

Lyapunov Functions and the Lyapunov stability theory

Def The solutions to $y' = f(y)$ are said to be exponentially stable if there exist β, γ and $c > 0$ so that

$$|y(0)| < \beta \Rightarrow |y(t)| < ce^{-\gamma t} \quad (t > 0).$$

Note If f is locally Lipschitz, then exponential stability implies asymptotic stability. This can be proven as follows:
 For $\varepsilon > 0$, there is $\alpha > 0$ so that $ce^{-\alpha t} < \varepsilon$.
 So if $|y_0| < \beta$, then if $y(t, y_0)$ is the solution with $y(0) = y_0$, satisfies $|y(t, y_0)| \leq \varepsilon e^{-\alpha(t-\alpha)}$ in $[0, \infty]$.
 Also, because of the Lip cond on f , there is $\delta < \beta$ so that if $|y_0| < \delta$, $|y(t, y_0)| < \varepsilon$ when $t \in [0, \alpha]$.

Consider now $V \in C^1(D, \mathbb{R})$ where $D \subset \mathbb{R}^n$, $y_0 \in D$.

and let

$$\dot{V}(x) = \text{grad } V(x) \cdot f(x) = \sum_{i=1}^n \frac{\partial V}{\partial x_i}(x) f_i(x),$$

i.e. the directional derivative of V in the direction of f .

Note that if $y(t)$ solves $y'(t) = f(y)$ then

$$\frac{d}{dt} V(y(t)) = \dot{V}(y(t)).$$

Definition A Lyapunov function to $y' = f(y)$ is a function $V : \mathbb{R}^n \rightarrow \mathbb{R}$ (or $V : D \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$) such that

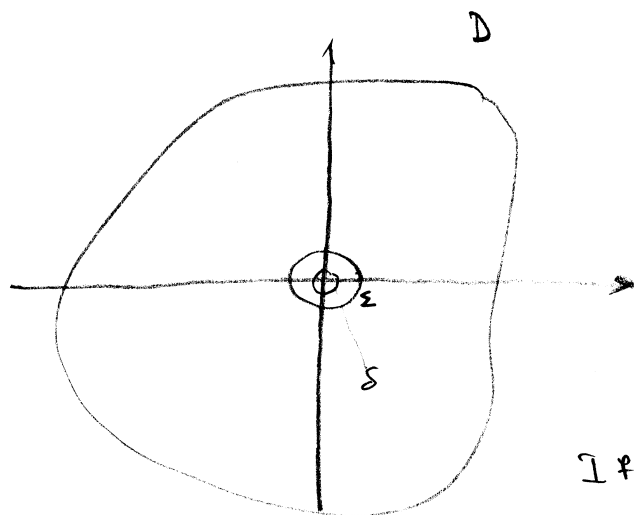
- $V \in C^1(D)$
- $V(x) > 0$ for $x \neq 0$
- $\dot{V}(x) \leq 0$ in $D \subseteq \mathbb{R}^n$.

Theorem Let $f \in C(D)$, $f(0) = 0$, and assume that there is a Lyapunov function to f . Then

- a) if $\dot{V} \leq 0$ in D , then $y \equiv 0$ is a stable solution to $y' = f(y)$
- b) if $\dot{V} < 0$ in $D \setminus \{0\}$ then $y \equiv 0$ is asymptotically stable
- c) if $\dot{V} \leq -\alpha V$ and $V(x) \geq b|x|^\beta$ in D (α, β, b positive), then $y \equiv 0$ is an exponentially stable solution.

Proof

a)



$$y' = f(y), \quad f(0) = 0$$

$$\frac{d}{dt} V(y(t)) = \dot{V}(y) \leq 0.$$

Take γ : $V(y) > \gamma$ on $|y| = \epsilon$

Take $\delta \in]0, \epsilon[$ so that $V(y) < \gamma$ in $|y| < \delta$.

If $|y(0)| < \delta$, we know

$$\dot{V}(y) = \frac{d}{dt} V(y(t)) \leq 0 \Rightarrow$$

$$V(y(t)) < \gamma \text{ for all } t > 0.$$

But then $|y(t)| < \epsilon$ for all $t > 0$

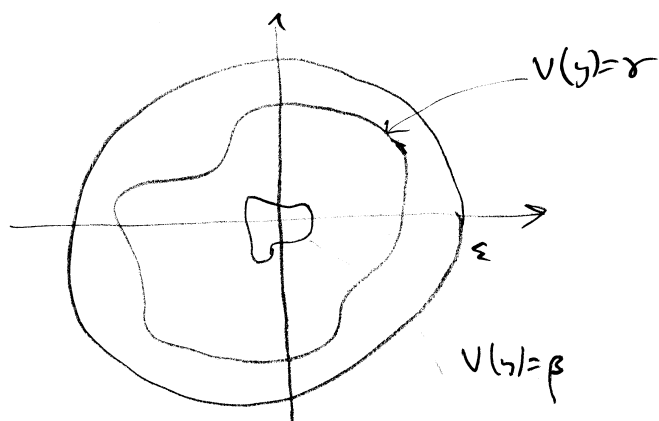
because $y(t)$ is continuous.

b Take $y(t)$ as in a), and let $\phi(t) = V(y(t))$.

Then $\frac{d\phi}{dt} < 0 \Rightarrow \phi(t) \rightarrow \beta < \gamma$ when $t \rightarrow \infty$

(because ϕ is strictly decreasing). Want to prove that $\beta = 0$.

If $\beta > 0$, let $M = \{y : |y| \leq \varepsilon, \beta \leq V(y) \leq \gamma\}$



Then M is a closed and bounded subset of $\{0 < |y| \leq \varepsilon\}$.

Let $-\alpha = \max(\{\dot{V}(y), y \in M\})$.

We have $-\alpha < 0$.

If $y(t)$ remains in M ,

then $\phi'(t) \leq -\alpha \Rightarrow \phi(t) \leq \phi(0) - \alpha t$

which contradicts the statement $\phi(t) > 0$.

This implies $y(t) \rightarrow 0$, because let

$\delta = \min\{V(y) : \varepsilon_1 \leq |y| \leq \varepsilon\}$.

$V(y(t)) \rightarrow 0 \Rightarrow \exists t_0:$

$|y(t)| < \varepsilon_1$ for $t > t_0$.

c We have in this case $b|y(t)|^\beta \leq V(y(t)) = \phi(t)$

and $\phi' \leq -\alpha \phi \Rightarrow \phi(t) \leq \phi(0)e^{-\alpha t}$

$\Rightarrow |y(t)| \leq \left(\frac{\phi(t)}{b}\right)^{1/\beta} \leq \left(\frac{\phi(0)}{b}\right)^{1/\beta} e^{-\frac{\alpha}{\beta}t}$.

Theorem (instability)

Let $V \in C^1(D)$ satisfy $V(0) = 0$ and assume that there is a sequence $\{y_k\}$, $0 < |y_k| \rightarrow 0$ when $k \rightarrow \infty$ such that $V(y_k) > 0$.

If $\dot{V} > 0$ for $y \neq 0$, or $\dot{V} \geq \lambda V$ ($\lambda > 0$),

then $y(t) \equiv 0$ is an unstable solution.

Proof Let $y(t)$ solve $\begin{cases} y' = f(y) \\ y(0) = y_k \end{cases}$ Then

$\phi(0) = \alpha > 0$, where $\phi(t) = V(y(t))$. If $\dot{V} > 0$ for $y \neq 0$,

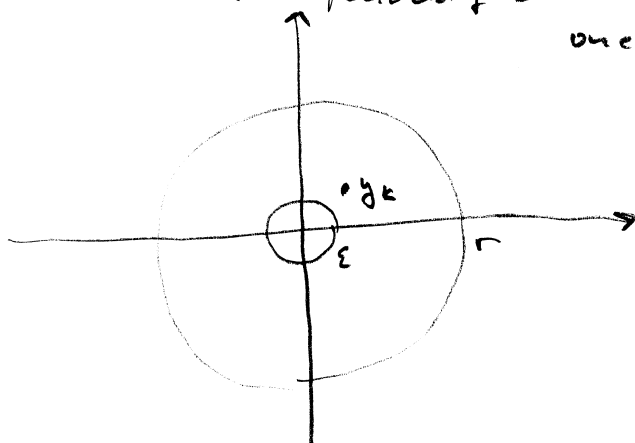
take $\varepsilon > 0$ so that $V(y) < \alpha$ for $|y| \leq \varepsilon$. We have

$\phi' > 0$, and so $\alpha = \phi(0) \leq \phi(t) \Rightarrow y(t) > \varepsilon$.

Take $r > \varepsilon$ so that $\{|x| \leq r\} \subset D$. If $\varepsilon \leq |y| \leq r$,

then $\dot{V}(y) \geq \beta > 0$ ($\dot{V}$ cont.) $\Rightarrow \phi' \geq \beta \Rightarrow \phi(t) \geq \alpha + \beta t$.

But $V(y)$ is bounded when $|y| \leq r \Rightarrow y(t)$ must leave the ball $\{|y| \leq r\}$. Note that y_k can be chosen arbitrarily close to 0, and hence the result holds independently of how close to the origin one starts.



If $\dot{V} \geq \lambda V$ then $\phi' \geq \lambda \phi \Rightarrow y(t)$ must leave any ball $\{|y| \leq r\} \subset D$.

An example

$$u''(t) + h(u(t)) = 0$$

$$\Leftrightarrow \begin{cases} x(t) = u(t) \\ y(t) = u'(t) \end{cases}, \quad \begin{cases} y' = -h(x) \\ x' = y \end{cases}$$

$$\text{take } E(x, y) = \frac{1}{2} y^2 + \int_0^x h(s) ds$$

$$= \frac{dE}{dt} = \frac{\partial E}{\partial x} \dot{x} + \frac{\partial E}{\partial y} \dot{y} = y(-h(x)) + h(x)y = 0$$

conservative

$$u''(t) + \varepsilon u'(t) + h(u) = 0$$

$$\Leftrightarrow \begin{cases} x' = y \\ y' = -h(x) - \varepsilon y \end{cases}$$

$$\Rightarrow \dot{E} = h(x)y + y(-h(x) - \varepsilon y) = -\varepsilon y^2$$

dissipative

More examples

$$y' = Ay + \varphi(s)By + g(s)$$

$$\varphi: \mathbb{R}^n \rightarrow \mathbb{R} \\ (D \rightarrow \mathbb{R})$$

$$g: \mathbb{R}^n \rightarrow \mathbb{R}^n, \quad g(u) = 0$$

$$B = -A^T$$

$$\text{Take } V(y) = y \cdot y = |y|^2$$

$$\dot{V}(y) = 2y \cdot \dot{y} = 2y \cdot Ay + \varphi(s) 2y \cdot By + 2y \cdot g(s)$$

$$= 2\langle y, Ay \rangle + 2\langle y, g(s) \rangle$$

need to find out if $\langle y, Ay \rangle < 0$

$$\langle y, g(s) \rangle < 0$$

(A negative definite...)

all eigenvalues negative)

$$u'' + a_1(x)u' + a_0(x)u = g(x), \quad a \leq x \leq b$$

boundary cond

$$(0 \leq x \leq 1)$$

I $u(a) = \eta_1, \quad u(b) = \eta_2$ (Dirichlet)

II $u'(a) = \eta_1, \quad u'(b) = \eta_2$ (Neumann)

III $\alpha_1 u(a) + \alpha_2 u'(a) = \eta_1$ (mixed)

S Sturm-Liouville problems

$$\text{Let } \begin{cases} Lu(x) = (p(x)u'(x))' + q(x)u(x) \\ R_1 u = \alpha_1 u(a) + \alpha_2 p(a)u'(a) \\ R_2 u = \beta_1 u(b) + \beta_2 p(b)u'(b) \end{cases}$$

where $p \in C^1(J), \quad q, g \in C(J)$

$$J = [a, b]$$

$$p(x) > 0, \quad \alpha_1^2 + \alpha_2^2 > 0, \quad \beta_1^2 + \beta_2^2 > 0$$

A boundary value problem

$$\begin{cases} Lu = g & \text{in } J \\ R_1 u = \eta_1, \quad R_2 u = \eta_2 \end{cases}$$

Note

with $\begin{cases} y_1 = u \\ y_2 = pu' \end{cases}$

we can write

$$\begin{cases} y_2' + qy_1 = g \\ y_1' = y_2/p \end{cases}$$

with bc ~~$y_2(a) = \eta_1$~~

$$\alpha_1 y_1(a) + \alpha_2 y_2(a) = \eta_1$$

Note any system of the form

$u'' + a_1 u' + a_0 u = f(x)$ can be written in the "self adjoint" form: let $p(x) = e^{\int a_1 dx}$

$$\begin{aligned} \text{Then } pu'' + a_1 pu' + p a_0 u &= \\ &= (pu')' + p a_0 u \end{aligned}$$

Lagrange's identity

1) If $u, v \in C^2(J)$, then

$$vLu - uLv = (p(u'v - v'u))'$$

2) If $R_i u = R_i v = 0 \quad (i=1,2)$ then

$$\int_a^b (vLu - uLv) dx = 0$$

Proof a direct calculation:

$$\begin{aligned} 1) \quad v((pu')' + qv) - u((pv')' + qu) &= \\ = v(pu')' - u(pv')' &= p'(vu' - uv') + p(vu'' - uv'') \\ &= p'(vu' - uv') + p(vu'' + v'u' - v'u' - uv'') \\ &= (p(vu' - uv'))' \end{aligned}$$

$$\begin{aligned} 2) \quad \int_a^b (vLu - uLv) dx &= \int_a^b \frac{d}{dx} (p(vu' - uv')) dx \\ &= [p(x)(v(x)u'(x) - u(x)v'(x))]_a^b = 0 \quad \text{if } R_i \text{ are self-adjoint.} \end{aligned}$$

The boundary value problem is linear $\Rightarrow$

- a) if u_j $j=1, \dots, n$ solve the hom. problem
then $\sum c_j u_j$ also is a solution
- b) if v_1, v_2 solve the (inhom) probl., then
 $v_1 - v_2$ solves the hom. problem.
- c) one can add any solution of the hom problem
to a solution of the inhom probl. and
still have a solution
- d) Let u^* solve the inhomogeneous problem.
Then all solutions to the inhom probl. can be
found by adding a solution to the hom. problem.

Theorem Let u_1, u_2 be a fundamental system
of solutions to $Lu=0$. Then the inhom
boundary value probl. can be solved uniquely
if and only if the homogeneous problem
has only the solution $u=0$. This holds

$$\text{iff } \det \begin{pmatrix} R_1 u_1 & R_1 u_2 \\ R_2 u_1 & R_2 u_2 \end{pmatrix} \neq 0.$$

Compare the linear (algebraic) system

$$Ax = b$$

$$A \text{ } n \times n$$

$$x, b \in \mathbb{R}^n$$

this has a unique soln $\Leftrightarrow \det A \neq 0$

$\Leftrightarrow Ax=0$ has only $x=0$ as solution.

"The Fredholm alternative"

Proof The difference $w \in \Phi$ two solutions to

$$\begin{cases} Lu = g \\ R_1 u = \eta_1, R_2 u = \eta_2 \end{cases} \quad \text{soln } \begin{cases} Lw = 0 \\ R_1 w = R_2 w = 0 \end{cases}$$

which gives the uniqueness statement.

Take any solution v_* to $Lu = g$.

The general solution is

$$v = v_* + c_1 u_1 + c_2 u_2$$

check b.c.:

$$R_i v = R_i v_* + c_1 R_i u_1 + c_2 R_i u_2 = \eta_i$$

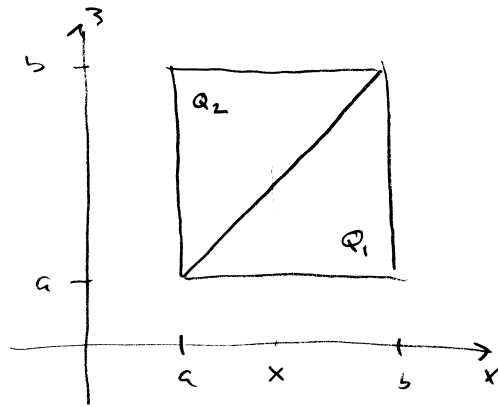
The eq.
$$\begin{cases} R_1 u_1 c_1 + R_1 u_2 c_2 = \eta_1 - R_1 v_* \\ R_2 u_1 c_1 + R_2 u_2 c_2 = \eta_2 - R_2 v_* \end{cases}$$

has a unique soln. $\Leftrightarrow \det(\quad) \neq 0$.

$\square$

Fundamental solutions

A function $\gamma : Q \rightarrow \mathbb{R}$ is called a fundamental solution to $Lu = 0$ if



$$Q = Q_1 \cup Q_2$$

Q_1, Q_2 closed triangles

a) $\gamma(x, z)$ is cont in Q

b) $\frac{\partial \gamma}{\partial x}, \frac{\partial^2 \gamma}{\partial x^2}$ are cont in Q_1 and Q_2 (with one sided derivatives on the diagonal)

c) For ξ fixed γ (considered as a function of x)
soln $L\gamma = 0$ on $Q \setminus \{x = \xi\}$

d) On $x = \xi$, $\frac{\partial \gamma}{\partial x}$ makes a jump of magnitude $\frac{1}{p}$, $\gamma_x(x^+, x) - \gamma_x(x^-, x) = \frac{1}{p(x)}$.

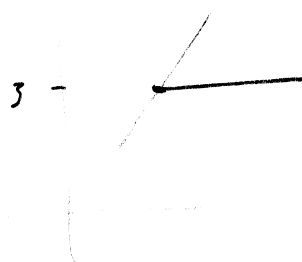
Lemma Fundamental solutions exist

Proof Let $u(x, \xi)$ solve

$$Lu = 0$$

$$u(\xi) = 0$$

$$u'(\xi) = \frac{1}{p(\xi)}$$



$$\text{and let } \gamma(x, \xi) = \begin{cases} 0 & 0 \leq x \leq \xi \leq b \\ u(x, \xi) & \xi \leq x \leq b. \end{cases}$$

This is not unique because

$$\tilde{\gamma} = \gamma + g(x)h(\xi) \text{ is also a solution}$$

$$\text{if } Lg = 0 \quad (g \in C^2(J)) \quad h \in C^0(J).$$

Theorem Consider $\begin{cases} Lu = g & \text{in } J \\ R_1 u = R_2 u \end{cases}$

and that the hypotheses in P_1, P_2, P_3 hold.

Then

$$v(x) = \int_a^b \gamma(x, \xi) g(\xi) d\xi \text{ is in } C^2(J)$$

$$\text{and } Lv = g \text{ in } J.$$

$$\text{Proof } v(x) = \int_a^x \gamma(x, \xi) g(\xi) d\xi + \int_x^b \gamma(x, \xi) g(\xi) d\xi$$

$$v'(x) = \gamma(x, x)g(x) + \int_a^x \frac{\partial \gamma}{\partial x}(x, \xi) g(\xi) d\xi$$

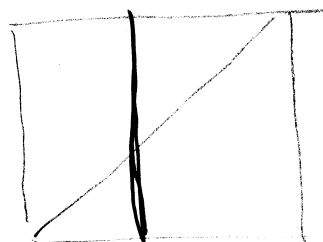
$$- \gamma(x, x)g(x) + \int_x^b \frac{\partial \gamma}{\partial x}(x, \xi) g(\xi) d\xi$$

$$= \int_a^b \frac{\partial \gamma}{\partial x}(x, \xi) g(\xi) d\xi.$$

$$v''(x) = \frac{\partial \gamma}{\partial x}(x^+, x)g(x) - \frac{\partial \gamma}{\partial x}(x^-, x)g(x)$$

$$+ \int_a^b \frac{\partial^2 \gamma}{\partial x^2}(x, \xi) g(\xi) d\xi$$

$$= \int_a^b \frac{\partial^2 \gamma}{\partial x^2}(x, \xi) g(\xi) d\xi + \frac{g(x)}{p(x)}.$$



$$\begin{aligned}
Lv &= p v'' + p' v' + q v \\
&= p \int \frac{\partial^2 \delta}{\partial x^2} g d\mathcal{Z} + p' \int \frac{\partial \delta}{\partial x} g d\mathcal{Z} + q \int \delta g d\mathcal{Z} \\
&\quad + g(x) \\
&= g \quad \text{because } L\delta = 0.
\end{aligned}$$

□

Def Let $\begin{cases} Lu=0 \\ R_1 u = R_2 u \end{cases}$ define a Sturmian boundary

value problem. A Green's function is a function $\Gamma(x, \mathcal{Z}) : \mathcal{J} \times \mathcal{J} \rightarrow \mathbb{R}$ such that

- $\Gamma(x, \mathcal{Z})$ is a fundamental solution to $Lu=0$
- $R_1 \Gamma = R_2 \Gamma = 0$ for each $\mathcal{Z} \in \mathcal{J}^* =]a, b[$

Assuming that $Lu=0$ has only the trivial solution, the Green's function exists, and can be constructed as follows:

Let u_1, u_2 satisfy $Lu_1 = Lu_2 = 0$ and $R_1 u_1 = 0, R_2 u_2 = 0$. There can be obtained as

$$\begin{cases} Lu_1 = 0 \\ u_1(a) = \lambda \quad p(a)u_1'(a) = \mu \end{cases}$$

where $(\lambda, \mu) \neq (0, 0)$ and $\alpha, \lambda + \beta, \mu = 0$ (so that $R_1 u_1 = 0$)

and similarly for u_2 .

u_1, u_2 is a fundamental system, because if u_1 were proportional to u_2 , then we would have $R_1 u_1 = R_1 u_2 = 0$, giving non-trivial solutions to $\begin{cases} Lu=0 \\ R_1 u = R_2 u = 0 \end{cases}$

$$\text{Let } c = p(u_1 u_2' - u_1' u_2)$$

Then c is a non-zero constant, because of Lagrange's identity.

$$\text{Now let } \quad \textcircled{*} \quad P(x, \xi) = \frac{1}{c} \begin{cases} u_1(\xi) u_2(x) & \text{in } a \leq \xi \leq x \leq b \\ u_1(x) u_2(\xi) & \text{in } a \leq x \leq \xi \leq b \end{cases}$$

Theorem If the homogeneous problem has only the trivial solution, then the Green's function exist and is unique.

Moreover, the solution to

$$\begin{cases} Lu = g \\ R_1 u = R_2 u = 0 \end{cases}$$

is given by

$$u(x) = \int_a^b P(x, \xi) g(\xi) d\xi$$

Proof We need to prove uniqueness. Assume there are two Green's functions, $P(x, \xi)$ and $P'(x, \xi)$

$$\text{Let } v(x) = \int_a^b P(x, \xi) g(\xi) d\xi, \quad w(x) = \int_a^b P'(x, \xi) h(\xi) d\xi \quad \textcircled{**}$$

where g and h are continuous.

Because $R_i v = R_i w = 0 \quad (i=1, 2)$

$$\int_a^b (v Lw - w Lv) dx = 0 \quad (\text{Lagrange})$$

Replace Lw by h and Lv by g and use $\textcircled{**}$:

Then

$$\int_a^b \left(\int_a^b \Gamma(x, \xi) g(\xi) d\xi h(x) - \int_a^b \Gamma'(x, \xi) h(\xi) d\xi g(x) \right) dx$$

$$= \int_a^b \int_a^b \left(\Gamma(x, \xi) g(\xi) h(x) - \Gamma'(x, \xi) h(\xi) g(x) \right) dx d\xi$$

$$= \int_a^b \int_a^b \left(\Gamma(x, \xi) - \Gamma'(\xi, x) \right) h(x) g(\xi) dx d\xi$$

Here we have assumed that it is ok to change the order of integration (Fubini's theorem).

But $\Gamma'(\xi, x) = \Gamma'(x, \xi)$ so

$$\int_a^b \int_a^b \left(\Gamma(x, \xi) - \Gamma'(\xi, x) \right) h(x) g(\xi) dx d\xi = 0$$

This holds for arbitrary functions $h(x)$ and $g(\xi)$,
and therefore $\Gamma(x, \xi) = \Gamma'(\xi, x)$.

Ex $Lu = u''$ $R_1 u = u(0)$, $R_2 u = u(1)$ ($\mathcal{D} = [0, 1]$)

Then $\Gamma(x, \xi) = \begin{cases} \xi(x-1) & 0 \leq \xi \leq x \leq 1 \\ x(\xi-1) & 0 \leq x \leq \xi \leq 1 \end{cases}$

