

## Back to linear systems

$$\dot{x} = Ax \quad \text{Fixed point: } x=0.$$

Assume  $A$  in Jordan form:

$$A = \begin{pmatrix} \boxed{\phantom{0}} & & \\ & \boxed{\phantom{0}} & \\ & & \boxed{\phantom{0}} \end{pmatrix}$$

$\text{Re } \lambda < 0$  for all eigenvalues here  
 $\text{Re } \lambda = 0$   
 $\text{Re } \lambda > 0$

Def  $E^+(e^A) = \bigoplus_{\text{Re } \alpha_j < 0} N((A - \alpha_j)^{a_j})$  stable subspace

( $\alpha_j$  eigenvalue to a Jordan block)

$E^-(e^A)$  unstable subspace

$$x \in E^+ \Rightarrow e^{tA} x \rightarrow 0$$

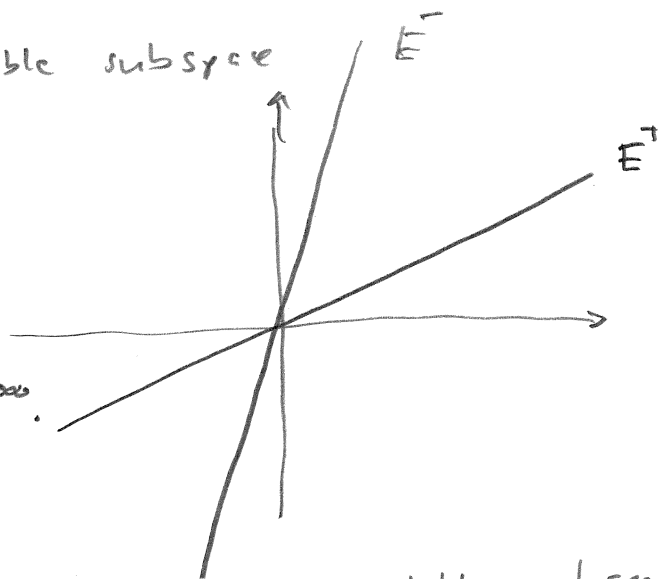
and there is  $\alpha > 0$  such that

$$e^{\alpha t} |e^{tA} x| \rightarrow 0 \text{ when } t \rightarrow \infty.$$

$$x \in E^- \Rightarrow e^{-tA} x \rightarrow 0$$

and there is  $\alpha > 0$  s.t.

$$e^{\alpha t} |e^{-tA} x| \rightarrow 0 \text{ when } t \rightarrow \infty$$



unstable subspace

$$E^0(e^A) = \bigoplus_{\text{Re } \alpha_j = 0} N((A - \alpha_j)^{a_j})$$

center subspace.

Def A system is hyperbolic if all eigenvalues satisfy  $\operatorname{Re} \alpha \neq 0$ .

† why is this the typical case? †

Theorem Consider  $\dot{x} = Ax$

where the eigenvalues  $\alpha_j$  have algebraic and geometric multiplicity  $a_j, g_j$ .

Then  $x=0$  is stable  $\Leftrightarrow \operatorname{Re} \alpha_j \leq 0$  and  $a_j = g_j$  if  $\operatorname{Re} \alpha_j = 0$   
asymptotically stable  $\Leftrightarrow \operatorname{Re} \alpha_j < 0$ .

There is a constant  $\alpha$  such that

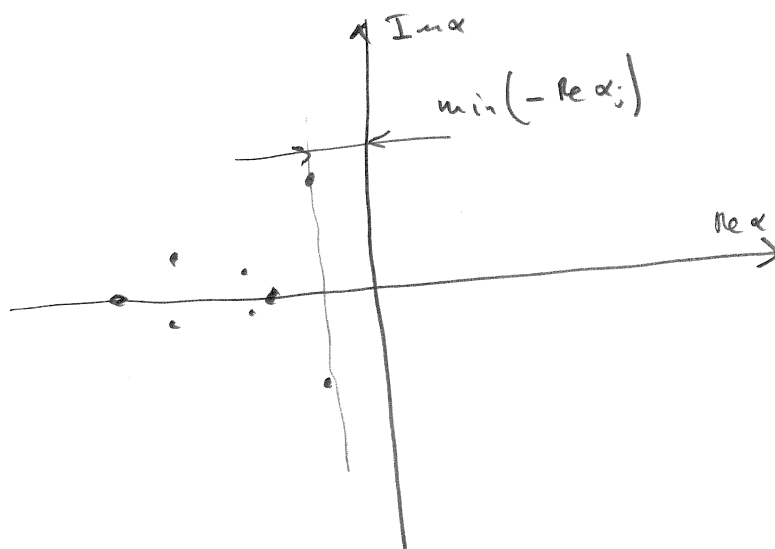
$$0 < \alpha < \min \{-\operatorname{Re} \alpha_j\}$$

and  $\|e^{tA}\| \leq C e^{-\alpha t} \quad (\rightarrow 0 \text{ when } t \rightarrow \infty).$

Theorem The linear stable and unstable manifolds  $E^+, E^-$  are invariant.

$$\text{and } x_0 \in E^+ \Rightarrow |e^{tA} x_0| < C e^{-\alpha t} |x_0|$$

$$x_0 \in E^- \Rightarrow |e^{-tA} x_0| < C e^{-\alpha t} |x_0|$$



Def  $E^{+, \alpha} = \bigoplus_{-\operatorname{Re}(\alpha_j) > \alpha} \mathcal{N}((A - \alpha_j)^{q_j}) = E^+(e^{A+\alpha})$

$E^{-, \alpha} = E^-(e^{A-\alpha})$

Equiv  $E^{+, \alpha}(e^A) = \{x : \lim_{t \rightarrow \infty} e^{\alpha t} \|e^{tA}\| = 0\}$

What to do about nonlinear systems?

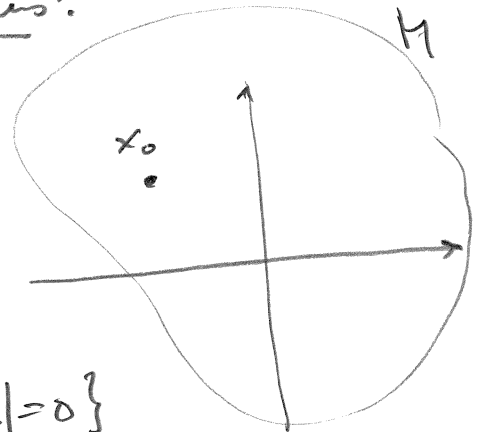
$\dot{x} = f(x)$  with  $f(x_0) = 0$ .

Def The stable set is

$W^+ = \{x \in M : \lim_{t \rightarrow \infty} |\Phi_t(x) - x_0| = 0\}$

The unstable set is

$W^- = \{x \in M : \lim_{t \rightarrow -\infty} |\Phi_t(x) - x_0| = 0\}$



Def Let  $f(x) = A(x - x_0) + g(x - x_0)$

where  $g(z) = o(|z|)$ .

$x_0$  is said to be hyperbolic if  $A$  is.

Question: What do  $W^+$  and  $W^-$  look like?

Theorem Assume that  $f \in C^k(\mathcal{H})$  and that

$$f(x_0) = 0, \quad f(x) = A(x - x_0) + g(x - x_0) \text{ where}$$

$$g(z) = o(|z|). \text{ Take } \alpha > 0 \text{ and assume}$$

$A + \alpha I$  is hyperbolic. Then there is

$$U(x_0) = x_0 + U \text{ and } h^{+\alpha} \in C^k(E^{+\alpha} \cap U, E^{-\alpha})$$

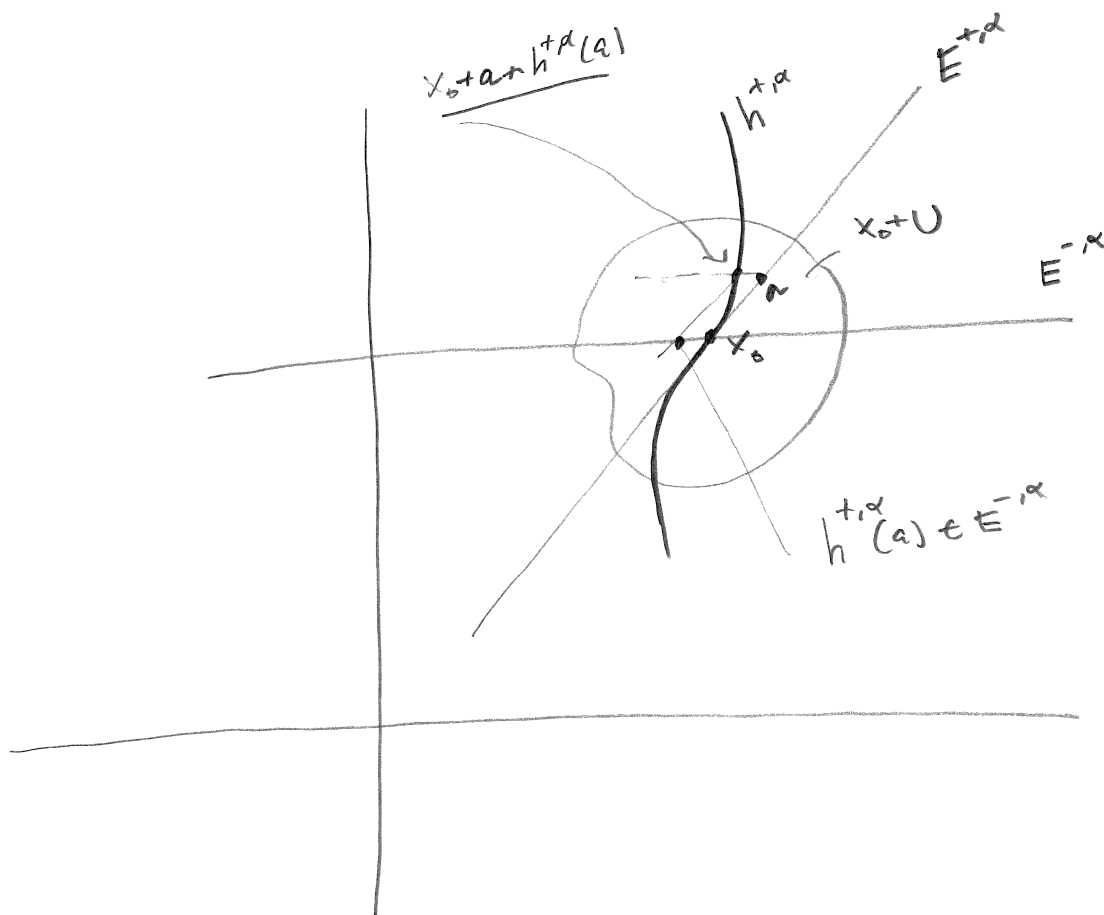
such that

$$M^{+\alpha}(x_0) \cap U(x_0) = \{x_0 + a + h^{+\alpha}(a), a \in E^{+\alpha} \cap U\}$$

$M^{+\alpha}$  is tangent to  $E^{-\alpha}$  at  $x_0$ .

Proof: A contraction mapping argument,  
not so easy.

What does the theorem mean?



# Diffeomorphisms

Discrete dynamical systems:

$$x_{n+1} = f(x_n) \quad f: \mathbb{R}^n \rightarrow \mathbb{R}^n \quad (\varphi: M \rightarrow M)$$

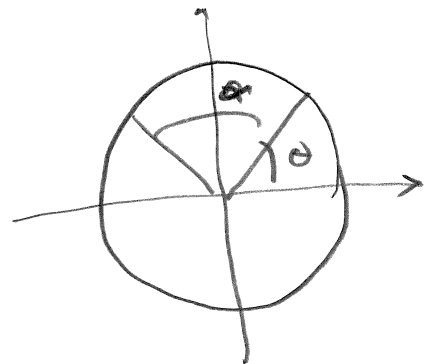
Def  $f$  is a  $C^r$ -map if it is  $r$  times cont differentiable

$f$  is a  $C^k$ -diffeomorphism if it is a bijection and  $f$  and  $f^{-1}$  are  $C^k$ .

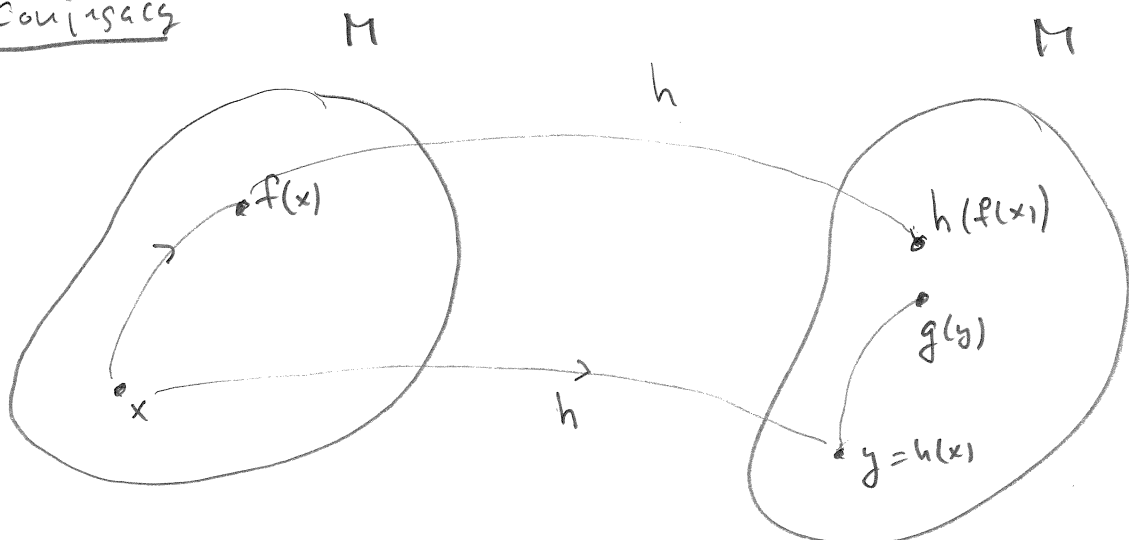
$f$  is a homeomorphism if it is a bijection and  $f$  and  $f^{-1}$  are  $C^0$ .

Ex Diffeomorphisms on the circle:

$R_\alpha: \theta \mapsto \theta + \alpha \pmod{1}$   
rotation with angle  $\alpha$



Conjugacy



Can it happen that  $g(h(x)) = h(f(x))$ ?

Def Two diffeomorphisms  $f, g: M \rightarrow M$  are topologically conjugate if there is a homeomorphism  $h: M \rightarrow M$  such that  $h \circ f = g \circ h$  for all  $x \in M$

For flows  $\Phi(t, x)$ :

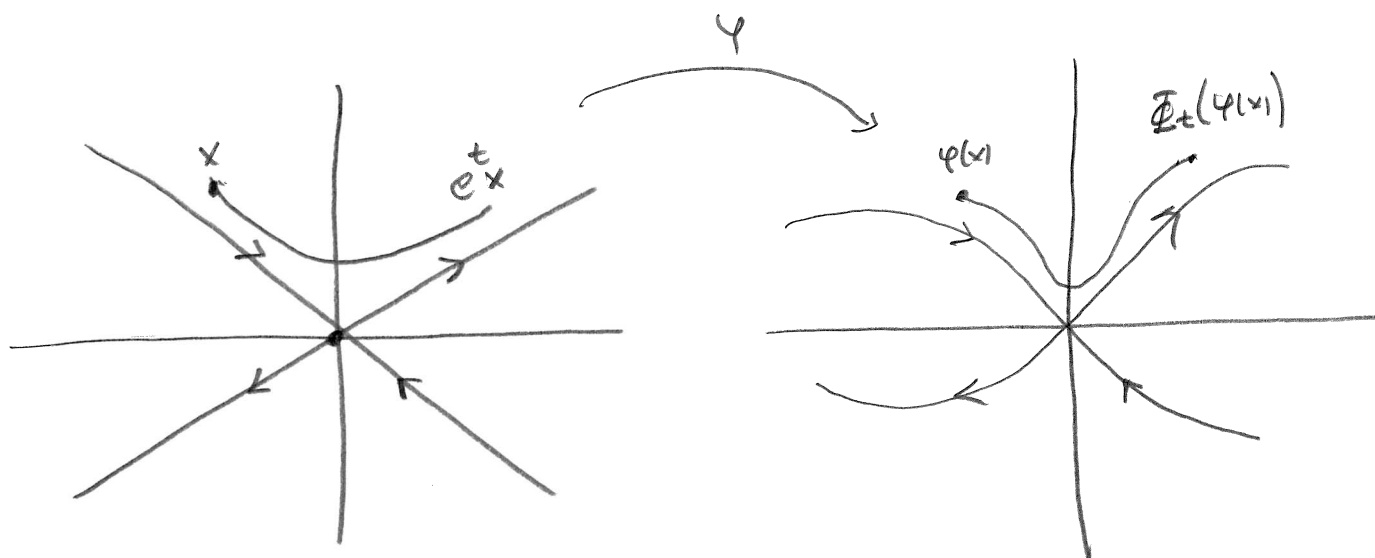
Def  $\Phi_t$  and  $\psi_t$  are topologically conjugate if there is  $h: M \rightarrow M$  such that  $h(\Phi_t(x)) = \psi_t(h(x))$  for all  $t$ .

Def The flows  $\Phi_t$  and  $\psi_t$  are topologically equivalent if there is a homeomorphism  $h: M \rightarrow M$  such that  $h$  maps orbits of  $\Phi_t$  into orbits of  $\psi_t$ .

| Which of these is a stronger statement? |

Theorem Assume  $f$  is  $C^1$ , and that  $f(0) = 0$  is a hyperbolic fixed point. Let  $\Phi(t, x)$  be the flow of  $\dot{x} = f(x)$  and let  $A = df(0)$  ( $= f'(0)$ ) (so that  $f(x) = Ax + g(x)$  with  $g(x) = o(|x|)$ ). There is a homeomorphism  $\varphi(x) = x + h(x)$  such that (locally)

$$\varphi \circ e^{tA} = \Phi_t \circ \varphi$$



Question Have we seen other examples of topologically conjugate flows?

The straightening of a vector field theorem.