

# Analysis of multiscale methods

Axel Målqvist   Daniel Peterseim

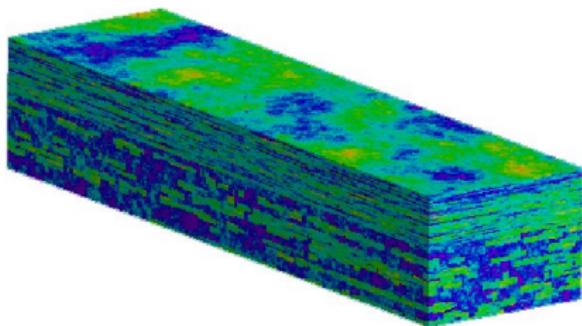
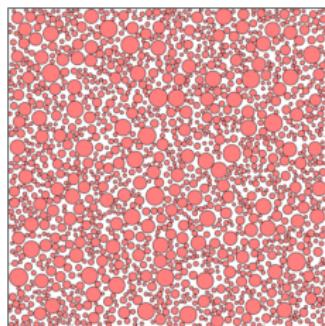
Uppsala University

Humboldt Universität

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# Multiscale problems

Applications such as



- ▷ composite materials      ▷ flow in a porous medium

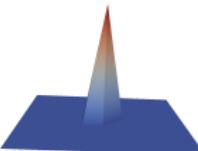
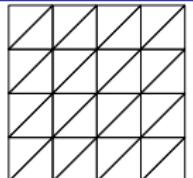
require numerical solution of partial differential equations with rough data (module of elasticity, conductivity, or permeability).

Major challenge: Features on multiple non-separated scales.

# Finite elements (FE) – methodology

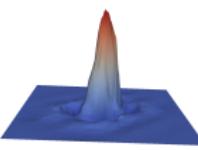
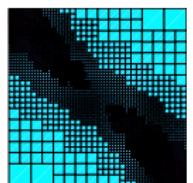
The numerical solution of PDEs by FEM consists of

- construction of an “appropriate” FE mesh
- choosing (local) basis functions (of variable degree of approximation)



An optimal construction should be adapted to the local behavior of the exact solution and, hence, should take into account

- local singularities of the solution  
(e.g. singularities at re-entrant corners)
- effects of singular perturbations in the solutions  
(e.g. boundary layers)
- scales and amplitudes of rough coefficients



# Outline

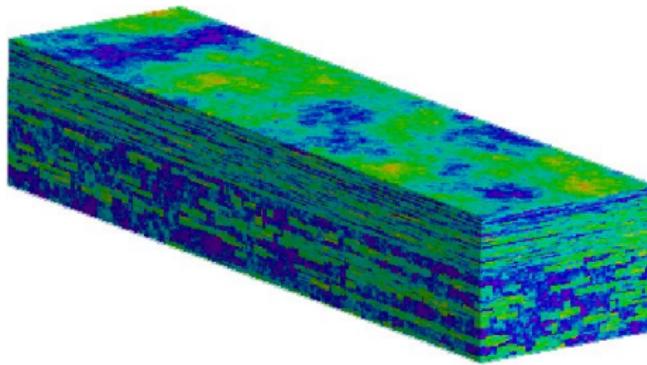
- ① **Setting and Motivation**
- ② Multiscale Method and Convergence
- ③ Full Discretization and Numerical Experiments
- ④ Application to Other Problems
- ⑤ Conclusion

# Model multiscale problem

Poisson's equation

$$-\nabla \cdot A \nabla u = f \quad \text{in } \Omega \quad u = 0 \quad \text{on } \partial\Omega$$

with data  $f \in L^2(\Omega)$  and  $0 < \alpha \leq A \in L^\infty(\Omega)$

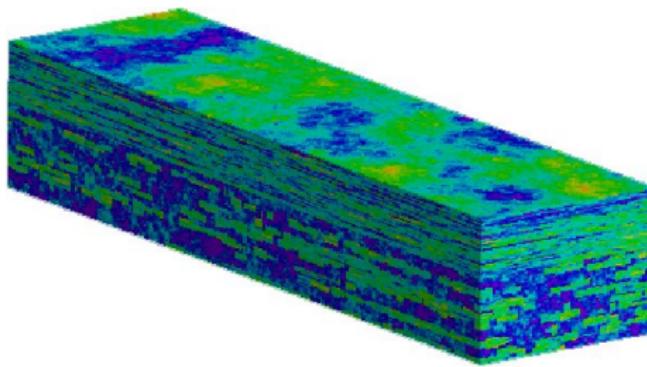


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Poisson's equation (variational form):  $u \in V := H_0^1(\Omega)$  s.t.

$$a(u, v) := \int_{\Omega} (\textcolor{brown}{A} \nabla u) \cdot \nabla v \, dx = \int_{\Omega} f \cdot v \, dx =: F(v) \text{ for all } v \in V$$

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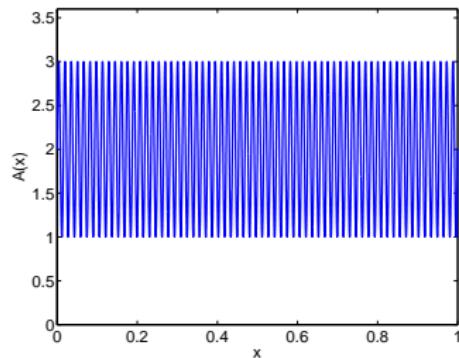
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**Example** (periodic coefficient):  $A(x) = 2 + \sin(2\pi x/\varepsilon)$ ,  $\varepsilon = 2^{-6}$ ,  $f = 1$



oscillatory coefficient

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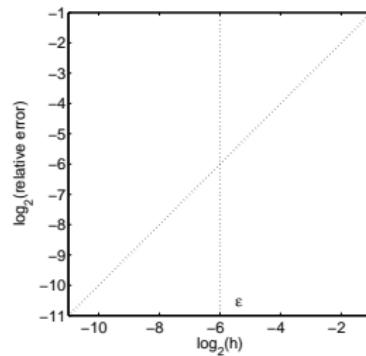
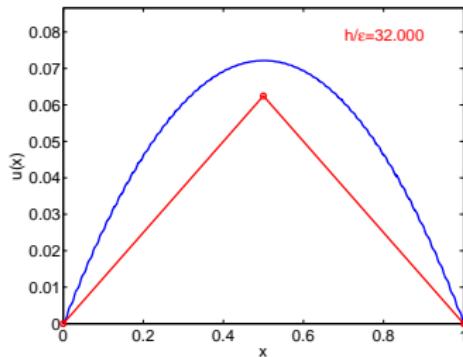
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solution and P1-FEM-approximation

$\log_2(H^1(\Omega) - \text{error})$  vs.  $\log_2(h)$

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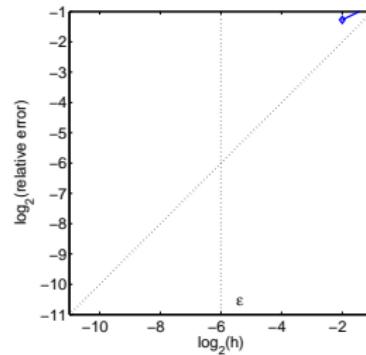
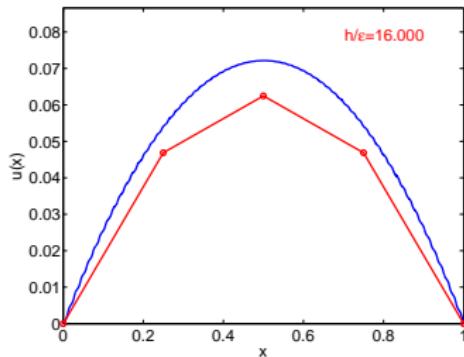
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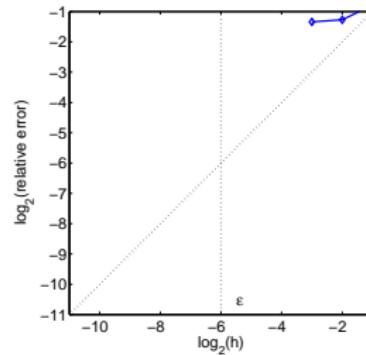
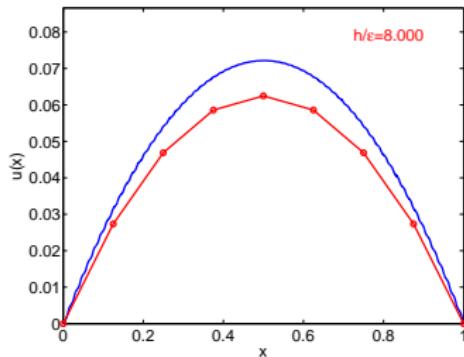
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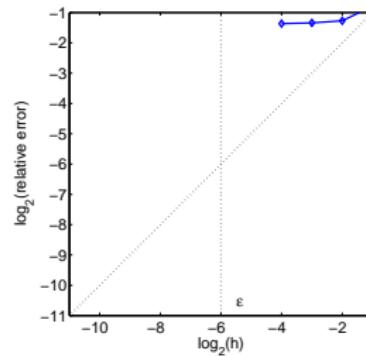
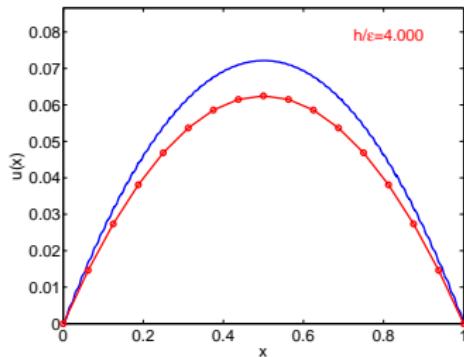
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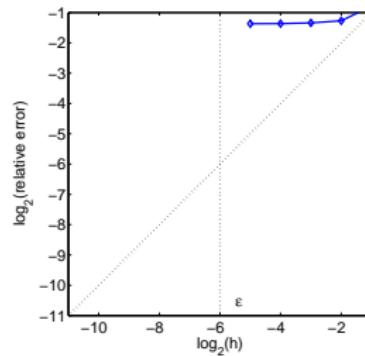
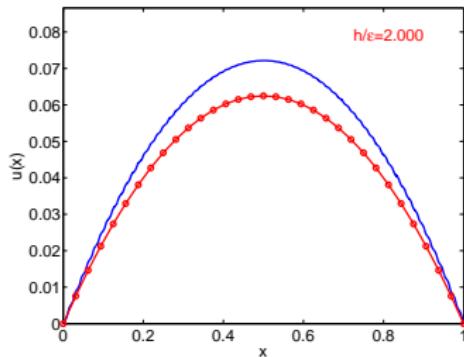
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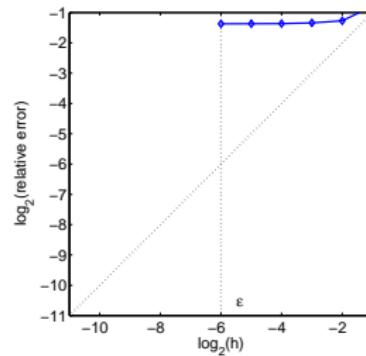
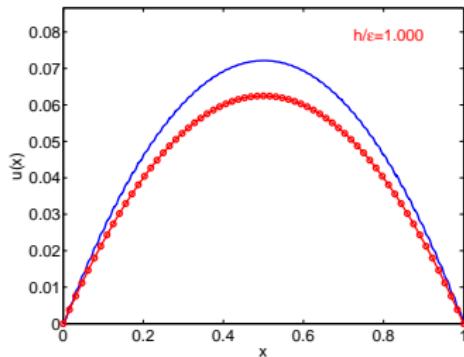
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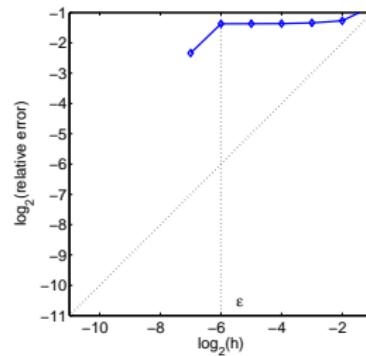
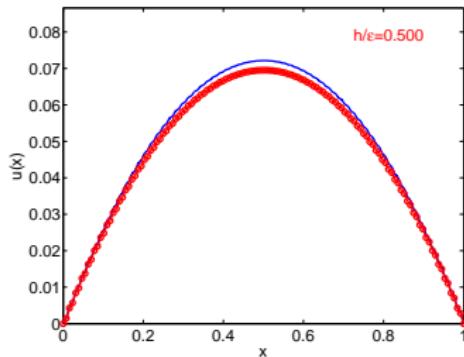
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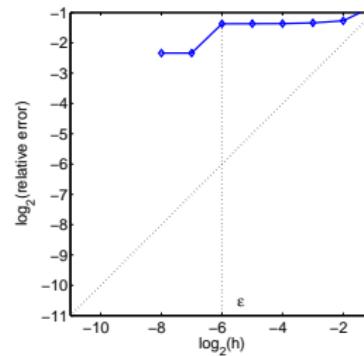
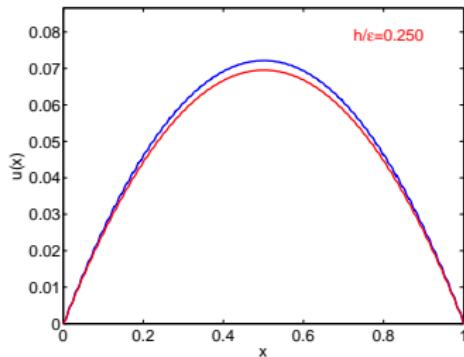
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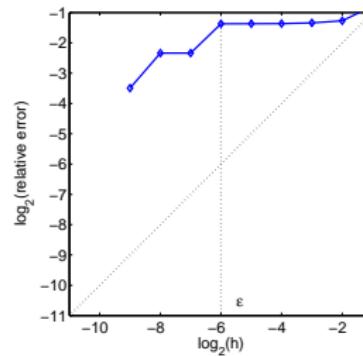
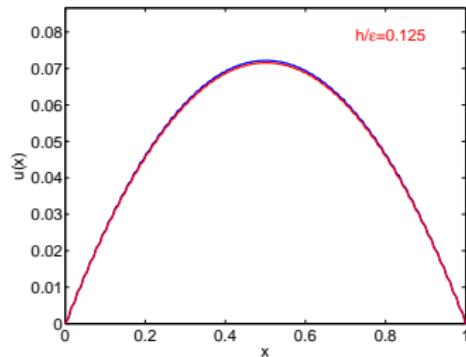
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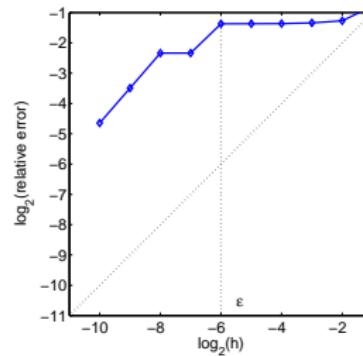
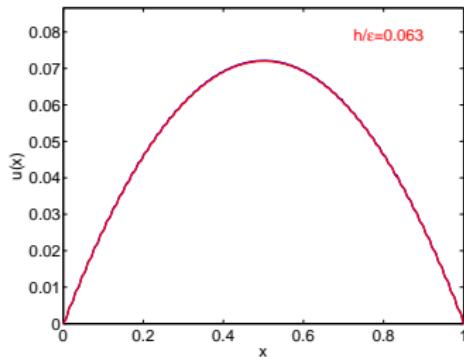
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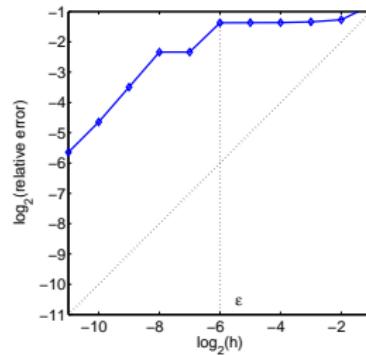
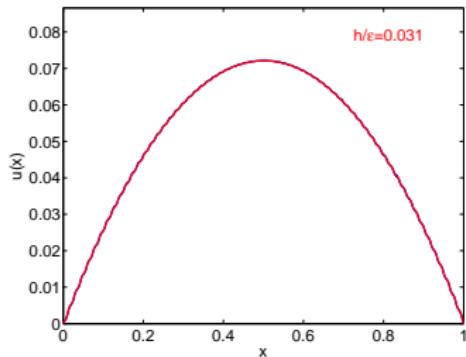
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## Examples (periodic coefficients)

- We have  $\|u - u_h\| := \|A^{1/2} \nabla(u - u_h)\| \leq C(A, f)h = C'(f) \frac{h}{\epsilon}$ .
- We need to resolve the fine scale features even to get the coarse scale behavior right.

# Model multiscale problem

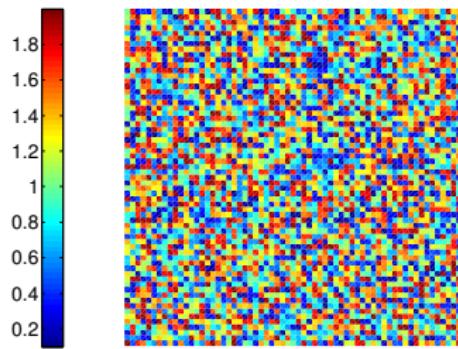
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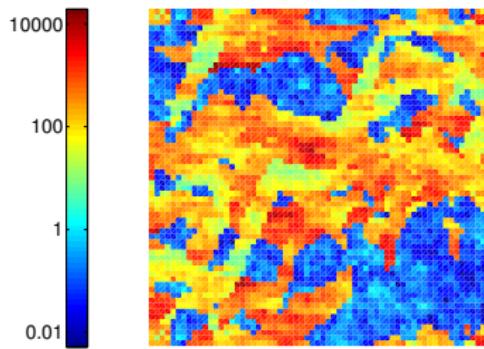
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## Examples (rough coefficients)



random material (academic)



porous medium (SPE10 benchmark)

# Objectives

Without any assumptions on scales ...

- Construction of an upscaled variational problem based on a generalized FEM (coarse mesh  $\mathcal{T}$  of size  $H$  & modified nodal basis functions)
- Computation of basis functions involves solution of PDE only on local patches of coarse elements with  $\text{diam} \approx H \log(1/H)$
- Error estimate

$$\|u - u_H^{\text{ms}}\| := \|A^{1/2} \nabla(u - u_H^{\text{ms}})\| \leq C(f)H$$

with  $C(f)$  independent of scales of  $A$



A. Målqvist and D. Peterseim.

Localization of Elliptic Multiscale Problems.

ArXiv e-prints, Oct. 2011.

# Some known methods

- Upscaling techniques: Durlofsky et al. 98, Iliev et al. 08
- Variational multiscale method: Hughes et al. 95, Arbogast 04, Larson-Målqvist 05, Nolen et al. 08
- Multiscale FEM: Hou-Wu 96, Efendiev-Ginting 04, Aarnes-Lie 06
- Residual free bubbles: Brezzi et al. 98
- Multiscale finite volume method: Jenny et al. 03
- Heterogeneous multiscale method: Engquist-E 03, E-Ming-Zhang 04, Ohlberger 05
- Equation free: Kevrekidis et al. 05
- Metric based upscaling: Owhadi et al. 06
- ...

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## Common idea

Local approximations (in parallel) on a fine scale are used to modify a coarse scale space or equation

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## Remark

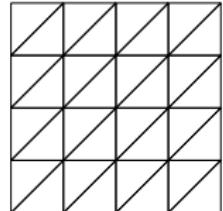
Error analysis rely on strong assumptions such as scale separation and periodicity

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# Multiscale decomposition

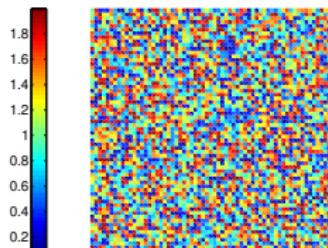
- (coarse) FE mesh  $\mathcal{T}$  with parameter  $H$
- P1-FE space  $V_H := \{v \in V \mid \forall T \in \mathcal{T}, v|_T \in P_1(T)\}$
- $\mathfrak{I}_{\mathcal{T}} : V \rightarrow V_H$  quasi-interpolation operator



## Decomposition

$$V = V_H \oplus V^f \quad \text{with } V^f := \text{kernel } \mathfrak{I}_{\mathcal{T}} = \{v \in V \mid \mathfrak{I}_{\mathcal{T}} v = 0\}$$

Example:



rough coefficient

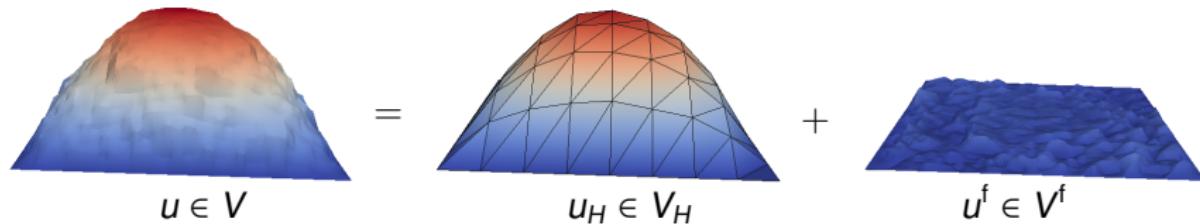
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Example:



# Orthogonalization

- For each  $v \in V_H$  define finescale projection  $\mathfrak{F}v \in V^f$  by

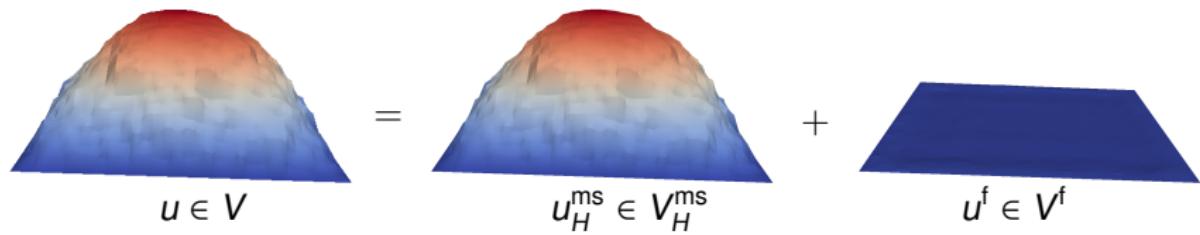
$$a(\mathfrak{F}v, w) = a(v, w) \quad \text{for all } w \in V^f$$

## Orthogonal Decomposition

$$V = V_H^{\text{ms}} \oplus V^f \quad \text{with } V_H^{\text{ms}} := (V_H - \mathfrak{F}V_H)$$

---

Example:



# Error analysis

## Lemma

$$|||u - u_H^{\text{ms}}||| \leq C_{\text{ol}} C_{\mathfrak{I}_{\mathcal{T}}} \alpha^{-1/2} \|Hf\|_{L^2(\Omega)}$$

*Sketch of proof:*

- recall  $\|v - \mathfrak{I}_{\mathcal{T}}v\|_{L^2(T)} \leq C_{\mathfrak{I}_{\mathcal{T}}} H \|\nabla v\|_{L^2(\omega_T)}$  with  
 $\omega_T := \cup\{K \in \mathcal{T} \mid T \cap K \neq \emptyset\}$  [Carstensen/Verfürth '99]
- orthogonal decomposition yields  $u^f := u - u_H^{\text{ms}} \in V^f$
- $\mathfrak{I}_{\mathcal{T}}u^f = 0$ , interpolation error estimate, and finite overlap of the patches  $\omega_T$  conclude the proof

$$|||u^f|||^2 = a(\underbrace{u^f + u_H^{\text{ms}}}_{=u}, u^f) = F(u^f) = F(u^f - \mathfrak{I}_{\mathcal{T}}u^f)$$

$$\leq \sum_{T \in \mathcal{T}} \|f\|_{L^2(T)} \|u^f - \mathfrak{I}_{\mathcal{T}}u^f\|_{L^2(T)} \leq C_{\text{ol}} C_{\mathfrak{I}_{\mathcal{T}}} \alpha^{-1/2} \|Hf\|_{L^2(\Omega)} |||u^f||| \quad \square$$

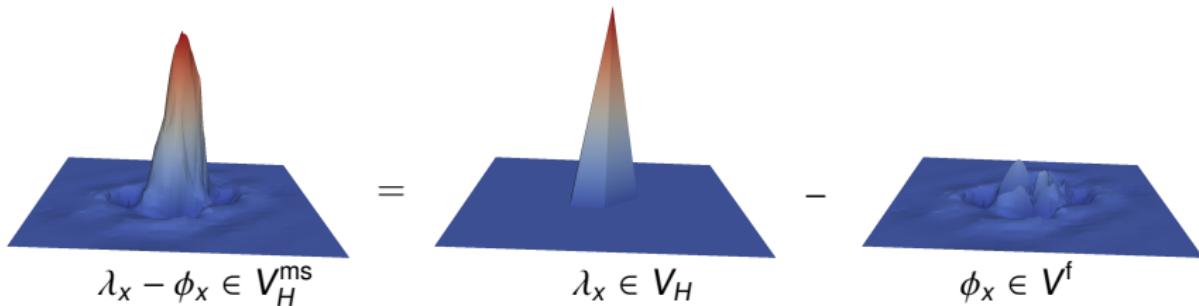
# Modified nodal basis

- $\mathcal{N}$  denotes set of interior vertices of  $\mathcal{T}$
- $\lambda_x \in V_H$  denotes classical nodal basis function ( $x \in \mathcal{N}$ )
- $\phi_x = \mathfrak{F}\lambda_x \in V^f$  denotes finescale correction of  $\lambda_x$  ( $x \in \mathcal{N}$ )

Ideal multiscale FE space

$$V_H^{\text{ms}} = \text{span} \{ \lambda_x - \phi_x \mid x \in \mathcal{N} \}$$

Example



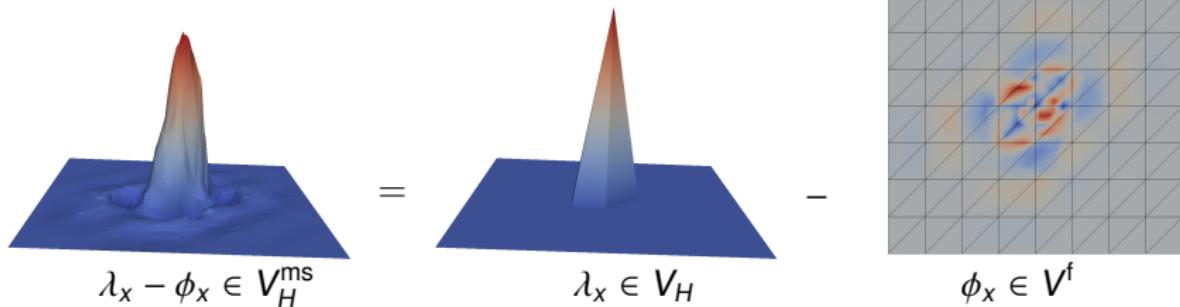
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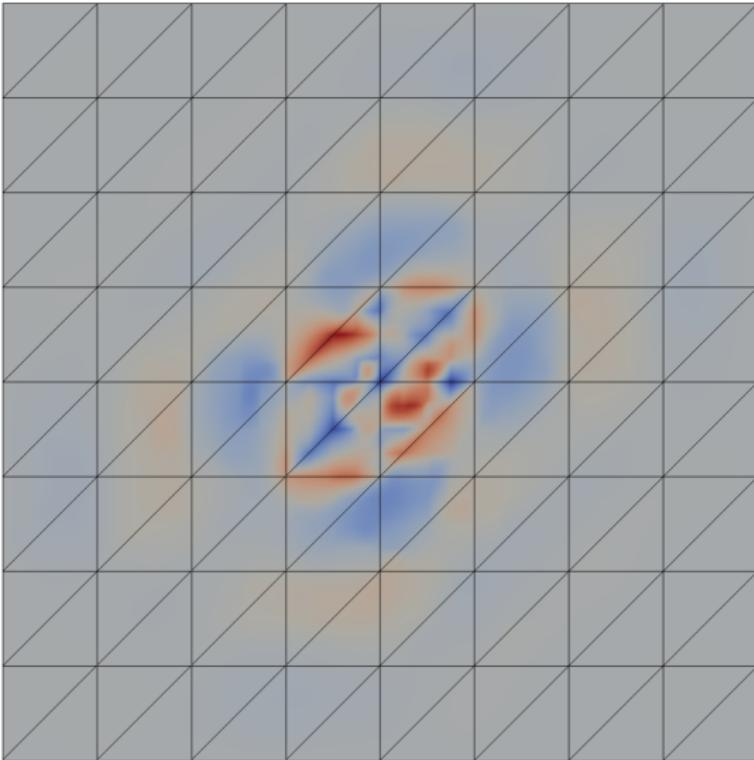
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Example



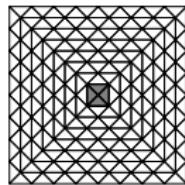
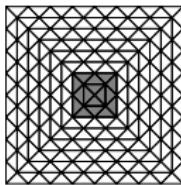
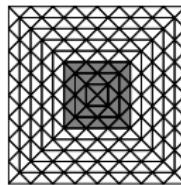
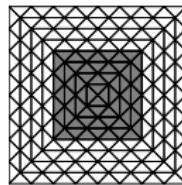
# Modified nodal basis



Assuming more regularity on  $A$  we have  $\lambda_x - \phi_x \in H^2(\Omega) \cap H_0^1(\Omega)$ .

# Localization

- Define nodal patches of  $k$ -th order  $\omega_{x,k}$  about  $x \in \mathcal{N}$

 $\omega_{x,1}$  $\omega_{x,2}$  $\omega_{x,3}$  $\omega_{x,4}$ 

- Localized corrections  $\phi_{x,k} \in V^f(\omega_{x,k}) := \{v \in V^f \mid v|_{\Omega \setminus \omega_{x,k}} = 0\}$  solve

$$a(\phi_{x,k}, w) = a(\lambda_x, w) \quad \text{for all } w \in V^f(\omega_{x,k})$$

## Localized multiscale FE spaces

$$V_{H,k}^{\text{ms}} = \text{span}\{\lambda_x - \phi_{x,k} \mid x \in \mathcal{N}\}$$

# The multiscale method

Multiscale approximation seeks  $u_{H,k}^{\text{ms}} \in V_{H,k}^{\text{ms}}$  such that

$$a(u_{H,k}^{\text{ms}}, v) = F(v) \quad \text{for all } v \in V_{H,k}^{\text{ms}}$$

---

## Remarks:

- $\dim V_{H,k}^{\text{ms}} = |\mathcal{N}| = \dim V_H$
- basis functions of the multiscale method have local support and are totally independent
- overlap of the supports is proportional to the parameter  $k$
- error analysis suggests  $k \approx \log \frac{1}{H}$
- method can take advantage of periodicity

# Error Analysis

## Lemma (Truncation error)

There exist  $C_1 < \infty$  and  $\gamma < 1$  independent of  $x, k, H$  such that

$$\|\phi_x - \phi_{x,k}\| \leq C_1 \gamma^k \|\phi_x\|.$$

Sketch of proof:

- Let  $\zeta_{k,\ell} = \begin{cases} 0, & \text{in } \omega_{x,k-\ell} \\ 1, & \text{in } \Omega \setminus \omega_{x,k} \end{cases}$  be a cut off function.
- Since  $(1 - \zeta_{k,1})\phi_x \in V^t(\omega_k)$  we have
$$\|\phi_x - \phi_{x,k}\| \lesssim \|\phi_x - (1 - \zeta_{k,1})\phi_x\| \lesssim \|\zeta_{k,1}\|_{L^\infty(\Omega)} \|\phi_x\|_{\Omega \setminus \omega_{x,k-1}} + \|\nabla \zeta_{x,k}\|_{L^\infty(\Omega)} \|\phi_x - \mathfrak{I}_T \phi_x\|_{L^2(\Omega \setminus \omega_{x,k-1})} \lesssim \|\phi_x\|_{\Omega \setminus \omega_{x,k-1}}.$$
- We have  $\|\phi_x\|_{\Omega \setminus \omega_{x,k}}^2 \leq (A \zeta_{k,\ell}^2 \nabla \phi_x, \nabla \phi_x) = (\mathbf{A} \nabla \phi_x, \nabla (\zeta_{k,\ell}^2 \phi_x)) - 2(A \zeta_{k,\ell} (\phi_x - \mathfrak{I}_T \phi_x) \nabla \zeta_{k,\ell}, \nabla \phi_x) \lesssim \ell^{-1} \|\phi_x\|_{\Omega \setminus \omega_{x,k-\ell}}^2.$
- Repeat  $\|\phi_x\|_{\Omega \setminus \omega_{x,k-\ell}}^2 \lesssim (C_2/\ell)^k \|\phi_x\|^2 := \gamma^k \|\phi_x\|^2$ , where  $C_2$  depends on the contrast in  $A$ .

# Error Analysis

## Theorem (Main result)

$$\|u - u_{H,k}^{\text{ms}}\| \leq C_2 \left( k^d \|H^{-1}\|_{L^\infty(\Omega)} \gamma^k \|f\|_{L^2(\Omega)} + \|\mathbf{H}f\|_{L^2(\Omega)} \right)$$

holds with a constant  $C_2$  that does not depend on  $H$ ,  $k$ ,  $f$ , or  $u$ .

Sketch of proof:

- Let  $\tilde{u}_{H,k}^{\text{ms}} = \sum_{x \in N} u_H^{\text{ms}}(x)(\lambda_x - \phi_{x,k})$  and note  $\|u - u_{H,k}^{\text{ms}}\|^2 \leq \|u - \tilde{u}_{H,k}^{\text{ms}}\|^2$  since  $u_{H,k}^{\text{ms}}$  is a projection.
- We split the error  $u - \tilde{u}_{H,k}^{\text{ms}} = (u - u_H^{\text{ms}}) + (u_H^{\text{ms}} - \tilde{u}_{H,k}^{\text{ms}})$  and note  $\|u - u_H^{\text{ms}}\| \lesssim \|\mathbf{H}f\|_{L^2(\Omega)}$  using previous Lemma.
- Finally  $\|u_H^{\text{ms}} - \tilde{u}_{H,k}^{\text{ms}}\|^2 \lesssim \sum_{x \in N} u_H^{\text{ms}}(x)^2 \|\phi_x - \phi_{x,k}\|^2 \lesssim \sum_{x \in N} u_H^{\text{ms}}(x)^2 \gamma^{2k} \|\phi_x\|^2 \lesssim k^{2d} \|H^{-1}\|_{L^\infty(\Omega)}^2 \gamma^{2k} \|f\|_{L^2(\Omega)}^2$ .

# Error Analysis

## Theorem (Main result)

$$\|u - u_{H,k}^{\text{ms}}\| \leq C_2 \left( k^d \|H^{-1}\|_{L^\infty(\Omega)} \gamma^k \|f\|_{L^2(\Omega)} + \|\mathbf{H}f\|_{L^2(\Omega)} \right)$$

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- Finally  $\|u_H^{\text{ms}} - \tilde{u}_{H,k}^{\text{ms}}\|^2 \lesssim \sum_{x \in N} u_H^{\text{ms}}(x)^2 \|\phi_x - \phi_{x,k}\|^2 \lesssim \sum_{x \in N} u_H^{\text{ms}}(x)^2 \gamma^{2k} \|\phi_x\|^2 \lesssim k^{2d} \|H^{-1}\|_{L^\infty(\Omega)}^2 \gamma^{2k} \|f\|_{L^2(\Omega)}^2$ .

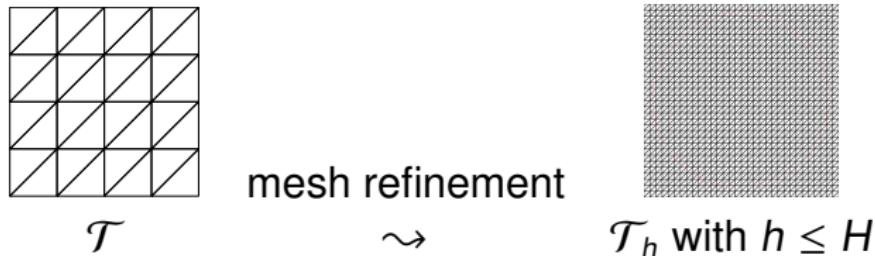
Theorem holds without any assumptions on scales or regularity!

# Outline

- ① Setting and Motivation
- ② Multiscale Method and Convergence
- ③ **Full Discretization and Numerical Experiments**
- ④ Application to Other Problems
- ⑤ Conclusion

# Full discretization

- Finescale mesh



- Reference FE space

$$V_h := \{v \in V \mid \forall T \in \mathcal{T}(\Omega), v|_T \in P_1(T)\}$$

- Reference FE solution  $u_h \in V_h$  solves

$$a(u_h, v) = F(v) \quad \text{for all } v \in V_h$$

- Fully discrete corrections  $\phi_{x,k}^h \in V_h^f(\omega_{x,k}) := V^f(\omega_{x,k}) \cap V_h$  satisfy

$$a(\phi_{x,k}^h, w) = a(\lambda_x, w) \quad \text{for all } w \in V_h^f(\omega_{x,k})$$

# Full discretization

## Fully discrete multiscale FE spaces

$$V_{H,k}^{\text{ms},h} = \text{span}\{\lambda_x - \phi_{x,k}^h \mid x \in \mathcal{N}\}$$

Fully discrete multiscale approximation  $u_{H,k}^{\text{ms},h} \in V_{H,k}^{\text{ms},h}$  satisfies

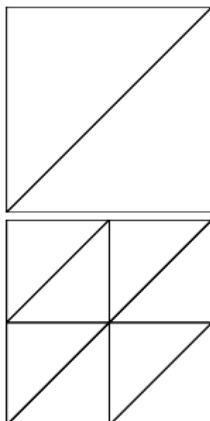
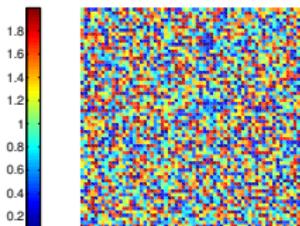
$$a(u_{H,k}^{\text{ms},h}, v) = F(v) \quad \text{for all } v \in V_{H,k}^{\text{ms},h}$$

## Theorem (Error estimate)

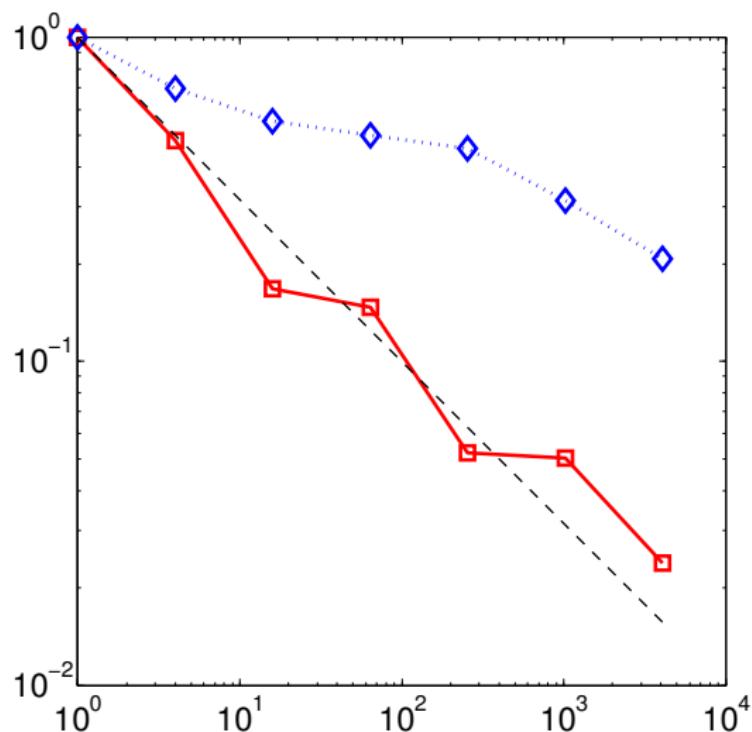
$$\|u - u_{H,k}^{\text{ms},h}\| \leq C_3 \left( \|u - u_h\| + k^d \|H^{-1}\|_{L^\infty(\Omega)} \gamma^k \|f\|_{L^2(\Omega)} + \|Hf\|_{L^2(\Omega)} \right)$$

holds with a constant  $C_3$  that does not depend on  $H$ ,  $h$ ,  $k$ ,  $f$ , or  $u$ .

# Numerical experiment I

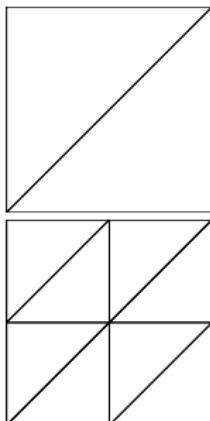
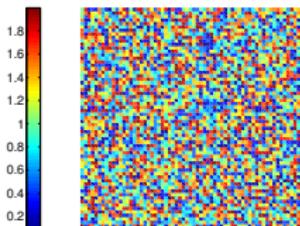


$$H = 2^{-1}, 2^{-2}, \dots, 2^{-7}$$
$$h = 2^{-9}, k = \log(1/H)$$

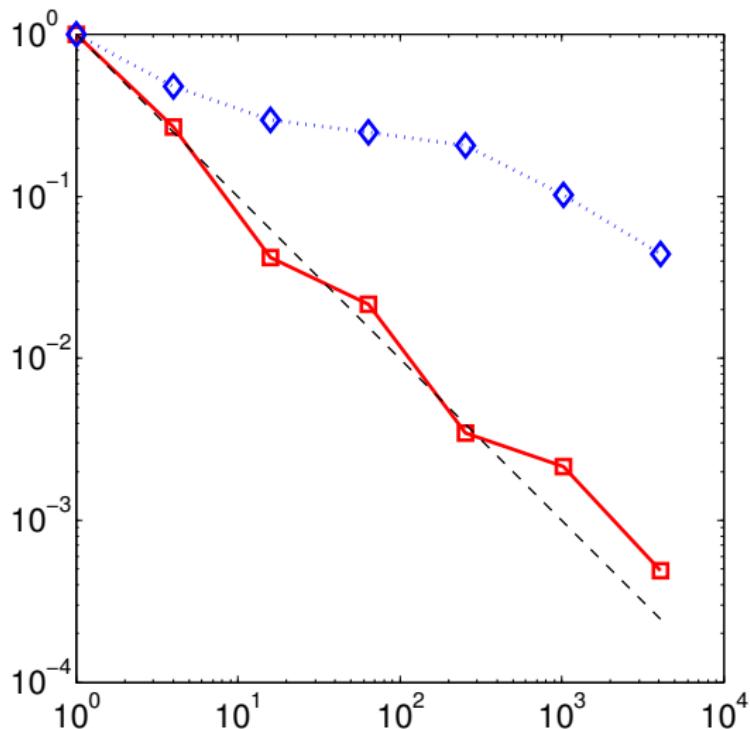


$\|u_h - u_{H,k}^{\text{ms},h}\|$  vs. #dof

# Numerical experiment I

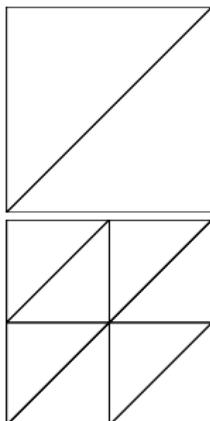
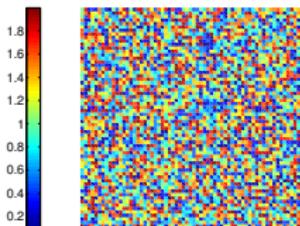


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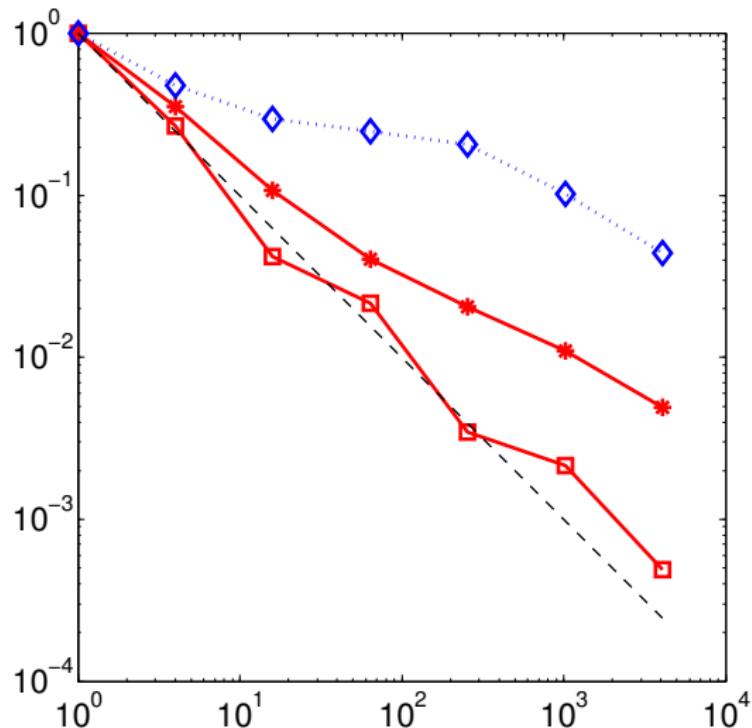


$\|u_h - u_{H,k}^{ms,h}\|$  vs. #dof

# Numerical experiment I

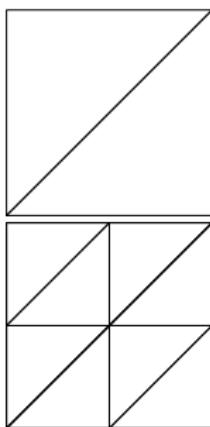
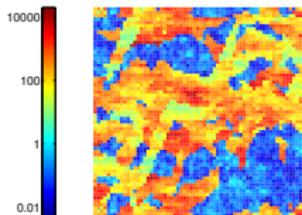


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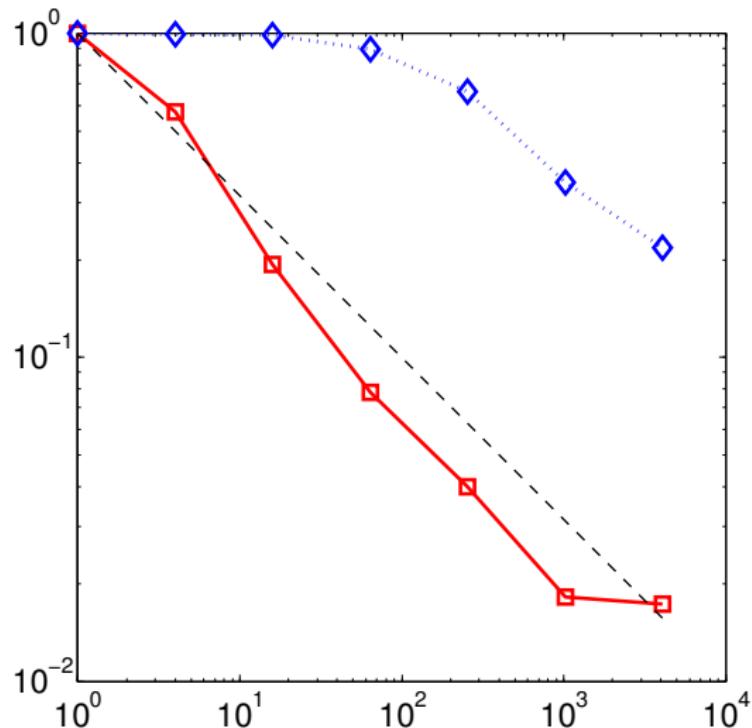
$\|u_h - \mathfrak{I}_\mathcal{T} u_{H,k}^{ms,h}\|$  vs. #dof

# Numerical experiment II



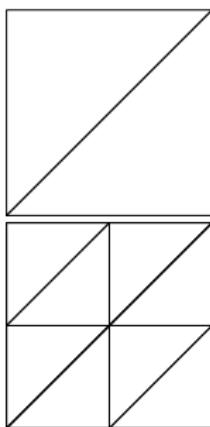
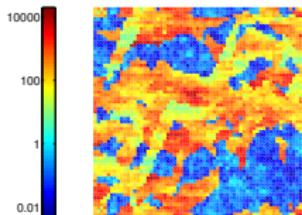
$$H = 2^{-1}, 2^{-2}, \dots, 2^{-7}$$

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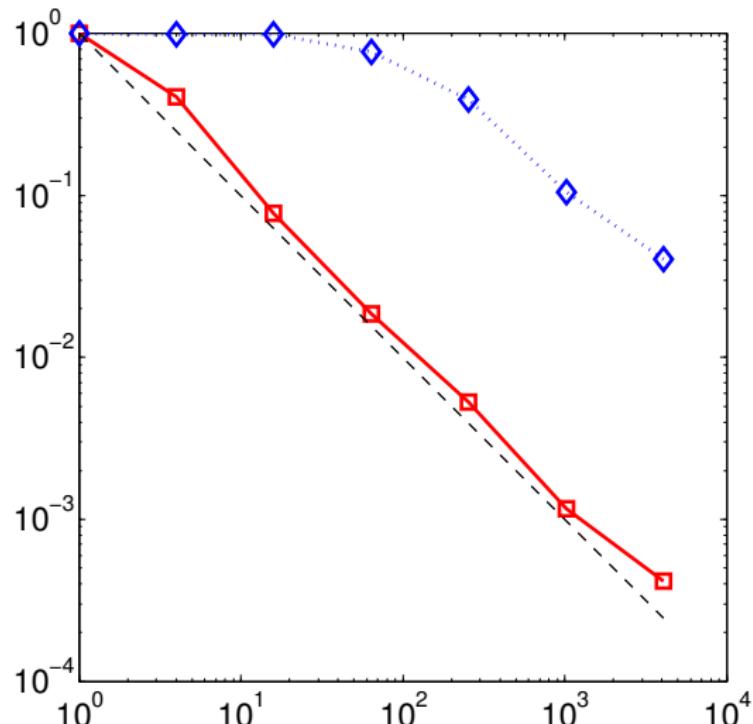
$\|u_h - u_{H,k}^{\text{ms},h}\|$  vs. #dof

# Numerical experiment II



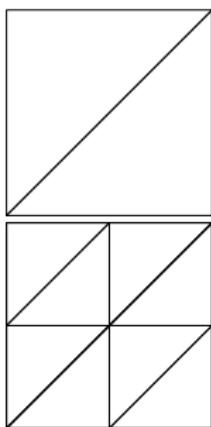
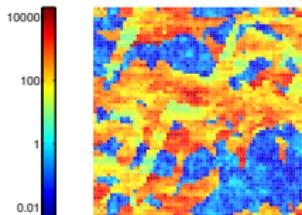
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$$h = 2^{-9}, k = \log(1/H)$$



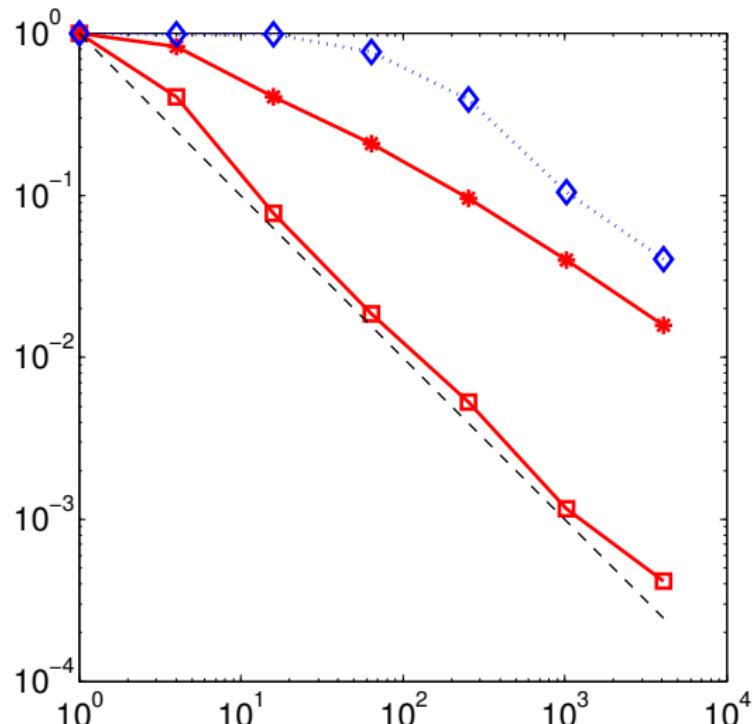
$\|u_h - u_{H,k}^{\text{ms},h}\|$  vs. #dof

# Numerical experiment II



$$H = 2^{-1}, 2^{-2}, \dots, 2^{-7}$$

$$h = 2^{-9}, k = \log(1/H)$$



$\|u_h - \mathfrak{I}_T u_{H,k}^{\text{ms},h}\|$  vs.  $\#\text{dof}$

# Outline

- ① Setting and Motivation
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# Semi-linear PDE's

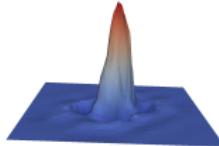
Let  $u \in V$  solve,

$$-\nabla \cdot A \nabla u + F(u, \nabla u) = g, \text{ in } \Omega \quad u = 0 \text{ on } \partial\Omega,$$

where  $0 < \alpha \leq A \leq \beta$ ,  $F$  is monotone and Lipschitz continuous in both arguments ( $L_1, L_2$  of same size or less than  $\beta$ ). Let

$$V_H^{\text{ms}} = \text{span}\{\lambda_x - \phi_x \mid x \in \mathcal{N}\}$$

as before (i.e. only depending on  $A$  **not**  $F$ ).



P. Henning, A. Målqvist, and D. Peterseim.

A rigorous multiscale method for semi-linear elliptic problems.

ArXiv e-prints, Nov. 2012.

# Semi-linear PDE's

## Error bound

Let  $u_h$  be the finite element reference solution on a fine mesh.

### Lemma

$$\|\nabla(u_h - u_H^{\text{ms},h})\|_{L^2(\Omega)} \lesssim \|Hf\|_{L^2(\Omega)} + H(L_1 + L_2)\|f\|_{H^{-1}(\Omega)}$$

- Same basis functions are used i.e. same decay rate.
- A bound for  $u_{H,k}^{\text{ms},h}$  follows using monotonicity and similar arguments as in the linear case.
- The basis will not change in the non-linear iteration.

# Eigenvalue Problems

Let  $u \in V$  and  $\lambda \in \mathbf{R}$  solve,

$$-\nabla \cdot A \nabla u = \lambda u, \text{ in } \Omega \quad u = 0 \text{ on } \partial\Omega.$$

We use the same space  $V_H^{\text{ms}}$  and solve,

$$a(u_H^{\text{ms}}, v) = \lambda_H(u_H^{\text{ms}}, v),$$

for all  $v \in V_H^{\text{ms}}$ . We let  $\mathfrak{I}_T$  be the modified Clement interpolant defined by  $(\mathfrak{I}_T v)(x) = \int_{\Omega} \lambda_x v \, dx / \int_{\Omega} \lambda_x \, dx$ ,  $\mathfrak{I}_T v = \sum_{x \in N} (\mathfrak{I}_T v)(x) \lambda_x$ . Note that  $u_H^{\text{ms}}$  is  $a$ -orthogonal and almost  $L^2$ -orthogonal to  $V_f$  since,

$$(u_H^{\text{ms}}, v_f) = (u_H^{\text{ms}} - \mathfrak{I}_T u_H^{\text{ms}}, v_f - \mathfrak{I}_T v_f) \lesssim H^2 \|A^{1/2} \nabla u_H^{\text{ms}}\|_{L^2(\Omega)} \|A^{1/2} \nabla v_f\|_{L^2(\Omega)},$$

since  $(\lambda_x, v_f) = 0$  by the definition of  $V_f = \{v \in V : \mathfrak{I}_T v = 0\}$ .

# Eigenvalue Problems

## Lemma

For  $H \leq \ell^{-1/4} \alpha^{1/2} (\lambda_h^{(\ell)})^{-1/2}$  it holds,  $\frac{\lambda_h^{(\ell)} - \lambda_H^{(\ell)}}{\lambda_h^{(\ell)}} \leq \ell^{1/2} (\lambda_h^{(\ell)})^2 \alpha^{-2} H^4$ .

We get very rapid convergence for the lowest eigenvalues using approximations in the space  $V_H^{\text{ms}}$ .

- A very coarse  $H$  can be used:  $H^{-d}$  basis functions has to be computed on patches of size  $H \cdot \log(H)$ .
- A coarse ( $H^{-d}$ ) eigenvalue problem then has to be solved in order to approximate the  $H^{-d}$  smallest eigenvalues

The choice of interpolation operator when constructing

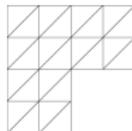
$V^f = \{v \in V : \Im_T v = 0\}$  is crucial.



A. Målqvist and D. Peterseim.

Computation of eigenvalues by numerical upscaling. *ArXiv e-prints*, Dec. 2012.

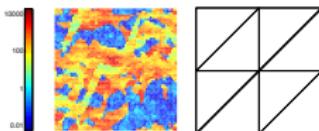
# Eigenvalue Problem



$\ell$	$\lambda_h^{(\ell)}$	$e^{(\ell)}(1/2\sqrt{2})$	$e^{(\ell)}(1/4\sqrt{2})$	$e^{(\ell)}(1/8\sqrt{2})$	$e^{(\ell)}(1/16\sqrt{2})$
1	9.6436869	0.003494567	0.000034466	0.000000546	0.000000010
2	15.1989274	0.009621397	0.000079887	0.000000845	0.000000010
3	19.7421815	0.023813222	0.000213097	0.000002073	0.000000023
4	29.5281571	0.096910157	0.000724615	0.000006574	0.000000076
5	31.9265496	0.094454625	0.000874659	0.000009627	0.000000138
6	41.4922250	-	0.002395227	0.000019934	0.000000254
7	44.9604884	-	0.002443271	0.000019683	0.000000223
8	49.3631826	-	0.003651870	0.000028869	0.000000308
9	49.3655623	-	0.004266472	0.000032835	0.000000355
10	56.7389993	-	0.006863742	0.000055219	0.000000618
11	65.4085991	-	0.011534878	0.000082414	0.000000856
12	71.0947630	-	0.012596114	0.000090083	0.000001002
13	71.6064671	-	0.014249938	0.000098736	0.000001006
14	79.0043994	-	0.021801461	0.000164436	0.000001605
15	89.3706421	-	0.033550079	0.000211985	0.000002296
16	92.3648207	-	0.040060692	0.000239441	0.000002295
17	97.4459210	-	0.037438984	0.000284936	0.000002724
18	98.7545147	-	0.044544409	0.000269854	0.000002559
19	98.7545639	-	0.047835987	0.000276139	0.000002539
20	101.6755971	-	0.038203654	0.000297356	0.000002909

Table : Errors  $e^{(\ell)}(H) =: \frac{\lambda_H^{(\ell)} - \lambda_h^{(\ell)}}{\lambda_h^{(\ell)}}$  and  $h = 2^{-7}\sqrt{2}$ .

# Eigenvalue Problem



$\ell$	$\lambda_h^{(\ell)}$	$e^{(\ell)}(1/2\sqrt{2})$	$e^{(\ell)}(1/4\sqrt{2})$	$e^{(\ell)}(1/8\sqrt{2})$	$e^{(\ell)}(1/16\sqrt{2})$
1	21.4144522	5.472755371	0.237181706	0.010328293	0.000781683
2	40.9134676	-	0.649080539	0.032761482	0.002447049
3	44.1561133	-	1.687388874	0.097540102	0.004131422
4	60.8278691	-	1.648439518	0.028076168	0.002079812
5	65.6962136	-	2.071005692	0.247424446	0.006569640
6	70.1273082	-	4.265936007	0.232458016	0.016551520
7	82.2960238	-	3.632888104	0.355050163	0.013987920
8	92.8677605	-	6.850048057	0.377881216	0.049841235
9	99.6061234	-	10.305084010	0.469770376	0.026027378
10	109.1543283	-	-	0.476741452	0.005606426
11	129.3741945	-	-	0.505888044	0.062382302
12	138.2164330	-	-	0.554736550	0.039487317
13	141.5464639	-	-	0.540480876	0.043935515
14	145.7469718	-	-	0.765411709	0.034249528
15	152.6283573	-	-	0.712383825	0.024716759
16	155.2965039	-	-	0.761104705	0.026228034
17	158.2610708	-	-	0.749058367	0.091826207
18	164.1452194	-	-	0.840736127	0.118353184
19	171.1756923	-	-	0.946719951	0.111314058
20	179.3917590	-	-	0.928617606	0.119627862

Table : Errors  $e^{(\ell)}(H) = \frac{\lambda_H^{(\ell)} - \lambda_h^{(\ell)}}{\lambda_h^{(\ell)}}$  and  $h = 2^{-7}\sqrt{2}$ .

# Outline

- ① Setting and Motivation
- ② Multiscale Method and Convergence
- ③ Full discretization and Numerical Experiments
- ④ Application to Other Problems
- ⑤ Conclusion

# Conclusion

- A variational multiscale FEM that yields scale-independent textbook convergence and, hence, leads to reliable computational approximation of multiscale problems.
- Numerical experiments confirms the theoretical results but shows less sensitive to high contrast than theory suggests.
- The basis functions are useful for other equations e.g. semi-linear problems and eigenvalue problems.