilde{H}^*(-z)$$

$$\tilde{G}(z) = -z^{-L} \tilde{H}^*(-z), \text{ where } L \text{ is odd.}$$

Example

The Haar basis: $P(z) = \frac{1}{2} (z + 1 + z^{-1})$
 $= \frac{1}{\sqrt{2}} (z+1) \frac{1}{\sqrt{2}} (\frac{1}{z}+1)$

Example (Ingrid Daubechies)

$$P(z) = \left(\frac{1+z}{2}\right)^N \left(\frac{1+z^{-1}}{2}\right)^N Q_N(z),$$

where $Q_N(z)$ is symmetric

$$Q_N(z) = a_{N-1} z^{N-1} + \dots + a_1 z^1 + a_0 + a_1 z^{-1} + \dots + a_{N-1} z^{-N}$$

$N=1$ then gives the Haar wavelet,

$$N=2: \quad P(z) = \left(\frac{1+z}{2}\right)^2 \left(\frac{1+z^{-1}}{2}\right)^2 Q_2(z),$$

$$Q_2(z) = a_1 z + a_0 + a_1 z^{-1}.$$

Wavelets

Recall the Fourier transform (w.r.t. definition)

$$\hat{f}(\omega) = \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt = \langle f, e^{i\omega \cdot} \rangle$$

$$\text{Def} \quad \langle f, g \rangle = \int f(t) \overline{g(t)} dt$$

The Fourier transform gives a decomposition in pure frequencies: $e^{i\omega t}$.

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \langle f, e^{i\omega t} \rangle e^{i\omega t} d\omega.$$

The market decomposition is different.

Let $\psi(t)$ be a given function, and let

$$\Psi_{j,k}(t) = 2^{j/2} \psi(2^j t - k)$$

↑ dilation ↗ translation .

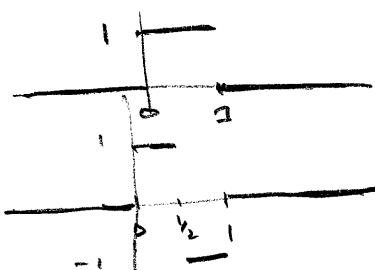
Under suitable conditions,

$$f(t) = \sum_{j,k=-\infty}^{\infty} \langle f, \psi_{jk} \rangle \psi_{jk}(t).$$

Example The Haar wavelet.

$$\begin{aligned} \text{Let } \psi(t) &= \psi(2t) + \psi(2t-1) && \leftarrow \text{need to check} \\ &&& \text{that it is possible} \\ \psi(t) &= \psi(2t) - \psi(2t-1) && \leftarrow \text{can always be achieved.} \end{aligned}$$

ψ is called a scaling function and φ a wavelet.

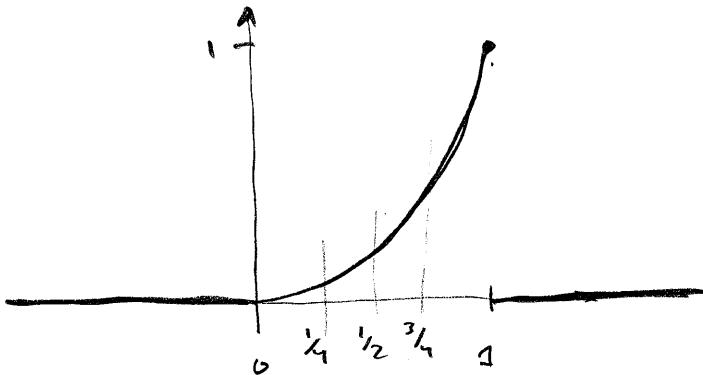


Note that $\langle \varphi, \varphi \rangle = 0$,

$$\langle \varphi(\cdot - k), \varphi(\cdot - n) \rangle = 0 \quad (n \neq k)$$

$$\langle \varphi(\cdot - k), \varphi(\cdot - n) \rangle = 0 \quad (n \neq k)$$

As an example, let $f(t) = \begin{cases} t^2 & 0 < t < 1 \\ 0 & \text{elsewhere} \end{cases}$



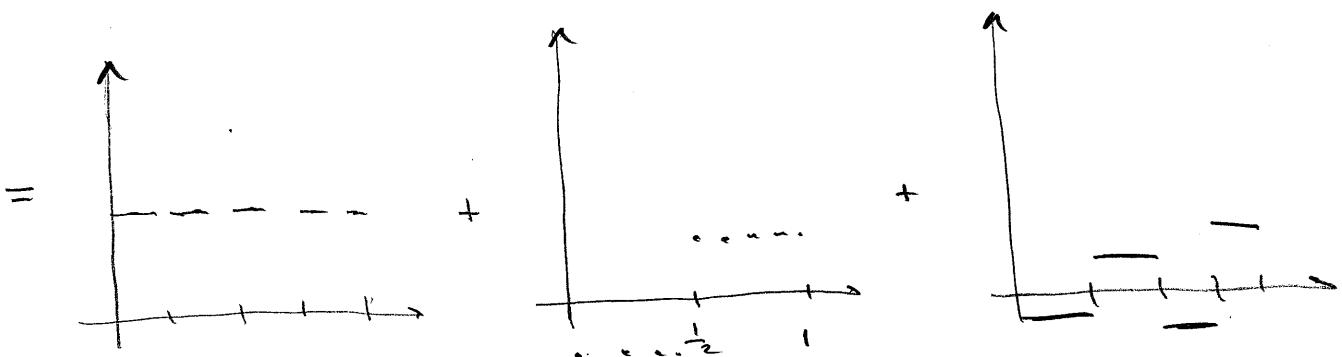
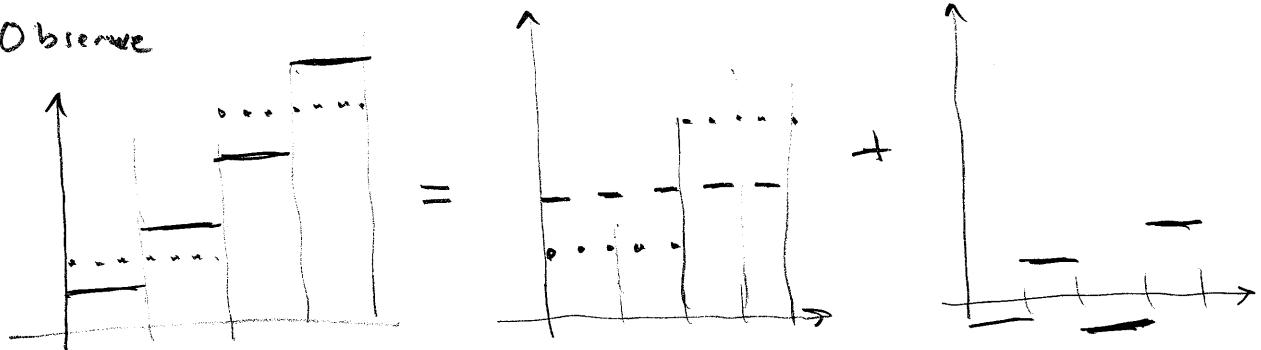
The function $f(t)$ can be approximated by step functions, which is the mean of f in each interval

For example, in the interval $[t_n, t_{n+1}]$

we have

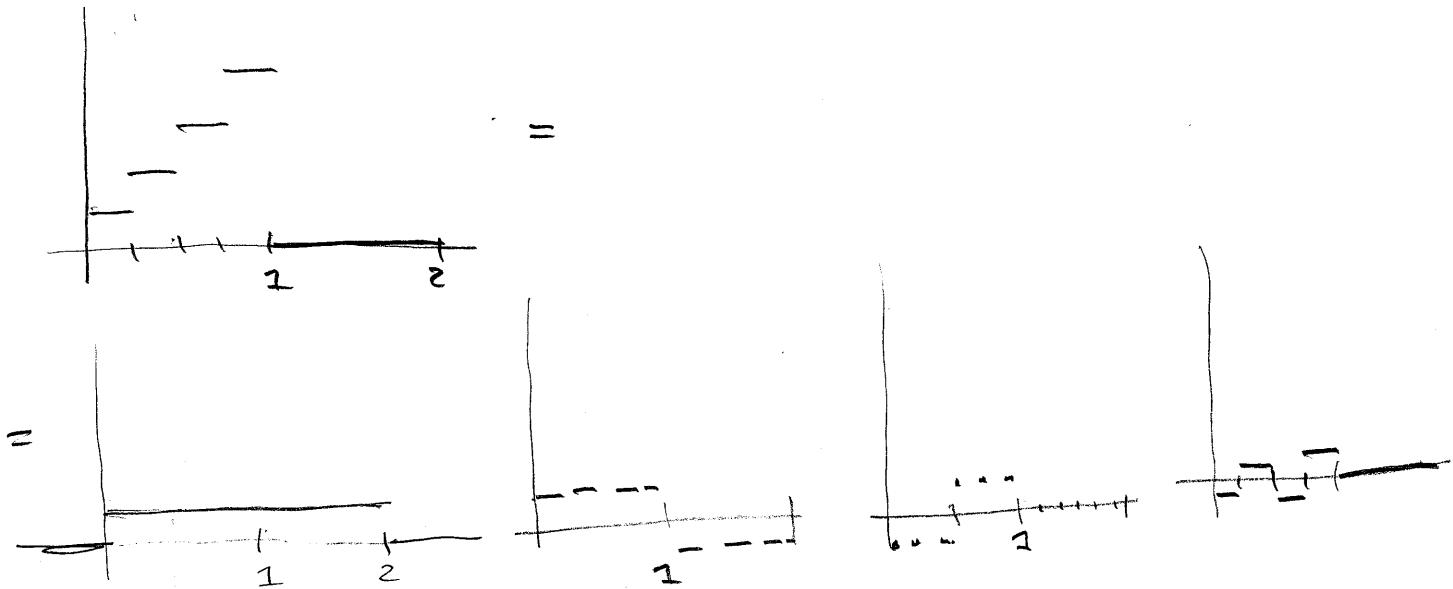
$$\begin{aligned} \langle f, \varphi(2^2 \cdot - 1) \rangle &= \int_0^1 t^2 \varphi(2^2 t - 1) dt \\ &= \int_{1/4}^{1/2} t^2 dt \approx 0.093. \end{aligned}$$

Observe



This is the basic idea behind wavelets:

we can express the signal as an average plus finer and finer details. Note that we can continue:



$$2^{j/2} \varphi\left(\frac{t}{2^j}\right)$$

Note that $\langle f, 2^{j/2} \varphi(2^j \cdot - k) \rangle \rightarrow 0$
when $j \rightarrow -\infty$ (i.e. taking the
average over larger and larger intervals).

Multi resolution analysis

The Hilbert space $L^2(\mathbb{R})$

$$L^2(\mathbb{R}) = \{ f : \mathbb{R} \rightarrow \mathbb{C} : \int |f(t)|^2 dt < \infty \}$$

(for a proper definition, we need the concept of measurability).

The norm of f is defined as

$$\|f\| = \left(\int_{\mathbb{R}} |f(t)|^2 dt \right)^{1/2}$$

Properties of a norm: $\|f\| \geq 0$, $\|f\|=0 \iff f=0$

$$\|cf\| = |c| \|f\| \quad c \in \mathbb{C}$$

$$\|f+g\| \leq \|f\| + \|g\|.$$

In a Hilbert space, the norm is defined via the scalar product: $\|f\| = \langle f, f \rangle^{1/2}$

Recall the Parseval formula: $\int_{\mathbb{R}} |\hat{f}(\omega)|^2 d\omega = 2\pi \int_{\mathbb{R}} |f(t)|^2 dt$.

Closed subspaces and projections

A linear subspace $V \subset L^2(\mathbb{R})$ is closed

if $f_n \in V$ ($n=1\dots\infty$) and $f_n \rightarrow f$ in $L^2(\mathbb{R})$ implies that $f \in V$.

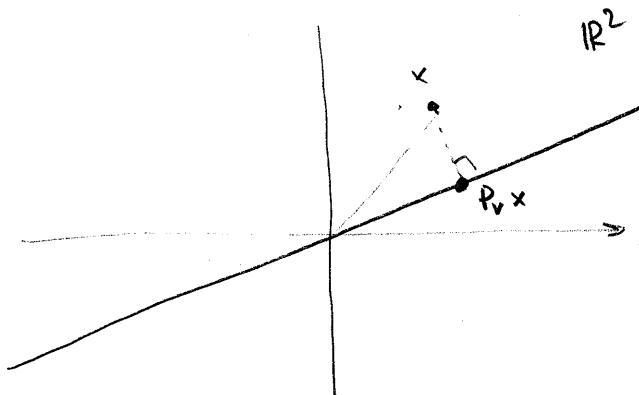
Example $\{f \in L^2(\mathbb{R}), f(t) = 0 \text{ when } t < 0\}$

$$V_{BL} = \{f \in L^2(\mathbb{R}) : |\hat{f}(\omega)| = 0 \text{ when } |\omega| > a\}$$

Def A linear operator $P : L^2(\mathbb{R}) \rightarrow L^2(\mathbb{R})$ is called a projection if

$$P(Pf) = Pf \quad \text{for all } f \in L^2(\mathbb{R}).$$

Def The orthogonal projection of f onto the closed subspace V is the unique $w \in V$ such that $\|f-w\| \leq \|f-v\|$ for all $v \in V$. This projection is denoted P_V .



Here is an example of a subspace of \mathbb{R}^2 . It is clear that

$$P_V(P_V x) = P_V x.$$

Note that $\langle f - P_V f, v \rangle = 0$
for all $v \in V$.

Bases A family of functions $\{\varphi_k\}_{k \in \mathbb{Z}}$ is a basis for $V \subset L^2(\mathbb{R})$ if any $f \in V$ can be written (in a unique way) as

$$f = \sum_k c_k \varphi_k,$$

where $c_k \in \mathbb{C}$.