

Solvability estimates for the Dirichlet problem 1

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(A) Divergence form equations

Want to solve BVP = boundary value problem

$$\begin{cases} \operatorname{div} A(x) \nabla u(x) = 0 & \text{in } \Omega \subseteq \mathbb{R}^n \end{cases} \quad (1)$$

$$\begin{cases} u(x) = g(x) & \text{on } \partial\Omega \end{cases} \quad (2)$$

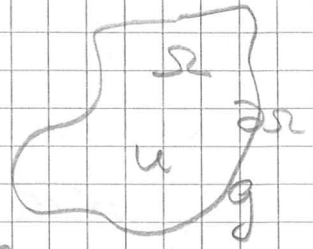
for u , given Dirichlet data g .

Consider first the PDE (1).

Want to allow as general

coefficient matrices $A(x) = (A_{ij}(x))_{i,j=1}^n$,

and domains $\Omega \subseteq \mathbb{R}^n$.



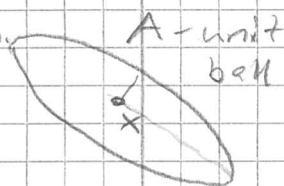
- Only $A \in L_\infty(\Omega)$ in general is assumed.
(even degenerate A , where A is unbounded is sometimes considered.)
- Lower ellipticity / accretivity bound on A :
 $\langle A(x)v, v \rangle \geq \kappa |v|^2, \forall x \in \Omega, v \in \mathbb{R}^n$
- We assume here that A_{ij} are real-valued,
 $A_{ij}(x) \in \mathbb{R}$. (Complex-valued A_{ij} , or more general systems can be considered.)
- In general, we do not assume A to be symmetric, i.e. $A_{ji} \neq A_{ij}$ may happen.
(For constant A wlog $A_{ji} = A_{ij}$ can be assumed, but non-symmetric non-smooth A are challenging.)

Some motivations:

- Solving non-linear PDE using fixed-point

iterations with linear PDEs typically requires 2 estimates for potentially non-smooth $A=A(u)$. [GT:83]

- Div form elliptic PDEs $\operatorname{div}(A \nabla u) = 0$ are the most natural ones. Symmetric A can model an anisotropic heat conductivity/diffusion.



- Div. form systems where $u: \Omega \rightarrow \mathbb{R}^N$ and $A: \mathbb{R}^N \otimes \mathbb{R}^N \rightarrow \mathbb{R}^N \otimes \mathbb{R}^N$ arise for example in elasticity theory. Here accretivity of A need to be weakened to a Gårding inequality

$$\int_{\Omega} \langle A \nabla f, \nabla f \rangle dx \geq \kappa \int_{\Omega} |\nabla f|^2 dx, \quad \forall f: \Omega \rightarrow \mathbb{R}^N.$$

When $u: \Omega \rightarrow \mathbb{R}$ is scalar-valued, this is which holds by Korn's inequality equivalent to accretivity.

- Equations arising in homogenization theory have often non-symmetric coeffs. Estimates that uniform in the scaling parameter are needed, amounting to non-smooth A quantitatively.
- The only known technique for obtaining sharp perturbation estimates $A \mapsto u$, require estimates for complex (in particular non-symmetric) A .

Local / interior estimates

The classical de Giorgi - Nash - Moser ^{interior} estimates for solutions $u(x)$ to $\operatorname{div} A \nabla u = 0$ hold for general real-valued, possibly non-symmetric, accretive coefficients $A \in L_{\infty}(\Omega; \mathbb{R}^{N \times N})$.

See e.g. Moser [M:61]:

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Harnack: $\max_K u \leq \min_K u$

if solution $u \geq 0$ in Ω , for any compact $K \subset \Omega$.

Proof is by reverse Hölder estimates of $(\int_K |u|^p dx)^{1/p}$, from $p = -\infty$ ($\min u$) to $p = +\infty$ ($\max u$).

Consequences:

- Interior Hölder regularity of u , some $\alpha > 0$.
- Interior Morrey regularity of ∇u [HK:07]

Estimates used: Caccioppoli, Poincaré, Sobolev embedding, John-Nirenberg.

Change of variables

Let $g: \Omega_1 \rightarrow \Omega_2$ be a diffeomorphism (g and g^{-1} are Lipschitz)

Assume $\operatorname{div} A_1 \nabla u_1 = 0$ in Ω_1 .

Define $u_2 = u_1 \circ g^{-1}$ and

$$A_2(g(x)) = \frac{1}{J_g(x)} \underline{g}_x A_1(x) \underline{g}_x^*$$

where $\underline{g}_x$ is Jacobian matrix of g ,

$\underline{g}_x^*$ = its transpose, and $J_g(x) = \det \underline{g}_x$.

Then $\operatorname{div} A_2 \nabla u_2 = 0$ in Ω_2 .

Proof: It is always assumed that

$\nabla u \in L_2^{\text{loc}}(\Omega)$, and div is taken in distributional sense, so

$$\int_{\Omega_1} \langle A_1(x) \nabla u_1(x), \nabla \varphi_1(x) \rangle dx = 0$$

$\forall \varphi_1 \in H_0^1(\Omega)$ is assumed.

(Changing variables $\Rightarrow$)

$$\int_{\Omega_2} \langle A_1 \underline{g}^* \nabla u_2, \underline{g}^* \nabla \psi_2 \rangle \frac{dx}{J_g} = 0$$

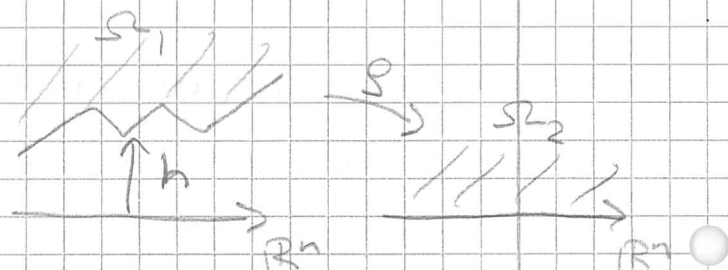
$$\forall \psi_2 = \psi_1 \circ g^{-1} \in H_0^1(\Omega_2) \quad \square$$

By changing of vars, we can "move the non-smoothness of Ω to A ",

Ex 1: $h: \mathbb{R}^n \rightarrow \mathbb{R}$

Lipschitz

$\Omega_1 \subset \mathbb{R}^{1+n}$ domain above
graph of h .



Assume $\Delta u_1 = \operatorname{div} I \nabla u_1 = 0$ in Ω_1 , and
map by $g(t, x) = (t - h(x), x)$ onto upper
half space $\mathbb{R}_+^{1+n}$.

$$\underline{g} = \begin{bmatrix} 1 & -\nabla h \\ 0 & I \end{bmatrix} \Rightarrow A_2 = \begin{bmatrix} 1 & -\nabla h \\ 0 & I \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -\nabla h^T & I \end{bmatrix}$$

$$= \begin{bmatrix} 1 + |\nabla h|^2 & -\nabla h \\ -\nabla h^T & I \end{bmatrix}$$

$u_2 = u_1 \circ g^{-1}$ solves $\operatorname{div} A_2 \nabla u_2 = 0$ in $\mathbb{R}_+^{1+n}$.

Note: A_2 is symmetric, L_∞ and accretive
and independent of vertical coord. t .

Ex 2: h and Ω_2 as in Ex 1.

Instead of

$$g^{-1}(t, x) = (t + h(x), x), \text{ we}$$

set

$$\tilde{g}^{-1}(t, x) = (t + \eta_t * h(x), x)$$

where $\eta(x) \in C_0^\infty(\mathbb{R}^n)$, $\int \eta = 1$, supp η small enough,

$\eta_t(x) = \frac{1}{t^n} \eta(\frac{x}{t})$ is a smooth mollifier.

This construction goes back to Dahlberg, Kenig,

Nečas, Stein.

[N:67] = very good book!

If $\Delta u_1 = 0$ in the Lipschitz domain Ω_1 ,
 then $\operatorname{div} \tilde{A}_2 \nabla u_2 = 0$ in $\mathbb{R}_+^{1+n}$ 5

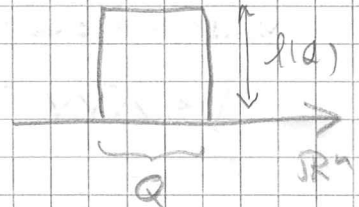
Now again $\tilde{A}_2$ is symmetric, L_∞ , accretive.

i : $\tilde{A}_2 \in C_{loc}^\infty$ ii : $\tilde{A}_2$ depends on t .

Qualitatively, $\nabla \tilde{A}_2$ satisfies a Carleson measure condition:

$$\int_{Q \times (0, \lambda(Q))} |\nabla \tilde{A}_2(t, x)|^2 t \, dt \, dx \lesssim |Q|$$

$\forall$ cubes $Q \subseteq \mathbb{R}^n$.



(A "corner" on $\partial\Omega_1$ above x_0 typically gives $|\nabla A_2| \sim \frac{1}{t+|x-x_0|}$.)

(B) Solvability estimates

Recall: the PDE problem (1)+(2) is wellposed in the sense of Hedemund if

1. $\forall g \exists$ solution u
2. the solution u is unique
3. u depends continuously on g

From Fredholm perspective, 1 & 2 are "algebraic" issues, while 3 is the real analysis problem.

Given a norm $\|\cdot\|$ on Dirichlet data g , and a norm $\|\cdot\|$ on solutions u , our main problem is to prove the solvability estimate

$$\|u\| \leq C \|g\|, \text{ for some } C < \infty.$$

Energy solvability estimate

The most fundamental / simplest / most natural solvability estimate is for

$$\|g\| = \|g\|_{H^{1/2}(\partial\Omega)} \quad \text{and} \quad \|u\| = \|u\|_{H^1(\Omega)}.$$

This follows from Lax-Milgram's thm:

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Fix an extension operator

$$g \in H^{1/2}(\partial\Omega) \mapsto f \in H^1(\Omega)$$

so that $f|_{\partial\Omega} = g$. With $u = v + f$

$$\begin{cases} \operatorname{div} A \nabla u = 0 \text{ in } \Omega \\ u = g \text{ on } \partial\Omega \end{cases} \Leftrightarrow \begin{cases} \operatorname{div} A \nabla v = -\operatorname{div} A \nabla f \text{ in } \Omega \\ v = 0 \text{ on } \partial\Omega \end{cases}$$

Variational formulation for $v \in H_0^1(\Omega)$ is

$$\underbrace{\int_{\Omega} \langle A \nabla v, \nabla \varphi \rangle dx}_{= B(v, \varphi)} = - \underbrace{\int_{\Omega} \langle A \nabla f, \nabla \varphi \rangle dx}_{= F(\varphi)}, \quad \forall \varphi \in H_0^1(\Omega)$$

Symmetry is not needed.

Lax-Milgram applies and give $v \in H_0^1(\Omega)$ with

$$\|v\|_{H^1} \leq \|f\|_{H^1} \leq \|g\|_{H^{1/2}}, \text{ and } \|u\|_{H^1} \leq \|g\|_{H^{1/2}},$$

whenever $A \in L_{\infty}(\Omega)$ is accretive. (For system, only the Gårding ineq. suffices.)

Maximum principle:

This gives the solvability estimate for

$$\|g\| = \|g\|_{L_{\infty}(\partial\Omega)} \text{ and } \|u\| = \|u\|_{L_{\infty}(\Omega)}.$$

The following proof from [LSW: 63, thm 2.5] only requires that A_{ij} be real coefficient.

Thm: Assume $A \in L_{\infty}(\Omega)$ are accretive and real.

Then $g \leq C$ on $\partial\Omega \Rightarrow u \leq C$ in Ω .

Proof: Let $\varepsilon > 0$,

$$\Omega_0 = \{x \in \Omega; u(x) > C + \varepsilon\} \text{ and}$$

$$\varphi(x) = \begin{cases} u(x) - C - \varepsilon & , x \in \Omega_0 \\ 0 & , x \notin \Omega_0 \end{cases}$$

$\Omega_0 \subset \Omega$ is compact, so $\varphi \in H_0^1(\Omega)$ and

$$\int_{\Omega} \langle A \nabla u, \nabla \varphi \rangle dx = 0.$$

But $\nabla \varphi \neq 0 \Rightarrow x \in \Omega_0 \Rightarrow \nabla u(x) = \nabla \varphi(x)$, so

$$\int_{\Omega} |\nabla \varphi|^2 dx \stackrel{\uparrow}{\approx} \int_{\Omega} \langle A \nabla \varphi, \nabla \varphi \rangle dx = 0$$

accredivity

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$\therefore \nabla \varphi = 0$ in Ω , so $\Omega_0 = \emptyset$ and

$u \leq C + \varepsilon$, $\forall \varepsilon > 0$ follows, hence $u \leq C$. $\square$

↑ Higher regularity

If $A \in C^\infty$ and if Ω has a C^∞ boundary, then the solvability estimate

$$\|u\|_{H^{s+1/2}(\Omega)} \lesssim \|g\|_{H^s(\Omega)}$$

can be proved for any Sobolev regularity $s \geq \frac{1}{2}$

See e.g. [T:96, chapter 5.1, prop. 1.7.].

The half space setup

From now on, we assume that $\Omega = \mathbb{R}_+^{1+n}$
 $= \{(t, x) ; t > 0, x \in \mathbb{R}^n\}$. Write $\bar{x} = (t, x)$, $t = x_0$.

By examples 1 & 2, p. 4-5, a solvability estimate on $\mathbb{R}_+^{1+n}$ gives solvability results for general Lipschitz domains Ω , via a change of variables and partition of unity argument.

Note that it is natural to work with a scale-invariant domain $\mathbb{R}_+^{1+n}$ since the solvability estimates that we aim for are scale invariant:

If $\|u\| \leq \|g\|$ for solutions $\operatorname{div} A \nabla u = 0$ in Ω with $u = g$ on $\partial\Omega$, then

$\|u_R\| \leq \|g_R\|$ for solutions $\operatorname{div} A_R \nabla u_R = 0$ in $\mathbb{R}_+^{1+n}$ with $u_R = g_R$ on $\partial\Omega_R$.

$u_R(x) = u(\frac{x}{R})$, $g_R(x) = g(\frac{x}{R})$, $A_R(x) = A(\frac{x}{R})$ for $x \in R \cdot \Omega = \{Ry; y \in \Omega\}$.

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Note that $\|A_R\|_\infty = \|A\|_\infty$ and that equality constants are equal.

C.f. the case when Ω and A are smooth: here by localizing/rescaling, one can reduce to $\Omega = \mathbb{R}_+^n$ and $A = \text{constant}$, and apply Fourier transform.

A-harmonic measure

For $\bar{x} = (t, x) \in \mathbb{R}_+^{1+n}$, the functional

$g \mapsto u(t, x) = \text{solution}$

is bounded on $C(\mathbb{R}^n)$ by max. principle, if

A is real, so $\exists$ measure $\omega_{\bar{x}} = \omega_{\bar{x}}^A$ on $\mathbb{R}^n$ s.t.

$$u(\bar{x}) = \int_{\mathbb{R}^n} g(y) d\omega_{\bar{x}}(y)$$

$\omega_{\bar{x}}$ is called A-harmonic measure.

It is a probability measure: $\int_{\mathbb{R}^n} d\omega_{\bar{x}}(y) = 1$ & positive.

• By Harnack's ineq., $\omega_{\bar{x}}$ and $\omega_{\bar{y}}$ are mutually absolutely continuous, $\forall \bar{x}, \bar{y} \in \mathbb{R}_+^{1+n}$.

Examples by [CFK: 81], using the theory for quasiconformal mappings, show that $\omega_{\bar{x}}$ may be completely singular with respect to Lebesgue meas. dx .

like in Ex 1 and Ex 2

Heuristics: some regularity of $A(t, x)$ in the transversal coordinate t is needed for $\omega_{\bar{x}}$ to be abs. cont. w.r.t. dx .

• Green's formula:

$$\begin{aligned} \iint_{\mathbb{R}_+^{1+n}} \left((\operatorname{div} A^* \nabla G^*) u - G^* (\operatorname{div} A \nabla u) \right) dt dx \\ = \int_{\mathbb{R}^n} \left((v \cdot A^* \nabla G^*) u - G^* (v \cdot A \nabla u) \right) dx \end{aligned}$$

If a Green's function $G^*(\bar{y}, \bar{x})$

$$(dv_y A^*(\bar{y}) \nabla_y G^*(\bar{y}, \bar{x}) = \delta_x(\bar{y}), \quad G^*(\bar{y}, \bar{x}) = 0, \quad \bar{y} \in \mathbb{R}^n)$$

is known, then

$$\frac{dw_x(\bar{y})}{d\bar{y}} = \underset{(0, -1)}{v(\bar{y}) \circ A^*(\bar{y}) \nabla_y G^*(\bar{y}, \bar{x})}.$$

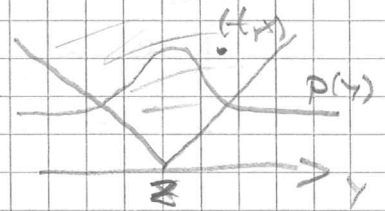
Non-tangential maximal function

For Δ , harm. measure is

$$dw_{(t,x)}(\bar{y}) = c \cdot \frac{t}{(t^2 + |\bar{y} - x|^2)^{\frac{n+1}{2}}} d\bar{y}$$

$$\text{Write } p(\bar{y}) = c \frac{1}{(1 + |\bar{y}|^2)^{\frac{n+1}{2}}}, \text{ so}$$

$$u(t, x) = \int_{\mathbb{R}^n} \frac{1}{t^n} p\left(\frac{x - \bar{y}}{t}\right) g(\bar{y}) d\bar{y}.$$



Defn: The non-tangential max. function of u is

$$(N_* u)(z) = \sup_{t, z: |x-z| \leq t} |u(t, z)|, \quad z \in \mathbb{R}^n$$

(Hardy-Littlewood) max. function of g is

$$(Mg)(z) = \sup_{r>0} \int_{|y-z|<r} |g(y)| dy$$

Subordination $\Rightarrow$

$$N_* u(z) \lesssim Mg(z), \quad \forall z \in \mathbb{R}^n.$$

$M: L_p(\mathbb{R}^n) \rightarrow L_p(\mathbb{R}^n)$ is bounded if $1 < p \leq \infty$.

We get a solvability estimate for Δ :

$$\|N_* u\|_p \lesssim \|g\|_p \quad \text{if } p > 1.$$

$$= \|u\|$$

A main problem: for which coeff. $A(t, x)$ and which $1 < p < \infty$ do we have the solvability estimate

$$\|N_* u\|_p \lesssim \|g\|_p \quad ?$$

Call this the p -solvability estimate.

It is known to hold iff

$d\omega = f dy$ is absolute cont. w.r.t. dy
with reverse Hölder estimate $(\frac{1}{p} + \frac{1}{q} = 1)$

$$\left(\int_Q f^q dy \right)^{1/q} \leq \int_Q f dy, \quad \forall \text{ cubes } Q \subseteq \mathbb{R}^n.$$

See [KKPT:00, p. 241].
[K:91] for symmetric eqns.

Here $\omega = \omega_{x_0}$ is harmonic measure for any fixed pole $x_0 \in \mathbb{R}_+^{1+n}$.

The pioneer:

Thm: B. Dahlberg [D:77]

The 2-solvability est. holds for Δ
on Lipschitz domains.

By change of vars as in Ex 1, this corresponds
to a symmetric t-independent $A = A(x)$
on $\mathbb{R}_+^{1+n}$. We shall prove this for all such A .
2-solvability

BMO-solvability

It is known that p -solvability $\Rightarrow q$ -solvability
if $q > p$. At the endpoint $p = \infty$, there
is a deeper solvability estimate than the
maximum principle.

Consider Δ on $\mathbb{R}_+^{1+n}$.

Write $t \nabla_{t,x} \left(\frac{1}{t^n} p\left(\frac{x}{t}\right) \right) = \frac{1}{t^n} q\left(\frac{x}{t}\right)$,
so that $\int_{\mathbb{R}^n} q(x) dx = 0$ and

$$t \nabla_{t,x} u(t, x) = \int_{\mathbb{R}^n} \frac{1}{t^n} q\left(\frac{x-y}{t}\right) g(y) dy.$$

$$\Rightarrow \iint_{\mathbb{R}_+^{1+n}} |t \nabla_{t,x} u|^2 \frac{dt dx}{t} = \int_0^\infty \frac{dt}{t} \int dx \left| \frac{1}{t^n} q\left(\frac{x}{t}\right) * g \right|^2$$

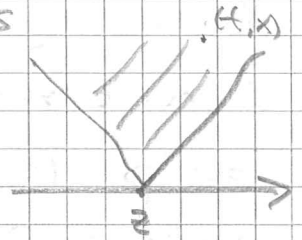
$$\begin{aligned} &= \text{Plancherel} = \int_0^\infty \frac{dt}{t} \int_{\mathbb{R}^n} d\zeta \left| \hat{q}\left(t\zeta\right) \hat{g}(\zeta) \right|^2 = \text{Fubini and } t \mapsto t/|\zeta| \\ &= \int_{\mathbb{R}^n} d\zeta \left(\int_0^\infty \frac{dt}{t} \left| \hat{q}\left(t \frac{\zeta}{|\zeta|}\right) \right|^2 \right) |\hat{g}(\zeta)|^2 \end{aligned}$$

$$= C \cdot \int_{\mathbb{R}^n} |g(x)|^2 dx \quad \text{since } \hat{g}(0) = 0 \text{ so that } \int_0^\infty \frac{dt}{t^{\frac{n+1}{2}}} \text{ is convergent.} \quad ||$$

This proves a square function L_2 -solvability estimate: $\|Su\|_2 \lesssim \|g\|_2$.

Defn: The square function of u is

$$S_u(z) = \left(\int_{|x-z|<t} |\nabla_{t,x} u|^2 + \frac{dt dx}{t^n} \right)^{1/2}$$



Now assume $g \in \text{BMO}(\mathbb{R}^n)$, i.e.,

$$\int_Q |g(y) - g_Q|^2 dy \leq C^2, \quad \forall \text{ cubes } Q \subset \mathbb{R}^n$$

L average $\int_Q g$.

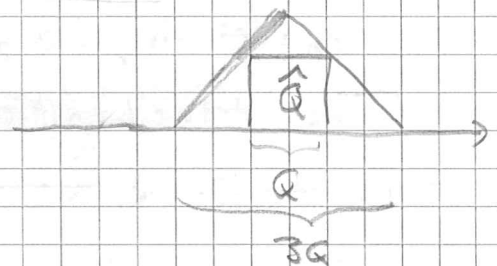
Best $C = \|g\|_{\text{BMO}(\mathbb{R}^n)}$.

$$\text{BMO}(\mathbb{R}^n) \stackrel{\ln|x|}{\neq} L_\infty(\mathbb{R}^n)$$

Given cube $Q \subset \mathbb{R}^n$, consider

$$\iint_Q |\nabla_{t,x} u|^2 + dt dx \quad \text{over the}$$

Corleison box $\hat{Q} = (0, \ell(Q)) \times Q$
 $\uparrow$
 side length.



$$\text{Set } h(y) = (g(y) - g_{3Q}) \cdot 1_{3Q}(y)$$

$g(x) \sim \frac{1}{|x|^{n+1}}$ as $x \rightarrow \infty$, but pretend

$\text{supp } g \subset B(0, 1)$ to avoid tail technicalities.

Let v be solution with $v|_{\mathbb{R}^n} = h$.

$$\Rightarrow \nabla v = \nabla u \text{ on } \hat{Q}$$

L_2 estimate $\Rightarrow$

$$\begin{aligned} \iint_{\hat{Q}} |\nabla u|^2 + dt dx &= \iint_{\hat{Q}} |\nabla v|^2 + dt dx \leq \iint_{\mathbb{R}_+^{n+1}} |\nabla v|^2 + dt dx \\ &\leq \|h\|_2^2 = \int_Q |g - g_Q|^2 dy \end{aligned}$$

We get the solvability est.

$$\|\nabla u\|_2 + \| \cdot \|_C^{1/2} \lesssim \|g\|_{\text{BMO}},$$

where

the Carleson norm is

$$\|f\|_C = \sup_{\substack{\text{cube} \\ Q \subset \mathbb{R}^n}} \frac{1}{|Q|} \iint_Q |f| dt dx.$$

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We shall prove this solvability estimate for all t-independent real A , not necessarily symmetric, and that this entails p -solvability for p large enough depending on A .

Note: Unlike the maximum principle, the BMO estimate relies on cancellations ($\int g dy = 0$)

- It is known that the BMO solvability estimate holds iff harmonic measure $\omega \in A_\infty(dy)$

The Muckenhoupt class of weight A_∞ is defined as follows: $\exists \varepsilon, \delta \in (0, 1)$:

$E \subset Q$, $Q = \text{cube in } \mathbb{R}^n$, E any subset

$$\frac{|E|}{|Q|} < \delta \quad \Rightarrow \quad \frac{\omega(E)}{\omega(Q)} < \varepsilon$$

$\uparrow$ Lebesgue meas.

$\uparrow$ A -harmonic meas. $\omega(E) = \int_E d\omega$

See [DKP: 10, Thm 2.1].

- It is known that

$$A_\infty(dy) = \bigcup_{q \geq 1} B_q(dy)$$

where $B_q(dy)$ is the class of weights ω satisfying the reverse Hölder est.

$$\forall \text{ cubes } Q \subset \mathbb{R}^n : \left(\int_Q \left(\frac{d\omega}{dy} \right)^q dy \right)^{1/q} \leq \int_Q \frac{d\omega}{dy} dy.$$

- For coefficient A , the BMO solv. est. holds iff the p -solvability est. holds for some $p < \infty$.

①

L_2 theory for conjugate systems

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Philosophy: analytic functions are more fundamental than harmonic functions,

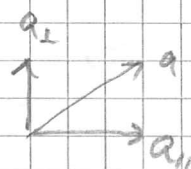
We generalize $\Delta u = 0$ in $\mathbb{R}^2 = \mathbb{C}$ to $\operatorname{div} A \nabla u = 0$ in $\mathbb{R}^{1+n}$, and seek generalized conjugate functions to u . Assume $\operatorname{div}_{t,x} A(x) \nabla_{t,x} u = 0$ in $\Omega = \mathbb{R}_+^{1+n}$.

Split matrix: $A(x) = \begin{bmatrix} a(x) & b(x) \\ c(x) & d(x) \end{bmatrix}$ $\begin{matrix} t & \\ & x \end{matrix}$

The natural "normal derivative" is the conormal derivative

$$\partial_A u = (A \nabla_{t,x} u)_\perp = a \partial_t u + b \nabla_x u$$

Notation: $a = \begin{bmatrix} a_1 \\ a_n \end{bmatrix} \in \mathbb{R}^{1+n}$



In $\mathbb{R}^{1+n}$, u will have n conjugate functions $V_\parallel(t, x) \in \mathbb{R}^n$, defined as follows:

Write $\partial_A u = \operatorname{div}_x V_\parallel$ at each fixed height t .

Possible since ∇_x is injective $\Leftrightarrow \operatorname{div}_x$ is surjective.

Then insert into $\operatorname{div}_{t,x} A \nabla_{t,x} u = 0$:

$$\underbrace{\partial_t (A \nabla_{t,x} u)_\perp}_{\substack{= \operatorname{div}_x V_\parallel \\ \text{commute}}} + \underbrace{\operatorname{div}_x (A \nabla_{t,x} u)_\parallel}_{= c \partial_t u + d \nabla_x u} = 0$$

We may, and will, choose $V_\parallel$ s.t.

$$\partial_t V_\parallel + c \partial_t u + d \nabla_x u = 0$$

Together with $a \partial_t u + b \nabla_x u = \operatorname{div}_x V_\parallel$, we have

$$\underbrace{\partial_t \begin{bmatrix} -u \\ V_\parallel \end{bmatrix}}_V + \underbrace{\begin{bmatrix} a^{-1} & -a^{-1}b \\ ca^{-1} & d - ca^{-1}b \end{bmatrix}}_B \underbrace{\begin{bmatrix} 0 & \operatorname{div}_x \\ -\nabla_x & 0 \end{bmatrix}}_D \underbrace{\begin{bmatrix} -u \\ V_\parallel \end{bmatrix}}_V = 0$$

$\therefore$ We have a conjugate system V ,

containing $u = -V_{\perp}$, that solves a generalized Cauchy-Riemann equation

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$$\partial_t V + BDV = 0,$$

We view B and D as multiplication / differential operators acting horizontally, in $L_2(\mathbb{R}^n; \mathbb{R}^{1+n}) = L_2(\mathbb{R}^n)$, for each fixed t .

Properties of B and D :

$D = \begin{bmatrix} 0 & \text{div} \\ -\nabla & 0 \end{bmatrix}$ is self-adjoint, closed, densely defined unbounded in L_2 .

Its range $R(D)$ is not closed, its closure is

$$\mathcal{H} = \begin{bmatrix} L_2 \\ \mathcal{H}_{\parallel} \end{bmatrix} \quad \text{where } \mathcal{H}_{\parallel} = \{ \text{curl-free vector fields} \}.$$

By self-adjointness, its nullspace is $\mathcal{H}^{\perp} = \begin{bmatrix} 0 \\ \mathcal{H}_{\parallel}^{\perp} \end{bmatrix}$ div-free fields.

Prop: A is accretive $\Leftrightarrow B$ is accretive.

(A is self-adjoint $\nRightarrow B$ is self-adjoint!)

Proof: For $V \in \mathbb{R}^{1+n}$, write $V_A = \begin{bmatrix} aV_{\perp} + bV_{\parallel} \\ V_{\parallel} \end{bmatrix}$ and note $|V| \approx |V_A|$, if A bounded and accretive.

$$\langle B V_A, V_A \rangle = \left\langle \begin{bmatrix} a^{-1} & -\bar{a}^{-1}b \\ c\bar{a}^{-1} & d - c\bar{a}^{-1}b \end{bmatrix} \begin{bmatrix} aV_{\perp} + bV_{\parallel} \\ V_{\parallel} \end{bmatrix}, \begin{bmatrix} aV_{\perp} + bV_{\parallel} \\ V_{\parallel} \end{bmatrix} \right\rangle$$

$$= \begin{bmatrix} V_{\perp} \\ cV_{\perp} + dV_{\parallel} \end{bmatrix}$$

$$= \left\langle \begin{bmatrix} aV_{\perp} + bV_{\parallel} \\ cV_{\perp} + dV_{\parallel} \end{bmatrix}, \begin{bmatrix} V_{\perp} \\ V_{\parallel} \end{bmatrix} \right\rangle = \langle AV, V \rangle \gtrsim |V|^2 \approx |V_A|^2$$

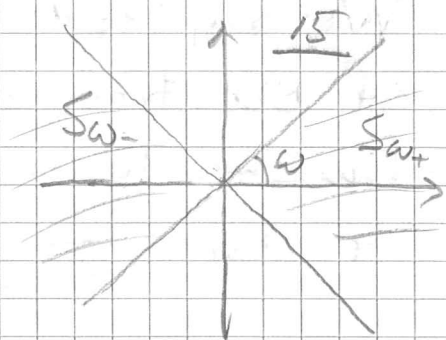
$\Leftarrow$ follows since

$A \mapsto B = \hat{A}$ is self-inverse. $\square$

Remark: $d - c\bar{a}^{-1}b$ appearing in B is a well-known construction in matrix theory called a Schur complement.

Prop: The spectrum $\sigma(BD)$

is contained in a
bisector $S_\omega = S_{\omega+} \cup S_{\omega-}$,
for $\omega < \frac{\pi}{2}$ depending on B .



Proof: Let $\lambda u - BDu = f$.

$$\Rightarrow \underbrace{\langle B^{-1}(\lambda u - BDu), u \rangle}_{\text{Im}} = \underbrace{\langle B^{-1}f, u \rangle}_{\text{Im}}$$

$$D^* = D \Rightarrow \text{Im}(\lambda \langle B^{-1}u, u \rangle) = \text{Im} \langle B^{-1}f, u \rangle$$

lies in compact
subset of right
half-plane

$$\lambda \notin S_\omega \Rightarrow \|u\|^2 \lesssim \|f\| \cdot \|u\|$$

$$\therefore \|(\lambda - BD)^{-1}f\| \lesssim \|f\|$$

(A duality argument shows $\lambda - BD$ surjective.) $\square$

Prop: We have a topological (not orth.)

"perturbed Hodge" splitting

$$L_2 = \underbrace{B\mathcal{H}}_{\cong R(D)} \oplus \underbrace{\mathcal{H}^\perp}_{\cong N(D)} = \overline{R(BD)} \oplus N(BD).$$

Proof: Let $f \in \mathcal{H}$, $g \in \mathcal{H}^\perp$.

Accredibility $\Rightarrow$

$$\|Bf\| \approx \|f\| \lesssim \langle Bf, f \rangle$$

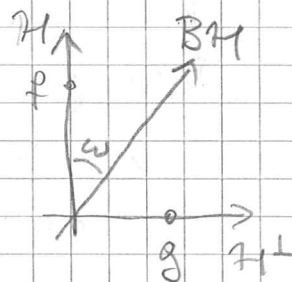
$$= \langle Bf + g, f \rangle \lesssim \|Bf + g\| \cdot \|f\|$$

$$\Rightarrow \|Bf\| \lesssim \|Bf + g\|, \text{ so}$$

$$\|Bf\| + \|g\| \approx \|Bf + g\|, \text{ proving that}$$

$B\mathcal{H}$ and $\mathcal{H}^\perp$ are transversal.

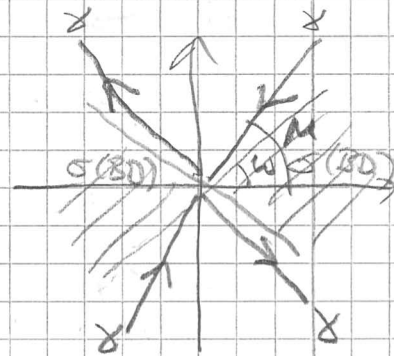
(A duality argument shows that $B\mathcal{H}$ and $\mathcal{H}^\perp$
span L_2 .) $\square$



We synthesise more general functions $\varphi(BD)$ of BD from the resolvents $\frac{1}{\lambda - BD}$, by Dunford functional calculus:

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$$\varphi(BD) = \frac{1}{2\pi i} \int_{\gamma} \frac{\varphi(\lambda)}{\lambda - BD} d\lambda$$



with a curve $\gamma = \partial S_\mu$, for some $\omega < \mu < \frac{\pi}{2}$, positively oriented around $\sigma(BD) \subset S_\omega$

The integral is convergent if $\varphi(\lambda) \rightarrow 0$ as $\lambda \rightarrow 0$ and $\lambda \rightarrow \infty$, not too slowly, since

$$\left\| \frac{1}{\lambda - BD} \right\| \approx \frac{1}{|\lambda|} \text{ on } \gamma.$$

Since BD is not self-adjoint, the symbol $\varphi(\lambda)$ must be holomorphic on some neighbourhood of S_μ .

Thm: By strong continuity, the Dunford functional calculus extends to a bounded homomorphism

$$\varphi(\lambda) \in H^\infty(S_\mu) \longrightarrow L(L_2(\mathbb{R}^n)) \ni \varphi(BD)$$

i.e., $\exists C < \infty$:

$$\|\varphi(BD)\|_{L_2 \rightarrow L_2} \leq C \|\varphi\|_{L^\infty(S_\mu)}$$

This is a very deep result, essentially equivalent to the Kato square root problem estimate

$$\|\sqrt{-\Delta} \nabla u\|_{L_2} \approx \|\nabla u\|_{L_2}.$$

See [AAMC: 10a], [AAMC: 10b].

Ex: $\varphi(\lambda) = 1_{S_{\mu+}}(\lambda) = \begin{cases} 1, & \lambda \in S_{\mu+} \\ 0, & \text{else} \end{cases}$

gives a bounded projection

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$E^+ = 1_{S_{\mu+}}(BD) = \text{spectral projection for } S_{\mu+}$.

The subspace $E^+ L_2 = R(E^+)$ is a generalized Hardy subspace for $\partial_t V + BDV = 0$ in $\mathbb{R}_+^{1+n}$.

- If $V_0(x) \in E^+ L_2$, define

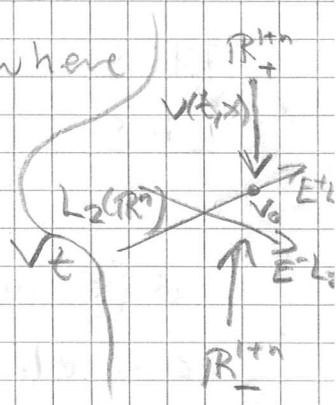
$$V_t(\cdot) = V(t, \cdot) = \varphi_t(BD) V_0, \text{ where}$$

$$\varphi_t(\lambda) = \begin{cases} e^{-t\lambda} & \lambda \in S_{\mu+} \\ 0 & \text{else.} \end{cases}$$

$$\Rightarrow \partial_t V_t = \partial_t e^{-tBD} V_0 = -BD V_t$$

$$\text{and } V_t \xrightarrow{L^3} V_0 \text{ as } t \rightarrow 0^+.$$

$$V_t \xrightarrow{L^3} 0 \text{ as } t \rightarrow \infty.$$



- By an integrability factor argument, all such solutions V to $\partial_t V_t + BD V_t = 0$ in $\mathbb{R}_+^{1+n}$ is the "Cauchy integral" $V_t = e^{-tBD} V_0$ of $V_0 = \lim_{t \rightarrow 0^+} V_t \in E^+ L_2$.

Square function / quadratic estimates

Let $\varphi(\lambda) = \frac{\lambda}{1+\lambda^2}$ (or use any other $\varphi \in C^\infty(\mathbb{R})$ with decay at 0 and ∞).

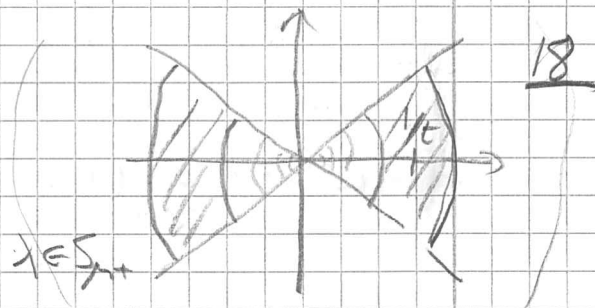
Set $\varphi_t(\lambda) = \varphi(t\lambda)$, where $t > 0$ is scaling parameter. We have quadratic estimates

$$\int_0^\infty \|\varphi_t(BD) f\|_{L_2(\mathbb{R}^n)}^2 \frac{dt}{t} \approx \|f\|_{L_2}^2, \quad \forall f \in B^{\infty,1}_2$$

This is another deep result, equivalent to Thm, and is a "Littlewood-Paley decomposition" for the operator BD .

Interpretation: $\varphi_t(BD) \approx$ spectral projection for the dyadic band

$$\left\{ \frac{1}{2\epsilon} < |\lambda| < \frac{2}{\epsilon} \right\} \cap S_{\mu}.$$



Ex: Apply Q.E. with

$$\psi(\lambda) = \lambda e^{-|\lambda|} = \begin{cases} \lambda e^{-\lambda}, & \lambda \in S_{\mu+} \\ \lambda e^{+\lambda}, & \lambda \in S_{\mu-} \end{cases}$$

and $f = v_0 \in E^+ L_2 \subset BM$

$$RHS = \|v_0\|_2^2 = \|u(0, \cdot)\|_2^2 + \|v_{||}(0, \cdot)\|_2^2$$

$$LHS: \mathcal{H}_t(BD) v_0 = tBD e^{-tBD} v_0 = tBD v_t \\ = -t \partial_t v_t$$

But since $\partial_t v_{||} + c \partial_t u + d \nabla_x u = 0$, we can eliminate $v_{||}$:

$$\|\partial_t v\|_2^2 = \|\partial_t u\|_2^2 + \|\partial_t v_{||}\|_2^2 \approx \|\nabla_{t,x} u\|_2^2$$

Q.E. $\Leftrightarrow$

$$\iint_{\mathbb{R}_+^{1+n}} |\nabla_{t,x} u|^2 t dt dx \approx \|u_0\|_2^2 + \|v_{||,0}\|_2^2$$

Compare to square function est. for Δ on p. 10-11:

Only assuming $A \in L_\infty$ accretive and t -independent, (the BD L_2 -theory works even for systems)

the square function L_2 -solubility estimate

$$\|Su\|_2 \approx \|u\|_2 \quad \text{hold}$$

if at $\mathbb{R}^n$, we can prove the Hilbert transform estimate

$$\|v_{||,0}\|_2 \lesssim \|u_0\|_2$$

Also note that $\|Su\|_2 \gtrsim \|u\|_2$ always holds.

Non-tangential maximal estimates

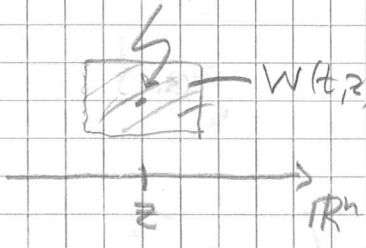
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Next we prove:

Thm: For a conjugate system $v = \begin{bmatrix} -u \\ v_{n,0} \end{bmatrix}$ in $\mathbb{R}^{1+n}$, and $v_t = e^{-tBD} v_0$, we have

$$\|N_*(u)\|_2 \lesssim \|v_0\|_2 \approx \|u_0\|_2 + \|v_{n,0}\|_2$$

It suffices to bound a modified NT-max for

$$\tilde{N}_*(v)(z) = \sup_{t>0} \left(\frac{\int_{W(t,z)} |v|^2}{\text{L}_2 \text{ Whitney average}} \right)^{1/2} (t,z)$$


The Whitney regions

- "ball/cube"-like around (t,z)

- diameter $\approx$ distance to $\mathbb{R}^n$

The precise geometry ^{of $W(t,z)$} is unimportant: give equivalent norms $\|\tilde{N}_*(v)\|_2$.

By interior regularity:

$$\|N_*(u)\|_2 \lesssim \|\tilde{N}_*(u)\|_2 \leq \|\tilde{N}_*(v)\|_2$$

if $dN \nabla u = 0$ and A is real.

To show

$$\|\tilde{N}_*(v)\|_2 \lesssim \|v_0\|_2$$

we use quadratic estimates to replace e^{-tBD} by $\frac{1}{1+i\lambda BD}$. Let

$$\varphi(\lambda) = \left(e^{-\lambda} - \frac{1}{1+i\lambda} \right) \cdot 1_{S_{\mu+}}(\lambda), \text{ so}$$

$$v_t = (1+i\lambda BD)^{-1} v_0 + \varphi(tBD) v_0 = I + II$$

II: $\varphi \rightarrow 0$ when $\lambda \rightarrow 0$ and when $\lambda \rightarrow \infty$.

$$\text{so } \int_0^\infty \|2_t(BD)V_0\|_2^2 \frac{dt}{t} \lesssim \|V_0\|_2^2.$$

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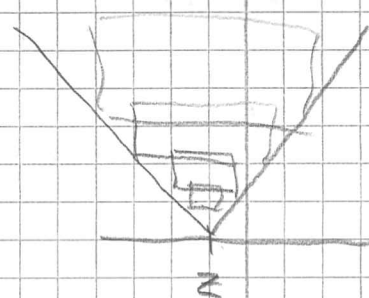
Now consider NT-max of $\tilde{D}$: $V_2 = 2_t(BD)V_0 \Rightarrow$

$$\tilde{N}_*(V_2)(z)^2 = \sup_{t>0} \frac{1}{t^{n+1}} \iint_{W(t,z)} |V_2|^2 ds dy$$

$$\leq \iint_{|y-z|<C\sqrt{t}} |V_2|^2 \frac{ds dy}{t^{n+1}}$$

$$\Rightarrow \|\tilde{N}_*(V_2)\|_2^2 \leq \int_{\mathbb{R}^n} dz \iint_{|y-z|<C\sqrt{t}} |V_2(s,y)|^2 \frac{ds dy}{t^{n+1}}$$

$$\leq \iint_{\mathbb{R}^{n+1}_+} |V_2(s,y)|^2 \frac{ds dy}{s} \lesssim \|V_0\|^2$$



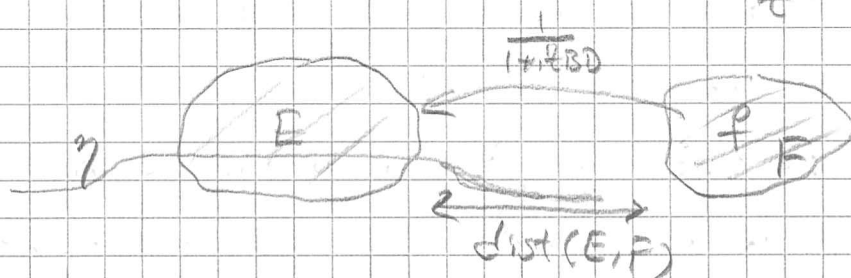
I: This term cannot be bounded by quadratic ests., since $(1+tBD)^{-1}V_0 \not\rightarrow 0, t \rightarrow \infty$.

Instead a max. fun argument based on the following is used. $\exists C_m < \infty$

Lemmas: $\forall m \in \mathbb{Z}_+ \exists \delta > 0 \forall q \in (2-\delta, 2+\delta) \forall t > 0$:

$$\|(1+tBD)^{-1}f\|_{L_q(E)} \leq \frac{C_m}{(1 + \frac{\text{dist}(E,F)}{t})^m} \|f\|_{L_q(F)}$$

if $\text{Supp } f \subset F$
 $E, F \subset \mathbb{R}^n$



Proof: (sketch):

• First $q=2$. We have proved $m=0$.

Proceed by induction, using commutator estimates:

$\eta \in C_c^\infty(\mathbb{R}^n)$, $\eta=0$ on F , $\eta=1$ on E

$\|\nabla \eta\|_\infty \lesssim \frac{1}{\text{dist}(E,F)}$ is used.

$$\begin{aligned}
& \| (1+i\tau BD)^{-1} f \|_{L_2(E)} \leq \| \gamma (1+i\tau BD)^{-1} f \|_{L_2(\mathbb{R}^n)} \\
& = \| [\gamma, (1+i\tau BD)^{-1}] f \|_{L_2(\mathbb{R}^n)} \\
& = - (1+i\tau BD)^{-1} [\gamma, 1+i\tau BD] (1+i\tau BD)^{-1} \\
& \quad = i\tau B [\gamma, D] \\
& \quad \| \cdot \| \lesssim \| \nabla \gamma \|_\infty
\end{aligned}$$

$$\lesssim \tau \frac{1}{\text{dist}(E, F)} \| (1+i\tau BD)^{-1} f \|_{L_2(\text{supp } \nabla \gamma)}$$

Iterate using $\text{dist}(\text{supp}(\nabla \gamma), F) \gtrsim \text{dist}(E, F)$.

- $q \approx 2$: Interpolation with $q=2 \Rightarrow$
suffices to consider $m=0$ when $q \neq 2$.

Consider $(1+i\tau BD) V = f$

$$V = \begin{bmatrix} -u \\ v \end{bmatrix}$$

$$\text{Need } \| V \|_{L_q(\mathbb{R}^n)} \lesssim \| f \|_{L_q(\mathbb{R}^n)}$$

The algebra on p.13, replacing ∂_t by $\frac{1}{it}$, shows

$$\begin{aligned}
& \underbrace{\begin{bmatrix} 1 & itdV_x \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ itD_x \end{bmatrix}}_{= L} u = \begin{bmatrix} 1 & itdV_x \end{bmatrix} \begin{bmatrix} -af_1 \\ f_1 - cf_1 \end{bmatrix}
\end{aligned}$$

$$L: W^{1,q}(\mathbb{R}^n) \rightarrow W^{-1,q}(\mathbb{R}^n), \quad \forall q.$$

Sneiberg extrapolation from $q=2$ shows invertibility when $|q-2| < 8$. See [5:74].

$$\Rightarrow \| u \|_q + \tau \| \nabla u \|_q \lesssim \| f \|_q$$

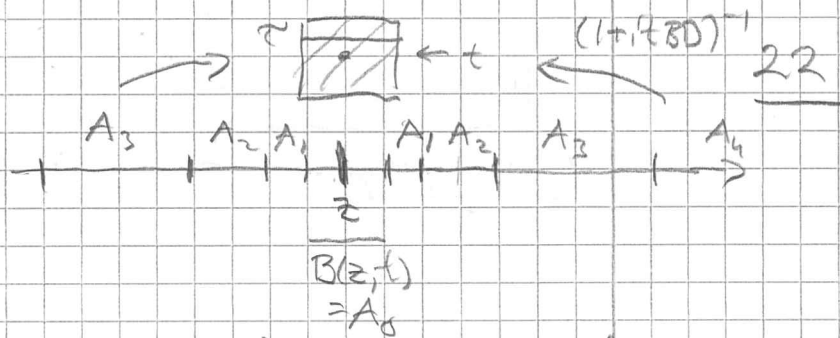
$$\Rightarrow \| v \|_q \lesssim \| u \|_q + \tau \| \nabla u \|_q + \| f \|_q \lesssim \| f \|_q.$$

□

Back to I:

Again by interior regularity, it suffices to bound $\| \tilde{N}_x^q(v_1) \|_2$ for some $q < 2$.
 q -Whitney averages $(1+i\tau BD)^{-1} v_0$

Fix Whitney region
 $W(t, z)$ and $\tau \approx t$.



Split

$$\mathbb{R}^n = \bigcup_{j=0}^{\infty} A_j$$

into dyadic annuli, $A_j = B(z, 2^j t) \setminus B(z, 2^{j-1} t)$.

Lemma $\Rightarrow$

$$\left(\int_{B(z, t)} |R_\tau f|^q \right)^{1/q} \leq \sum_{j=0}^{\infty} \underbrace{\left(\frac{2^j t}{\tau} \right)^{-m}}_{\approx 2^{-jm}} \left(\int_{A_j} |f|^q \right)^{1/q} \lesssim (2^j t)^n M(f^q) \lesssim (t^n M(f^q))^{1/q} \text{ if } m > n/q.$$

$$\Rightarrow \|\tilde{N}_*^q(v, \cdot)\|_2 \lesssim \|M(f^q)^{1/q}\|_2 = \left(\int (M(f^q))^{2/q} \right)^{1/2} \lesssim \|f\|_2.$$

$\lesssim \int f^q \cdot \frac{2}{q} \text{ if } q < 2$

□

Summary of part (C)

A solution to $\operatorname{div}_{t,x} A(x) \nabla_{t,x} u = 0$ in $\mathbb{R}_+^{1+n}$ has n conjugate functions $V_{\parallel}$.

- For any accretive t -independent $A \in L^\infty$ (even for systems, non-real A) we have a priori estimates

$$\|\operatorname{div}_x u\|_2 \lesssim \|u_0\|_2 + \|V_{\parallel,0}\|_2 \approx \|Su\|_2$$

For real A , we have $N_* u \approx \tilde{N}_* u$

- When L_2 -solvability holds in the sense that the Hilbert transform bound $\|V_{\parallel,0}\|_2 \lesssim \|u\|_2$ holds, then

We have L_2 solvability estimates

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$$\|N_* u\|_2 \lesssim \|u_0\|_2 \quad \text{and}$$

$$\|S u\|_2 \lesssim \|u_0\|_2$$

$$\text{In fact } \|\tilde{N}_* u\|_2 \approx \|S u\|_2 \approx \|u_0\|_2$$

⑤

p-solvability estimates

We shall prove such by proving $\|v_{1,0}\|_2 \lesssim \|u_0\|_2$
 assume certain algebraic structure of A ,
 using integration by parts.

Symmetric A :

Consider the generalized CR-system

$$\partial_t V + B D V = 0.$$

$$\text{Recall } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow B = \hat{A} = \begin{bmatrix} a^{-1} & -a^{-1}b \\ c a^{-1} & d - c a^{-1}b \end{bmatrix}$$

and note

$$B^* = \begin{bmatrix} a^{*-1} & a^{*-1}c^* \\ -b^* a^{*-1} & d^* - b^* a^{*-1}c^* \end{bmatrix} \neq \hat{A}^*$$

$$\text{Rather } B^* = N \hat{A}^* N, \text{ where } N = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.$$

$$\therefore A^* = A \not\Rightarrow B^* = B, \text{ but instead } B^* = N B N.$$

$$\text{Prop: } A^* = A \Rightarrow \|v_{1,0}\|_2 \lesssim \|u_0\|_2.$$

Proof:

$$\begin{aligned} & \int_{\mathbb{R}^n} \langle N B^{-1} v_0, v_0 \rangle dx \\ &= \iint_{\mathbb{R}_+^{1+n}} \underbrace{-\partial_t \langle N B^{-1} v, v \rangle}_{= \langle N B^{-1} (B D v), v \rangle + \langle N B^{-1} v, (B D v) \rangle} dt dx \\ &= \langle (N D + D N) v, v \rangle = 0. \end{aligned}$$

$$\Rightarrow \int_{\mathbb{R}^n} \langle B^{-1}(V_{\perp} + V_{\parallel}), -V_{\perp} + V_{\parallel} \rangle dx = 0 \quad \underline{24}$$

$$\Rightarrow \int |V_{\parallel}|^2 dx \leq \underbrace{\int \langle B^{-1} V_{\parallel}, V_{\parallel} \rangle dx}_{B^{-1} \text{ acc.}} + \|u\|_2 \|V_{\parallel}\|_2 + \|u\|_2^2$$

$$\approx \frac{\varepsilon}{2} \|V_{\parallel}\|_2^2 + \frac{1}{2\varepsilon} \|u\|_2^2$$

ε small $\Rightarrow$

$$\|V_{\parallel}\|_2^2 \lesssim \|u\|_2^2 \quad \square$$

Note: this proves in particular Dehnborg's thm on L_2 solvability for Δ on Lipschitz domain. (p.10). Indeed, parametrizing as in Ex. 1 (p.4), this amounts to symmetric coefficient of the special form

$$A = \begin{bmatrix} 1 + |Dh|^2 & -Dh \\ -Dh & I \end{bmatrix} \quad \text{in } \mathbb{R}_+^{1+n}.$$

Triangular A:

A second class of coefficients, for which L_2 -solvability holds is the following triangular matrices.

Prop: If $A = \begin{bmatrix} a & 0 \\ c & d \end{bmatrix}$, that is, if $b=0$, then $\|V_{\parallel,0}\|_2 \lesssim \|u\|_2$.

Proof: Since $\|Su\|_2 \approx \|V_{\parallel,0}\|_2 + \|u\|_2$, it suffices to show

$\|Su\|_2 \lesssim \|u\|_2$, or explicitly

$$\iint_{\mathbb{R}_+^{1+n}} |Du|^2 + |u|^2 dx \lesssim \int_{\mathbb{R}^n} |u|^2 dx.$$

Calculate:

$$\int_{\mathbb{R}^n} |u|^2 dx \underset{\text{accretivity}}{\approx} \int_{\mathbb{R}^n} a |u|^2 dx = - \iint_{\mathbb{R}_+^{1+n}} \overset{a(x)}{a} \overset{\frac{1}{\sqrt{a}}}{\partial_t(u^2)} dt dx$$

$$\begin{aligned} &= \iint a \partial_t^2(u^2) + dt dx \\ &\quad \text{integration by parts in } t. \\ &= a \partial_t(2u \partial_t u) = 2a(\partial_t u)^2 + 2u \partial_t(a \partial_t u) \end{aligned} \quad 25$$

$$/ \operatorname{div} A \nabla u = 0 \Leftrightarrow \partial_t(a \partial_t u) + \operatorname{div}_x(c \partial_t u + d \nabla_x u) /$$

$$= \iint 2a(\partial_t u)^2 + dt dx - \iint 2u \operatorname{div}_x(c \partial_t u + d \nabla_x u) + dt dx$$

$$= \iint (2a(\partial_t u)^2 + 2 \langle \nabla_x u, c \partial_t u + d \nabla_x u \rangle) + dt dx$$

int. by parts in x .

$$= 2 \iint \langle \nabla_{t,x} u, A \nabla_{t,x} u \rangle + dt dx \approx \iint_{\mathbb{R}_+^{1+n}} |\nabla_{t,x} u|^2 + dt dx$$

eccentricity.

$\rightarrow (*)$

The Koch counterexample

We have seen that the 2-solvability estimate holds for real t -independent coefficients $A(x)$, provided A is symmetric or lower triangular.

A concrete example where it fails is provided by

$$\text{by } A(x) = \begin{bmatrix} 1 & k \cdot \operatorname{sgn}(x) \\ -k \operatorname{sgn}(x) & 1 \end{bmatrix}$$

in $\mathbb{R}_+^2$, where $k \in \mathbb{R}$.

Concretely, the PDE

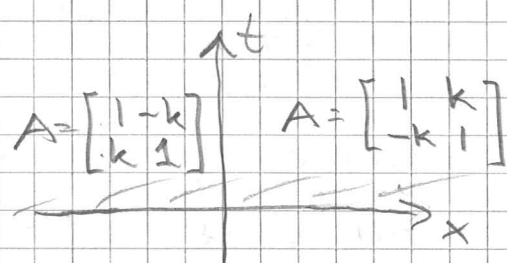
$$\operatorname{div} A \nabla u = 0 \text{ for } u \text{ in } \mathbb{R}_+^2$$

means that

$\Delta u = 0$ in quadrants 1 and 2, and for

$x=0, t>0$ u is continuous but its gradient has jumps

$$|\partial_x u(0+, t) - \partial_x u(0-, t)| = 2k |\partial_t u(0, t)| \quad \text{at } x=0.$$



$\hookrightarrow (*)$ See [AMM:12] for the connection to the Kato estimate and interpolation theory.

Indeed, the jump on the positive t -axis amounts to $(A \nabla u) \cdot e_1 = 0$, which means that $\Delta u A \nabla u = 0$ holds in distribution sense there. Note that $\Delta u \left[\frac{1}{k} \pm \frac{k}{1} \right] \nabla u = \Delta u$ inside the quadrants.

For these equations $\Delta u A \nabla u = 0$, the harmonic measure is explicitly known:

$$u(t, x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{2xt + |y|^{-\alpha} \operatorname{Im} \left\{ (|x| + it)^{\alpha+1} (y^2 - (|x| - it)^2) \right\}}{(t^2 + (x-y)^2)(t^2 + (x+y)^2)} g(y) dy$$

$$= \frac{d\omega(t, x)(y)}{dy} = f(y)$$

where $\tan\left(\frac{\pi}{2}\alpha\right) = k$, $|\alpha| < 1$

Let $p \in (1, \infty)$ and consider the p -solvability estimate, see p. 9-10. We need to verify the reverse Hölder estimate

$$\left(\int_Q f^q dy \right)^{1/q} \leq \int_Q f dy, \quad \forall Q.$$

where $\frac{1}{p} + \frac{1}{q} = 1$. In particular $f \in L^q(\mathbb{R})$.

We note $f(y) \sim |y|^{-\alpha}$ around $y=0$.

Hence $f \notin L^q(\mathbb{R})$ if $\alpha q > 1$.

$$\Leftrightarrow k = \tan\left(\frac{\pi}{2}\alpha\right) > \frac{1}{\tan\left(\frac{\pi}{2p}\right)}$$

$\therefore$ 2-solvability fails if $k > 1$.

Moreover, $\forall p < \infty$: p -solvability fails if k is large enough.

See [KKPT:00, p. 251-253]

and [A:09, eqn. (3)].

We end these lectures by discussing the proof of the following state-of-the-art solvability estimate for the Dirichlet problem

Thm: If $A(x)$ are real and t -independent coefficients, not necessarily symmetric or triangular, then the BMO solvability estimate (p. 11-12) holds. Equivalently, A -harmonic measure $\omega \in A_\infty(dy)$.

Cor: For real and t -independent $A(x)$, the p -solvability estimate holds $\forall p > p_0$, for some $p_0 < \infty$ depending on A .

This was proved in [HKMP:15, thm 1.23], building on the 2-dimensional ($n=1$) proof from [KKPT:00, thm 3.1]. These proofs contained 3 main steps.

(A) Proving equivalence between the non-tang. maximal function and square function:

$$\|S\|_p \approx \|N\|_p, \quad \forall \text{ solutions } u.$$

It is known that if this holds for some p , then it holds for all p .

(B) Proving the ε -approximability property:
Fix $\varepsilon > 0$. $\forall$ solutions u with $\|u\|_\infty \leq 1$

$$\exists \varphi: \mathbb{R}_+^n \rightarrow \mathbb{R} \text{ s.t.}$$

$$\|u - \varphi\|_\infty \leq \varepsilon$$

$$\sup_{\substack{Q \in \mathbb{R}^n \\ \text{cube}}} \frac{1}{|Q|} \int_Q |\nabla \varphi| dA dx \leq C_\varepsilon. \quad (*)$$

Recall that we aim for the BMO solvability estimate

$$\sup_Q \frac{1}{|Q|} \iint_Q |\nabla u|^2 t dt dx \leq \|g\|_{\text{BMO}}^2.$$

For bounded u we expect $|\nabla u| \leq \frac{1}{t}$, so $|\nabla u|^2 t \leq |\nabla u|$. However, (*) is known to fail for $\varphi = u$. This is why we need to allow for $\varphi \neq u$.

(C) Proving $\omega \in A_\infty(dy)$.

(A) $\Rightarrow$ (B) : $N < S$ we know from part C of these notes. $S < N$ was proved in [HKMP:15, thm 1.7].

(A) $\Rightarrow$ (B) : This involves a stopping time argument related to Carleson's corona theorem and the H^1 -BMO duality. See [G:81, sec. VIII.6], [D:81].

(B) $\Rightarrow$ (C) : This builds on Garnett's quantitative Fatou result [G:81, cor. 6.2, p. 339]. See [KKPT:00, thm 2.3, p. 242-249].

In fact (A)-(C) are all equivalent, since the implication (C) $\Rightarrow$ (A) was proved in [DJK:84].

There is a simpler proof of BMO-solvability due to [KKPT:16], which avoids step (B) and the use of ε -approx., which we now outline.

Recall that $L_\infty \subseteq \text{BMO}$, so $\|g\|_{\text{BMO}} \leq \|g\|_\infty$. One first proves the following weaker version of the BMO solvability estimate.

Thm [HKMP: 15, cor. 1.10]

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$$\sup_{\mathbb{R}} \frac{1}{|x|} \int_{\mathbb{R}} |\nabla u|^2 dx \lesssim \|u\|_{\infty}^2 \quad (*)$$

holds for bounded solutions u .

Proof-idea:

- If $A = \begin{bmatrix} a & 0 \\ c & d \end{bmatrix}$ is triangular, we proved (p. 24-25) that

$$\int_{\mathbb{R}^{1+n}_+} |\nabla u|^2 dx \lesssim \int_{\mathbb{R}^n} |u|^2 dx$$

Localization as on p. 11 gives $(*)$

- For general $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ we do the change of variables in Ex 1, p. 4. The corresponding coeffs. A_1 in the Lipschitz domain Ω_1 satisfies

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & -\nabla h \\ 0 & I \end{bmatrix} A_1 \begin{bmatrix} 1 & 0 \\ -\nabla h^T & I \end{bmatrix}$$

$$\begin{aligned} \Rightarrow A_1 &= \begin{bmatrix} 1 & \nabla h \\ 0 & I \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \nabla h^T & I \end{bmatrix} \\ &= \begin{bmatrix} a + \nabla h \cdot c + c \cdot \nabla h^T & b + \nabla h \cdot d \\ c + \nabla h^T \cdot d & d \end{bmatrix} \end{aligned}$$

We get triangular coeff $A_1 = \begin{bmatrix} a' & 0 \\ c' & d' \end{bmatrix}$ if we can choose $h(x)$ s.t. $b + \nabla h \cdot d = 0$.

This is possible when $n=1$. See

[KKPT: 00, thm 3.1], where they generalize the triangular estimate from $\mathbb{R}^{1+n}_+$ to Ω_1 .

- In higher dimension $n \geq 2$, there is in general no scalar function $h: \mathbb{R}^n \rightarrow \mathbb{R}$ s.t. $\nabla h = -b \cdot d^{-1}$

We can however make a Helmholtz / Hodge splitting of the vector field $v = -b \cdot d^{-1}$;

$$v = \nabla h + \tilde{v}, \text{ where } \tilde{v} \text{ is a}$$

divergence free vector field on $\mathbb{R}^n$.

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Choosing instead $\vec{v}$ in an A -adapted complement to $\{\text{gradients } \nabla h\}$, similar to 2^{nd} prep. on p. 15, the above reduction to triangular matrices is extended to dim. $n \geq 2$. See [HKMP: 15, sec. 2-3]. $\square$

We now sketch the proof of $\omega \in A_\infty(dy)$.

[Need: $\exists \delta, \varepsilon \in (0, 1)$:

$$[\omega(E) \leq \delta \omega(Q) \Rightarrow |E| \leq \varepsilon |Q|, \forall \text{ cubes } Q, E \subset Q]$$

The A_∞ condition is "symmetric", so this gives

$$|E| \leq (1-\varepsilon)|Q| \Rightarrow |Q \setminus E| > \varepsilon |Q| \Rightarrow$$

$$\omega(Q \setminus E) > \delta \omega(Q) \Rightarrow \omega(E) \leq (1-\delta)\omega(Q), \text{ so } \omega \in A_\infty(dy)$$

A toy model for the needed construction is as follows.

Ex: $Q \in \mathbb{R}^n$ ^{dyadic} cube, $E \subset Q$ small subset, $\gamma \in (0, 1)$ given.

Select the maximal ^{dyadic} subcubes $\{Q_k\}$ s.t.

$$|Q_k \cap E| > \gamma |Q_k|$$

Disjointness $\Rightarrow$

$$\sum_k |Q_k| \leq \frac{1}{\gamma} \sum_k |Q_k \cap E| \leq \frac{1}{\gamma} |E| \ll |Q|$$

doubling
property
of
 ω

$$\text{maximality} \Rightarrow |Q_k \cap E| \leq \underbrace{|\tilde{Q}_k \cap E|}_{\text{part of } Q_k} \leq \delta |\tilde{Q}_k| \leq \delta \cdot 2^n |Q_k|$$

Set $E_1 = \cup Q_k$. Replace E by E_1 and repeat construction $\Rightarrow$

$$E \subset E_1 \subset E_2 \subset \dots \subset E_N \subset Q$$

$$\bullet |E_{j+1}| \leq \frac{1}{\gamma} |E_j|$$

$$\bullet E_j \text{ is "small in } E_{j+1}": |E_j \cap Q_k^{(j)}| \leq 2^n \delta \cdot |Q_k^{(j)}|, \forall k$$

where $E_{j+1} = \bigcup_k Q_k^{j+1}$ 3.1

Need $(\frac{1}{\delta})^N \cdot |E| \lesssim |Q|$, so $N \lesssim \log \frac{|Q|}{|E|}$.

$\therefore E$ can be enlarged $\sim \log \frac{|Q|}{|E|}$ times.

$E \subset E_1 \subset \dots \subset E_N$ is said to be a good $2^N \cdot \gamma$ -cover of E of length N . ✓

The proof of [KKPT:16, thm 3.1] goes as follows.

Given $E \subset \mathbb{Q}$ with $\omega(E) \leq \delta \omega(Q)$.

Replace Lebesgue meas. 1.1 by harm. meas. ω .
is construction of good cover. This works since

- ω is known to be a doubling measure:

$$\omega(2Q) \leq C \cdot \omega(Q)$$

- "dyadic cubes" Q_k adopted



to ω can be constructed. See [C:90].

We get a good cover $E \subset E_1 \subset \dots \subset E_N \subset Q$

where E_j is " ω -small" in E_{j+1} : $\log \frac{\omega(Q)}{\omega(E)}$

$$\omega(E_j \cap Q_k^{j+1}) \leq \omega(Q_k^{j+1}).$$

From this good cover, one constructs a subset

$H \subset \mathbb{Q}$ and considers the solution u to

$$\begin{aligned} \Delta u &= 0 \text{ in } \mathbb{R}_+^n \\ u &= 1_H \text{ on } \mathbb{R}^n \end{aligned}$$

The idea is that u is very oscillatory on

E , and it is proved it [KKPT:16, prop. 3.1

and thm 3.1] that

$$N \cdot |E| \lesssim \int_{\mathbb{Q}} |\nabla u|^2 dx$$

With (*), p. 29, we get $N \cdot |E| \lesssim \|1_H\|_\infty \cdot |Q|$

$$\text{so } |E| \leq \frac{1}{\log \frac{\omega(Q)}{\omega(E)}} \cdot |Q|$$

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Since $\frac{1}{\log 1/t} \rightarrow 0$ as $t \rightarrow 0$, this proves
 $\exists \delta, \varepsilon \in (0, 1) : \omega(E) \leq \delta \omega(Q) \Rightarrow |E| \leq \varepsilon |Q|.$

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