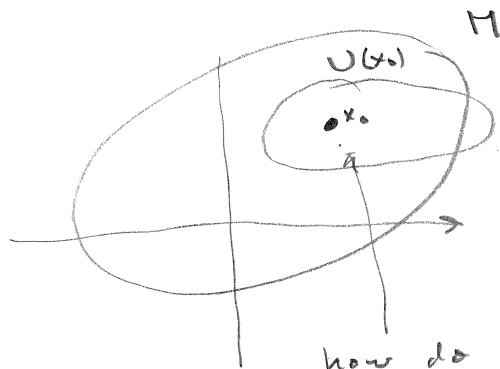


Stability via Lyapunov functions



how do we prove stability (if it is true)?

Exercise: 6.15:

$$\dot{x} = x - y - x(x^2 + y^2) + \frac{xy}{\sqrt{x^2 + y^2}}$$

$$\dot{y} = x + y - y(x^2 + y^2) - \frac{x^2}{\sqrt{x^2 + y^2}}$$

Def Let $L: U(x_0) \rightarrow \mathbb{R}$ satisfy

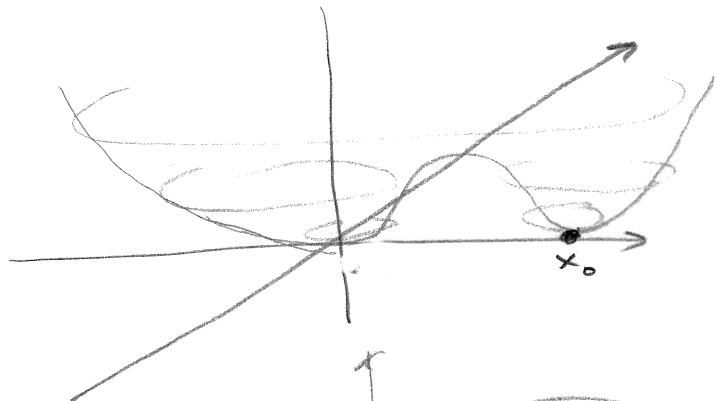
1) $L(x_0) = 0$

2) $L(x) > 0$, > 0 if $x \neq x_0$

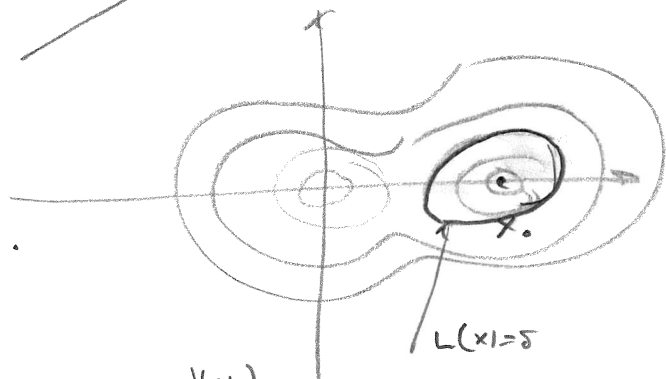
3) If $t_1 > t_0$, $\phi(t_1) \in U(x_0)$, $\phi(t_0) \in U(x_0)$ ($\neq x_0$)
 $\Rightarrow L(\phi(t_1)) < L(\phi(t_0))$

Def

S_δ is the connected component of $\{x \in U(x_0) \mid L(x) \leq \delta\}$ such that $x_0 \in S_\delta$



Lemma If S_δ is closed, it is positively invariant.

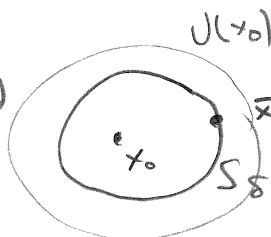


Proof If $\phi(t)$ leaves

S_δ at $\bar{x}$ there is a ball $B_r(\bar{x}) = \{x \mid |x - \bar{x}| < r\} \subset U(x_0)$

such that $\phi(t_0) = \bar{x}$,

$$\phi(t_0 + \epsilon) \in U(x_0) \setminus S_\delta$$



$$\Rightarrow L(\phi(t_0 + \epsilon)) < L(\phi(t_0)) \Rightarrow L \text{ not Lyapunov}$$

Lemma For all $\delta > 0$ there is $\varepsilon > 0$

such that

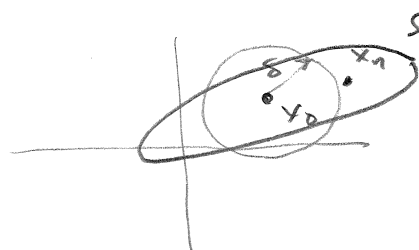
1) $S_\varepsilon \subseteq B_\delta(x_0)$ and

2) $B_\varepsilon(x_0) \subseteq S_\delta$

Proof

If 1) is false, then for all $n \geq 1$, there is

$x_n \in S_{1/n}$ but $|x_n - x_0| > \delta$, we may take



x_n such that $|x_n - x_0| = \delta$,
and the sphere $\{x: |x - x_0| = \delta\}$
is compact $\Rightarrow$

there is $\{x_{n_j}\}$ so that $x_{n_j} \rightarrow y$

with $|y - x_0| = \delta$. But $L(x_n) \leq \frac{1}{n}$ and

L is cont $\Rightarrow L(y) = 0$, contradicting

the fact that $L(y) = 0$ only at $x = x_0$.

If 2) is false there is $\{x_n\}$ such that

$$|x_n - x_0| \leq \frac{1}{n} \text{ and } L(x_n) \geq \delta$$

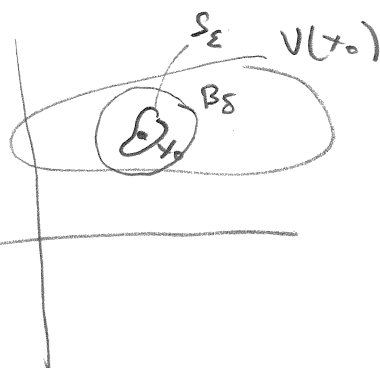
Then $\delta \leq L(x_n) \rightarrow 0$ because $x_n \rightarrow x_0$ and $L(x_0) = 0$.

This implies:

Theorem: If x_0 is a fixed point of f
and there is a Lyapunov function, then
 x_0 is stable.

Proof Take a (small) neighborhood $V(x_0)$
of x_0 .

S_ε is closed
and hence
positively invariant.





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Example of Lyapunov

$$\begin{cases} \frac{dx}{dt} = -3x^3 - y \\ \frac{dy}{dt} = x^5 - 2y^3 \end{cases}$$

Show that $(0,0)$ is an asymptotically stable fixed point.

Common idea: try a Lyapunov function of

the form $V(x,y) = ax^{2m} + by^{2n} \quad (a, b > 0)$

$$\frac{d}{dt} V(x(t), y(t)) = 2ma x^{2m-1} \dot{x} + 2nb y^{2n-1} \dot{y}$$

$$= 2ma x^{2m-1} (-3x^3 - y) + 2nb y^{2n-1} (x^5 - 2y^3)$$

$$= -6ma x^{2m+2} - 2ma x^{2m-1} y + 2nb y^{2n+1} x^5 - 4nb y^{2n+2}$$

$$\text{Let } \begin{matrix} 2m-1=5 & m=3 \\ 2n-1=1 & n=1 \end{matrix}$$

$$\Rightarrow \frac{dV}{dt} = -18a x^8 - \underbrace{6ax^5y + 2byx^5}_{=0 \text{ if (e.g.) } a=1, b=3} - 4nb y^4$$

$$= 0 \text{ if (e.g.) } a=1, b=3$$

$$\text{So } V(x,y) = x^6 + 3y^2 \text{ is a strict}$$

$$\text{Lyapunov function} \Rightarrow (0,0) \text{ is a}$$

stable fixed point.



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Back to linear equations (temporality)

$\dot{x} = Ax$ and in Jordan form

$$A = \begin{pmatrix} \boxed{} & & \\ & \boxed{} & \\ & & \ddots \\ & & & \boxed{} \end{pmatrix} \quad \text{where } \boxed{} = \begin{pmatrix} \alpha_j & 1 & & 0 \\ & \ddots & \ddots & \\ 0 & & \ddots & 1 \\ & & & \alpha_j \end{pmatrix}$$

Def $E^+(e^A) = \bigoplus_{\operatorname{Re} \alpha < 0} N((A - \alpha_j)^{q_j})$

If $A = \begin{pmatrix} \boxed{} & & \\ & \boxed{} & \\ & & \ddots \\ & & & \boxed{} \end{pmatrix}$ then

- $\operatorname{Re} \alpha < 0$ (points to the top-left block)
- $\operatorname{Re} \alpha = 0$ (points to the middle block)
- $\operatorname{Re} \alpha > 0$ (points to the bottom-right block)

When the blocks are ordered so that $\operatorname{Re} \alpha < 0$ are as in the figure then

$$E^+(e^A) = \operatorname{span} \left(\begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix} \right)$$

We define $E^-(e^A)$ similarly,

and $E^0(e^A)$ too.

Def $x \in E^+ \iff e^{tA}x \rightarrow 0$ when $t \rightarrow \infty$
 $x \in E^- \iff e^{-tA}x \rightarrow 0$ when $t \rightarrow \infty$



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Def A system is hyperbolic if
all eigenvalues to A satisfy $\operatorname{Re} \alpha \neq 0$.

Theorem Consider $\dot{x} = Ax$
where the eigenvalues are α_j with algebraic
and geometric multiplicities a_j, g_j .

• Then $\dot{x} = Ax$ is stable (globally)
 $\Leftrightarrow \operatorname{Re} \alpha_j \leq 0$ and $a_j = g_j$ when $\operatorname{Re} \alpha_j = 0$

• $\dot{x} = Ax$ is asymptotically stable if $\operatorname{Re} \alpha_j < 0$

Then there is a constant α , $\alpha < \min\{-\operatorname{Re} \alpha_j\}$
such that $\|e^{tA}\| \leq Ce^{-t\alpha}$

Theorem The stable and unstable subspaces E^+, E^-
are invariant.

$$x_0 \in E^+ \Rightarrow |e^{tA} x_0| \leq Ce^{-t\alpha} |x_0|$$

$$x_0 \in E^- \Rightarrow |e^{tA} x_0| \leq Ce^{-t\alpha} |x_0|$$

