

Ch 15. Decision theory and Bayesian inference

1. Minimax

Decision rule d

chooses an action $a = d(x)$

using uncertain measurement X with pmf/pdf $f(x|\theta)$
of unknown state of nature θ

Loss function $l(\theta, a)$ determines

risk function $R(\theta, d) = \text{E}(l(\theta, d(X))|\theta)$

Def 1: minimax decision

Minimax decision rule

find maximum risk $R_{\max}(d) = \max_{\theta} R(\theta, d)$ for all d
choose d minimizing $R_{\max}(d)$

Ex 1: steel section length

Two possible actions

steel section length $a = 40$ or $a = 50$ ft

Two possible states of nature

depth of a firm stratum $\theta = 40$ or $\theta = 50$ ft

Data $x = 45$ ft, uncertain measurement of θ

conditional pmf $f(x|\theta) = \text{P}(X = x|\theta)$

	$x = 40$	$x = 45$	$x = 50$	total
$\theta=40$	0.6	0.3	0.1	1
$\theta=50$	0.1	0.2	0.7	1

Four possible decision rules

	$x = 40$	$x = 45$	$x = 50$
$d_1(x)$	40	40	40
$d_2(x)$	40	40	50
$d_3(x)$	40	50	50
$d_4(x)$	50	50	50

Conditional distributions of $d_2(X)$ and $d_3(X)$

	$P_\theta(d_2 = 40)$	$P_\theta(d_2 = 50)$	$P_\theta(d_3 = 40)$	$P_\theta(d_3 = 50)$
$\theta=40$	0.9	0.1	0.6	0.4
$\theta=50$	0.3	0.7	0.1	0.9

Loss function $l(\theta, a)$

$$l(40, 40) = l(50, 50) = 0$$

$$l(40, 50) = \$100, l(50, 40) = \$400$$

Risk function

$$\text{expected loss } R(\theta, d) = \mathbb{E}(l(\theta, d(X)) | \theta)$$

	$d = d_1$	d_2	d_3	d_4
$\theta = 40$	0	10	40	100
$\theta = 50$	400	120	40	0
max risk $R_{\max}(d)$	400	120	40	100

Minimax decision d_3 with $R_{\max}(d_3) = 40$

$$\text{minimax action } d_3(45) = 50 \text{ ft}$$

2. Bayesian approach

parameter θ is treated as a random variable Θ

Def 2: prior and posterior distributions

Prior distribution $g(\theta) = P(\Theta = \theta)$

reflects our knowledge about θ before data are collected

Posterior distribution $h(\theta|x) = P(\Theta = \theta|X = x)$

our knowledge about θ updated by the collected data

$$\boxed{\text{Bayes formula } h(\theta|x) = \frac{1}{\phi(x)} f(x|\theta) g(\theta)}$$

Likelihood function $f(x|\theta) = P(X = x|\Theta = \theta)$

assigns weights on possible parameter values θ

judging from the observed data x

Joint distribution of (X, Θ)

$$f(x, \theta) = P(X = x, \Theta = \theta) = f(x|\theta)g(\theta)$$

Marginal distribution of X

$$\phi(x) = P(X = x) = \sum_{\theta} f(x, \theta) \text{ independent of } \theta$$

$$\boxed{\text{Posterior} = \text{const} \times \text{likelihood} \times \text{prior}}$$

Def 3: Bayes action

Bayes action is an action minimizing posterior risk

$$PR(a|x) = E(l(\Theta, a|X = x)) = \sum_{\theta} l(\theta, a)h(\theta|x)$$

= posterior mean loss caused by action a

Ex 1: steel section length

Given the prior probabilities $g(40) = 0.8$ and $g(50) = 0.2$

joint distribution

posterior distribution

$f(x, \theta)$	$x = 40$	45	50	$h(\theta x)$	$x = 40$	45	50
$\theta = 40$	0.48	0.24	0.08	$\theta = 40$	0.96	0.86	0.36
$\theta = 50$	0.02	0.04	0.14	$\theta = 50$	0.04	0.14	0.64
$\phi(x)$	0.50	0.28	0.22	Total	1.00	1.00	1.00

Posterior risk

$$PR(a|x) = l(40, a) \cdot h(40|x) + l(50, a) \cdot h(50|x)$$

	$a = 40$	$a = 50$	min PR	Bayes action
$x = 40$	16	96	16	$a = 40$
$x = 45$	56	86	56	$a = 40$
$x = 50$	256	36	36	$a = 50$

3. Conjugate priors

Data distribution	Prior	Posterior distribution
$X \sim N(\mu, \sigma^2)$	$\mu \sim N(\mu_0, \sigma_0^2)$	$N(c_1\mu_0 + (1 - c_1)x; c_1\sigma_0^2)$
$X \sim \text{Bin}(n, p)$	$p \sim B(a, b)$	$B(a+x, b+n-x)$
$Mn(n; p_1, \dots, p_r)$	$D(\alpha_1, \dots, \alpha_r)$	$D(\alpha_1 + x_1, \dots, \alpha_r + x_r)$
$X \sim \text{Pois}(\mu)$	$\mu \sim \Gamma(\alpha, \lambda)$	$\Gamma(\alpha + x, \lambda + 1)$
$X \sim \text{Exp}(\rho)$	$\rho \sim \Gamma(\alpha, \lambda)$	$\Gamma(\alpha + 1, \lambda + x)$

Def 4: conjugate prior

A parametric family of distributions G is called
a conjugate prior to a family of distributions H
if a G -prior and H -data give a G -posterior

Beta distribution $B(a, b)$

Continuous distribution over $[0, 1]$ interval

$$f(p) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} p^{a-1} (1-p)^{b-1}$$

$$\mu = \frac{a}{a+b}, \sigma^2 = \frac{\mu(1-\mu)}{a+b+1}, \text{ pseudocounts } a > 0, b > 0$$

Gamma function

$$\Gamma(\alpha) = \int_0^\infty x^{\alpha-1} e^{-x} dx, \text{ in particular } \Gamma(k) = (k-1)!$$

Dirichlet distribution $D(\alpha_1, \dots, \alpha_r)$

Joint pdf for (p_1, \dots, p_r) such that $p_1 + \dots + p_r = 1$

$$f(p_1, \dots, p_r) = \frac{\Gamma(\alpha_0)}{\Gamma(\alpha_1) \dots \Gamma(\alpha_r)} p_1^{\alpha_1-1} \dots p_r^{\alpha_r-1}$$

positive pseudocounts: $\alpha_1, \dots, \alpha_r$, $\alpha_0 = \alpha_1 + \dots + \alpha_r$

marginal distributions $p_j \sim \text{Beta}(\alpha_j, \alpha_0 - \alpha_j)$

Gamma distribution $\Gamma(\alpha, \lambda)$

Continuous distribution over $[0, \infty)$ interval

$$f(x) = \frac{1}{\Gamma(\alpha)} \lambda^\alpha x^{\alpha-1} e^{-\lambda x}, \mu = \frac{\alpha}{\lambda}, \sigma^2 = \frac{\alpha}{\lambda^2}$$

Two positive parameters

the shape parameter α and the scale parameter λ

Ex 2: IQ measurement

IQ distribution of a person $X \sim N(\theta, 100)$

prior distr $\theta \in N(100, 225)$, population as a whole

If observed IQ is $x = 130$, then

posterior distribution $\theta \sim N(120.7, 69.2)$

4. Bayesian updating

Normal/normal model n observations

$$\begin{aligned} (\mu_0, \sigma_0^2) &\xrightarrow{x_1} (c_1\mu_0 + (1 - c_1)x_1; c_1\sigma_0^2) \xrightarrow{x_2} \dots \\ &\xrightarrow{x_n} (c_n\mu_0 + (1 - c_n)\bar{x}; c_n\sigma_0^2) \end{aligned}$$

shrinkage factor $c_n = \frac{\sigma^2}{\sigma^2 + n\sigma_0^2} \rightarrow 0$ as $n \rightarrow \infty$

Ex 3: thumbtack experiment

Beta/binomial model

number of base landings $X \sim \text{Bin}(n, p)$

n tossings, $p = \text{P}(\text{landing on base})$

My personal Beta prior $p \sim \text{B}(a_0, b_0)$

$\mu_0 \approx 0.4, \sigma_0 \approx 0.1 \Rightarrow$ pseudocounts $a_0 = 10, b_0 = 15$

Experiment 1: $n_1 = 10$ tosses

counts $x_1 = 2, n_1 - x_1 = 8$, posterior distr $\text{B}(12, 23)$

PME $\hat{p} = \frac{12}{35} = 0.34, \sigma_1 = 0.08$

Experiment 2: $n_2 = 40$ tosses

counts $x_2 = 9, n_2 - x_2 = 31$, posterior distr $\text{B}(21, 54)$

PME $\hat{p} = \frac{21}{75} = 0.28, \sigma_2 = 0.05$

5. Bayesian estimation

Action $a = \{\text{assign value } a \text{ to unknown parameter } \theta\}$

optimal action depends on the choice of loss function

Def 5: MAP

MAP (maximum a posteriori probability) estimate $\hat{\theta}_{\text{map}}$
maximizes the posterior pdf $h(\theta|x)$

MAP answers to the 0-1 loss function: $l(\theta, a) = 1_{\{a=\theta\}}$
and minimizes misclassification probability

$$PR(a|x) = \sum_{\theta} h(\theta|x) = 1 - h(a|x)$$

If noninformative prior $g(\theta) = \text{const}$, then

$$h(\theta|x) = \text{const} \times f(x|\theta) \text{ and } \hat{\theta}_{\text{map}} = \hat{\theta}_{\text{mle}}$$

Def 6: PME

posterior mean estimate $\hat{\theta}_{\text{pme}} = E(\Theta|X=x)$

PME answers to the squared error loss: $l(\theta, a) = (\theta - a)^2$

$$PR(a|x) = E((\Theta - a)^2|x) = \text{Var}(\Theta|x) + [E(\Theta|x) - a]^2$$

Ex 4: loaded die experiment

a die is rolled 18 times: 211 453 324 142 343 515

The usual

MLE = sample proportions $(\frac{4}{18}, \frac{3}{18}, \frac{4}{18}, \frac{4}{18}, \frac{3}{18}, 0)$

is not good, since it assigns zero probability to side 6

Noninformative prior distribution $D(1,1,1,1,1,1)$

MAP = MLE

PME = $(\frac{5}{24}, \frac{4}{24}, \frac{5}{24}, \frac{5}{24}, \frac{4}{18}, \frac{1}{24})$

6. Interval estimation

Confidence interval

θ is an unknown constant and a CI is random

$$P(\theta_0(X) < \theta < \theta_1(X)) = 1 - \alpha$$

Def 7: credibility interval

CrI is such a nonrandom interval $(\theta_0(x), \theta_1(x))$ that

$$P(\theta_0(x) < \Theta < \theta_1(x) | X = x) = 1 - \alpha$$

Ex 2: IQ measurement

$n = 1$, standard error $\sigma_{\bar{X}} = 10$

exact 95% CI for θ is $130 \pm 1.96 \cdot 10 = 130 \pm 19.6$

Posterior distribution $N(120.7; 69.2)$

95% CrI for θ is $120.7 \pm 1.96 \cdot \sqrt{69.2} = 120.7 \pm 16.3$

7. Hypotheses testing

Choose between $H_0: \theta = \theta_0$ and $H_1: \theta = \theta_1$

given prior probabilities $P(H_0) = \pi_0$, $P(H_1) = \pi_1$
and the likelihoods $f(x|\theta_0)$, $f(x|\theta_1)$

Cost function

l_I = error type I cost, l_{II} = error type II cost

Rejection region minimizing the average cost

$$\boxed{\text{RR} = \{x: l_I \pi_0 f(x|\theta_0) < l_{II} \pi_1 f(x|\theta_1)\}}$$

Reject H_0 if small likelihood ratio $\frac{f(x|\theta_0)}{f(x|\theta_1)} < \frac{l_{II}\pi_1}{l_I\pi_0}$

or small posterior odds $\frac{h(\theta_0|x)}{h(\theta_1|x)} < \frac{l_{II}}{l_I}$

Ex 5: a rape case study

<http://www.law.umich.edu/thayer/redmay.htm>

The defendant A, age 37, local, is charged with rape

H_0 : A is innocent, H_1 : A is guilty

error type I: a nonguilty is convicted

error type II: a guilty is unpunished

Evidence

E_1 : DNA match, $P(E_1|H_0) = \frac{1}{200,000,000}$, $P(E_1|H_1)=1$

E_2 : A is not recognized by the victim

E_3 : alibi supported by the girlfriend

Assumptions

prior probability $P(H_1) = \frac{1}{200,000}$

$P(E_2|H_1) = 0.1$, $P(E_2|H_0) = 0.9$

$P(E_3|H_1) = 0.25$, $P(E_3|H_0) = 0.5$

Posterior probabilities

$$P(H_1|E_1) = \frac{P(E_1|H_1)P(H_1)}{P(E_1|H_1)P(H_1)+P(E_1|H_0)P(H_0)} = \frac{1000}{1001}$$

$$P(H_1|E_1, E_2) = \frac{P(E_2|H_1)P(H_1|E_1)}{P(E_2|H_1)P(H_1|E_1)+P(E_2|H_0)P(H_0|E_1)} = \frac{1000}{1009}$$

$$P(H_1|E_1, E_2, E_3) = \frac{P(E_3|H_1)P(H_1|E_1, E_2)}{P(E_3|H_1)P(H_1|E_1, E_2)+P(E_3|H_0)P(H_0|E_1, E_2)} = \frac{1000}{1018}$$

Posterior odds

$$\frac{P(H_0|E_1, E_2, E_3)}{P(H_1|E_1, E_2, E_3)} = \frac{18}{1000} = 0.018, \text{ reject } H_0 \text{ if } \frac{l_{II}}{l_I} > 0.018$$

Is it better for fifty guilty people to go unpunished than for one nonguilty man to be convicted?
--