TMA521/MMA510 Optimization, project course Lecture 1 Introduction: simple/difficult problems, matroid problems

Ann-Brith Strömberg

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TMA521/MMA510 Optimization, project course

- ► Examiner/lecturer Ann-Brith Strömberg (room 2087, anstr@chalmers.se)
- Lecturers Michael Patriksson, Karin Thörnblad, Adam Wojciechowski
- ► Schedule: 12 lectures, 3 seminars www.math.chalmers.se/Math/Grundutb/CTH/tma521/1112/
- ► Two projects:
 - Lagrangian relaxation for a VLSI design problem (Matlab)
 - Column generation applied to a real production scheduling problem (AMPL/Cplex, Matlab)
- ▶ Literature: Optimization theory for large systems (Lasdon, 2002, Cremona), An introduction to continuous optimization (Andréasson et al., Cremona), hand-outs from books and articles, lecture notes
- **Examination:** Written reports on the two projects, oral presentations and oppositions
- ► For higher grades than pass (4, 5, VG): oral exam



Topics: Turn difficult problems into sequences of simpler ones using decomposition and coordination

Prerequisites

 Linear Programming (LP), (Mixed) Integer Linear programming ((M)ILP), NonLinear Programming (NLP),

Decomposition methods covered

- Lagrangian relaxation (for MILP, NLP)
- Dantzig–Wolfe decomposition (for LP)
- Column generation (for LP, MILP, NLP)
- Benders decomposition (for MILP, NLP)
- Heuristics (for ILP)
- Branch & Bound (for MILP, non-convex NLP)
- Greedy algorithms (for ILP, NLP)
- Subgradient optimization (for convex NLP, Lagrangian duals)



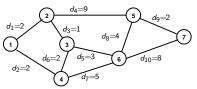
Examples of simple problems

- ► For *simple problems*, there exist *polynomial algorithms* preferably with a small largest exponent
- lacktriangle Simple problems belong to the complexity class ${\cal P}$
- Network flow problems (see Wolsey):
 - Shortest paths
 - Maximum flows
 - Minimum cost (single-commodity) network flows
 - The transportation problem
 - The assignment problem
 - Maximum cardinality matching
- Linear programming (see Andréasson et al.)
- Problems over simple matroids next!



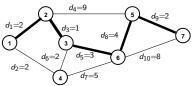
Example: Shortest path

Find the shortest path from node 1 to node 7



 $d_i = \text{length of edge } i$

Shortest path from node 1 to node 7

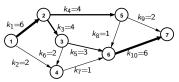


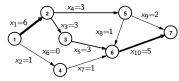
Total length: 12

Example: Maximum flow

Find the maximum flow from node 1 to node 7

Maximum flow from node 1 to node 7

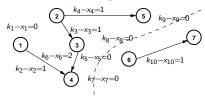




 $k_i = \text{flow capacity of arc } i$

 $x_i = \text{optimal flow through arc } i$

Minimum cut separating nodes 1 and 7



 $k_i - x_i = \text{residual flow capacity on arc } i$

Matroids and the greedy algorithm (Lawler)

- ► Greedy algorithm
 - Create a "complete solution" by iteratively choosing the best alternative
 - Never regret a previous choice

- Which problems can be solved using such a simple method?
- Problems whose feasible sets can be described by matroids

Matroids and independent sets

- ▶ Given a finite set $\mathcal E$ and a family $\mathcal F$ of subsets of $\mathcal E$: If $\mathcal I \in \mathcal F$ and $\mathcal I' \subseteq \mathcal I$ imply $\mathcal I' \in \mathcal F$, then the elements of $\mathcal F$ are called independent
- ▶ A matroid $M = (\mathcal{E}, \mathcal{F})$ is a structure in which \mathcal{E} is a finite set of elements and \mathcal{F} is a family of subsets of \mathcal{E} , such that
 - 1. $\emptyset \in \mathcal{F}$ and all proper subsets of a set \mathcal{I} in \mathcal{F} are in \mathcal{F}
 - 2. If \mathcal{I}_p and \mathcal{I}_{p+1} are sets in \mathcal{F} with $|\mathcal{I}_p| = p$ and $|\mathcal{I}_{p+1}| = p+1$, then \exists an element $e \in \mathcal{I}_{p+1} \setminus \mathcal{I}_p$ such that $\mathcal{I}_p \cup \{e\} \in \mathcal{F}$
- ▶ Let $M = (\mathcal{E}, \mathcal{F})$ be a matroid and $\mathcal{A} \subseteq \mathcal{E}$. If \mathcal{I} and \mathcal{I}' are maximal independent subsets of \mathcal{A} , then $|\mathcal{I}| = |\mathcal{I}'|$



Example I: Matric matroids

- $\triangleright \mathcal{E} = \text{a set of column vectors in } \mathbb{R}^n$
- $ightharpoonup \mathcal{F} =$ the set of linearly independent subsets of vectors in \mathcal{E} .

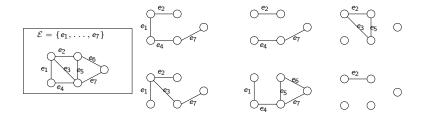
▶ Let
$$n = 3$$
 and $\mathcal{E} = [e_1, \dots, e_5] = \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 3 & 2 & 0 & 0 & 1 \end{bmatrix}$

- We have:
 - ▶ ${e_1, e_2, e_3} \in \mathcal{F}$ and ${e_2, e_3} \in \mathcal{F}$ but
 - ▶ $\{e_1, e_2, e_3, e_5\} \not\in \mathcal{F} \text{ and } \{e_1, e_4, e_5\} \not\in \mathcal{F}$



Example II: Graphic matroids

- ▶ $\mathcal{E} = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7\}$ = the set of edges in an undirected graph
- $m \mathcal{F}=$ the set of all cycle-free subsets of edges in \mathcal{E}



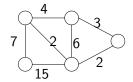
 $\begin{array}{ll} \blacktriangleright \ \{e_1, e_2, e_4, e_7\} \in \mathcal{F}, & \{e_2, e_4, e_7\} \in \mathcal{F}, & \{e_2, e_3, e_5\} \not \in \mathcal{F}, \\ \{e_1, e_2, e_3, e_7\} \in \mathcal{F}, & \{e_1, e_4, e_5, e_6, e_7\} \not \in \mathcal{F}, & \{e_2\} \in \mathcal{F}. \end{array}$

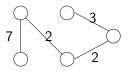
Matroids and the greedy algorithm applied to Example II

- ▶ Let w(e) be the cost of element $e \in \mathcal{E}$.

 Problem: Find the element $\mathcal{I} \in \mathcal{F}$ of maximal cardinality such

 that the total cost is at minimum/maximum
- ► Example II, continued: $w(\mathcal{E}) = (7, 4, 2, 15, 6, 3, 2)$





An element $\mathcal{I} \in \mathcal{F}$ of maximal cardinality with minimum total cost

The Greedy algorithm for minimization problems

- 1. $\mathcal{A} = \emptyset$.
- 2. Sort the elements of \mathcal{E} in increasing order with respect to w(e).
- 3. Take the first element $e \in \mathcal{E}$ in the list. If $\mathcal{A} \cup \{e\}$ is still independent \Longrightarrow let $\mathcal{A} := \mathcal{A} \cup \{e\}$.
- 4. Repeat from step 3. with the next element—until either the list is empty, or \mathcal{A} possesses the maximal cardinality.

Which are the special versions of this algorithm for Examples I and II?



Example I: Linearly independent vectors—matric matroids

▶ Let

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 2 & 0 & 1 \\ 0 & -1 & -1 & 1 & 1 \\ 3 & 2 & 8 & 1 & 4 \\ 2 & 1 & 5 & 0 & 2 \end{pmatrix},$$

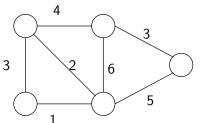
$$\mathbf{w}^{\mathrm{T}} = \begin{pmatrix} 10 & 9 & 8 & 4 & 1 \end{pmatrix}.$$

- Choose the maximal independent set with the maximum weight
- Can this technique solve linear programming problems?



Example II: minimum spanning trees (MST) —graphic matroids

- ► The maximal cycle-free set of links in an undirected graph is a spanning tree
- ▶ In a graph $\mathcal{G} = (\mathcal{N}, \mathcal{E})$, it has $|\mathcal{N}| 1$ links
- ▶ Classic greedy algorithm—Kruskal's algorithm has complexity $O(|\mathcal{E}| \cdot \log(|\mathcal{E}|))$. The main cost is in the sorting itself
- ▶ Prim's algorithm builds the spanning tree through graph search techniques, from node to node; complexity $O(|\mathcal{N}|^2)$.



Example III: continuous knapsack problem (in fact not a matroid problem)

► Continuous relaxation of the 0/1-knapsack problem (BKP):

maximize
$$f(\mathbf{x}) := \sum_{j=1}^{n} c_j x_j$$
, subject to $\sum_{j=1}^{n} a_j x_j \leq b$, $(a_j, b \in \mathcal{Z}_+)$ $0 \leq x_j \leq 1, \quad j = 1, \ldots, n$.

- Greedy algorithm:
 - 1. Sort c_i/a_i in descending order
 - 2. Set the variables to 1 until the knapsack is full
 - 3. One variable may become fractional and the rest zero
- ► Linear programming duality shows that the greedy algorithm solves the problem correctly



Example III, continued

Linear programming dual:

Hint: Complementarity slackness.



Example III, continued: Binary knapsack problem

- Rounding down the fractional variable value yields a feasible solution to (BKP)
- Is it also optimal in (BKP)?

$$\begin{aligned} \text{maximize } f(\mathbf{x}) &:= 2x_1 + c \, x_2, \\ \text{subject to} \quad x_1 + c \, x_2 \leq c, \qquad (c \in \mathcal{Z}_+) \\ \quad x_1, x_2 &\in \{0, 1\}, \end{aligned}$$

- ▶ If $c \ge 2$ then $\mathbf{x}^* = (0,1)^{\mathrm{T}}$ and $f^* = c$.
- The greedy algorithm, plus rounding, always yields $\bar{\mathbf{x}} = (1,0)^{\mathrm{T}}$, with $f(\bar{\mathbf{x}}) = 2$
- This solution is arbitrarily bad (when c is large)

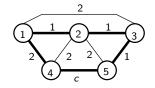


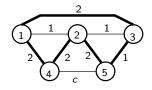
Example IV: The traveling salesperson problem (TSP)

The greedy algorithm for the TSP:

- 1. Start in node 1
- 2. Go to the nearest node which is not yet visited
- 3. Repeat step 2 until no nodes are left
- 4. Return to node 1; the tour is closed
 - Greedy solution

Not optimal whenever c > 4.



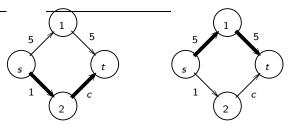


Optimal solution for $c \ge 4$

Example V: the shortest path problem (SPP)

- ► The greedy algorithm constructs a path that uses locally the cheapest link to reach a new node. Optimal?
- ► Greedy solution

 Not optimal whenever *c* > 9



Optimal solution for $c \geq 9$

Example VI: Semi-matching

$$\begin{aligned} & \text{maximize } f(\mathbf{x}) := \sum_{i=1}^m \sum_{j=1}^n w_{ij} x_{ij}, \\ & \text{subject to } \sum_{j=1}^n x_{ij} \leq 1, \quad i = 1, \dots, m, \\ & x_{ij} \in \{0, 1\}, \quad i = 1, \dots, m, \ j = 1, \dots, n. \end{aligned}$$

- ► Semi-assignment Replace maximum \Longrightarrow minimum; " \le " \Longrightarrow "="; let m = n
- ► Algorithm For each *i*:
 - 1. choose the best (lowest) w_{ij}
 - 2. Set $x_{ij} = 1$ for that j, and $x_{ij} = 0$ for every other j



Matroid types

- ▶ Graph matroid: $\mathcal{F} =$ the set of forests in a graph $\mathcal{G} = (\mathcal{N}, \mathcal{E})$. Example problem: MST
- ▶ Partition matroid: Consider a partition of \mathcal{E} into m sets $\mathcal{B}_1, \ldots, \mathcal{B}_m$ and let d_i $(i = 1, \ldots, m)$ be non-negative integers. Let

$$\mathcal{F} = \{ \mathcal{I} \mid \mathcal{I} \subseteq \mathcal{E}; \quad |\mathcal{I} \cap \mathcal{B}_i| \leq d_i, \ i = 1, \ldots, m \}.$$

Example problem: semi-matching in bipartite graphs.

- ▶ Matrix matroid: $S = (\mathcal{E}, \mathcal{F})$, where \mathcal{E} is a set of column vectors and \mathcal{F} is the set of subsets of \mathcal{E} with linearly independent vectors.
- Observe: The above matroids can be expressed as matrix matroids!



Problems over matroid intersections

- ▶ Given two matroids $M = (\mathcal{E}, \mathcal{P})$ and $N = (\mathcal{E}, \mathcal{R})$, find the maximum cardinality set in $\mathcal{P} \cap \mathcal{R}$
- Example 1: maximum-cardinality matching in a bipartite graph is the intersection of two partition matroids (with $d_i = 1$). Draw ILLUSTRATION!
- ► The intersection of two matroids can *not* be solved by using the *greedy algorithm*
- ▶ There exist *polynomial algorithms* for them, though
- Examples: bipartite matching and assignment problems can be solved as maximum flow problems, which are polynomially solvable



Problems over matroid intersections, cont.

- ► Example 2: The traveling salesperson problem (TSP) is the intersection of three matroids:
 - one graph matroid
 - two partition matroids

(formulation on next page: assignment + tree constraints)

- ► TSP is *not* solvable in polynomial time.
- Conclusion (not proven here):
 - Matroid problems are extremely easy to solve (greedy works)
 - Two-matroid problems are polynomially solvable
 - Three-matroid problems are very difficult (exponential solution time)
- ► The TSP—different mathematical formulations give rise to different algorithms when Lagrangean relaxed or otherwise decomposed



Tree formulation

minimize
$$\sum_{i=1}^{n} \sum_{j=1}^{n} c_{ij} x_{ij}$$
subject to
$$\sum_{j=1}^{n} x_{ij} = 1, \qquad i \in \mathcal{N}, \qquad (1)$$

$$\sum_{i=1}^{n} x_{ij} = 1, \qquad j \in \mathcal{N}, \qquad (2)$$

$$\sum_{i \in \mathcal{S}} \sum_{j \in \mathcal{S}} x_{ij} \leq |\mathcal{S}| - 1, \quad \mathcal{S} \subset \mathcal{N}, \qquad (3)$$

$$x_{ij} \in \{0, 1\}, \quad i, j \in \mathcal{N}.$$

- ▶ (1)–(2): assignment; (3): cycle-free
- ightharpoonup Relax (3) \Rightarrow Assignment
- ▶ Relax (1)–(2) & add the sum of (1) \Rightarrow 1-MST



Node valence based formulation

minimize
$$\sum_{i=1}^{n} \sum_{j=1}^{n} c_{ij} x_{ij}$$
subject to
$$\sum_{j=1}^{n} x_{ij} = 2, \qquad i \in \mathcal{N}, \qquad (1)$$

$$\sum_{i=1}^{n} \sum_{j=1}^{n} x_{ij} = n, \qquad (2)$$

$$\sum_{(i,j) \in (\mathcal{S}, \mathcal{N} \setminus \mathcal{S})} x_{ij} \ge 1, \qquad \mathcal{S} \subset \mathcal{N}, \qquad (3)$$

$$x_{ij} \in \{0,1\}, \quad i, j \in \mathcal{N}.$$

- ▶ (1): valence = 2; (2): sum of (1); (3): cycle-free (alt. version)
- ► Hamiltonian cycle = spanning tree + one link ⇒ every node receives valence = 2
- ▶ Relax (1), except for node $s \Rightarrow 1$ -tree relaxation.
- Relax (3) ⇒ 2-matching.



Tree-based formulation for directed graphs

minimize
$$\sum_{\substack{(i,j)\in\mathcal{E}\\ \text{subject to}}} c_{ij}x_{ij}$$
subject to
$$\sum_{\substack{j:(i,j)\in\mathcal{E}\\ i:(i,j)\in\mathcal{E}}} x_{ij} = 1, \qquad i\in\mathcal{N}, \qquad (1)$$

$$\sum_{\substack{i:(i,j)\in\mathcal{E}\\ x_{ij} = |\mathcal{N}|, \qquad (3)}} x_{ij} = |\mathcal{N}|, \qquad (3)$$

$$\sum_{\substack{(i,j)\in(\mathcal{S},\mathcal{N}\setminus\mathcal{S})^+\\ x_{ij}\in\{0,1\}, \quad (i,j)\in\mathcal{E}}} x_{ij} \geq 1, \qquad \mathcal{S}\subset\mathcal{N}, \qquad (4)$$

- ▶ (1)–(2): assignment; (3): redundant; (4) cycle-free
- ▶ Relax (1) or (2), plus (4) \Rightarrow semi-assignment
- ▶ Relax (3) plus (4) \Rightarrow assignment
- ▶ Relax (1), and (2) except for node $s \Rightarrow$ directed 1-tree

